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High Bandwidth, CMOS 8-Bit Serial Interface Multiplying DAC

Preliminary Technical Data

AD5425*

FEATURES

+2.5 V to +5.5 V Supply Operation
50MHz Serial Interface
8-Bit (Byte Load) serial interface, 6MHz Update Rate
10MHz Multiplying Bandwidth
 $\pm 10V$ Reference Input
10-Lead μ SOIC Package
Guaranteed Monotonic
Four Quadrant Multiplication
Power On Reset
LDAC function
5 μ A typical Power Consumption

APPLICATIONS

Portable Battery Powered Applications
Waveform Generators
Analog Processing
Instrumentation Applications
Programmable Amplifiers and Attenuators
Digitally-Controlled Calibration
Programmable Filters and Oscillators
Composite Video
Ultrasound
Gain, offset and Voltage Trimming

GENERAL DESCRIPTION

The AD5425 is a CMOS 8-bit current output digital-to-analog converter which operates from a +2.5 V to 5.5 V power supply, making it suited to battery powered applications and many other applications.

This DAC utilizes a double buffered 3-wire serial interface that is compatible with SPITM, QSPITM, MICROWIRETM and most DSP interface standards. In addition, an **LDAC** pin is provided which allows simultaneous update in multi DAC configuration. On power-up, the internal shift register and latches are filled with zeros and the DAC outputs are at 0V.

As a result of processing on a CMOS sub micron process, this DAC offers excellent four quadrant multiplication characteristics, with large signal multiplying bandwidths of 10MHz.

*US Patent Number 5,689,257

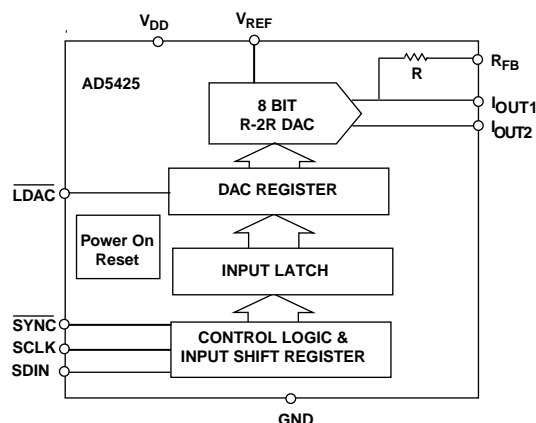
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FUNCTIONAL BLOCK DIAGRAM



The applied external reference input voltage (V_{REF}) determines the full scale output current. An integrated feedback resistor (R_{FB}) provides temperature tracking and full scale voltage output when combined with an external I-toV precision amplifier.

The AD5425 DAC is available in a small 10-lead μ SOIC package.

PRODUCT HIGHLIGHTS

1. 10MHz Multiplying Bandwidth
2. 3mm x 5mm 10-lead μ SOIC package
3. Low Voltage, Low Power Current Output DAC.

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PRELIMINARY TECHNICAL DATA

AD5425–SPECIFICATIONS¹

($V_{DD} = 2.5\text{ V}$ to 5.5 V , $V_{REF} = +10\text{ V}$, $I_{OUTX} = 0\text{ V}$. All specifications T_{MIN} to T_{MAX} unless otherwise noted. DC performance measured with OP1177, AC performance with AD811 unless otherwise noted.)

