

General Description

The MAX3996 is a high-speed laser driver for smallform-factor (SFF) fiber optic LAN transmitters. It contains a bias generator, a laser modulator, and comprehensive safety features. Automatic power control (APC) adjusts the laser bias current to maintain average optical power, regardless of changes in temperature or laser properties. The driver accommodates common anode or differential laser configurations. The output current range of the MAX3996 is appropriate for VCSELs and high-efficiency edge-emitting lasers.

The MAX3996 operates up to 3.2Gbps. It can switch up to 30mA of laser modulation current and sink up to 60mA bias current. Adjustable temperature compensation is provided to keep the optical extinction ratio within specifications over the operating temperature range. The MAX3996 accommodates various laser packages, including low-cost TO-46 headers. Low deterministic jitter (9psp-p), combined with fast edge transitions, (65ps) provides excellent margins compared to industry-standard transmitter eye masks.

This laser driver provides extensive safety features to guarantee single-point fault tolerance. Safety features include a transmit disable, redundant shutdown, and laser-bias monitoring. The safety circuit detects faults that could cause hazardous light levels and immediately disables the laser output. The MAX3996 safety circuits are compliant with SFF and small-form-factor pluggable (SFP) multisource agreements (MSA).

The MAX3996 is available in a compact 4mm × 4mm, 20-pin QFN package and operates over a temperature range of 0°C to +70°C.

Applications

Fibre Channel Optical Transmitters **VCSEL** Transmitters Gigabit Ethernet Optical Transmitters ATM LAN Optical Transmitters 10 Gigabit Ethernet WWDM

Pin Configuration appears at end of data sheet.

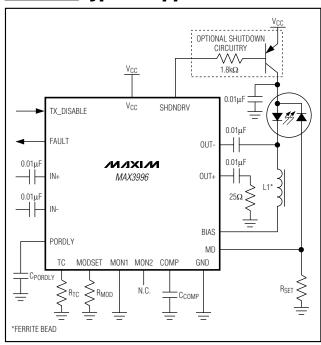
Features

- ♦ 9psp-p Deterministic Jitter
- ◆ 20-Pin QFN 4mm × 4mm Package
- ♦ 3.0V to 5.5V Supply Voltage
- **♦ Automatic Power Control**
- ♦ Integrated Safety Circuits
- ♦ 30mA Laser Modulation Current
- **♦ Temperature Compensation of Modulation** Current
- ♦ Compliant with SFF and SFP MSA

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX3996CGP	0°C to +70°C	20 QFN

Typical Application Circuit



MIXIM

Maxim Integrated Products 1

ABSOLUTE MAXIMUM RATINGS

Supply Voltage at V _{CC} 0.5V to +7.0	V	С
Voltage at TX_DISABLE, PORDLY, MON1, COMP,		С
IN+, IN-, MD, BIAS, MODSET, TC0.5V to (V _{CC} + 0.5)	V)	С
Voltage between COMP and MON22.3	3V	С
Voltage between IN+ and IN5	δV	
Voltage at OUT+, OUT(VCC - 2V) to (VCC + 2'	V)	0
Voltage between MON1 and MON21.5	ōV	0
Voltage between BIAS and MON2	1V	St

Current into FAULT, SHDNDRV	
Current into OUT+, OUT	60mA
Current into BIAS	120mA
Continuous Power Dissipation ($T_A = +70$ °C)	
20-Pin QFN (derate 20mW/°C)	1600mW
Operating Ambient Temperature Range	40°C to +85°C
Operating Junction Temperature Range	40°C to +150°C
Storage Temperature Range	55°C to +150°C
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Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{CC} = 3.0V \text{ to } 5.5V, T_A = 0^{\circ}\text{C to } +70^{\circ}\text{C}, \text{ unless otherwise noted.}$ Typical values are at $V_{CC} = 3.3V, TC$ pin not connected, $T_A = +25^{\circ}\text{C.}$) (Figure 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
	lcc	V _{CC} = 3.3V, I _{MOD} = 15mA		47		
Supply Current	(Figure1) (Note 1)	V_{CC} = 5.5V, I_{MOD} = 30mA, R_{MODSET} = 2.37k Ω		52	75	mA
Data Input Voltage Swing	V _{ID}	Total differential signal (Figure 2)	200		2200	MV _{P-P}
TX_DISABLE Input Current		0 < V _{PIN} < V _{CC}	-100		100	μΑ
TX_DISABLE Input High Voltage	VIH		2.0			V
TX_DISABLE Input Low Voltage	VIL				0.8	V
FAULT Output High Voltage	VoH	I_{OH} = -100μA, 4.7k Ω < R _{FAULT} < 10k Ω	2.4			V
FAULT Output Low Voltage	V _{OL}	I _{OL} = 1mA			0.4	V
BIAS GENERATOR						
Minimum Bias Current	I _{BIAS}	Current into BIAS pin			1	mA
Maximum Bias Current	IBIAS	Current into BIAS pin	60			mA
		APC loop is closed	1.04	1.12		
MD Quiescent Voltage	V _{MD}	FAULT = high		Vcc - 0.7	73	V
		TX_DISABLE = high		Vcc - 0.7	73	
Monitor Resistance	RMON	(Figure 4)	9.3	11	12.7	Ω
MD Input Current		FAULT = low, TX_DISABLE = low	-3	0.8	3	μΑ
BIAS Current During Fault	IBIAS_OFF				10	μΑ
APC Time Constant		С _{СОМР} = 0.1µF		35		μs
POWER-ON RESET (POR)			•			•
POR Threshold		Measured at V _{CC}	2.65	2.7	3.0	V
DOD Delevi		PORDLY = open (Note 3)	30	55		μs
POR Delay	tpordly	CPORDLY = 0.001µF (Note 3)	1.7	2.4		ms
POR Hysteresis				20		mV
SHUTDOWN			•			•
		ISHDNDRV = 10µA, FAULT = high	V _{CC} - 0.	4		
Voltage at SHDNDRV		ISHDNDRV = 1mA, FAULT = low			V _{CC} - 2.4	V
		ISHDNDRV = 15mA, FAULT = low	0		V _{CC} - 1.2	
LASER MODULATOR						
Data Rate				< 3.2		Gbps

