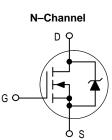
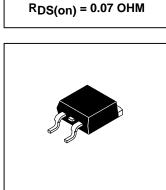
Product Preview **TMOS E-FET** ™ **Power Field Effect Transistor** N-Channel Enhancement-Mode Silicon Gate

This advanced TMOS E–FET is designed to withstand high energy in the avalanche and commutation modes. The new energy efficient design also offers a drain–to–source diode with a fast recovery time. Designed for low voltage, high speed switching applications in power supplies, converters and PWM motor controls. These devices are particularly well suited for bridge circuits where diode speed and commutating safe operating areas are critical and offer additional safety margin against unexpected voltage transients.

- Avalanche Energy Specified
- Source-to-Drain Diode Recovery Time Comparable to a Discrete Fast Recovery Diode
- Diode is Characterized for Use in Bridge Circuits
- IDSS and VDS(on) Specified at Elevated Temperature







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TMOS POWER FET

29 AMPERES

150 VOLTS

CASE 418B-03, Style 2 D²PAK

| MAXIMUM RATINGS (T _C = 25°C unle | ess otherwise noted) |
|---|----------------------|
|---|----------------------|

| Rating | Symbol | Value | Unit |
|--|---|-------------------|------------------------|
| Drain-to-Source Voltage | V _{DSS} | 150 | Vdc |
| Drain–to–Gate Voltage (R _{GS} = 1.0 M Ω) | VDGR | 150 | Vdc |
| Gate–to–Source Voltage — Continuous — Non–Repetitive (t _p ≤ 10 ms) | VGS VGSM | ± 20 ± 40 | Vdc Vpk |
| Drain Current — Continuous — Continuous @ 100°C — Single Pulse (t _p ≤ 10 μs) | I _D I _D I _{DM} | 29 19 102 | Adc Apk |
| Total Power Dissipation Derate above 25°C Total Power Dissipation @ T _A = 25°C ⁽¹⁾ | PD | 125 1.0 2.5 | Watts W/°C Watts |
| Operating and Storage Temperature Range | TJ, Tstg | – 55 to 150 | °C |
| Single Pulse Drain–to–Source Avalanche Energy — STARTING T _J = 25° C (V _{DD} = 25 Vdc, V _{GS} = 10 Vdc, PEAK I _L = 29 Apk, L = 1.0 mH, R _G = 25Ω) | E _{AS} | 421 | mJ |
| Thermal Resistance — Junction to Case — Junction to Ambient — Junction to Ambient ⁽¹⁾ | R _θ JC R _θ JA R _θ JA | 1.0 62.5 50 | °C/W |
| Maximum Lead Temperature for Soldering Purposes, 1/8" from case for 10 seconds | тլ | 260 | °C |

(1) When surface mounted to an FR4 board using the minimum recommended pad size.

This document contains information on a product under development. Motorola reserves the right to change or discontinue this product without notice.

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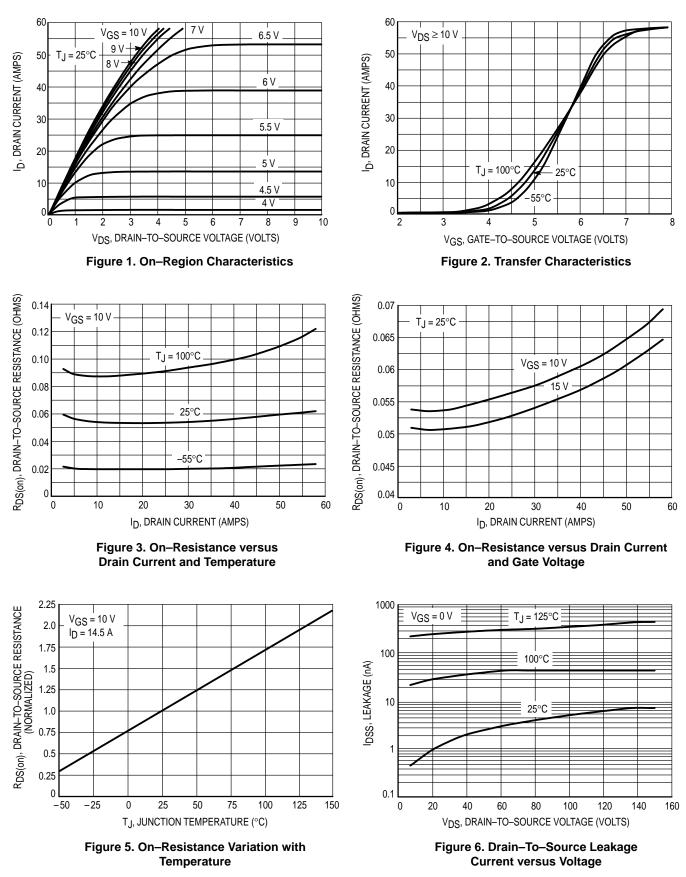
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ELECTRICAL CHARACTERISTICS (T₁ = 25°C unless otherwise noted)

