

Preliminary Datasheet

Specifications in this document are tentative and subject to change.

R8C/32G Group, R8C/32H Group RENESAS MCU

R01DS0026EJ0010 Rev.0.10 Feb 08, 2011

1. Overview

1.1 Features

The R8C/32G Group, R8C/32H Group of single-chip MCUs incorporates the R8C CPU core, employing sophisticated instructions for a high level of efficiency. With 1 Mbyte of address space, and it is capable of executing instructions at high speed. In addition, the CPU core boasts a multiplier for high-speed operation processing.

Power consumption is low, and the supported operating modes allow additional power control. These MCUs are designed to maximize EMI/EMS performance.

Integration of many peripheral functions, including multifunction timer and serial interface, reduces the number of system components.

The R8C/32G Group has data flash (1 KB \times 4 blocks) with the background operation (BGO) function.

1.1.1 Applications

Automobiles and others



1.1.2 Specifications

Tables 1.1 and 1.2 outline the Specifications for R8C/32G Group. Tables 1.3 and 1.4 outline the Specifications for R8C/32H Group.

Item	Function	Specification
CPU	Central processing	R8C CPU core
	unit	Number of fundamental instructions: 89
		Minimum instruction execution time:
		50 ns (f(XIN) = 20 MHz, VCC = 2.7 to 5.5 V)
		• Multiplier: 16 bits \times 16 bits \rightarrow 32 bits
		• Multiply-accumulate instruction: 16 bits \times 16 bits $+$ 32 bits \rightarrow 32 bits
		Operation mode: Single-chip mode (address space: 1 Mbyte)
Memory	ROM, RAM, Data	Refer to Table 1.5 Product List for R8C/32G Group.
	flash	
Power Supply	Voltage detection	Power-on reset
Voltage Detection	circuit	Voltage detection 3 (detection level of voltage detection 1 selectable)
I/O Ports	Programmable I/O	Input-only: 1 pin
	ports	 CMOS I/O ports: 15, selectable pull-up resistor
Clock	Clock generation	3 circuits: XIN clock oscillation circuit,
	circuits	High-speed on-chip oscillator (with frequency adjustment function),
		Low-speed on-chip oscillator
		Oscillation stop detection: XIN clock oscillation stop detection function
		• Frequency divider circuit: Dividing selectable 1, 2, 4, 8, and 16
		Low power consumption modes:
		Standard operating mode (high-speed clock, high-speed on-chip oscillator,
		low-speed on-chip oscillator), wait mode, stop mode
Interrupts	ł	Number of interrupt vectors: 69
•		• External Interrupt: 7 (INT × 3, Key input × 4)
		Priority levels: 7 levels
Watchdog Time	er	• 14 bits × 1 (with prescaler)
0		Reset start selectable
		 Low-speed on-chip oscillator for watchdog timer selectable
DTC (Data Tra	nsfer Controller)	• 1 channel
,	,	Activation sources: 28
		Transfer modes: 2 (normal mode, repeat mode)
Timer	Timer RA	8 bits x 1 (with 8-bit prescaler)
		Timer mode (period timer), pulse output mode (output level inverted every
		period), event counter mode, pulse width measurement mode, pulse period
		measurement mode
	Timer RB	8 bits × 1 (with 8-bit prescaler)
		Timer mode (period timer), programmable waveform generation mode (PWM
		output), programmable one-shot generation mode, programmable wait one-
	Ŧ DO	shot generation mode
	Timer RC	16 bits x 1 (with 4 capture/compare registers)
		Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin)
	Timer RD ⁽¹⁾	16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode
		(output 6 pins), reset synchronous PWM mode (output three-phase
		waveforms (6 pins), sawtooth wave modulation), complementary PWM mode
		(output three-phase waveforms (6 pins), triangular wave modulation), PWM3
		mode (PWM output 2 pins with fixed period)
		inode (i www.output.z.pins.withinked.penod)

Table 1.1	Specifications for R8C/32G Group (1)

Note:

1. Timer RD in these products does not support full-spec emulators. Use the on-chip debugging emulator for debugging.

Item Function Specification UART0 Clock synchronous serial I/O/UART × 1 channel Serial Interface UART2 Clock synchronous serial I/O/UART, I²C mode (I²C-bus), IE mode (IEBus), multiprocessor communication function Synchronous Serial 1 Communication Unit (SSU) LIN Module Hardware LIN: 1 (timer RA, UART0) A/D Converter 10-bit resolution × 4 channels, includes sample and hold function, with sweep mode Comparator B 2 circuits Flash Memory Programming and erasure voltage: VCC = 2.7 to 5.5 V Programming and erasure endurance: 10,000 times (data flash) 1,000 times (program ROM) • Program security: ROM code protect, ID code check • Debug functions: On-chip debug, on-board flash rewrite function • Background operation (BGO) function f(XIN) = 20 MHz (VCC = 2.7 to 5.5 V) **Operating Frequency/Supply** Voltage Current consumption Typ. 7 mA (VCC = 5.0 V, f(XIN) = 20 MHz) -40 to 85°C (J version) -80 to 125°C (K version) ⁽¹⁾ **Operating Ambient Temperature** 20-pin SSOP Package Package code: PLSP0020JB-A (previous code: 20P2F-A)

