

Isolated RS485 Interface with Handshake IL485W



The IL485W is a galvanically isolated, high-speed differential bus transceiver, designed for bi-directional data communication on balanced transmission lines. The IL485W uses patented IsoLoop[®] technology and is the first isolated RS-485 interface available in a standard 16 pin SOIC package, which meets the ANSI Standards EIA/TIA-422-B and RS485.

The IL485W has current limiting and thermal shutdown features to protect against output short circuits and bus contention situations where these may cause excessive power dissipation.

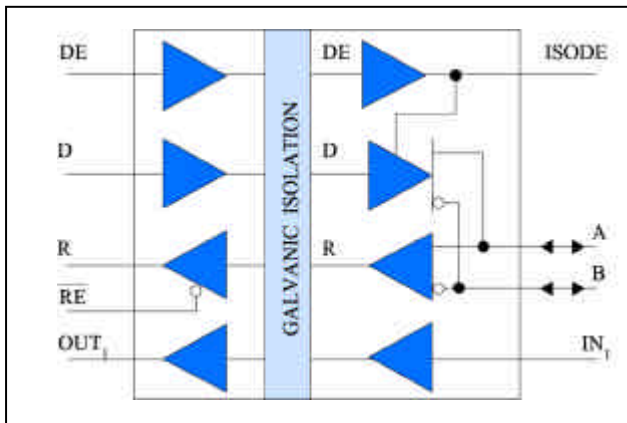
With a 1 nsec pulse skew and 16 nsec propagation delay, the IL485W is ideal for PROFIBUS applications. Use of DE/ISODE and IN1/OUT1 allows the IL485W to perform the handshaking operations of RTSAS and DTSAS of PROFIBUS.

- 2500 Vrms Isolation (1 min)
- 25 ns Maximum Propagation Delay
- 35 MBaud Data Rate
- 1 ns Pulse Skew (typ.)
- Designed for Multi-point Transmission on Long Bus Lines in Noisy Environments
- ±60 mA Driver Output Capability
- Thermal Shutdown Protection
- Meets or Exceeds ANSI RS-485 and ISO 8482:1987 (E)
- -40°C to +85°C Temperature Range
- 16 Pin SOIC Package
- PROFIBUS International Component Recognition
- UL1577 Approval (pending)
- IEC 61010-1 Approval (pending)

Applications

- PROFIBUS/RS485
- RS-485 Systems
- Multiple Data Point Transmission

Functional Diagram (IL485W)



Function Table

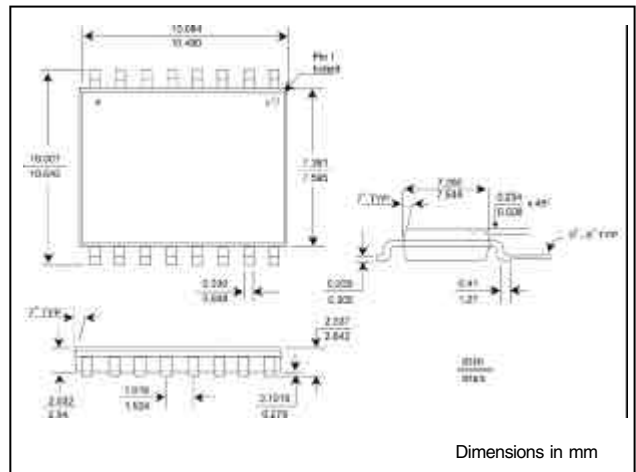
| V _{ID} (A-B) | DE | RE | ISODE | R | D | MODE |
|--------------------------|----|----|-------|---|---|-------------------|
| ≥0.2V | L | L | L | H | X | Receive |
| ≤-0.2V | L | L | L | L | X | Receive |
| -7<V _{ID} <12 | X | H | X | Z | X | Receive/ Drive |
| ≥ 1.5 | H | L | H | H | H | Drive |
| ≤-1.5 | H | L | H | L | L | Drive |
| Open | L | L | L | H | X | Receive |