| Cha | racteristic | Symbol | Min | Тур | Max | Unit |
|--|--|---------------------|-----|--------------|------------|-------|
| OFF CHARACTERISTICS | | | | | | |
| Drain–to–Source Breakdown Voltage ($V_{GS} = 0 \text{ Vdc}, I_D = 0.25 \text{ mAdc}$) | | V(BR)DSS | 150 | _ | _ | Vdc |
| Temperature Coefficient (Positive | | | — | 151 | _ | mV/°C |
| Zero Gate Voltage Drain Current (VDS = 150 Vdc, VGS = 0 Vdc) (VDS = 150 Vdc, VGS = 0 Vdc, TJ = 125° C) | | IDSS | | _ | 10 100 | μAdc |
| $Gate-Body Leakage Current (V_{GS} = \pm 20 Vdc, V_{DS} = 0 Vdc)$ | | I _{GSS} | | _ | 100 | nAdc |
| ON CHARACTERISTICS (1) | | 000 | | | | |
| Gate Threshold Voltage | | V _{GS(th)} | | | | Vdc |
| $(V_{DS} = V_{GS}, I_D = 250 \ \mu Adc)$ Threshold Temperature Coefficient (Negative) | | · (3)(iii) | 2.0 | 2.7 5.4 | 4.0 | mV/°C |
| Static Drain–to–Source On–Resistance (V _{GS} = 10 Vdc, I _D = 14.5 Adc) | | R _{DS(on)} | _ | 0.054 | 0.07 | Ohms |
| Drain-to-Source On-Voltage (V _{GS} = 10 Vdc) (I_D = 29 Adc) (I_D = 14.5 Adc, T _J = 125°C) | | V _{DS(on)} | _ | _ | 2.4 2.1 | Vdc |
| Forward Transconductance (V _{DS} = | 8.6 Vdc ID = 14.5 Adc) | 050 | 10 | 20 | | mhos |
| | | 9FS | 10 | 20 | | |
| Input Capacitance | | C _{iss} | _ | 2300 | 3220 | pF |
| Output Capacitance | $(V_{DS} = 25 \text{ Vdc}, V_{GS} = 0 \text{ Vdc},$ | C _{OSS} | | 450 | 630 | |
| Transfer Capacitance | f = 1.0 MHz) | C _{rss} | | 130 | 260 | |
| SWITCHING CHARACTERISTICS (| 2) | orss | | 100 | 200 | |
| Turn–On Delay Time | | ^t d(on) | _ | 19 | 40 | ns |
| Rise Time | (V _{DD} = 75 Vdc, I _D = 29 Adc, | t _r | | 95 | 190 | |
| Turn–Off Delay Time | $V_{GS} = 10 V dc,$ | td(off) | | 90 | 180 | |
| Fall Time | R _G = 9.1 Ω) | tf | | 85 | 170 | |
| Gate Charge | | Q _T | | 83 | 120 | nC |
| Cuto Onlargo | $(V_{DS} = 120 \text{ Vdc}, I_D = 29 \text{ Adc}, V_{GS} = 10 \text{ Vdc})$ | Q ₁ | | 12 | | |
| | | Q ₂ | | 37 | | |
| | | _ | | 23 | | |
| SOURCE-DRAIN DIODE CHARAC | | Q ₃ | | 23 | | |
| Forward On–Voltage | | V _{SD} | | 1 | 1 | Vdc |
| Torward off Voltage | (I _S = 29 Adc, V _{GS} = 0 Vdc) (I _S = 29 Adc, V _{GS} = 0 Vdc, T _J = 125°C) | •50 | | 0.92 0.84 | 1.3 — | Vuc |
| Reverse Recovery Time | | t _{rr} | | 174 | _ | ns |
| | (I _S = 29 Adc, V _{GS} = 0 Vdc, | ta | _ | 126 | _ | - |
| | $dl_S/dt = 100 A/\mu s$ | tb | _ | 48 | _ | |
| Reverse Recovery Stored Charge | | Q _{RR} | _ | 1.4 | _ | μC |
| INTERNAL PACKAGE INDUCTANC | E | | | | 1 | |
| Internal Drain Inductance (Measured from the contact screw on tab to center of die) (Measured from the drain lead 0.25" from package to center of die) | | LD | _ | 3.5 4.5 | _ | nH |
| Internal Source Inductance (Measured from the source lead 0.25" from package to source bond pad) | | LS | | 7.5 | _ | 1 |