Table 1.2 Specifications for R8C/32G Group (2)

Note:

1. Specify the K version if K version functions are to be used.



Item Function Specification R8C CPU core CPU Central processing Number of fundamental instructions: 89 unit • Minimum instruction execution time: 50 ns (f(XIN) = 20 MHz, VCC = 2.7 to 5.5 V) • Multiplier: 16 bits \times 16 bits \rightarrow 32 bits • Multiply-accumulate instruction: 16 bits \times 16 bits + 32 bits \rightarrow 32 bits • Operation mode: Single-chip mode (address space: 1 Mbyte) Memory ROM, RAM Refer to Table 1.6 Product List for R8C/32H Group. Power Supply Voltage detection Power-on reset Voltage circuit Voltage detection 3 (detection level of voltage detection 1 selectable) Detection I/O Ports Programmable I/O • Input-only: 1 pin CMOS I/O ports: 15, selectable pull-up resistor ports Clock Clock generation 3 circuits: XIN clock oscillation circuit, High-speed on-chip oscillator (with frequency adjustment function), circuits Low-speed on-chip oscillator · Oscillation stop detection: XIN clock oscillation stop detection function • Frequency divider circuit: Dividing selectable 1, 2, 4, 8, and 16 Low power consumption modes: Standard operating mode (high-speed clock, high-speed on-chip oscillator, low-speed on-chip oscillator), wait mode, stop mode Interrupts Number of interrupt vectors: 69 External Interrupt: 7 (INT × 3, Key input × 4) · Priority levels: 7 levels Watchdog Timer 14 bits × 1 (with prescaler) • Reset start selectable • Low-speed on-chip oscillator for watchdog timer selectable DTC (Data Transfer Controller) 1 channel Activation sources: 28 Transfer modes: 2 (normal mode, repeat mode) Timer Timer RA 8 bits x 1 (with 8-bit prescaler) Timer mode (period timer), pulse output mode (output level inverted every period), event counter mode, pulse width measurement mode, pulse period measurement mode Timer RB 8 bits x 1 (with 8-bit prescaler) Timer mode (period timer), programmable waveform generation mode (PWM output), programmable one-shot generation mode, programmable wait oneshot generation mode 16 bits x 1 (with 4 capture/compare registers) Timer RC Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits x 2 (with 4 capture/compare registers) Timer RD⁽¹⁾ Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode (output three-phase waveforms (6 pins), triangular wave modulation), PWM3 mode (PWM output 2 pins with fixed period)

Table 1.3 Specifications for R8C/32H Group (1)

Note:

1. Timer RD in these products does not support full-spec emulators. Use the on-chip debugging emulator for debugging.



	opeemeatiene	1 ()	
Item	Function	Specification	
Serial	UART0	Clock synchronous serial I/O/UART × 1 channel	
Interface	UART2	Clock synchronous serial I/O/UART, I ² C mode (I ² C-bus), IE mode (IEBus), multiprocessor communication function	
Synchronous	Serial	1	
Communicatio	on Unit (SSU)		
LIN Module		Hardware LIN: 1 (timer RA, UART0)	
A/D Converte	r	10-bit resolution × 4 channels, includes sample and hold function, with sweep mode	
Comparator E	3	2 circuits	
Flash Memory		 Programming and erasure voltage: VCC = 2.7 to 5.5 V 	
		 Programming and erasure endurance: 100 times (program ROM) 	
		 Program security: ROM code protect, ID code check 	
		Debug functions: On-chip debug, on-board flash rewrite function	
Operating Fre Voltage	equency/Supply	f(XIN) = 20 MHz (VCC = 2.7 to 5.5 V)	
Current consu	umption	Typ. 7 mA (VCC = 5.0 V, f(XIN) = 20 MHz)	
Operating Ambient Temperature		-40 to 85°C (J version) -80 to 125°C (K version) ⁽¹⁾	
Package		20-pin SSOP	
-		Package code: PLSP0020JB-A (previous code: 20P2F-A)	

Table 1.4 Specifications for R8C/32H Group (2)

Note:

1. Specify the K version if K version functions are to be used.



1.2 Product List

Table 1.5 lists Product List for R8C/32G Group and Figure 1.1 shows a Part Number, Memory Size, and Package of R8C/32G Group. Table 1.6 lists Product List for R8C/32H Group and Figure 1.2 shows a Part Number, Memory Size, and Package of R8C/32H Group.

