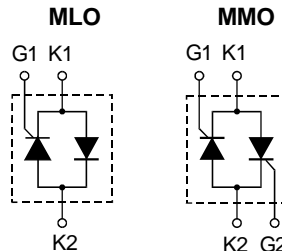
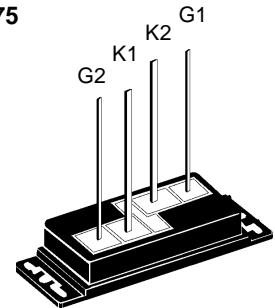


# AC Controller Modules

**$I_{RMS} = 86 \text{ A}$**   
 **$V_{RRM} = 1200-1600 \text{ V}$**

| $V_{RSM}$ | $V_{RRM}$ | Type         |              |
|-----------|-----------|--------------|--------------|
| $V_{DSM}$ | $V_{DRM}$ |              |              |
| V         | V         |              |              |
| 1200      | 1200      | MLO 75-12io1 | MMO 75-12io1 |
| 1600      | 1600      | MLO 75-16io1 | MMO 75-16io1 |


**MMO 75**


K1 = Cathode 1, G1 = Gate 1  
 K2 = Cathode 2, G2 = Gate 2  
 (MLO 36 has no G2 lead)

| Symbol         | Test Conditions   | Maximum Ratings                   |                            |
|----------------|---|-----------------------------------|----------------------------|
| $I_{RMS}$      | $T_K = 85^\circ\text{C}$ , 50 - 400 Hz (for single controller)  | 86                                | A                          |
| $I_{TRMS}$     | $T_{VJ} = T_{VJM}$  | 62                                | A                          |
| $I_{TAVM}$     | $T_K = 85^\circ\text{C}$ ; (180° sine)  | 39                                | A                          |
| $I_{TSM}$      | $T_{VJ} = 45^\circ\text{C}$ ;<br>$V_R = 0$  | t = 10 ms (50 Hz), sine           | 1150 A                     |
|                |   | t = 8.3 ms (60 Hz), sine          | 1230 A                     |
| $I_{\rho t}$   | $T_{VJ} = 45^\circ\text{C}$ ;<br>$V_R = 0$  | t = 10 ms (50 Hz), sine           | 6600 A <sup>2</sup> s      |
|                |   | t = 8.3 ms (60 Hz), sine          | 6280 A <sup>2</sup> s      |
| $(di/dt)_{cr}$ | $T_{VJ} = T_{VJM}$<br>f = 50 Hz, $t_p = 200 \mu\text{s}$<br>$V_D = 2/3 V_{DRM}$<br>$I_G = 0.45 \text{ A}$<br>$di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | repetitive, $I_T = 150 \text{ A}$ | 100 A/ $\mu\text{s}$       |
|                |   | non repetitive, $I_T = I_{TAVM}$  | 500 A/ $\mu\text{s}$       |
| $(dv/dt)_{cr}$ | $T_{VJ} = T_{VJM}$ ;<br>$R_{GK} = \infty$ ; method 1 (linear voltage rise)  | $V_{DR} = 2/3 V_{DRM}$            | 1000 V/ $\mu\text{s}$      |
| $P_{GM}$       | $T_{VJ} = T_{VJM}$  | $t_p = 30 \mu\text{s}$            | 10 W                       |
|                | $I_T = I_{TAVM}$  | $t_p = 300 \mu\text{s}$           | 5 W                        |
| $P_{GAVM}$     |   |                                   | 0.5 W                      |
| $V_{RGM}$      |   |                                   | 10 V                       |
| $T_{VJ}$       |   | -40...+125                        | °C                         |
| $T_{VJM}$      |   | 125                               | °C                         |
| $T_{stg}$      |   | -40...+125                        | °C                         |
| $V_{ISOL}$     | 50/60 Hz, RMS   | t = 1 min                         | 3000 V~                    |
|                | $I_{ISOL} \leq 1 \text{ mA}$  | t = 1 s                           | 3600 V~                    |
| $M_d$          | Mounting torque   | (M3)                              | $0.7 \pm 0.1 \text{ Nm}$   |
|                |   | (UNF 4-32)                        | $6 \pm 0.9 \text{ lb.in.}$ |
| <b>Weight</b>  | typ.  |                                   | 15 g                       |