H = High Level

L = Low Level

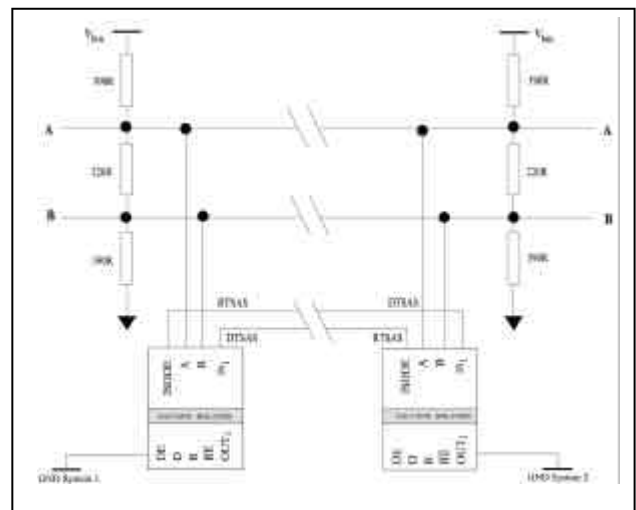
X = Irrelevant

Z = High Impedance

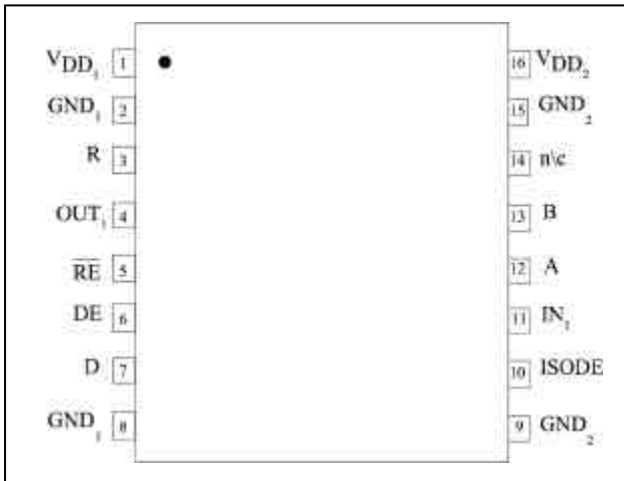


Dimensions in mm

PROFIBUS Fault Interrogation



Pin Configuration (IL485W)



Pin Connections (IL485W)

| | | |
|----|------------------|--|
| 1 | V _{DD1} | Input Power Supply |
| 2 | GND ₁ | Input Power Supply Ground Return |
| 3 | R | Output Data from Bus |
| 4 | OUT ₁ | Output from Auxiliary Isolation Channel |
| 5 | RE | Read Data Enable (If RE is high, R = High Impedance) |
| 6 | DE | Drive Enable |
| 7 | D | Data Input to Bus |
| 8 | GND ₁ | Input Power Supply Ground Return |
| 9 | GND ₂ | Output Power Supply Ground Return |
| 10 | ISODE | Isolated DE Output for use in Profibus applications where the state of the drive enable node needs to be monitored |
| 11 | IN ₁ | Input to the Auxiliary Isolation Channel |
| 12 | A | 'A' Bus (Receive - True) |
| 13 | B | 'B' Bus (Receive - Inverse) |
| 14 | n/c | No Internal Connection |
| 15 | GND ₂ | Output Power Supply Return |
| 16 | V _{DD2} | Output Power Supply |

Absolute Maximum Ratings

| PARAMETERS | SYMBOL | MIN. | MAX. | UNITS |
|---|-------------------------------------|------|-----------------------|--------|
| Storage Temperature | T _S | -65 | 150 | °C |
| Ambient Operating Temperature | T _A | -40 | 85 | °C |
| Voltage Range at A or B Bus Pins | | -7 | 12 | Volts |
| Supply Voltage ⁽¹⁾ | V _{DD1} , V _{DD2} | -0.5 | 7 | Volts |
| Digital Input Voltage | | -0.5 | 5.5 | Volts |
| Digital Output Voltage | | -0.5 | V _{DD} + 0.1 | Volts |
| Continuous Total Power Dissipation (25°C) | | | 725 | mWatts |
| Power Dissipation (85°C) | | | 377 | mWatts |
| Maximum Output Current | I _O | | 95 | mA |
| Lead Solder Temperature (10s) | | | 260 | °C |
| ESD | 2kV Human Body Model | | | |

Insulation Specifications

| PARAMETERS | CONDITION | MIN. | TYP. | MAX. | UNITS |
|------------------------------|-----------------------------|-----------------------|------|------|-------|
| Creepage Distance (External) | | 8.077 | | | mm |
| Barrier Impedance | | >10 ¹⁴ 7 | | | Ω pF |
| Leakage Current | 240V _{RMS} 60Hz | | 0.2 | | μAmps |