Pulse Test: Pulse Width ≤ 300 μs, Duty Cycle ≤ 2%.
 Switching characteristics are independent of operating junction temperature.

TYPICAL ELECTRICAL CHARACTERISTICS



POWER MOSFET SWITCHING

Switching behavior is most easily modeled and predicted by recognizing that the power MOSFET is charge controlled. The lengths of various switching intervals (Δt) are determined by how fast the FET input capacitance can be charged by current from the generator.

The published capacitance data is difficult to use for calculating rise and fall because drain–gate capacitance varies greatly with applied voltage. Accordingly, gate charge data is used. In most cases, a satisfactory estimate of average input current ($I_{G(AV)}$) can be made from a rudimentary analysis of the drive circuit so that

 $t = Q/I_G(AV)$

During the rise and fall time interval when switching a resistive load, V_{GS} remains virtually constant at a level known as the plateau voltage, V_{SGP} . Therefore, rise and fall times may be approximated by the following:

 $t_r = Q_2 \times R_G/(V_{GG} - V_{GSP})$

 $t_f = Q_2 \times R_G / V_{GSP}$

where

 V_{GG} = the gate drive voltage, which varies from zero to V_{GG}

R_G = the gate drive resistance

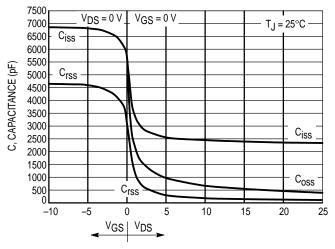
and Q2 and VGSP are read from the gate charge curve.

During the turn-on and turn-off delay times, gate current is not constant. The simplest calculation uses appropriate values from the capacitance curves in a standard equation for voltage change in an RC network. The equations are:

 $t_{d(on)} = R_G C_{iss} ln [V_{GG}/(V_{GG} - V_{GSP})]$ $t_{d(off)} = R_G C_{iss} ln (V_{GG}/V_{GSP})$ The capacitance (C_{ISS}) is read from the capacitance curve at a voltage corresponding to the off–state condition when calculating $t_{d(on)}$ and is read at a voltage corresponding to the on–state when calculating $t_{d(off)}$.

At high switching speeds, parasitic circuit elements complicate the analysis. The inductance of the MOSFET source lead, inside the package and in the circuit wiring which is common to both the drain and gate current paths, produces a voltage at the source which reduces the gate drive current. The voltage is determined by Ldi/dt, but since di/dt is a function of drain current, the mathematical solution is complex. The MOSFET output capacitance also complicates the mathematics. And finally, MOSFETs have finite internal gate resistance which effectively adds to the resistance of the driving source, but the internal resistance is difficult to measure and, consequently, is not specified.

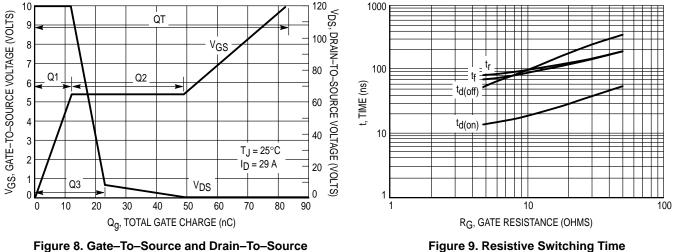
The resistive switching time variation versus gate resistance (Figure 9) shows how typical switching performance is affected by the parasitic circuit elements. If the parasitics were not present, the slope of the curves would maintain a value of unity regardless of the switching speed. The circuit used to obtain the data is constructed to minimize common inductance in the drain and gate circuit loops and is believed readily achievable with board mounted components. Most power electronic loads are inductive; the data in the figure is taken with a resistive load, which approximates an optimally snubbed inductive load. Power MOSFETs may be safely operated into an inductive load; however, snubbing reduces switching losses.