Parameter	Min	Typ	Max	Units	Conditions
STATIC PERFORMANCE					
Resolution			8	Bits	Guaranteed Monotonic Data = 0000 _H , $T_A = 25^\circ\text{C}$, I_{OUT1} Data = 0000 _H , I_{OUT1}
Relative Accuracy			± 0.5	LSB	
Differential Nonlinearity			± 1	LSB	
Gain Error			± 2	mV	
Gain Error Temp Coefficient ²		± 5		ppm FSR/ $^\circ\text{C}$	
Output Leakage Current			± 10	nA	
			± 50	nA	
Output Voltage Compliance Range		TBD		V	
REFERENCE INPUT ²					
Reference Input Range		± 10		V	Input resistance TC = $-50\text{ ppm}/^\circ\text{C}$
V_{REF} Input Resistance	8	10	12	k Ω	
DIGITAL INPUTS/OUTPUT ²					
Input High Voltage, V_{IH}	1.7			V	$V_{DD} = 2.5\text{ V}$ to 5.5 V $V_{DD} = 2.7\text{ V}$ to 5.5 V $V_{DD} = 2.5\text{ V}$ to 2.7 V
Input Low Voltage, V_{IL}			0.8	V	
			0.7	V	
Input Leakage Current, I_{IL}			1	μA	
Input Capacitance			10	pF	
DYNAMIC PERFORMANCE ²					
Reference Multiplying BW	10			MHz	$V_{REF} = 100\text{ mV rms}$, DAC loaded all 1s $V_{REF} = 6\text{ V rms}$, DAC loaded all 1s
	TBD			MHz	
Output Voltage Settling Time		30	TBD	ns	Measured to $\frac{1}{2}$ LSB. $R_{LOAD} = 100\Omega$, $C_{LOAD} = 15\text{ pF}$. DAC latch alternately loaded with 0s and 1s.
Slew Rate		100		V/ μs	1 LSB change around Major Carry DAC latch loaded with all 0s. Reference = 10kHz. DAC Latches Loaded with all 0s DAC Latches Loaded with all 1s Feedthrough to DAC output with <i>SYNC</i> high and Alternate Loading of all 0s and all 1s. $V_{REF} = 6\text{ V rms}$, All 1s loaded, $f = 1\text{ kHz}$ $V_{REF} = 5\text{ V}$, Sinewave generated from digital code. @ 1kHz
Digital to Analog Glitch Impulse		3		nV-s	
Multiplying Feedthrough Error			-75	dB	
Output Capacitance			2	pF	
			4	pF	
Digital Feedthrough		5		nV-s	
Total Harmonic Distortion		-85		dB	$V_{REF} = 6\text{ V rms}$, All 1s loaded, $f = 1\text{ kHz}$ $V_{REF} = 5\text{ V}$, Sinewave generated from digital code. @ 1kHz
		-85		dB	
Output Noise Spectral Density		25		nV/ $\sqrt{\text{Hz}}$	
SFDR performance		72		dB	
Intermodulation Distortion		TBD		dB	
POWER REQUIREMENTS					
Power Supply Range	2.5		5.5	V	Logic Inputs = 0 V or V_{DD} $\Delta V_{DD} = \pm 5\%$
I_{DD}			10	μA	
Power Supply Sensitivity ²			0.001	%/%	

NOTES

¹Temperature range is as follows: B Version: -40°C to $+105^\circ\text{C}$.

²Guaranteed by design, not subject to production test.

Specifications subject to change without notice.

Single Supply Operation (Biased Mode)

AD5425

($V_{DD} = 2.5\text{ V to }5.5\text{ V}$, $V_{REF} = +2\text{ V}$, $I_{OUT2} = +1\text{ V}$. All specifications T_{MIN} to T_{MAX} unless otherwise noted. DC performance measured with OP1177, AC performance with AD811 unless otherwise noted.)

