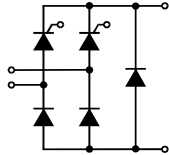
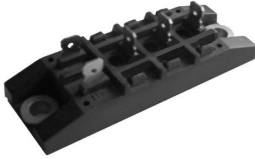


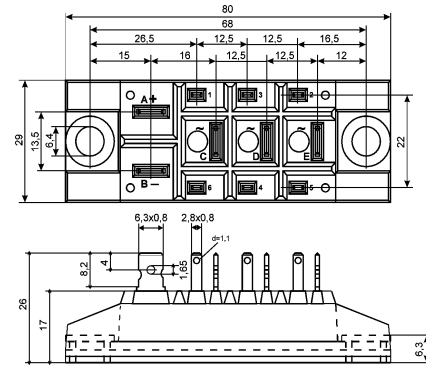
# S1PHB55

## Single Phase Half Controlled Bridge With Free Wheeling Diode



Type	$V_{RSM}$ $V_{DSM}$ V	$V_{RRM}$ $V_{DRM}$ V
S1PHB55-08	900	800
S1PHB55-12	1300	1200
S1PHB55-14	1500	1400
S1PHB55-16	1700	1600
S1PHB55-18	1900	1800

Dimensions in mm (1mm=0.0394")



Symbol	Test Conditions	Maximum Ratings	Unit	
$I_{dAV}$ $I_{dAVM}$ $I_{FRMS}, I_{TRMS}$	$T_K=85^{\circ}C$ , module module per leg	55 55 41	A	
$I_{TSM}, I_{FSM}$	$T_{VJ}=45^{\circ}C$ $V_R=0$ $t=10ms$ (50Hz), sine $t=8.3ms$ (60Hz), sine	550 600	A	
	$T_{VJ}=T_{VJM}$ $V_R=0$ $t=10ms$ (50Hz), sine $t=8.3ms$ (60Hz), sine	500 550		
$I^2t$	$T_{VJ}=45^{\circ}C$ $V_R=0$ $t=10ms$ (50Hz), sine $t=8.3ms$ (60Hz), sine	1520 1520	A <sup>2</sup> s	
	$T_{VJ}=T_{VJM}$ $V_R=0$ $t=10ms$ (50Hz), sine $t=8.3ms$ (60Hz), sine	1250 1250		
$(di/dt)_{cr}$	$T_{VJ}=125^{\circ}C$ $f=50Hz, t_p=200\mu s$ $V_D=2/3V_{DRM}$ $I_G=0.3A$ $di_G/dt=0.3A/\mu s$	repetitive, $I_T=50A$  non repetitive, $I_T=1/2I_{dAV}$	150  500	A/ $\mu s$
	$(dv/dt)_{cr}$	$T_{VJ}=T_{VJM};$ $R_{GK}=\infty$ ; method 1 (linear voltage rise)	$V_{DR}=2/3V_{DRM}$  1000	
$P_{GM}$	$T_{VJ}=T_{VJM}$ $I_T=I_{TAVM}$	$t_p=30\mu s$ $t_p=500\mu s$	10 5	W
$P_{GAVM}$			0.5	W
$V_{RGM}$			10	V
$T_{VJ}$ $T_{VJM}$ $T_{stg}$			-40...+125 125 -40...+125	$^{\circ}C$
$V_{ISOL}$	50/60Hz, RMS $I_{ISOL} \leq 1mA$	$t=1min$ $t=1s$	2500 3000	V~
$M_d$	Mounting torque (M5) (10-32 UNF)		5 $\pm$ 15% 44 $\pm$ 15%	Nm lb.in.
Weight			110	g

# S1PHB55

## Single Phase Half Controlled Bridge With Free Wheeling Diode

Symbol	Test Conditions	Characteristic Values	Unit
$I_R, I_D$	$T_{VJ}=T_{VJM}; V_R=V_{RRM}; V_D=V_{DRM}$	5	mA
$V_T$	$I_T=80A; T_{VJ}=25^{\circ}C$	1.64	V
$V_{To}$	For power-loss calculations only	0.85	V
$r_T$		11	$m\Omega$
$V_{GT}$	$V_D=6V;$ $T_{VJ}=25^{\circ}C$ $T_{VJ}=-40^{\circ}C$	1.5 1.6	V
$I_{GT}$	$V_D=6V;$ $T_{VJ}=25^{\circ}C$ $T_{VJ}=-40^{\circ}C$	100 200	mA
$V_{GD}$	$T_{VJ}=T_{VJM};$ $V_D=2/3V_{DRM}$	0.2	V
$I_{GD}$		5	mA
$I_L$	$t_p=10\mu s; I_G=0.45A; T_{VJ}=25^{\circ}C$ $di_G/dt=0.45A/\mu s$	450	mA
$I_H$	$T_{VJ}=25^{\circ}C; V_D=6V; R_{GK}=\infty$	200	mA
$t_{gd}$	$T_{VJ}=25^{\circ}C; V_D=1/2V_{DRM}$ $I_G=0.45A; di_G/dt=0.45A/\mu s$	2	$\mu s$
$t_q$	$T_{VJ}=T_{VJM}; I_T=20A; t_p=200\mu s; V_R=100V$ $V_D=2/3V_{DRM}; dv/dt=15V/\mu s; di/dt=-10A/\mu s$	typ. 250	$\mu s$
$R_{thJC}$	per thyristor/Diode; DC per module	0.9 0.18	K/W
$R_{thJK}$	per thyristor/Diode; DC per module	1.1 0.22	K/W
$d_s$	Creeping distance on surface	16.1	mm
$d_A$	Creepage distance in air	7.1	mm
$a$	Maximum allowable acceleration	50	$m/s^2$