GATE-TO-SOURCE OR DRAIN-TO-SOURCE VOLTAGE (VOLTS)

Figure 7. Capacitance Variation

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Voltage versus Total Charge

Figure 9. Resistive Switching Time Variation versus Gate Resistance

DRAIN-TO-SOURCE DIODE CHARACTERISTICS

The switching characteristics of a MOSFET body diode are very important in systems using it as a freewheeling or commutating diode. Of particular interest are the reverse recovery characteristics which play a major role in determining switching losses, radiated noise, EMI and RFI.

System switching losses are largely due to the nature of the body diode itself. The body diode is a minority carrier device, therefore it has a finite reverse recovery time, t_{rr} , due to the storage of minority carrier charge, Q_{RR} , as shown in the typical reverse recovery wave form of Figure 15. It is this stored charge that, when cleared from the diode, passes through a potential and defines an energy loss. Obviously, repeatedly forcing the diode through reverse recovery further increases switching losses. Therefore, one would like a diode with short t_{rr} and low Q_{RR} specifications to minimize these losses.

The abruptness of diode reverse recovery effects the amount of radiated noise, voltage spikes, and current ringing. The mechanisms at work are finite irremovable circuit parasitic inductances and capacitances acted upon by high di/dts. The diode's negative di/dt during t_a is directly controlled by the device clearing the stored charge. However, the positive di/dt during t_b is an uncontrollable diode characteristic and is usually the culprit that induces current ringing. Therefore, when comparing diodes, the ratio of t_b/t_a serves as a good indicator of recovery abruptness and thus gives a comparative estimate of probable noise generated. A ratio of 1 is considered ideal and values less than 0.5 are considered snappy.

Compared to Motorola standard cell density low voltage MOSFETs, high cell density MOSFET diodes are faster (shorter $t_{\Gamma\Gamma}$), have less stored charge and a softer reverse recovery characteristic. The softness advantage of the high cell density diode means they can be forced through reverse recovery at a higher di/dt than a standard cell MOSFET diode without increasing the current ringing or the noise generated. In addition, power dissipation incurred from switching the diode will be less due to the shorter recovery time and lower switching losses.

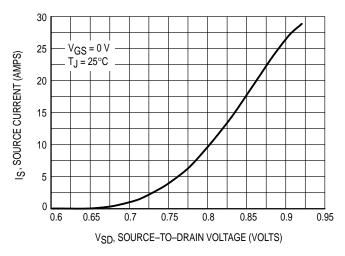
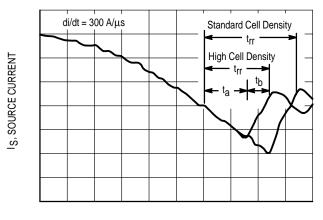


Figure 10. Diode Forward Voltage versus Current



t, TIME

Figure 11. Reverse Recovery Time (trr)

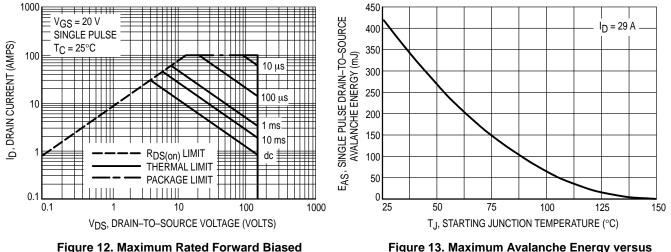
SAFE OPERATING AREA

The Forward Biased Safe Operating Area curves define the maximum simultaneous drain–to–source voltage and drain current that a transistor can handle safely when it is forward biased. Curves are based upon maximum peak junction temperature and a case temperature (T_C) of 25°C. Peak repetitive pulsed power limits are determined by using the thermal response data in conjunction with the procedures discussed in AN569, "Transient Thermal Resistance – General Data and Its Use."

Switching between the off-state and the on-state may traverse any load line provided neither rated peak current (I_{DM}) nor rated voltage (V_{DSS}) is exceeded, and that the transition time (t_r , t_f) does not exceed 10 μ s. In addition the total power

averaged over a complete switching cycle must not exceed $(T_J(MAX) - T_C)/(R_{\theta JC})$.