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = 3.0V \text{ to } 5.5V, T_A = 0^{\circ}\text{C} \text{ to } +70^{\circ}\text{C}, \text{ unless otherwise noted.}$ Typical values are at $V_{CC} = 3.3V, TC$ pin not connected, $T_A = +25^{\circ}\text{C}.)$ (Figure 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Minimum Modulation Current	iMOD				2	mA _{P-P}	
Maximum Modulation Current	iMOD	$R_L \le 25\Omega$	30	40		mA _{P-P}	
Accuracy of Modulation Current (Part-to-Part Variation)		R _{MODSET} = 2.37 kΩ (i _{MOD} ≈ 30 mAp-p into 25 Ω)	-10		+10	%	
		i_{MOD} = 5mA into 25 Ω , 20% to 80% (Note 3)		54	100		
Edge Transition Time	t _r , t _f	$i_{MOD} = 10 \text{mA} \text{ into } 25\Omega, 20\% \text{ to } 80\% \text{ (Note 3)}$		55	125	ps	
		$i_{MOD} = 30 \text{mA} \text{ into } 25\Omega, 20\% \text{ to } 80\% \text{ (Note 3)}$		65	130		
		$i_{MOD} = 5mA \text{ into } 25\Omega \text{ (Notes 2, 3)}$		17	35		
Deterministic Jitter		$i_{MOD} = 10 \text{mA} \text{ into } 25\Omega \text{ (Notes 2, 3)}$		14	22	psp-p	
	,	$i_{MOD} = 30 \text{mA} \text{ into } 25\Omega \text{ (Notes 2, 3)}$		9	20		
Random Jitter		(Note 3)		2	8	ps _{RMS}	
Modulation Current During Fault	iMOD_OFF			15	200	μA _{P-P}	
M I I II O I I T		Tempco = MAX, R _{MOD} = open		4000		100	
Modulation Current Tempco	Tempco = MIN, RTC = open			50		ppm/°C	
Input Resistance	R _{IN}	Differential	85		115	Ω	
Output Resistance	Rout	Single ended; outputs to V _{CC}	42	50	58	Ω	
Input Common-Mode Voltage				V _C C - 0.3		V	
SAFETY FEATURES (See Typical	l Operating (Characteristics)	I			1	
MODSET and TC Pin Fault Threshold			200			mV	
BIAS Pin Fault Threshold		A fault will be triggered if V _{BIAS} is less than this voltage	300	400		mV	
Excessive Bias Current Fault		A fault will be triggered if V _{MON2} exceeds this voltage		400	440	mV	
TX Disable Time	t_off	Time from rising edge of TX_DISABLE to IBIAS = IBIAS_OFF and iMOD = iMOD_OFF (Note 3)		0.06	5	μs	
TX Disable Negate Time	t_on	Time from falling edge of TX_DISABLE to IBIAS and iMOD at 95% of steady state (Note 3)		37	500	μs	
Reset Initialization Time	t_init	From power ON or negation of FAULT using TX_DISABLE. Time to set FAULT = low, i _{MOD} = 95% of steady state and I _{BIAS} = 95% of steady state (Note 3)		23	200	ms	
Fault Assert Time	t_fault	Time from fault to FAULT = high, CFAULT < 20pF, RFAULT = $4.7k\Omega$ (Note 3)		14	50	μs	
TX_DISABLE Reset	t_reset	Time TX_DISABLE must be held high to reset FAULT (Note 3)		0.01	1	μs	

Note 1: Supply current excludes bias and modulation currents.

Note 2: Deterministic jitter is the peak-to-peak deviation from the ideal time crossings measured with a K28.5 bit pattern 00111110101100000101.

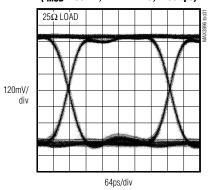
Note 3: AC characteristics guaranteed by design and characterization.



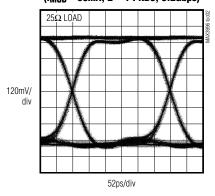
Typical Operating Characteristics

($V_{CC} = 3.3V$, $T_A = +25$ °C, unless otherwise noted.)