Parameter	Min	Typ	Max	Units	Conditions
STATIC PERFORMANCE					
Resolution			8	Bits	Guaranteed Monotonic Data = 0000 _H , $T_A = 25^\circ\text{C}$, I_{OUT1} Data = 0000 _H , I_{OUT1}
Relative Accuracy			± 0.5	LSB	
Differential Nonlinearity			± 1	LSB	
Gain Error			± 2	mV	
Gain Error Temp Coefficient ²		± 5		ppm FSR/ $^\circ\text{C}$	
Output Leakage Current			± 10	nA	
Output Voltage Compliance Range		TBD	± 50	nA V	
REFERENCE INPUT ²					
Reference Input Range		tbd		V	Input resistance TC = -50ppm/ $^\circ\text{C}$
V_{REF} Input Resistance	8	10	12	k Ω	
DIGITAL INPUTS/OUTPUT ²					
Input High Voltage, V_{IH}	1.7			V	$V_{DD} = 2.5\text{ V to }5.5\text{ V}$ $V_{DD} = 2.7\text{ V to }5.5\text{ V}$ $V_{DD} = 2.5\text{ V to }2.7\text{ V}$
Input Low Voltage, V_{IL}			0.8	V	
			0.7	V	
Input Leakage Current, I_{IL}			1	μA	
Input Capacitance			10	pF	
DYNAMIC PERFORMANCE ²					
Reference Multiplying BW	10 TBD			MHz MHz	$V_{REF} = 100\text{ mV rms}$, DAC loaded all 1s $V_{REF} = 2\text{ V p-p}$, 1 V Bias, DAC loaded all 1s Measured to $\frac{1}{2}$ LSB. $R_{LOAD} = 100\Omega$, $C_{LOAD} = 15\text{pF}$. $V_{REF} = 0\text{V}$, DAC latch alternately loaded with 0s & 1s. 1 LSB change around Major Carry DAC latch loaded with all 0s. Reference = 10kHz. DAC Latches Loaded with all 0s DAC Latches Loaded with all 1s Feedthrough to DAC output with <i>SYNC</i> high and Alternate Loading of all 0s and all 1s. $V_{REF} = 2\text{ Vp-p}$, 1 V Bias, All 1s loaded, $f = 1\text{kHz}$ $V_{REF} = 2\text{ V}$, Sinewave generated from digital code. @ 1kHz
Output Voltage Settling Time		20	TBD	ns	
Slew Rate		100		V/ μs	
Digital to Analog Glitch Impulse		3		nV-s	
Multiplying Feedthrough Error			-75	dB	
Output Capacitance			2	pF	
			4	pF	
Digital Feedthrough		5		nV-s	
Total Harmonic Distortion		-85		dB	
		-85		dB	
Output Noise Spectral Density		25		nV/ $\sqrt{\text{Hz}}$	
SFDR performance		72		dB	
Intermodulation Distortion		TBD		dB	
POWER REQUIREMENTS					
Power Supply Range	2.5		5.5	V	Logic Inputs = 0 V or V_{DD} $\Delta V_{DD} = \pm 5\%$
I_{DD}			10	μA	
Power Supply Sensitivity ²			0.001	%/%	

NOTES

¹Temperature range is as follows: B Version: -40°C to $+105^\circ\text{C}$.

²Guaranteed by design and characterisation, not subject to production test.

Specifications subject to change without notice.

AD5425–SPECIFICATIONS¹TIMING CHARACTERISTICS^{1,2} ($V_{DD} = 2.5\text{ V to }5.5\text{ V}$, $V_{REF} = +5\text{ V}$, $I_{OUT2} = 0\text{ V}$. All specifications T_{MIN} to T_{MAX} unless otherwise noted.)