Table 1.5	Product List for R8C/32G Group
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Current of Feb 2011

Part No.	ROM C	Capacity	RAM	Package Type	Remarks	
Fait NO.	Program ROM	Data flash	Capacity	Fackage Type		
R5F21324GJSP (D)	16 Kbytes	1 Kbyte × 4	1.5 Kbytes	PLSP0020JB-A	J version	
R5F21326GJSP (D)	32 Kbytes	1 Kbyte × 4	2.5 Kbytes	PLSP0020JB-A		
R5F21324GKSP (D)	16 Kbytes	1 Kbyte × 4	1.5 Kbytes	PLSP0020JB-A	K version	
R5F21332GKSP (D)	32 Kbytes	1 Kbyte × 4	2.5 Kbytes	PLSP0020JB-A		

(D): Under development

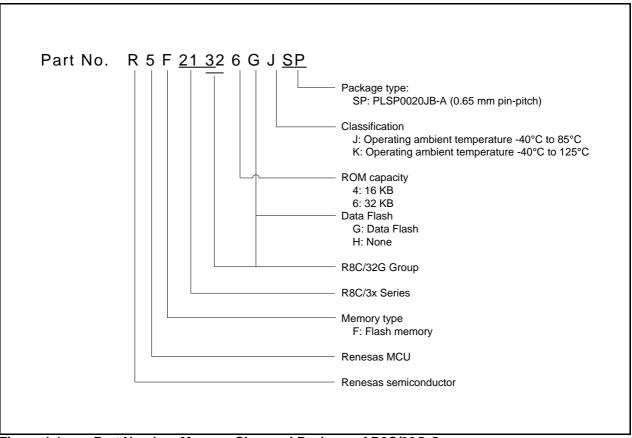


Figure 1.1 Part Number, Memory Size, and Package of R8C/32G Group



Part No.	ROM C	apacity	RAM	Package Type	Remarks	
Fait NO.	Program ROM	Data flash	Capacity	Fackage Type		
R5F21324HJSP (D)	16 Kbytes	1 Kbyte × 4	1.5 Kbytes	PLSP0020JB-A	J version	
R5F21326HJSP (D)	32 Kbytes	1 Kbyte × 4	2.5 Kbytes	PLSP0020JB-A		
R5F21324HKSP (D)	16 Kbytes	1 Kbyte × 4	1.5 Kbytes	PLSP0020JB-A	K version	
R5F21326HKSP (D)	32 Kbytes	1 Kbyte × 4	2.5 Kbytes	PLSP0020JB-A		

Table 1.6 Product List for R8C/32H Group

(D): Under development

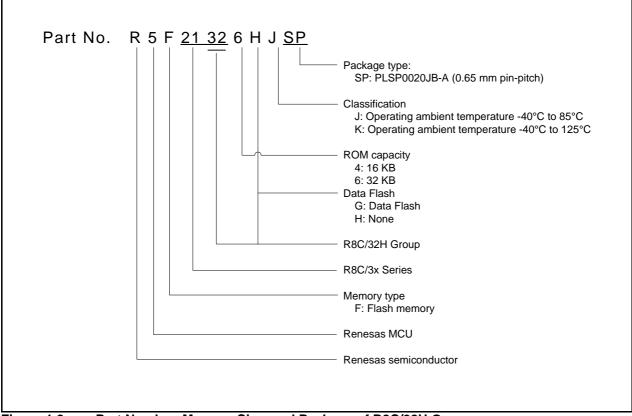


Figure 1.2 Part Number, Memory Size, and Package of R8C/32H Group



Current of Feb 2011

Under development Preliminary document Specifications in this document are tentative and subject to change.

R8C/32G Group, R8C/32H Group

1.3 Block Diagram

Figure 1.2 shows a Block Diagram.