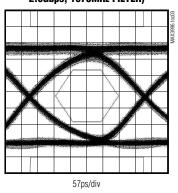
ELECTRICAL EYE DIAGRAM (i_{MOD} = 30mA, 2⁷ - 1 PRBS, 2.5Gbps)



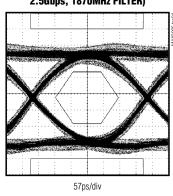
ELECTRICAL EYE DIAGRAM (i_{mod} = 30mA, 2⁷ - 1 PRBS, 3.2Gbps)



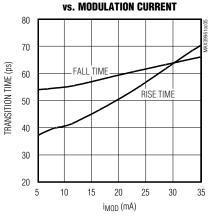
OPTICAL EYE DIAGRAM (i_{MOD} = 5mA, 850nm VCSEL, 2⁷ - 1 PRBS, 2.5Gbps, 1870MHz FILTER)



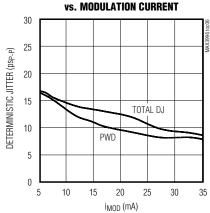
OPTICAL EYE DIAGRAM
(iMOD = 15mA, 1310nm LASER, 2⁷ - 1 PRBS, 2.5Gbps, 1870MHz FILTER)



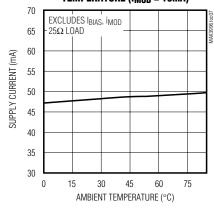
TRANSITION TIME



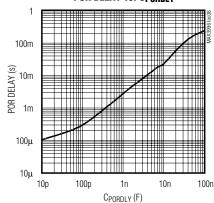
DETERMINISTIC JITTER



SUPPLY CURRENT vs.
TEMPERATURE (i_{MOD} = 15mA)

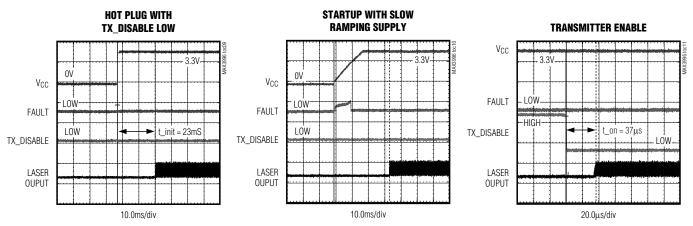


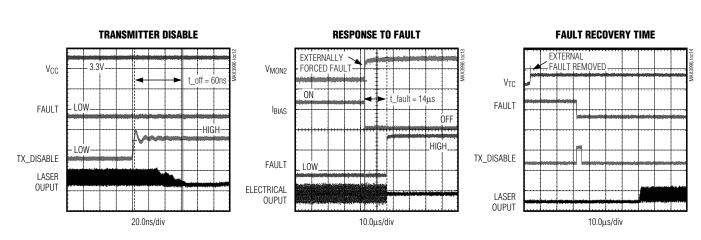
POR DELAY vs. CPORDLY

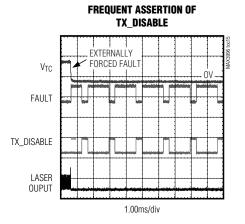


Typical Operating Characteristics (continued)

($V_{CC} = 3.3V$, $T_A = +25$ °C, unless otherwise noted.)







Pin Description

PIN	NAME	FUNCTION
1	TC	Temperature Compensation Set. The resistor at TC programs the temperature-increasing component of the laser-modulation current.
2	FAULT	Fault Indicator. See Table 1.
3, 9	GND	Ground
4	TX_DISABLE	Transmit Disable. Laser output is disabled when TX_DISABLE is high or left unconnected. The laser output is enabled when this pin is asserted low.
5	PORDLY	Power-On Reset Delay. A capacitor connected between PORDLY and GND can be used to extend the delay for the power-on reset circuit. See the <i>Design Procedure</i> section.
6, 16, 19	Vcc	Supply Voltage
7	IN+	Noninverting Data Input
8	IN-	Inverting Data Input
10	MON1	Attaches to the emitter of the bias driving transistor through a 10Ω resistor. See the <i>Design Procedure</i> section.
11	MON2	This pin attaches to the emitter of the bias driving transistor. See the Design Procedure section.
12	COMP	A capacitor connected from this pin to ground sets the dominant pole of the APC loop. See the <i>Design Procedure</i> section.
13	MD	Monitor Diode Connection. MD is used for automatic power control.
14	SHDNDRV	Shutdown Driver Output. Provides a redundant laser shutdown.
15	BIAS	Laser Bias Current Output
17	OUT+	Positive Modulation-Current Output. Current flows from this pin when input data is high.
18	OUT-	Negative Modulation-Current Output. Current flows to this pin when input data is high.
20	MODSET	A resistor connected from this pin to ground sets the desired modulation current.
EP	Exposed Pad	Ground. This must be soldered to the circuit board ground for proper thermal and electrical performance. See the <i>Layout Considerations</i> section.

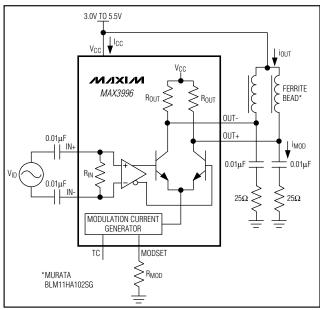


Figure 1. Output Load for AC Specification

Detailed Description

The MAX3996 contains a bias generator with automatic power control and smooth start, a laser modulator, a power-on reset (POR) circuit, and safety circuitry (Figure 3).