A power MOSFET designated E–FET can be safely used in switching circuits with unclamped inductive loads. For reliable operation, the stored energy from circuit inductance dissipated in the transistor while in avalanche must be less than the rated limit and must be adjusted for operating conditions differing from those specified. Although industry practice is to rate in terms of energy, avalanche energy capability is not a constant. The energy rating decreases non–linearly with an increase of peak current in avalanche and peak junction temperature.



Safe Operating Area



TYPICAL ELECTRICAL CHARACTERISTICS

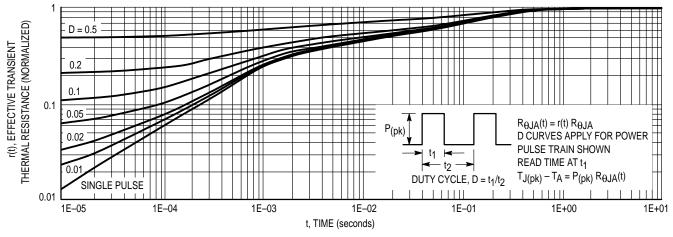


Figure 14. Thermal Response

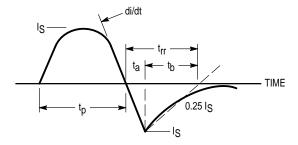
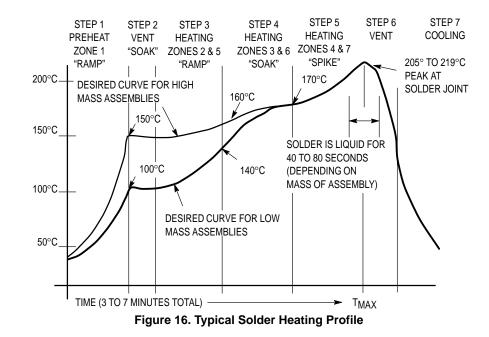


Figure 15. Diode Reverse Recovery Waveform

TYPICAL SOLDER HEATING PROFILE

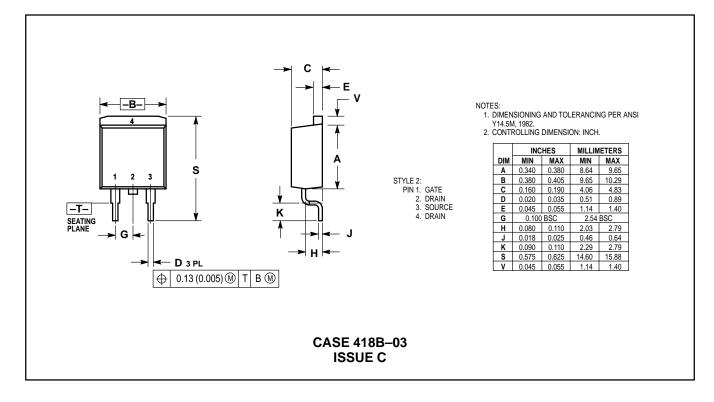
For any given circuit board, there will be a group of control settings that will give the desired heat pattern. The operator must set temperatures for several heating zones and a figure for belt speed. Taken together, these control settings make up a heating "profile" for that particular circuit board. On machines controlled by a computer, the computer remembers these profiles from one operating session to the next. Figure 16 shows a typical heating profile for use when soldering a surface mount device to a printed circuit board. This profile will vary among soldering systems, but it is a good starting point. Factors that can affect the profile include the type of soldering system in use, density and types of components on the board, type of solder used, and the type of board or substrate material being used. This profile shows temperature versus time. The

line on the graph shows the actual temperature that might be experienced on the surface of a test board at or near a central solder joint. The two profiles are based on a high density and a low density board. The Vitronics SMD310 convection/in-frared reflow soldering system was used to generate this profile. The type of solder used was 62/36/2 Tin Lead Silver with a melting point between 177–189°C. When this type of furnace is used for solder reflow work, the circuit boards and solder joints tend to heat first. The components on the board are then heated by conduction. The circuit board, because it has a large surface area, absorbs the thermal energy more efficiently, then distributes this energy to the components. Because of this effect, the main body of a component may be up to 30 degrees cooler than the adjacent solder joints.



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PACKAGE DIMENSIONS



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