### Features

- Thyristor controller for AC (circuit W1C acc. to IEC) for mains frequency
- Direct copper bonded  $\text{Al}_2\text{O}_3$  -ceramic base plate
- Isolation voltage 3600 V~
- Planar passivated chips
- UL registered, E 72873
- Long wire leads suitable for PC board soldering

### Applications

- Switching and control of single and three phase AC
- Softstart AC motor controller
- Solid state switches
- Light and temperature control

### Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density

Data according to IEC 60747 and to a single thyristor/diode unless otherwise stated.  
 IXYS reserves the right to change limits, test conditions and dimensions.

| Symbol     | Test Conditions  | Characteristic Values  |
|------------|--|------------------------|
| $I_R, I_D$ | $T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$   | $\leq 5$ mA            |
| $V_T$      | $I_T = 100$ A; $T_{VJ} = 25^\circ\text{C}$   | $\leq 1.4$ V           |
| $V_{T0}$   | For power-loss calculations only   | 0.85 V                 |
| $r_T$      |  | 5.0 m $\Omega$         |
| $V_{GT}$   | $V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$   | $\leq 1.5$ V           |
|            | $T_{VJ} = -40^\circ\text{C}$   | $\leq 1.6$ V           |
| $I_{GT}$   | $V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$   | $\leq 150$ mA          |
|            | $T_{VJ} = -40^\circ\text{C}$   | $\leq 200$ mA          |
| $I_{GM}$   | $t_p = 50$ $\mu\text{s}$ , $f = 60$ Hz, $I_T = I_{TAVM}$   | 6 A                    |
| $V_{GD}$   | $T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$  | $\leq 0.25$ V          |
| $I_{GD}$   |  | $\leq 5$ mA            |
| $I_L$      | $T_{VJ} = 25^\circ\text{C}$ ; $t_p = 10$ $\mu\text{s}$ , $V_D = 6$ V<br>$I_G = 0.45$ A; $di_G/dt = 0.45$ A/ $\mu\text{s}$  | $\leq 300$ mA          |
| $I_H$      | $T_{VJ} = 25^\circ\text{C}$ ; $V_D = 6$ V; $R_{GK} = \infty$   | $\leq 100$ mA          |
| $t_{gd}$   | $T_{VJ} = 25^\circ\text{C}$ ; $V_D = 1/2 V_{DRM}$<br>$I_G = 0.45$ A; $di_G/dt = 0.45$ A/ $\mu\text{s}$   | $\leq 2$ $\mu\text{s}$ |
| $t_q$      | $T_{VJ} = T_{VJM}; I_T = 50$ A, $t_p = 200$ $\mu\text{s}$ ; $-di/dt = 10$ A/ $\mu\text{s}$<br>$V_R = 100$ V; $dv/dt = 15$ V/ $\mu\text{s}$ ; $V_D = 2/3 V_{DRM}$ | typ. 150 $\mu\text{s}$ |
| $R_{thJC}$ | per thyristor/diode; DC current per module   | 0.55 K/W<br>0.275 K/W  |
| $R_{thJK}$ | per thyristor/diode; DC current per module   | 0.75 K/W<br>0.375 K/W  |
| $d_s$      | Creeping distance on surface   | 4.5 mm                 |
| $d_A$      | Creepage distance in air   | 4.5 mm                 |
| $a$        | Max. allowable acceleration  | 50 m/s <sup>2</sup>    |