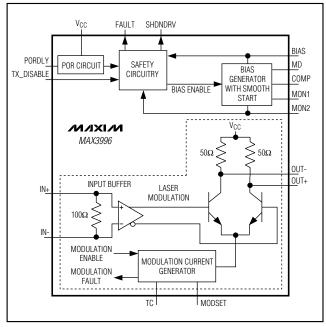


Figure 3. Laser Driver Functional Diagram

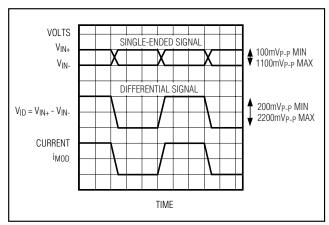


Figure 2. Required Input Signal and Modulation-Current Polarity

Bias Generator

Figure 4 shows the bias generator circuitry that contains a power-control amplifier, smooth-start circuitry, and two bias-fault sensors. The power-control amplifier combined with an internal NPN transistor provides DC laser current to bias the laser in a light-emitting state. The APC circuitry adjusts the laser bias current to maintain average power over temperature and changing laser properties. The smooth-start circuitry prevents current spikes to the laser during power-up or enable, ensuring compliance with safety requirements and extending the life of the laser.

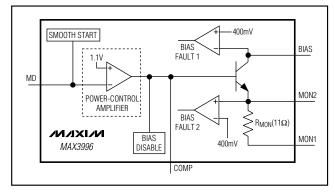


Figure 4. Bias Circuitry

The MD input is connected to the anode of a monitor diode, which is used to sense laser power. The BIAS output is connected to the cathode of the laser through an inductor or ferrite bead. The power-control amplifier drives a transistor to control the laser's bias current. In a fault condition (Table 1), the base of the bias-driving transistor is pulled low to ensure that bias current is turned off.

Table 1. Typical Fault Conditions

PIN	FAULT CONDITION
MON2	V _{MON2} > 400mV
BIAS	V _{BIAS} < 400mV
TC, MODSET	V _{MODSET} or V _{TC} < 200mV

Smooth-Start

During startup, the laser does not emit light, and the APC loop is not closed. The smooth-start circuit pulls the MD pin to approximately 2.5V during the POR delay and while TX_DISABLE is high. This causes the power-control amplifier to shut off the bias transistor. When POR delay is over and TX_DISABLE is low, the MD pin is released and pulled to GND by RSET because there is no laser power and thus no monitor diode current. The output voltage of the power-control amplifier then begins to increase. A capacitor attached to COMP (CCOMP) slows the slew rate and allows a controlled increase in bias current (Figure 11). Maxim recommends CCOMP = 0.1µF.

Modulation Circuitry

The modulation circuitry consists of an input buffer, a current mirror, and a high-speed current switch (Figure 5). The modulator drives up to 30mA of modulation current into a 25Ω load.

Many of the modulator performance specifications depend on total modulator current. To ensure good driver performance, the voltage at either OUT+ or OUT- must not be less than $V_{\rm CC}$ - 1V.

The amplitude of the modulation current is set with resistors at the MODSET and temperature coefficient (TC) pins. The resistor at MODSET (RMOD) programs the temperature-stable portion of the modulation current, and the resistor at TC (RTC) programs the temperature-increasing portion of the modulation current. Figure 6 shows modulation current as a function of temperature for two extremes: RTC is open (the modulation current has zero temperature coefficient), and RMOD is open (the modulation temperature coefficient values of the modulation current can be obtained as described in the Design Procedure section. Table 2 is the RTC and RMOD selection table.

Safety Circuitry

The safety circuitry contains a disable input, a fault latch, and fault detectors (Figure 7). This circuitry monitors the operation of the laser driver and forces a shutdown if a single-point fault is detected. A single-point fault can be a short to VCC or GND, or between any two

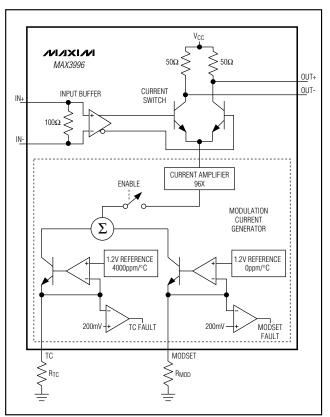


Figure 5. Modulation Circuitry

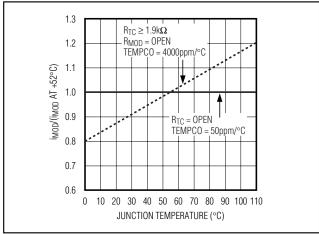


Figure 6. Modulation Current vs. Temperature for Maximum and Minimum Temperature Coefficient

Table 2. RTC and RMOD Selection Table

TEMPCO	i _{MOD} =	30mA	i _{MOD} =	: 15mA	i _{MOD} = 5mA			
(ppm/°C)	R_{MOD} ($k\Omega$)	R_{TC} ($k\Omega$)	R_{MOD} ($k\Omega$)	R_{TC} ($k\Omega$)	R_{MOD} ($k\Omega$)	R_{TC} ($k\Omega$)		
3500	17.1	1.85	34.4	3.94	104	12.3		
3000	8.04 2.19		16.3	4.64	49.5	14.4		
2500	5.20	2.68	10.6	5.62	32.4	17.4		
2000	3.81	3.42	7.86	7.08	24.1	21.8		
1500			6.21	9.53	19.1	29.1		
1000			5.12	14.4	15.9	43.8		
500	2.05	14.4	4.34	29.1	13.5	87.8		