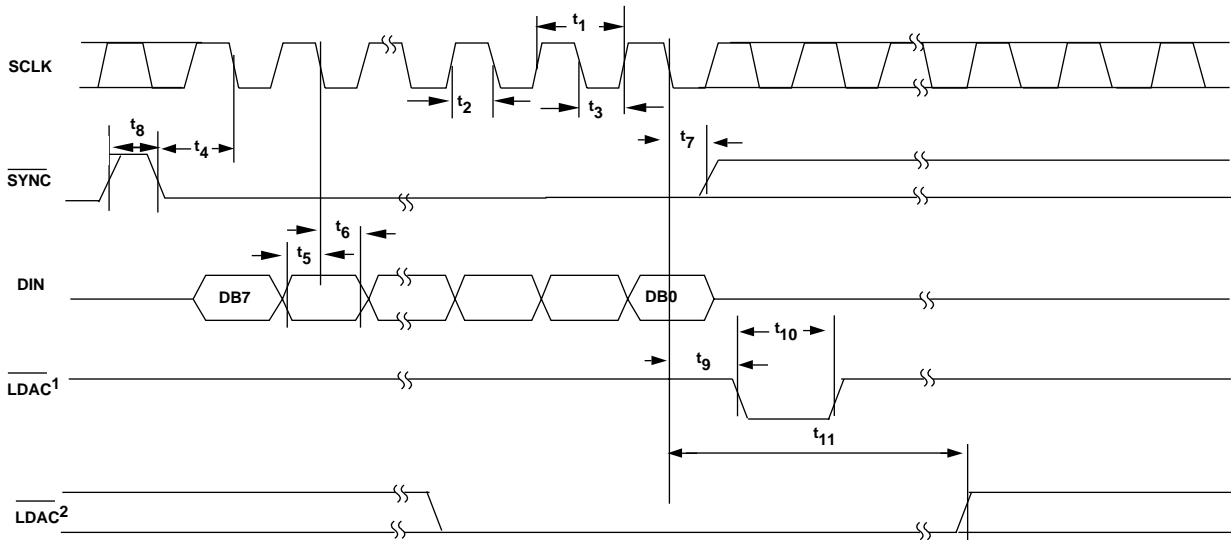
Parameter	Limit at T_{MIN} , T_{MAX}	Units	Conditions/Comments
f_{SCLK}	50	MHz max	Max Clock Frequency
t_1	20	ns min	SCLK Cycle time
t_2	8	ns min	SCLK High Time
t_3	8	ns min	SCLK Low Time
t_4	13	ns min	$SYNC$ falling edge to SCLK falling edge setup time
t_5	5	ns min	Data Setup Time
t_6	4	ns min	Data Hold Time
t_7	5	ns min	$SYNC$ Rising edge to SCLK falling edge
t_8	30	ns min	Minimum $SYNC$ high time
t_9	0	ns min	SCLK Falling edge to $LDAC$ falling edge
t_{10}	12	ns min	$LDAC$ pulse width
t_{11}	10	ns min	SCLK Falling edge to $LDAC$ rising edge

NOTES

¹See Figure 1. Temperature range is as follows: B Version: -40°C to $+105^{\circ}\text{C}$. Guaranteed by design and characterisation, not subject to production test.

²All input signals are specified with $t_r = t_f = 5\text{ ns}$ (10% to 90% of V_{DD}) and timed from a voltage level of $(V_{IL} + V_{IH})/2$.

Specifications subject to change without notice.



NOTES

1. ASYNCHRONOUS LDAC UPDATE MODE
2. SYNCHRONOUS LDAC UPDATE MODE

Figure 1. Timing Diagram.

ABSOLUTE MAXIMUM RATINGS¹(T_A = +25°C unless otherwise noted)

V _{DD} to GND	-0.3 V to +7 V
V _{REF} , R _{FB} to GND	-12 V to +12 V
I _{OUT1} , I _{OUT2} to GND	-0.3 V to +7 V
Logic Inputs & Output ²	-0.3V to V _{DD} +0.3 V
Operating Temperature Range	
Industrial (B Version)	-40°C to +105°C
Storage Temperature Range	-65°C to +150°C
Junction Temperature	+150°C
10 lead μ SOIC θ_{JA} Thermal Impedance	206°C/W
Lead Temperature, Soldering (10seconds)	300°C
IR Reflow, Peak Temperature (<20 seconds)	+235°C

NOTES

¹Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those listed in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Only one absolute maximum rating may be applied at any one time.

²Overvoltages at SCLK, SYNC, DIN and LDAC will be clamped by internal diodes. Current should be limited to the maximum ratings given.

CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD5425 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

**ORDERING GUIDE**

Model	Temperature Range	Package Description	Branding	Package Option
AD5425BRM	-40 °C to +105 °C	μ SOIC	D00	RM-10