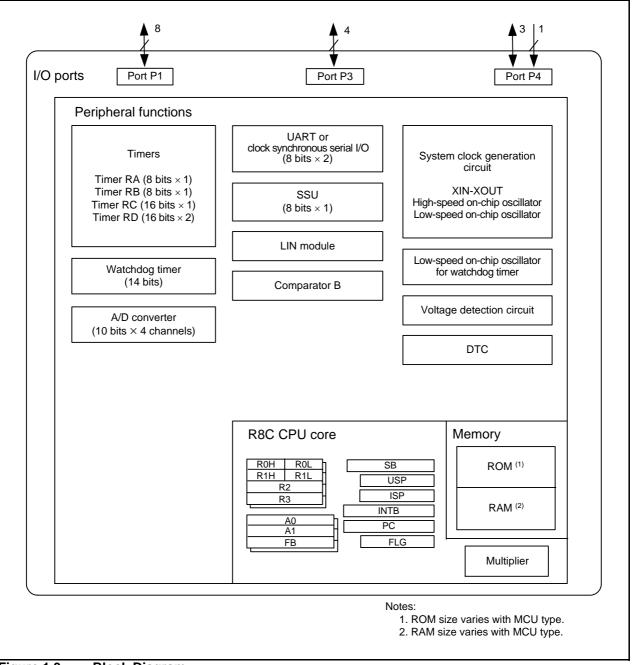
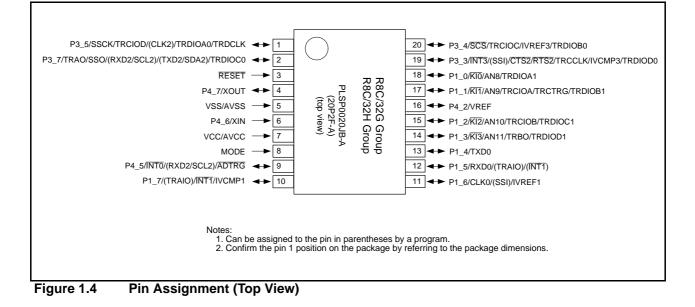


Figure 1.3 Block Diagram



1.4 Pin Assignment

Figure 1.4 shows the Pin Assignment (Top View). Table 1.7 outline the Pin Name Information by Pin Number.





Pin			I/O Pin Functions for Peripheral Modules				
Number	Control Pin	Port	Interrupt	Timer	Serial Interface	SSU	A/D Converter, Comparator B
1		P3_5		TRCIOD/TRDIOA0/ TRDCLK	(CLK2)	SSCK	
2		P3_7		TRAO/TRDIOC0	(RXD2/SCL2/ TXD2/SDA2)	SSO	
3	RESET						
4	XOUT	P4_7					
5	VSS/AVSS						
6	XIN	P4_6					
7	VCC/AVCC						
8	MODE						
9		P4_5	INT0		(RXD2/SCL2)		ADTRG
10		P1_7	INT1	(TRAIO)			IVCMP1
11		P1_6			CLK0	(SSI)	IVREF1
12		P1_5	(INT1)	(TRAIO)	RXD0		
13		P1_4			TXD0		
14		P1_3	KI3	TRBO(/TRDIOD1)			AN11
15		P1_2	KI2	(TRCIOB/ TRDIOC1)			AN10
16		P4_2					VREF
17		P1_1	KI1	TRCIOA/TRCTRG/ TRDIOB1			AN9
18		P1_0	KI0	TRDIOA1			AN8
19		P3_3	INT3	TRCCLK/TRDIOD0	CTS2/RTS2	(SSI)	IVCMP3
20		P3_4		TRCIOC/TRDIOB0		SCS	IVREF3

Table 1.7 Pin Name Information by Pin Number

Note:

1. Can be assigned to the pin in parentheses by a program.



1.5 Pin Functions

Tables 1.8 and 1.9 list Pin Functions.

Table 1.8Pin Functions (1)

Item	Pin Name	I/O Type	Description
Power supply input	VCC, VSS	-	Apply 2.7 V to 5.5 V to the VCC pin. Apply 0 V to the VSS pin.
Analog power supply input	AVCC, AVSS	-	Power supply for the A/D converter. Connect a capacitor between AVCC and AVSS.
Reset input	RESET	I	Input "L" on this pin resets the MCU.
MODE	MODE	I	Connect this pin to VCC via a resistor.
XIN clock input	XIN	I	These pins are provided for XIN clock generation circuit I/O. Connect a ceramic resonator or a crystal oscillator between
XIN clock output	XOUT	I/O	the XIN and XOUT pins ⁽¹⁾ . To use an external clock, input it to the XOUT pin and leave the XIN pin open.
INT interrupt input	INT0 to INT1, INT3	I	INT interrupt input pins. INT0 is timer RB, RC and RD input pin.
Key input interrupt	KI0 to KI3	I	Key input interrupt input pins
Timer RA	TRAIO	I/O	Timer RA I/O pin
	TRAO	0	Timer RA output pin
Timer RB	TRBO	0	Timer RB output pin
Timer RC	TRCCLK	I	External clock input pin
	TRCTRG	I	External trigger input pin
	TRCIOA, TRCIOB, TRCIOC, TRCIOD	I/O	Timer RC I/O pins
Timer RD	TRDIOA0, TRDIOA1, TRDIOB0, TRDIOB1, TRDIOC0, TRDIOC1, TRDIOD0, TRDIOD1	I/O	Timer RD I/O pins
	TRDCLK	I	External clock input pin
Serial interface	CLK0, CLK2	I/O	Transfer clock I/O pins
	RXD0, RXD2	I	Serial data input pins
	TXD0, TXD2	0	Serial data output pins
	CTS2	I	Transmission control input pin
	RTS2	0	Reception control output pin
	SCL2	I/O	I ² C mode clock I/O pin
	SDA2	I/O	I ² C mode data I/O pin
SSU	SSI	I/O	Data I/O pin
	SCS	I/O	Chip-select signal I/O pin
	SSCK	I/O	Clock I/O pin
	SSO	I/O	Data I/O pin