Table 3. Circuit Responses to Various Single-Point Faults

PIN NAME	CIRCUIT RESPONSE TO OVERVOLTAGE OR SHORT TO V _{CC}	CIRCUIT RESPONSE TO UNDERVOLTAGE OR SHORT TO GROUND					
TC	Does not affect laser power.	Fault state* occurs.					
FAULT	Does not affect laser power.	Does not affect laser power.					
TX_DISABLE	Modulation and bias current are disabled.	Normal condition for circuit operation.					
PORDLY	Does not affect laser power.	Modulation and bias current are disabled.					
IN+, IN-	Does not affect laser power.	Does not affect laser power.					
MON1	Fault state* occurs.	Does not affect laser power.					
MON2	Fault state* occurs.	Does not affect laser power.					
COMP	A fault is detected at either the collector or the emitter of the internal bias transistor, and a fault state* occurs. If the shutdown circuitry is used, bias current is shut off.	Disables bias current.					
MD	Disables bias current.	The APC circuit responds by increasing bias current until a fault is detected at the emitter or collector of the bias transistor, and then a fault* state occurs.					
SHDNDRV	Does not affect laser power. If the shutdown circuitry is used, bias current is shut off.	Does not affect laser power.					
BIAS	In this condition, laser forward voltage is 0V and no light is emitted.	Fault state* occurs. If the shutdown circuitry is used, bias current is shut off.					
OUT+, OUT-	Does not affect laser power.	Does not affect laser power.					
MODSET	Does not affect laser power. Fault* state may occur.	Fault state* occurs.					

^{*}A fault state asserts the FAULT pin, disables the modulator outputs, disables the bias output, and asserts the SHDNDRV pin.

IC pins. See Table 3 to view the circuit response to various single-point failures. The shutdown condition is latched until reset by a toggle of $TX_DISABLE$ or V_{CC} .

Fault Detection

All critical nodes are monitored for safety faults, and any node voltage that differs significantly from its expected value results in a fault (Table 1). When a fault condition is detected, the laser is shut down. See Applications Information for more information on laser safety.

Shutdown

The laser driver offers redundant bias shutdown. The SHDNDRV output drives an optional external transistor. The bias and modulation drivers have separate internal disable signals.

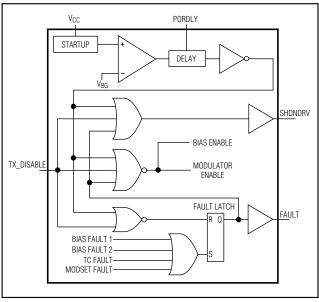


Figure 7. Safety Circuitry Functional Diagram

Latched Fault Output

An open-collector FAULT output is provided with the MAX3996. This output is latched until the power is switched off, then on, or until TX_DISABLE is switched to HIGH and then LOW.

Power-On Reset

The MAX3996 contains an internal power-on reset delay to reject noise on V_{CC} during power-on or hotplugging. Adding capacitance to the PORDLY pin can extend the delay. The POR comparator includes hysteresis to improve noise rejection.

_Design Procedure

Select Laser

Select a communications-grade laser with a rise time of 260ps or better for 1.25Gbps or 130ps or better for 2.5Gbps applications. To meet the MAX3996's AC specifications, the voltage at both OUT+ and OUT-must remain above V_{CC} - 1V at all times.

Use a high-efficiency laser that requires low modulation current and generates a low voltage swing. Trimming the leads can reduce laser package inductance. Typical package leads have inductance of 25nH per inch (1nH/mm); this inductance causes a large voltage swing across the laser. A compensation filter network also can be used to reduce ringing, edge speed, and voltage swing.

Programming Modulation Current

Resistors at the MODSET and TC pins set the amplitude of the modulation current. The resistor R_{MOD} sets the temperature-stable portion of the modulation current, and the resistor (RTC) sets the temperature-increasing portion of the modulation current. To determine the appropriate temperature coefficient from the slope efficiency (η) of the laser, use the following equation:

$$LASER_TEMPCO = \frac{\eta_{70} - \eta_{25}}{\eta_{25} \left(70^{\circ}C - 25^{\circ}C\right)} \times 10^{6}$$
[ppm/°C]

For example, if a laser has a slope efficiency $\eta_{25} = 0.021 \text{mW/mA}$, which reduces to $\eta_{70} = 0.018 \text{mW/mA}$. Using the above equation will produce a laser tempco of -3175ppm/°C.

To obtain the desired modulation current and tempco for the device, the following equations can be used to determine the required values of R_{MOD} and R_{TC} :

$$\begin{split} R_{TC} &= \frac{0.22}{\text{Tempco/10}^6 \times i_{MOD}} - 250\Omega \\ R_{MOD} &= \frac{\text{Tempco/10}^6 \left(R_{TC} + 250\Omega\right)52}{\left(0.19 - 48 \times \text{Tempco/10}^6\right)} - 250\Omega \end{split}$$

where tempco = -laser tempco, 0 < tempco < $4000ppm/^{\circ}C$, and $2mA < i_{MOD} < 30mA$.