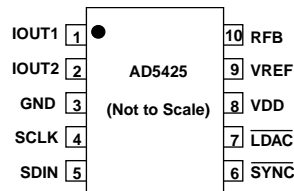
PRELIMINARY TECHNICAL DATA

AD5425

PIN FUNCTION DESCRIPTION

Pin	Mnemonic	Function
1	I_{OUT1}	DAC Current Output.
2	I_{OUT2}	DAC Analog Ground. This pin should normally be tied to the analog ground of the system.
3	GND	Digital Ground Pin.
4	SCLK	Serial Clock Input. Data is clocked into the input shift register on each falling edge of the serial clock input. These devices can accomodate serial input rates of up to 50MHz.
5	SDIN	Serial Data Input. Data is clocked into the 8-bit input register on each falling edge of the serial clock input.
6	SYNC	Active Low Control Input. This is the frame synchronization signal for the input data. When SYNC goes low, it powers on the SCLK and DIN buffers and the input shift register is enabled. Data is transferred on each falling edge of the following clocks.
7	LDAC	Load DAC input. Updates the DAC output. The DAC is updated when this signal goes low or alternatively if this line is held permanently low, an automatic update mode is selected whereby the DAC is updated on the 8th clock falling edge.
8	V_{DD}	Positive power supply input. These parts can be operated from a supply of +2.5 V to +5.5 V.
9	V_{REF}	DAC reference voltage input terminal.
10	R_{FB}	DAC feedback resistor pin. Establish voltage output for the DAC by connecting to external amplifier output.

PIN CONFIGURATION μSOIC



TERMINOLOGY**Relative Accuracy**

Relative accuracy or endpoint nonlinearity is a measure of the maximum deviation from a straight line passing through the endpoints of the DAC transfer function. It is measured after adjusting for zero and full scale and is normally expressed in LSBs or as a percentage of full scale reading.

Differential Nonlinearity

Differential nonlinearity is the difference between the measured change and the ideal 1 LSB change between any two adjacent codes. A specified differential nonlinearity of ± 1 LSB max over the operating temperature range ensures monotonicity.

Gain Error

Gain error or full-scale error is a measure of the output error between an ideal DAC and the actual device output. For these DACs, ideal maximum output is $V_{REF} - 1$ LSB. Gain error of the DACs is adjustable to zero with external resistance.

Output Leakage Current

Output leakage current is current which flows in the DAC ladder switches when these are turned off. For the I_{OUT1} terminal, it can be measured by loading all 0s to the DAC and measuring the I_{OUT1} current. Minimum current will flow in the I_{OUT2} line when the DAC is loaded with all 1s

Output Capacitance

Capacitance from I_{OUT1} or I_{OUT2} to AGND.

Output Current Settling Time

This is the amount of time it takes for the output to settle to a specified level for a full scale input change. For these devices, it is specified with a 100 Ω resistor to ground.

Digital to Analog Glitch Impulse

The amount of charge injected from the digital inputs to the analog output when the inputs change state. This is normally specified as the area of the glitch in either pA-sec or nV-sec depending upon whether the glitch is measured as a current or voltage signal.

Digital Feedthrough

When the device is not selected, high frequency logic activity on the device digital inputs is capacitively coupled through the device to show up as noise on the I_{OUT} pins and subsequently into the following circuitry. This noise is digital feedthrough.

Multiplying Feedthrough Error

This is the error due to capacitive feedthrough from the DAC reference input to the DAC I_{OUT1} terminal, when all 0s are loaded to the DAC.

Harmonic Distortion

The DAC is driven by an ac reference. The ratio of the rms sum of the harmonics of the DAC output to the fundamental value is the THD. Usually only the lower order harmonics are included, such as second to fifth.

$$THD = 20 \log \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + V_5^2}}{V_1}$$

Intermodulation Distortion

The DAC is driven by two combined sine waves references of frequencies f_a and f_b . Distortion products are produced at sum and difference frequencies of $m f_a \pm n f_b$ where $m, n = 0, 1, 2, 3 \dots$. Intermodulation terms are those for which m or n is not equal to zero. The second order terms include $(f_a + f_b)$ and $(f_a - f_b)$ and the third order terms are $(2f_a + f_b)$, $(2f_a - f_b)$, $(f + 2f_a + 2f_b)$ and $(f_a - 2f_b)$. IMD is defined as

$$IMD = 20 \log \frac{\text{rms sum of the sum and diff distortion products}}{\text{rms amplitude of the fundamental}}$$

Compliance Voltage Range

The maximum range of (output) terminal voltage for which the device will provide the specified current-output characteristics.

