4-bit Bidirectional Unviersal Shift Register

HITACHI

Description

This bidirectional shift register is designed to incorporate virtually all of the features a system designer may want in a shift register. It features parallel inputs, parallel outputs, right shift and left shift serial inputs, operating mode control inputs, and a direct overriding clear line. The register has four destinct modes of operation: parallel (broadside) load, shift right (in the direction Q_0 toward Q_3); shift left; inhibit clock (do nothing).

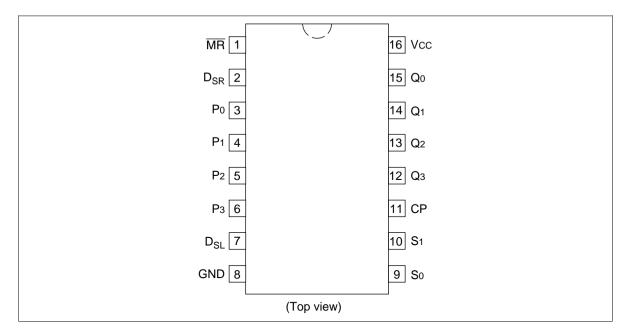
Synchronous parallel loading is accomplished by applying the four bits of data and taking both mode control inputs, S_0 and S_1 , high. The data are loaded into their respective flip-flops and appear at the output after the positive transition of the clock input. During loading, serial data flow is inhibited. Shift right is accomplished synchronously with the rising edge of the clock pulse when S_0 is high and S_1 is low. Serial date for this mode is entered at the shift right data input. When S_0 is low and S_1 is high, data shifts left synchronously and new data is entered at the shifts left serial input. Clocking of the flip-flops is inhibited when both mode control inputs are low. The mode control inputs should be changed only when the clock input is high.

Features

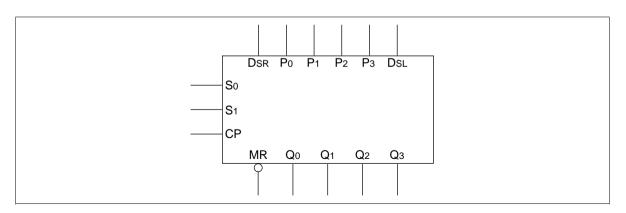
- Asynchronous Master Reset
- Hole (Do Nothing) Mode
- Outputs Source/Sink 24 mA



Pin Arrangement



Logic Symbol



Pin Names

 S_0, S_1 Mode Control Inputs P_0 to P_3 Parallel Data Inputs

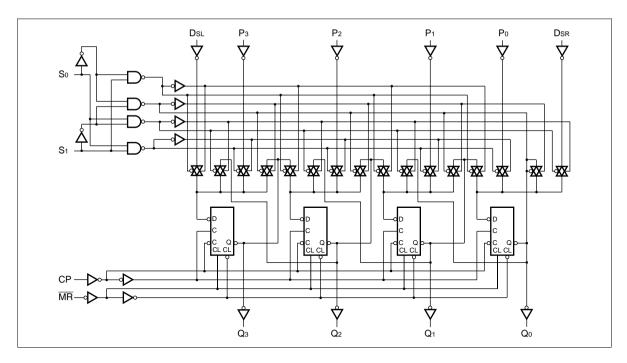
 $\begin{array}{ll} D_{SR} & & Serial \ Data \ Input \ (Shift \ Right) \\ D_{SL} & & Serial \ Data \ Input \ (Shift \ Left) \end{array}$

CP Clock Pulse Input (Active Rising Edge)

MR Asynchronous Master Reset Input (Active LOW)

Q₀ to Q₃ Parallel Outputs

Logic Diagram



Mode Select Table

| | Input | s | | | | | Outp | ut | | |
|----------------|-------|----------------|----------------|----------|-----------------|----------------|-------------------------------------|--------------------------------------|-------------------------------------|----------------|
| Operating Mode | MR | S ₁ | S ₀ | D_{SR} | D _{sL} | P _n | Q_0 | $\mathbf{Q}_{\scriptscriptstyle{1}}$ | Q_2 | Q_3 |
| Reset | L | Χ | Χ | Χ | Χ | Χ | L | L | L | L |
| Hold | Н | L | L | Χ | Χ | Χ | \mathbf{q}_{0} | q_1 | q_2 | q_3 |
| Shift Left | Н | Н | L | Χ | L | Χ | $\mathbf{q}_{\scriptscriptstyle 1}$ | q_2 | q_3 | L |
| | Н | Н | L | Χ | Н | Х | $q_{\scriptscriptstyle 1}$ | q_2 | q_3 | Н |
| Shift Right | Н | L | Н | L | Χ | Χ | L | q_{o} | $\mathbf{q}_{\scriptscriptstyle 1}$ | q_2 |
| | Н | L | Н | Н | Χ | Χ | Н | q_o | $q_{\scriptscriptstyle 1}$ | q_2 |
| Parallel Load | Н | Н | Н | Χ | Χ | p _n | p_0 | p ₁ | p ₂ | p ₃ |