Figure 8 shows a family of curves derived from these equations. The straight diagonal lines depict constant tempcos. The curved lines represent constant modulation currents. If no temperature compensation is desired, leave TC open, and the equation for imodesimplifies considerably.

The following equations were used to derive Figure 8 and the equations at the beginning of this section.

$$i_{MOD}(T) = 77 \times \frac{50}{50 + R_L} \left[\frac{1.15}{R_{MOD} + 250\Omega} + \frac{1.06}{R_{TC} + 250\Omega} \times 0.004(T - 25^{\circ}C) \right] Amps$$

$$i_{MOD}(70^{\circ}C) = i_{MOD}(25^{\circ}C) + i_{MOD}(25^{\circ}C) \times (70^{\circ}C - 25^{\circ}C)Amps$$

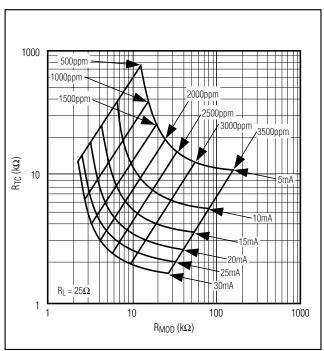


Figure 8. R_{TC} vs. R_{MOD} for Various Conditions

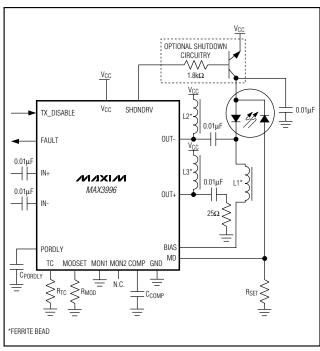


Figure 9. Large Modulation Current

Determine Modulator Configuration

The MAX3996 can be used in several configurations. For modulation currents less than 20mA, Maxim recommends the configuration shown in the *Typical Application Circuit*. Outputs greater than 20mA could cause the voltage at the modulator output to be less than V_{CC} - 1V, which might degrade laser output. For large currents, Maxim recommends the configuration in Figure 9. A differential configuration is in Figure 10.

Designing the Bias Filter and Output Pullup Beads

To reduce deterministic jitter, add a ferrite bead inductor (L1) between the BIAS pin and the cathode of the laser. Select L1 to have an impedance >100 Ω between f = 10MHz and f = 2GHz, and a DC resistance < 3 Ω ; Maxim recommends the Murata BLM11HA102SG. These inductors are also desirable for connecting the OUT+ and OUT- pins to VCC.

Programming Laser Power and Bias Fault Threshold

The IC is designed to drive a common anode laser with a photodiode. A servo-control loop is formed by the internal NPN bias-driving transistor, the laser diode, the monitor diode (RSET), and the power-control amplifier (Figure 11). The voltage at MD is stabilized to 1.1V. The

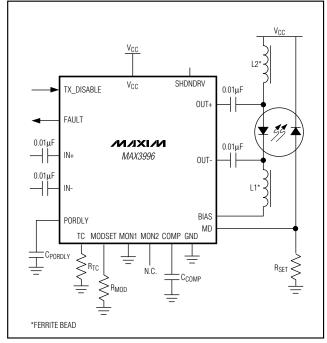


Figure 10. Differential Configuration

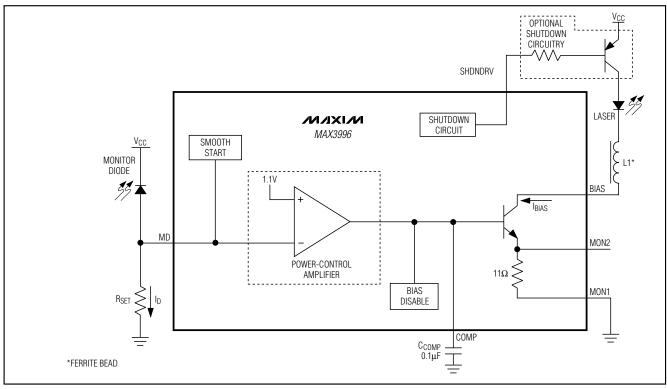


Figure 11. APC Loop

monitor photodiode current is set by $I_D = V_{MD}/R_{SET}$. Determine the desired monitor current (I_D), and then select $R_{SET} = 1.1V/I_D$.

A bias stabilizing capacitor (C_{COMP}) must be connected between the COMP pin and ground to obtain the desired APC loop time constant. This improves power-supply and ground noise rejection. A capacitance of 0.1 μ F usually is sufficient to obtain time constants of up to 35 μ s.

The degeneration resistance between MON2 and ground determines the bias current that causes a fault and affects the APC time constant. Select R_{MON} (the total resistance between MON2 and ground) = 400 mV/(maximum bias current). A degeneration resistance of 10Ω can be obtained by grounding MON1. Increasing R_{MON} increases the APC time constant.

The discrete components for use with the common anode with photodiode configuration are:

RSET = 1.1V/ID

 $C_{COMP} = 0.1 \mu F (typ)$

L1 = ferrite bead, see the *Bias Filter* section

RMON = 400mV/(maximum bias current)

Programming POR Delay

A capacitor can be added to PORDLY to increase the delay when powering up the part. The delay will be approximately:

$$t = \frac{C_{PORDLY}}{1.4 \times 10^{-6}}$$
 seconds

See the Typical Operating Characteristics section.