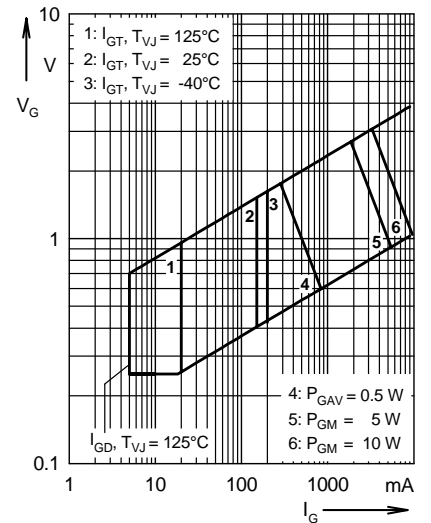


Fig. 1 Gate trigger characteristics

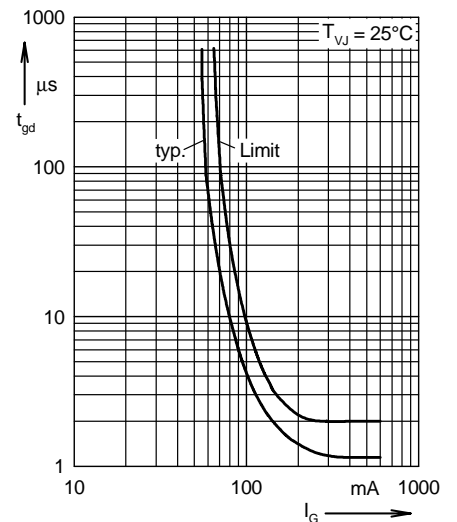
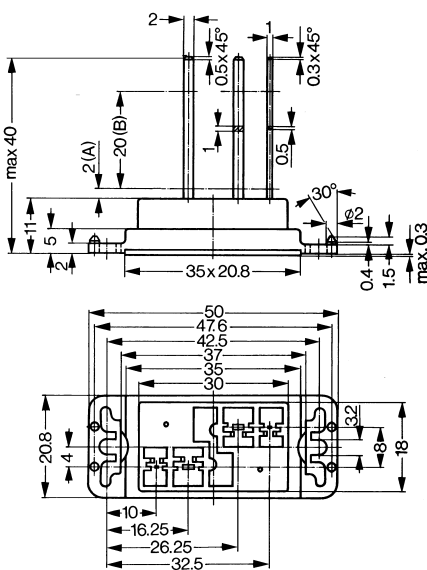


Fig. 2 Gate trigger delay time

### Dimensions in mm (1 mm = 0.0394") MLO 75



### MMO 75

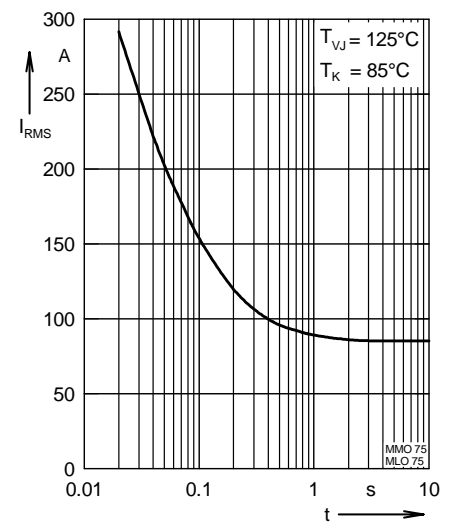
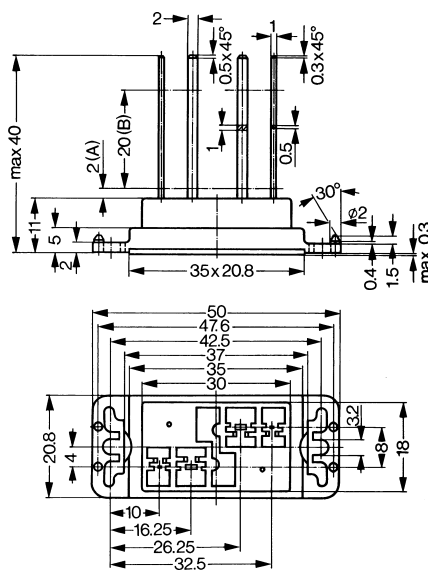