I: Input O: Output I/O: Input and output Note:

1. Refer to the oscillator manufacturer for oscillation characteristics.



Table 1.9Pin Functions (2)

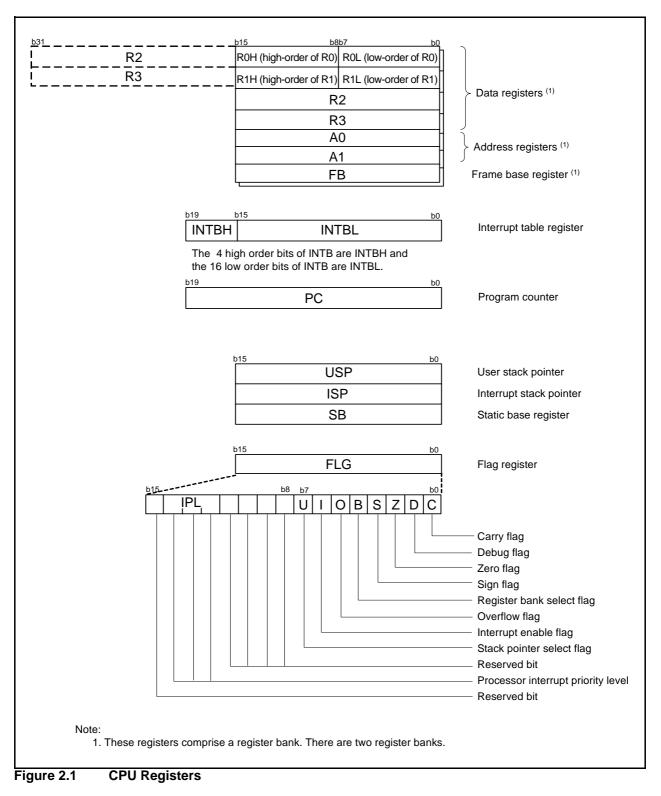
Item	Pin Name	I/O Type	Description
Reference voltage input	VREF	I	Reference voltage input pin to A/D converter
A/D converter	AN8 to AN11	I	Analog input pins to A/D converter
	ADTRG	I	A/D external trigger input pin
Comparator B	IVCMP1, IVCMP3	I	Comparator B analog voltage input pins
	IVREF1, IVREF3	I	Comparator B reference voltage input pins
I/O port	P1_0 to P1_7, P3_3 to P3_5, P3_7, P4_5 to P4_7	I/O	CMOS I/O ports. Each port has an I/O select direction register, allowing each pin in the port to be directed for input or output individually. Any port set to input can be set to use a pull-up resistor or not by a program.
Input port	P4_2	I	Input-only port

I: Input O: Output I/O: Input and output



2. Central Processing Unit (CPU)

Figure 2.1 shows the CPU Registers. The CPU contains 13 registers. R0, R1, R2, R3, A0, A1, and FB configure a register bank. There are two sets of register bank.





2.1 Data Registers (R0, R1, R2, and R3)

R0 is a 16-bit register for transfer, arithmetic, and logic operations. The same applies to R1 to R3. R0 can be split into high-order bits (R0H) and low-order bits (R0L) to be used separately as 8-bit data registers. R1H and R1L are analogous to R0H and R0L. R2 can be combined with R0 and used as a 32-bit data register (R2R0). R3R1 is analogous to R2R0.

2.2 Address Registers (A0 and A1)

A0 is a 16-bit register for address register indirect addressing and address register relative addressing. It is also used for transfer, arithmetic, and logic operations. A1 is analogous to A0. A1 can be combined with A0 and as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is a 16-bit register for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is a 20-bit register that indicates the starting address of an interrupt vector table.

2.5 Program Counter (PC)

PC is 20 bits wide and indicates the address of the next instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

The stack pointers (SP), USP and ISP, are each 16 bits wide. The U flag of FLG is used to switch between USP and ISP.