Designing the Laser-Compensation Filter Network

Laser package inductance causes the laser impedance to increase at high frequencies, leading to ringing, overshoot, and degradation of the laser output. A laser-compensation filter network can be used to reduce the laser impedance at high frequencies, thereby reducing output ringing and overshoot.

The compensation components (RF and CF) are most easily determined by experimentation. For interfacing with edge-emitting lasers, refer to application note HFAN-2.0, *Interfacing Maxim Laser Drivers with Laser Diodes*. Begin with RF = 50Ω and CF = 2pF. Increase CF until the desired transmitter response is obtained (Figure 12).

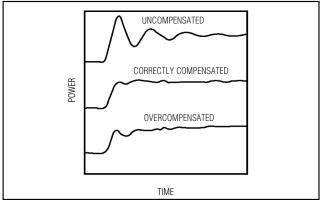


Figure 12. Laser Compensation

Using External Shutdown

To achieve single-point fault tolerance, Maxim recommends an external shutdown transistor (Figure 11). In the event of a fault, SHDNDRV asserts high, placing the shutdown transistor in cutoff mode and thereby shutting off the bias current.

Applications Information

Laser Safety and IEC825

The International Electrotechnical Commission (IEC) determines standards for hazardous light emissions from fiber optic transmitters. IEC 825 defines the maximum light output for various hazard levels. The MAX3996 provides features that facilitate compliance with IEC825. A common safety precaution is singlepoint fault tolerance, whereby one unplanned short, open, or resistive connection does not cause excess light output. When this laser driver is used, as shown in the Typical Application Circuit, the circuits respond to faults as listed in Table 3. Using this laser driver alone does not ensure that a transmitter design is compliant with IEC825. The entire transmitter circuit and component selections must be considered. Customers must determine the level of fault tolerance required by their applications, recognizing that Maxim products are not designed or authorized for use as components in systems intended for surgical implant into the body, for applications intended to support or sustain life, or for any other application where the failure of a Maxim

product could create a situation where personal injury or death may occur.

Layout Considerations

The MAX3996 is a high-frequency product whose performance largely depends upon the circuit board layout. Use a multilayer circuit board with a dedicated ground plane. Use short laser-package leads placed close to the modulator outputs. Power supplies must be capacitively bypassed to the ground plane, with surface-mount capacitors placed near the power-supply pins.

The dominant pole of the APC circuit normally is at COMP. To prevent a second pole in the APC that can lead to oscillations, ensure that parasitic capacitance at MD is minimized (10pF).

Common Questions

Laser output is ringing or contains overshoot. Inductive laser packaging often causes this. Try reducing the length of the laser leads. Modify the filter components to reduce the driver's output edge speed (see the *Design Procedure* section). Extreme ringing can be caused by low voltage at the OUT± pins. This might indicate that pullup beads or a lower modulation current are needed.

Low-frequency oscillation on the laser output. This is more prevalent at low temperatures. The APC might be oscillating. Try increasing the value of CCOMP or add additional degeneration by placing some resistance from MON1 to GND. Ensure that the parasitic capacitance at the MD node is kept very small (<10pF).

The APC is not needed. Connect BIAS to V_{CC}, leave MD open, and connect MON2 and COMP to ground.

The modulator is not needed. Leave TC and MODSET open. Connect IN+ to VCC, IN- to ground through 750Ω , and leave OUT+ and OUT- open.

Interface Models

Figures 13–17 show typical models for the inputs and outputs of the MAX3996, including package parasitics.