Recommended Operating Conditions

| PARAMETERS | SYMBOL | MIN. | MAX. | UNITS |
|---|-------------------------------------|-----------|----------|-------|
| Supply Voltage | V _{DD1} , V _{DD2} | 4.5 | 5.5 | Volts |
| Input Voltage at any bus terminal (separately or common mode) | V _I V _{IC} | | 12 -7 | Volts |
| High-Level Digital Input Voltage | V _{IH} | 3 | | Volts |
| Low-Level Digital Input Voltage | V _{IL} | | 0.8 | Volts |
| Differential Input Voltage (2) | V _{ID} | | +12/ - 7 | Volts |
| High-Level Output Current (Driver) | I _{OH} | | -60 | mA |
| High-Level Digital Output Current (Receiver) | I _{OH} | | 8 | mA |
| Low-Level Output Current (Driver) | I _{OL} | | 60 | mA |
| Low-Level Digital Output Current (Receiver) | I _{OL} | | 8 | mA |
| Operating Free Air Temperature | T _A | -40 | 85 | °C |
| Digital Input Signal Rise and Fall Times | t _{IR} , t _{IF} | DC Stable | | |

IEC61010-1

TUV Certificate Numbers: *Pending*

Classifications as Table 1

| MODEL | POLLUTION DEGREE | MATERIAL GROUP | MAX WORKING VOLTAGE | PACKAGE TYPE 16-SOIC (7.5mm) |
|--------|------------------|----------------|---------------------|------------------------------|
| IL485W | II | III | 300V _{RMS} | ✓ |

UL 1577

Component Recognition Program. File # *Pending*
Rated 2500V_{RMS} for 1 min.

Driver Section Specifications

All Specifications are T_{\min} to T_{\max} unless otherwise stated

| PARAMETERS | SYMBOL | MIN. | TYP. (5) | MAX. | UNITS | TEST CONDITIONS |
|---|------------------|------|----------|---------------------|----------------|--|
| Input Clamp Voltage | V_{IK} | | | -1.5 | V | $I_L = -18\text{mA}$ |
| Output Voltage | V_O | 0 | | 6 | V | $I_O = 0$ |
| Differential Output Voltage | $ V_{OD1} $ | 1.5 | | 6 | V | $I_O = 0$ |
| Differential Output Voltage (6) | $ V_{OD2} $ | 1.5 | 2.5 | 5 | V | $R_L = 54\Omega$ |
| Differential Output Voltage | V_{OD3} | 1.5 | | 5 | V | $V_{\text{test}} = -7$ to 12V |
| Change in Magnitude of (7) Differential Output Voltage | $\Delta V_{OD} $ | | | ± 0.2 | V | $R_L = 54$ or 100Ω |
| Common Mode Output Voltage | V_{OC} | | | 3 -1 | V | $R_L = 54$ or 100Ω |
| Change in Magnitude of (7) Common Mode Output Voltage | $\Delta V_{OC} $ | | | ± 0.2 | V | $R_L = 54$ or 100Ω |
| Output Current (4) | I_O | | | 1 -0.8 | mA mA | Output Disabled $V_O = 12$ $V_O = -7$ |
| High Level Input Current | I_{IH} | | | 10 | μA | $V_I = 3.5\text{V}$ |
| Low Level Input Current | I_{IL} | | | -10 | μA | $V_I = 0.4\text{V}$ |
| Short-Circuit Output Current | I_{OS} | | | -250 -150 250 | mA mA mA | $V_O = -6$ $V_O = 0$ $V_O = 8$ |
| Supply Current ($V_{DD2} = +5\text{V}$) | I_{DD2} | | 27 | 34 | mA | No Load (Outputs Enabled) |
| ($V_{DD1} = +5\text{V}$) | I_{DD1} | | 5 | 10 | mA | |
| Switching Characteristics | | | | | | |
| Maximum Data Rate | | 35 | | | Mbd | $R_L = 54\Omega$, $C_L = 50\text{pF}$ |
| Differential Output Delay Time | t_D (OD) | | 16 | 25 | ns | $R_L = 54\Omega$, $C_L = 50\text{pF}$ |
| Pulse Skew (10) | t_{SK} (P) | | 1 | 6 | ns | $R_L = 54\Omega$, $C_L = 50\text{pF}$ |
| Differential Output Transition Time | t_T (OD) | | 8 | 10 | ns | $R_L = 54\Omega$, $C_L = 50\text{pF}$ |
| Output Enable Time to High Level | t_{PZH} | | 31 | 65 | ns | $R_L = 54\Omega$, $C_L = 50\text{pF}$ |
| Output Enable Time to Low Level | t_{PZL} | | 22 | 35 | ns | $R_L = 54\Omega$, $C_L = 50\text{pF}$ |
| Output Disable Time from High Level | t_{PHZ} | | 28 | 50 | ns | $R_L = 54\Omega$, $C_L = 50\text{pF}$ |
| Output Disable Time from Low Level | t_{PLZ} | | 16 | 32 | ns | $R_L = 54\Omega$, $C_L = 50\text{pF}$ |
| Skew Limit (3) | t_{SK} (LIM) | | 2 | 8 | ns | $R_L = 54\Omega$, $C_L = 50\text{pF}$ |