2.7 Static Base Register (SB)

SB is a 16-bit register for SB relative addressing.

2.8 Flag Register (FLG)

FLG is an 11-bit register indicating the CPU state.

2.8.1 Carry Flag (C)

The C flag retains carry, borrow, or shift-out bits that have been generated by the arithmetic and logic unit.

2.8.2 Debug Flag (D)

The D flag is for debugging only. Set it to 0.

2.8.3 Zero Flag (Z)

The Z flag is set to 1 when an arithmetic operation results in 0; otherwise to 0.

2.8.4 Sign Flag (S)

The S flag is set to 1 when an arithmetic operation results in a negative value; otherwise to 0.

2.8.5 Register Bank Select Flag (B)

Register bank 0 is selected when the B flag is 0. Register bank 1 is selected when this flag is set to 1.

2.8.6 Overflow Flag (O)

The O flag is set to 1 when an operation results in an overflow; otherwise to 0.



2.8.7 Interrupt Enable Flag (I)

The I flag enables maskable interrupts.

Interrupts are disabled when the I flag is set to 0, and are enabled when the I flag is set to 1. The I flag is set to 0 when an interrupt request is acknowledged.

2.8.8 Stack Pointer Select Flag (U)

ISP is selected when the U flag is set to 0; USP is selected when the U flag is set to 1. The U flag is set to 0 when a hardware interrupt request is acknowledged or the INT instruction of software interrupt numbers 0 to 31 is executed.

2.8.9 Processor Interrupt Priority Level (IPL)

IPL is 3 bits wide and assigns processor interrupt priority levels from level 0 to level 7. If a requested interrupt has higher priority than IPL, the interrupt is enabled.

2.8.10 Reserved Bit

If necessary, set to 0. When read, the content is undefined.



3. Memory

3.1 R8C/32G Group

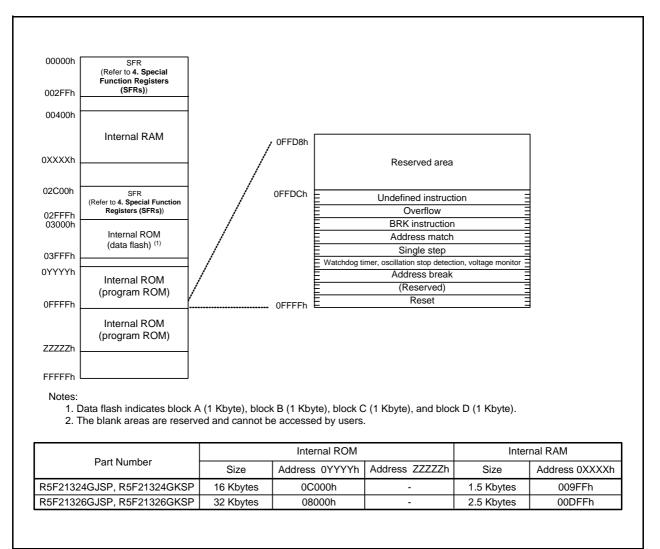
Figure 3.1 is a Memory Map of R8C/32G Group. The R8C/32G Group has a 1-Mbyte address space from addresses 00000h to FFFFFh. For example, a 32-Kbyte internal ROM area is allocated addresses 08000h to 0FFFFh.

The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. The starting address of each interrupt routine is stored here.

The internal ROM (data flash) is allocated addresses 03000h to 03FFFh.

The internal RAM is allocated higher addresses, beginning with address 00400h. For example, a 2.5-Kbyte internal RAM area is allocated addresses 00400h to 00DFFh. The internal RAM is used not only for data storage but also as a stack area when a subroutine is called or when an interrupt request is acknowledged.

Special function registers (SFRs) are allocated addresses 00000h to 002FFh and 02C00h to 02FFFh. Peripheral function control registers are allocated here. All unallocated spaces within the SFRs are reserved and cannot be accessed by users.







3.2 R8C/32H Group

Figure 3.2 is a Memory Map of R8C/32H Group. The R8C/32H Group has a 1-Mbyte address space from addresses 00000h to FFFFh. The internal ROM (program ROM) is allocated lower addresses, beginning with address 0FFFFh. For example, a 32-Kbyte internal ROM area is allocated addresses 08000h to 0FFFFh.

The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. The starting address of each interrupt routine is stored here.

The internal RAM is allocated higher addresses, beginning with address 00400h. For example, a 2.5-Kbyte internal RAM area is allocated addresses 00400h to 00DFFh. The internal RAM is used not only for data storage but also as a stack area when a subroutine is called or when an interrupt request is acknowledged.