GENERAL DESCRIPTION**DAC Section**

The AD5425 is an 8 bit current output DAC consisting of a standard inverting R-2R ladder configuration. A simplified diagram is shown in Figure 2. The feedback resistor R_{FB} has a value of R . The value of R is typically 10k Ω (minimum 8k Ω and maximum 12k Ω). If I_{OUT1} and I_{OUT2} are kept at the same potential, a constant current flows in each ladder leg, regardless of digital input code. Therefore, the input resistance presented at V_{REF} is always constant.

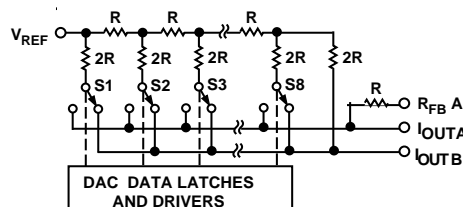


Figure 2. Simplified Ladder

Access is provided to the V_{REF} , R_{FB} , I_{OUT1} and I_{OUT2} terminals of the DAC, making the device extremely versatile and allowing it to be configured in several different operating modes, for example, to provide a unipolar output, bipolar output or in single supply modes of operation. in unipolar mode or four quadrant multiplication in bipolar mode.

Unipolar Mode

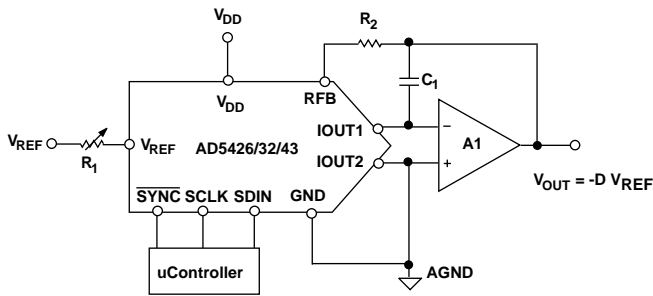
Using a single op amp, these devices can easily be configured to provide 2 quadrant multiplying operation or a unipolar output voltage swing as shown in Figure 3.

When an output amplifier is connected in unipolar mode, the output voltage is given by:

$$V_{OUT} = -D \times V_{REF}$$

Where D is the fractional representation of the digital word loaded to the DAC.

AD5425



NOTES:
¹R1 AND R2 USED ONLY IF GAIN ADJUSTMENT IS REQUIRED.
²C1 PHASE COMPENSATION (10pF-15pF) MAY BE REQUIRED
 IF A1 IS A HIGH SPEED AMPLIFIER.

Figure 3. Unipolar Operation

With a fixed 10 V reference, the circuit shown above will give an unipolar 0V to -10V output voltage swing. When V_{IN} is an ac signal, the circuit performs two-quadrant multiplication.

The following table shows the relationship between digital code and expected output voltage for unipolar operation.

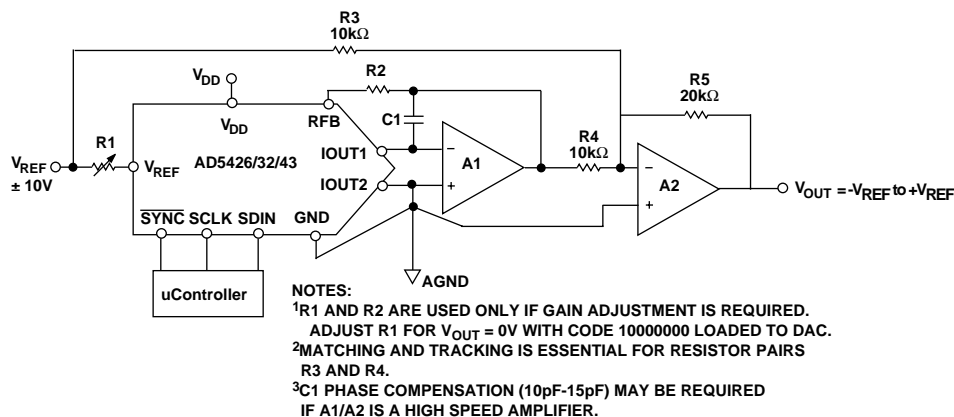
Table I. Unipolar Code Table

Digital Input	Analog Output (V)
1111 1111	$-V_{REF}$ (255/256)
1000 0000	$-V_{REF}$ (128/256) = $-V_{REF}/2$
0000 0001	$-V_{REF}$ (1/256)
0000 0000	$-V_{REF}$ (0/256) = 0