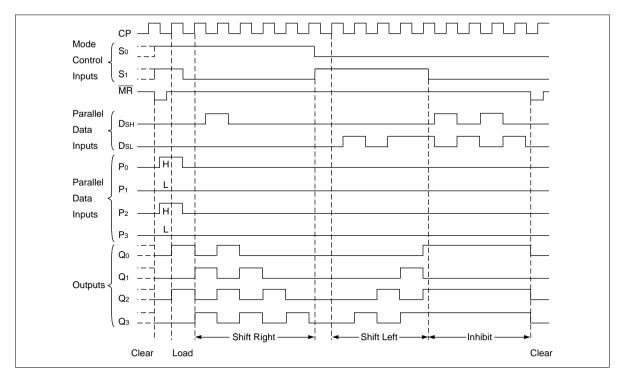
H : HIGH Voltage LevelL : LOW Voltage Level

 $p_n (q_n)$: Lower case letters indicate the state of the referenced input (or output) one setup time prior to the

LOW-to-HIGH clock transition

X : Immaterial

Timing Diagram



DC Characteristics (unless otherwise specified)

| Item | Symbol | Max | Unit | Condition |
|----------------------------------|-----------------|-----|------|---|
| Maximum quiescent supply current | I _{cc} | 80 | μΑ | $V_{IN} = V_{CC}$ or ground, $V_{CC} = 5.5 \text{ V}$, Ta = Worst case |
| Maximum quiescent supply current | I _{cc} | 8.0 | μΑ | $V_{IN} = V_{CC}$ or ground, $V_{CC} = 5.5 \text{ V}$, Ta = 25°C |

AC Characteristics: HD74AC194

| | | | Ta = + C _L = 5 | | | Ta = −4 C _L = 50 | 0°C to +85°C pF | |
|--|-----------------------------|-----------------------|------------------------------|-----|------|--------------------------------|--------------------|----------|
| Item | Symbol | V _{cc} (V)*1 | Min | Тур | Max | Min | Max | Unit |
| Maximum clock | \mathbf{f}_{max} | 3.3 | 7.5 | _ | | 65 | | MHz |
| frequency | | 5.0 | 100 | _ | | 85 | | _ |
| Propagation delay | t _{PLH} | 3.3 | 1.0 | _ | 13.0 | 1.0 | 15.0 | ns |
| CP to Q _n | | 5.0 | 1.0 | _ | 10.0 | 1.0 | 11.5 | _ |
| Propagation delay | $t_{\scriptscriptstylePHL}$ | 3.3 | 1.0 | _ | 13.0 | 1.0 | 15.0 | ns |
| CP to Q _n | | 5.0 | 1.0 | _ | 10.0 | 1.0 | 11.5 | _ |
| Propagation delay | $t_{\tiny PHL}$ | 3.3 | 1.0 | _ | 10.5 | 1.0 | 12.5 | ns |
| \overline{MR} to Q_{\scriptscriptstylen} | | 5.0 | 1.0 | _ | 8.0 | 1.0 | 9.0 | |

Note: 1. Voltage Range 3.3 is 3.3 V \pm 0.3 V Voltage Range 5.0 is 5.0 V \pm 0.5 V

AC Operating Requirements: HD74AC194

| | | | Ta = +25°C C _L = 50 pF | | $Ta = -40^{\circ}C$ $to +85^{\circ}C$ $C_{L} = 50 \text{ pF}$ | _ |
|------------------------------------|------------------|-----------------------|--------------------------------------|------------|---|--------------|
| Item | Symbol | V _{cc} (V)*1 | Тур | Guaranteed | l Minimum | Unit |
| Setup time, HIGH or LOW | t _{su} | 3.3 | _ | 5.5 | 7.0 | ns |
| Pn or D_{SR} or D_{SL} to CP | | 5.0 | _ | 4.0 | 5.0 | |
| Hold time, HIGH or LOW | t _h | 3.3 | _ | 2.0 | 3.0 | ns |
| Pn or D_{SR} or D_{SL} to CP | | 5.0 | _ | 1.5 | 2.0 | |
| Setup time, HIGH or LOW | t _{su} | 3.3 | _ | 6.0 | 7.5 | ns |
| S _n to CP | | 5.0 | _ | 4.5 | 5.5 | |
| Hold time, HIGH or LOW | t _h | 3.3 | _ | 0.0 | 0.0 | ns |
| S _n to CP | | 5.0 | _ | 0.0 | 0.0 | |
| Recovery time | t _{rec} | 3.3 | _ | 0.5 | 0.5 | ns |
| MR to CP | | 5.0 | _ | 0.5 | 0.5 | |
| Pulse width | t _w | 3.3 | _ | 5.5 | 7.0 | ns |
| | | 5.0 | _ | 4.5 | 5.0 | _ |