Special function registers (SFRs) are allocated addresses 00000h to 002FFh and 02C00h to 02FFFh. Peripheral function control registers are allocated here. All unallocated spaces within the SFRs are reserved and cannot be accessed by users.

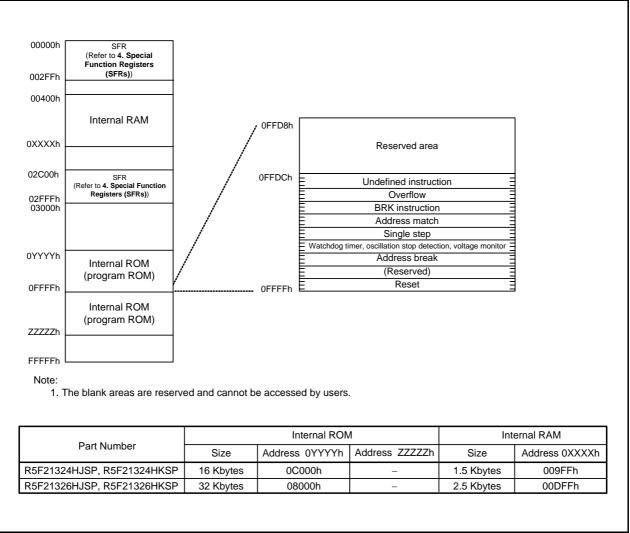


Figure 3.2

Memory Map of R8C/32H Group



Special Function Registers (SFRs) 4.

An SFR (special function register) is a control register for a peripheral function. Tables 4.1 to 4.12 list the special function registers and Table 4.13 lists the ID Code Areas and Option Function Select Area.

Table 4.1	SFR Information	(1)) (1)
		<u>۱</u>	, ` '

Address	Register	Symbol	After Reset
0000h			
0001h			
0002h			
0003h			
0004h	Processor Mode Register 0	PM0	00h
0005h	Processor Mode Register 1	PM1	00h
0006h	System Clock Control Register 0	CM0	00101000b
0007h	System Clock Control Register 1	CM1	0010000b
0008h	Module Standby Control Register	MSTCR	00h
0009h	System Clock Control Register 3	CM3	00h
000Ah	Protect Register	PRCR	00h
000Bh	Reset Source Determination Register	RSTFR	0XXXXXXXb ⁽²⁾
000Ch	Oscillation Stop Detection Register	OCD	00000100b
000Dh	Watchdog Timer Reset Register	WDTR	XXh
000Eh	Watchdog Timer Start Register	WDTS	XXh
000Fh	Watchdog Timer Control Register	WDTC	00111111b
0010h			
0011h			
0012h			
0013h			
0014h			
0015h	High-Speed On-Chip Oscillator Control Register 7	FRA7	When shipping
0016h			
0017h			
0018h			
0019h			
001Ah			
001Bh			
001Ch	Count Source Protection Mode Register	CSPR	00h
			1000000b ⁽³⁾
001Dh			
001Eh			
001Fh			
0020h			
0021h			
0022h			
0023h	High-Speed On-Chip Oscillator Control Register 0	FRA0	00h
0024h	High-Speed On-Chip Oscillator Control Register 1	FRA1	When shipping
0025h	High-Speed On-Chip Oscillator Control Register 2	FRA2	00h
0026h	On-Chip Reference Voltage Control Register	OCVREFCR	00h
0027h			
0028h			
0029h	High-Speed On-Chip Oscillator Control Register 4	FRA4	When Shipping
002Ah	High-Speed On-Chip Oscillator Control Register 5	FRA5	When Shipping
002Bh	High-Speed On-Chip Oscillator Control Register 6	FRA6	When Shipping
002Ch			
002Dh			
002Eh			
	High-Speed On-Chip Oscillator Control Register 3	FRA3	When shipping
002Fh	Voltage Monitor Circuit Control Register	CMPA	00h
0030h			00h
0030h 0031h	Voltage Monitor Circuit Edge Select Register	VCAC	
0030h 0031h 0032h	Voltage Monitor Circuit Edge Select Register		
0030h 0031h 0032h 0033h	Voltage Monitor Circuit Edge Select Register Voltage Detect Register 1	VCA1	00001000b
0030h 0031h 0032h	Voltage Monitor Circuit Edge Select Register		00001000b 00h ⁽⁴⁾
0030h 0031h 0032h 0033h 0034h	Voltage Monitor Circuit Edge Select Register Voltage Detect Register 1	VCA1	00001000b
0030h 0031h 0032h 0033h	Voltage Monitor Circuit Edge Select Register Voltage Detect Register 1	VCA1	00001000b 00h ⁽⁴⁾
0030h 0031h 0032h 0033h 0034h 0035h 0036h	Voltage Monitor Circuit Edge Select Register Voltage Detect Register 1	VCA1	00001000b 00h ⁽⁴⁾
0030h 0031h 0032h 0033h 0034h 0035h	Voltage Monitor Circuit Edge Select Register Voltage Detect Register 1 Voltage Detect Register 2	VCA1 VCA2	00001000b 00h (4) 00100000b (5)
0030h 0031h 0032h 0033h 0034h 0035h 0036h	Voltage Monitor Circuit Edge Select Register Voltage Detect Register 1 Voltage Detect Register 2	VCA1 VCA2	00001000b 00h (4) 00100000b (5)
0030h 0031h 0032h 0033h 0034h 0035h 0035h 0036h	Voltage Monitor Circuit Edge Select Register Voltage Detect Register 1 Voltage Detect Register 2 Voltage Detection 1 Level Select Register	VCA1 VCA2 VD1LS	00001000b 00h (4) 00100000b (5) 00000111b