Bipolar Operation

In some applications, it may be necessary to generate full 4-Quadrant multiplying operation or a bipolar output swing. This can be easily accomplished by using another external amplifier and some external resistors as shown in Figure 4.

When V_{IN} is an ac signal, the circuit performs four-quadrant multiplication.



NOTES:
¹R1 AND R2 ARE USED ONLY IF GAIN ADJUSTMENT IS REQUIRED.
 ADJUST R1 FOR $V_{OUT} = 0V$ WITH CODE 10000000 LOADED TO DAC.
²MATCHING AND TRACKING IS ESSENTIAL FOR RESISTOR PAIRS
 R3 AND R4.
³C1 PHASE COMPENSATION (10pF-15pF) MAY BE REQUIRED
 IF A1/A2 IS A HIGH SPEED AMPLIFIER.

Figure 4. Bipolar Operation (4 Quadrant Multiplication)

Table II. shows the relationship between digital code and the expected output voltage for bipolar operation.

Table II. Bipolar Code Table

Digital Input	Analog Output (V)
1111 1111	$+V_{REF}$ (127/128)
1000 0000	0
0000 0001	$-V_{REF}$ (127/128)
0000 0000	$-V_{REF}$ (128/128)

SERIAL INTERFACE

The AD5425 has a simple 3-wire interface which is compatible with SPI/QSPI/MicroWire and DSP interface standards. Data is written to the device in 8 bit words. This 8-bit word consists 8 data bits as shown in Figure 3.

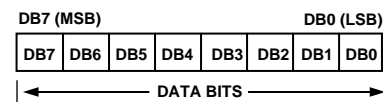


Figure 3. 8 bit Input Shift Register Contents

$SYNC$ is an edge-triggered input that acts as a frame synchronization signal and chip enable. Data can only be transferred into the device while $SYNC$ is low. To start the serial data transfer, $SYNC$ should be taken low observing the minimum $SYNC$ falling to SCLK falling edge setup time, t_4 .

After loading 8 data bits to the shift register, the $SYNC$ line is brought high. The contents of the DAC register and the output will be updated by bringing $LDAC$ low any time after the 8 bit data transfer is complete as can be seen in the timing diagram of Figure 1. $LDAC$ may be tied permanently low if required. In order for another serial transfer to take place the interface must be enabled by another falling edge of $SYNC$.

Low Power Serial Interface

To minimize the power consumption of the device, the interface only powers up fully when the device is being written to, i.e., on the falling edge of $SYNC$. The SCLK and DIN input buffers are powered down on the rising edge of $SYNC$.

AD5425

Part No	Resolution	#DACs	INL	Settling Time	Interface	Package	Features
AD5424	8	1	± 0.5	20ns	Parallel	RU-16, CP-20	10 MHz, 10 ns CS Pulse Width
AD5425	8	1	± 0.5	20ns	Serial	RM-10	Byte Load, 10 MHz BW, 50 MHz Serial
AD5426	8	1	± 0.5	20ns	Serial	RM-10	10 MHz BW, 50 MHz Serial
AD5432	10	1	± 1	25ns	Serial	RM-10	10 MHz BW, 50 MHz Serial
AD5433	10	1	± 1	25ns	Parallel	RU-20, CP-20	10 MHz, 10 ns CS Pulse Width
AD5443	12	1	± 2	30ns	Serial	RM-10	10 MHz BW, 50 MHz Serial
AD5445	12	1	± 2	30ns	Parallel	RU-20, CP-20	10 MHz, 10 ns CS Pulse Width