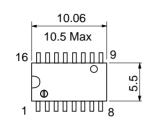
Note: 1. Voltage Range 3.3 is $3.3 \text{ V} \pm 0.3 \text{ V}$ Voltage Range 5.0 is $5.0 \text{ V} \pm 0.5 \text{ V}$

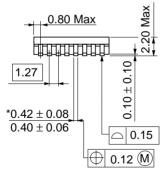
Capacitance

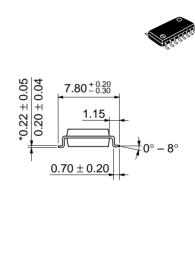
| Item | Symbol | Тур | Unit | Condition |
|-------------------------------|----------------------------|-----|------|--------------------------|
| Input capacitance | C _{IN} | 4.5 | pF | $V_{cc} = 5.5 \text{ V}$ |
| Power dissipation capacitance | C_{\scriptscriptstylePD} | 100 | pF | $V_{cc} = 5.0 \text{ V}$ |

Unit: mm 19.20 20.00 Max 16 7.40 Max 6.30 1.3 1.11 Max 7.62 5.06 Max 2.54 Min 0.51 Min $0.25^{+0.13}_{-0.05}$ 0.48 ± 0.10 2.54 ± 0.25 $0^{\circ} - 15^{\circ}$ Hitachi Code DP-16 **JEDEC** Conforms EIAJ Conforms Weight (reference value) 1.07 g

Unit: mm







*Dimension including the plating thickness
Base material dimension

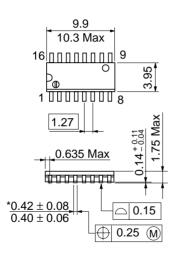
EIAJ Conforms
Weight (reference value) 0.24 g

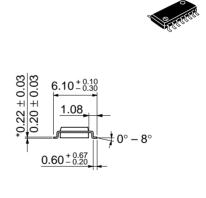
FP-16DA

Hitachi Code

JEDEC

Unit: mm

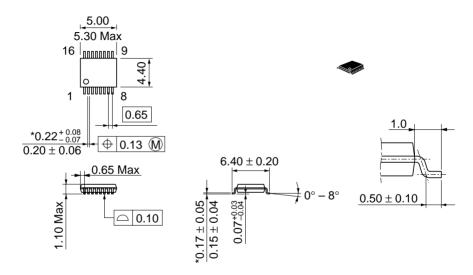




*Dimension including the plating thickness
Base material dimension

| Hitachi Code | FP-16DN |
|--------------------------|----------|
| JEDEC | Conforms |
| EIAJ | Conforms |
| Weight (reference value) | 0.15 g |

Unit: mm



| | Hitachi Code | TTP-16DA |
|--|--------------------------|----------|
| | JEDEC | _ |
| *Dimension including the plating thickness | EIAJ | |
| Base material dimension | Weight (reference value) | 0.05 g |

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HTACHI

Hitachi, Ltd.

Semiconductor & Integrated Circuits.

Nippon Bldg., 2-6-2, Ohte-machi, Chiyoda-ku, Tokyo 100-0004, Japan Tel: Tokyo (03) 3270-2111 Fax: (03) 3270-5109

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For further information write to:

Hitachi Semiconductor (America) Inc. 179 East Tasman Drive, San Jose,CA 95134 Tel: <1> (408) 433-1990 Fax: <1>(408) 433-0223 Hitachi Europe GmbH Electronic components Group Dornacher Stra§e 3 D-85622 Feldkirchen, Munich Germany Tel: <49> (89) 9 9180-0

Fax: <49> (89) 9 29 30 00 Hitachi Europe Ltd. Electronic Components Group. Whitebrook Park

Maidenhead Berkshire SL6 8YA, United Kingdom Tel: <44> (1628) 585000

Fax: <44> (1628) 778322

Lower Cookham Road

Hitachi Asia Pte. Ltd. 16 Collyer Quay #20-00 Hitachi Tower Singapore 049318 Tel: 535-2100 Fax: 535-1533

Hitachi Asia Ltd. Taipei Branch Office 3F, Hung Kuo Building. No.167, Tun-Hwa North Road, Taipei (105) Tel: <886> (2) 2718-3666

Fax: <886> (2) 2718-8180

7/F., North Tower, World Finance Centre, Harbour City, Canton Road, Tsim Sha Tsui, Kowloon, Hong Kong Tel: <852> (2) 735 9218 Fax: <852> (2) 730 0281 Telex: 40815 HITEC HX

Hitachi Asia (Hong Kong) Ltd.

Group III (Electronic Components)

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