Notes

- All Voltage values are with respect to network ground except differential I/O bus voltages.
- Differential input/output voltage is measured at the noninverting terminal A/Y with respect to the inverting terminal B/Z.
- Skew limit is the maximum difference in any two channels in one device.
- The power-off measurement in ANSI Standard EIA/TIA-422-B applies to disabled outputs only and is not applied to combined inputs and outputs.
- All typical values are at V_{DD1} , $V_{DD2} = 5\text{V}$ and $T_A = 25^\circ\text{C}$.
- The minimum V_{OD2} with a 100Ω load is either $\frac{1}{2}V_{OD1}$ or 2V, whichever is greater.
- $\Delta|V_{OD}|$ and $\Delta|V_{OC}|$ are the changes in magnitude of V_{OD} and V_{OC} , respectively, that occur when the input is changed from one logic state to the other.
- This applies for both power on and power off, refer to ANSI standard RS-485 for exact condition. The EIA/TIA-422-B limit does not apply for a combined driver and receiver terminal.
- Includes 8 ns read enable time. Maximum propagation delay is 25 ns after read assertion.
- Pulse skew is defined as the $|t_{PLH} - t_{PHL}|$ of each channel.

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Receiver Section Specifications

All Specifications are T_{min} to T_{max} unless otherwise stated

| PARAMETERS | SYMBOL | MIN. | TYP. (5) | MAX. | UNITS | TEST CONDITIONS |
|--|---------------|----------------|----------|-----------|------------|---|
| Positive-going Input Threshold Voltage | V_{IT+} | | | 0.2 | V | $V_O = 2.7V, I_O = -0.4mA$ |
| Negative-going Input Threshold Voltage | V_{IT-} | -0.2 | | | V | $V_O = 0.5V, I_O = 8mA$ |
| Hysteresis Voltage $V_{IT+} - V_{IT-}$ | V_{hys} | | 60 | | mV | |
| High Level Digital Output Voltage | V_{OH} | $V_{DD} - 0.2$ | | | V | $V_{ID} = 200mV, I_{OH} = -20\mu A$ |
| Low Level Digital Output Voltage | V_{OL} | | | 0.2 | V | $V_{ID} = -200mV, I_{OL} = 20\mu A$ |
| High-Impedance-State Output Current | I_{OZ} | | | ± 20 | μA | $V_O = 0.4$ to $(V_{DD2} - 0.5)$ V |
| Line Input Current (8) | I_I | | | 1 -0.8 | mA | Other Input - 0V $V_I = 12V$ $V_I = -7V$ |
| Input Resistance | r_I | | 50 | | k Ω | |
| Supply Current ($V_{DD2} = +5$) | I_{DD2} | | 27 | 34 | mA | No Load (Outputs Enabled) |
| ($V_{DD1} = +5$) | I_{DD1} | | 5 | 10 | mA | |
| Switching Characteristics | | | | | | |
| Maximum Data Rate | | 35 | | | Mbd | $R_L = 54\Omega, C_L = 50pF$ |
| Propagation Time (9) | t_{PD} | | 24 | 32 | ns | $V_O = -1.5$ to $1.5V, C_L = 15pF$ |
| Pulse Skew (10) | $t_{SK(P)}$ | | 1 | 6 | ns | $V_O = -1.5$ to $1.5V, C_L = 15pF$ |
| Skew Limit (3) | $t_{SK(lim)}$ | | 2 | 8 | ns | $R_L = 54\Omega, C_L = 50pF$ |
| Output Enable Time to High Level | t_{PZH} | | 17 | 24 | ns | $C_L = 15pF$ |
| Output Enable Time to Low Level | t_{PZL} | | 30 | 45 | ns | $C_L = 15pF$ |
| Output Disable Time from High Level | t_{PHZ} | | 30 | 45 | ns | $C_L = 15pF$ |
| Output Disable Time from Low Level | t_{PLZ} | | 18 | 27 | ns | $C_L = 15pF$ |

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