Fig. 3 Rated RMS current versus time (360° conduction)

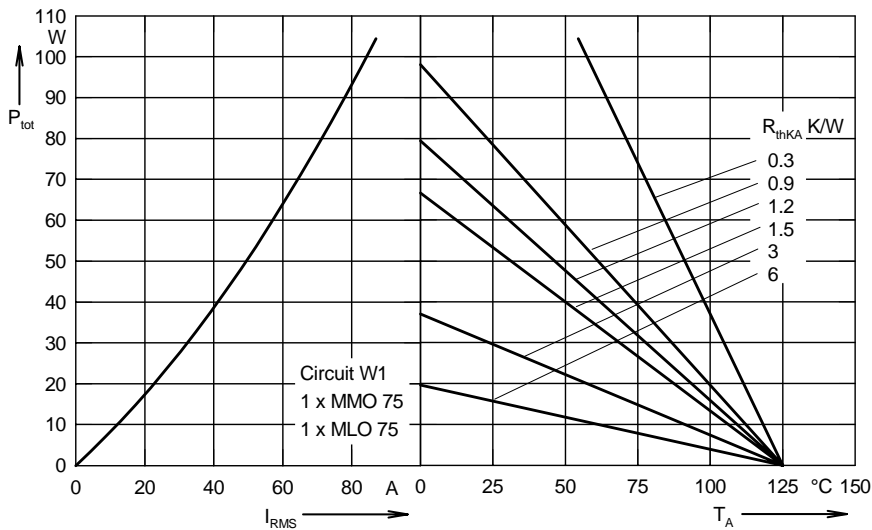


Fig. 4 Load current capability for single phase AC controller

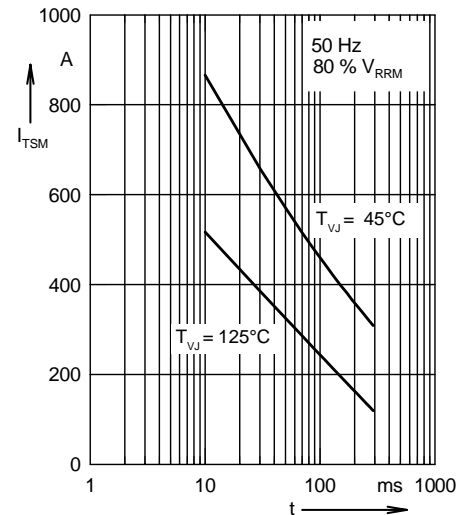


Fig. 5 Surge overload current  
 $I_{TSM}$ ,  $I_{FSM}$ : Crest value, t: duration