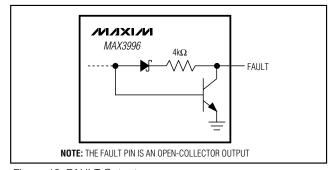


Figure 13. FAULT Output

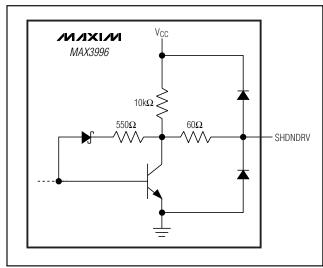


Figure 14. SHDNDRV Output

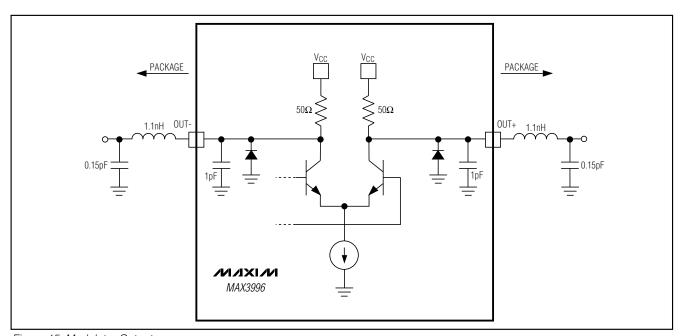


Figure 15. Modulator Outputs

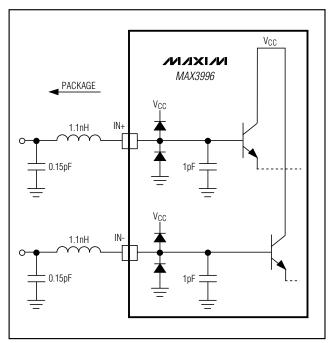


Figure 16. Data Inputs

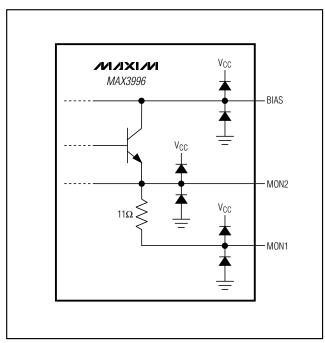


Figure 17. BIAS Output

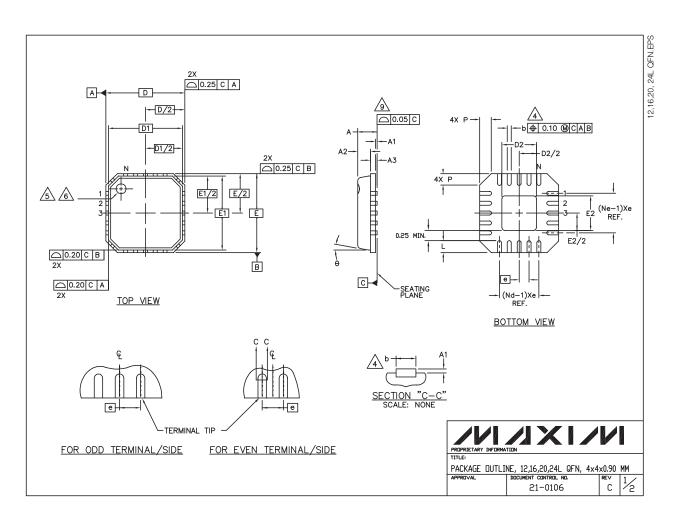
Pin Configuration

TOP VIEW TC 15 BIAS SHDNDRV FAULT 14 GND MD MAX3996 TX_DISABLE COMP 12 PORDLY MON2 QFN* *EXPOSED PAD IS CONNECTED TO GND

_Chip Information

TRANSISTOR COUNT: 1061 PROCESS: SILICON BIPOLAR

Package Information



Package Information (continued)

NOTES:

- 1. DIE THICKNESS ALLOWABLE IS 0.305mm MAXIMUM (.012 INCHES MAXIMUM)
- 2. DIMENSIONING & TOLERANCES CONFORM MUST TO ASME Y14.5M. 1994.

Ad is the number of terminals.

No is the number of terminals in X-direction & No is the number of terminals in Y-direction.

DIMENSION 6 APPLIES TO PLATED TERMINAL AND IS MEASURED BETWEEN 0.20 AND 0.25mm FROM TERMINAL TIP.

THE PIN #1 IDENTIFIER MUST BE EXISTED ON THE TOP SURFACE OF THE PACKAGE BY USING INDENTATION MARK OR INK/LASER MARKED.

6 EXACT SHAPE AND SIZE OF THIS FEATURE IS OPTIONAL.

7. ALL DIMENSIONS ARE IN MILLIMETERS.

8. PACKAGE WARPAGE MAX 0.05mm.

4. APPLIED FOR EXPOSED PAD AND TERMINALS. EXCLUDE EMBEDDING PART OF EXPOSED PAD FROM MEASURING.

10. MEETS JEDEC MO220.

11. THIS PACKAGE OUTLINE APPLIES TO ANVIL SINGULATION (STEPPED SIDES) AND TO SAW SINGULATION (STRAIGHT SIDES) QFN STYLES.

S	COMMON										
S M B O L	DI	MENSION	IS	NO _{TE}							
ို	MIN.	NOM.	MAX.	TΕ							
Α	0.80	0.90	1.00								
A1	0.00	0.01	0.05								
A2 A3	0.00	0.00 0.65 0.80									
А3		0.20 REF.									
D D1 E E1 Θ		4.00 BSC									
D1		3.75 BSC									
Ε		4.00 BSC									
E1		3.75 BSC									
θ	0,		12°								
Р	0.00	0.42	0.60								
D2	0.75		2.25								
F2	0.75		2.25								

S Y M	PITCH	VARIAT	ION A	N.	S Y M	PITCH	VARIA1	TION B	N.	S M	PITCH	VARIAT	TON C	N_	S M	PITCH	VARIAT	TON D	N.
٥	MIN.	NOM.	MAX.	°₁ _€	<u>"</u>	MIN.	NOM.	MAX.	°T _E	" !	MIN.	NOM.	MAX.	° _™ E	ီု	MIN.	NOM.	MAX.	°T _E
e		0.80 BSC			e		0.65 BSC			e		0.50 BSC			e		0.50 BSC		
N		12		3	INI		16		3	IN		20		3	N		24		3
Nd	Nd 3		3	Nd		4		3	Nd		5		3	Nd		6		3	
Ne	Ne 3		3	Ne		4		3	Ne		5		3	Ne		6		3	
L	0.50	0.60	0.75		П	0.50	0.60	0.75		П	0.50	0.60	0.75		L	0.30	0.40	0.55	
Ь	0.28	0.33	0.40	4	ы	0.23	0.28	0.35	4	ТЫ	0.18	0.23	0.30	4	ы	0.18	0.23	0.30	4



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