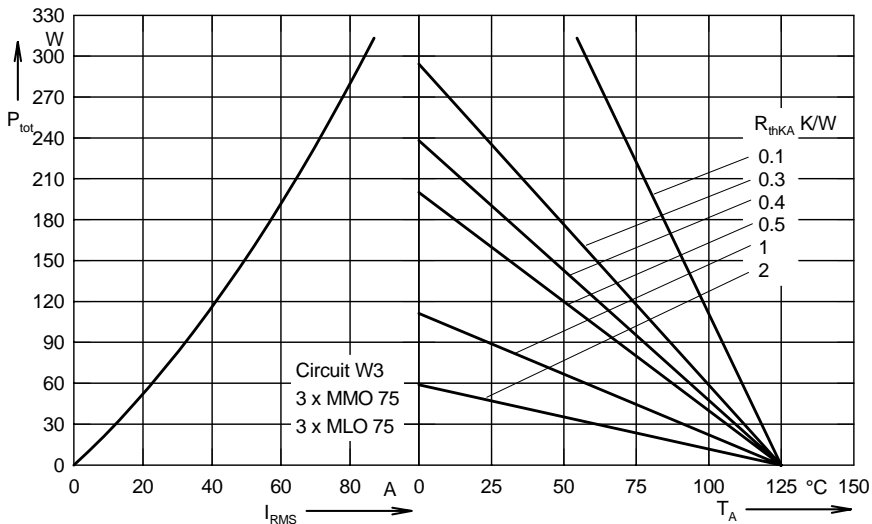


Fig. 6 Load current capability for three phase AC controller: 3xMMO 75/MLO 75

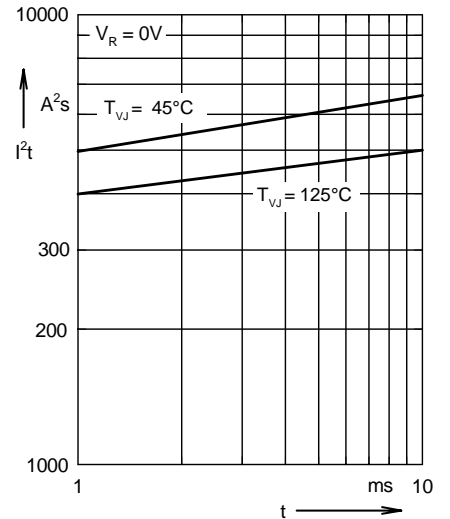


Fig. 7  $I^2t$  versus time (1-10 ms)

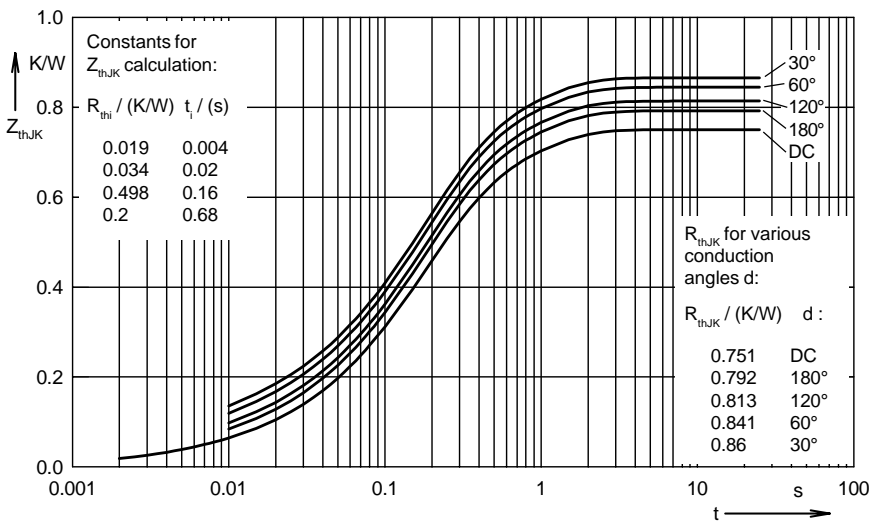


Fig. 8 Transient thermal impedance junction to heatsink (per thyristor or diode)

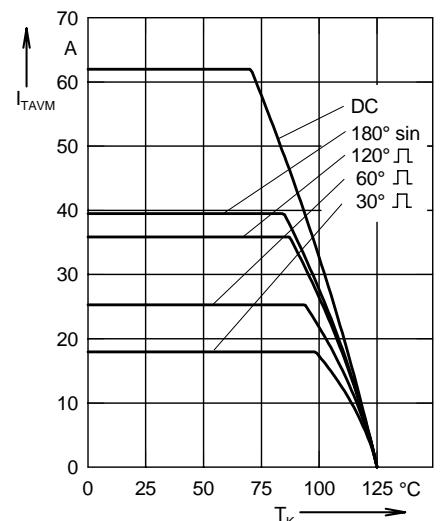


Fig. 9 Maximum on-state current versus heatsink temperature