X: Undefined Notes: 1. The

The blank areas are reserved and cannot be accessed by users. The CWR bit in the RSTFR register is set to 0 after power-on and voltage monitor 0 reset. Hardware reset, software reset, or watchdog timer 2. reset does not affect this bit.

The CSPROINI bit in the OFS register is set to 0. 3.

The LVDAS bit in the OFS register is set to 1. 4.

5. The LVDAS bit in the OFS register is set to 0.



SFR Information (2)⁽¹⁾ Table 4.2

Address	Register	Symbol	After Reset
003Ah	Voltage Monitor 2 Circuit Control Register	VW2C	10000010b
003Bh			
003Ch			
003Dh			
003Eh			
003Fh			
0040h			
0041h	Flash Memory Ready Interrupt Control Register	FMRDYIC	XXXXX000b
0042h			
0043h			
0044h			
0044h			
0046h			
0047h	Timer RC Interrupt Control Register	TRCIC	XXXXX000b
0048h	Timer RD0 Interrupt Control Register	TRD0IC	XXXXX000b
0049h	Timer RD1 Interrupt Control Register	TRD1IC	XXXXX000b
004Ah			
004Bh	UART2 Transmit Interrupt Control Register	S2TIC	XXXXX000b
004Ch	UART2 Receive Interrupt Control Register	S2RIC	XXXXX000b
	Key Input Interrupt Control Register		
004Dh		KUPIC	XXXXX000b
004Eh	A/D Conversion Interrupt Control Register	ADIC	XXXXX000b
004Fh	SSU Interrupt Control Register	SSUIC	XXXXX000b
0050h			
0051h	UART0 Transmit Interrupt Control Register	SOTIC	XXXXX000b
0052h	UART0 Receive Interrupt Control Register	SORIC	XXXXX000b
0053h	,		
0054h			
0055h			
0056h	Timer RA Interrupt Control Register	TRAIC	XXXXX000b
0057h			
0058h	Timer RB Interrupt Control Register	TRBIC	XXXXX000b
0059h	INT1 Interrupt Control Register	INT1IC	XX00X000b
005Ah	INT3 Interrupt Control Register	INT3IC	XX00X000b
005Bh			
005Ch			
005Dh	INTO Interrupt Control Degister		XX00X000h
	INTO Interrupt Control Register	INTOIC	XX00X000b
005Eh	UART2 Bus Collision Detection Interrupt Control Register	U2BCNIC	XXXXX000b
005Fh			
0060h			
0061h			
0062h			
0063h			
0064h			
0065h			
0066h			
0067h			
0068h			
0069h			
006Ah			
006Bh			
006Ch			
006Dh			
006Eh			
006Fh			
0070h			Ì
0071h			
0072h	Voltage Monitor 1 Interrupt Control Register	VCMP1IC	XXXXX000b
0072h	Voltage Monitor 2 Interrupt Control Register	VCMP2IC	XXXXX000b
	volage wonitor 2 mierrupi Control Register	VCIVIFZIC	~~~~~
0074h			
0075h			
0076h			
0077h			
0078h			
0079h			
007Ah			
007Bh			
007Ch			
007Dh			



SFR Information (3)⁽¹⁾ Table 4.3

Address	Register	Symbol	After Reset
0080h	DTC Activation Control Register	DTCTL	00h
0081h			
0082h			
0083h			
0084h			
0085h			
0086h			
0080h			
	DTO Astivation Enable Desister 0	DTOENO	0.01
0088h	DTC Activation Enable Register 0	DTCEN0	00h
0089h	DTC Activation Enable Register 1	DTCEN1	00h
008Ah	DTC Activation Enable Register 2	DTCEN2	00h
008Bh	DTC Activation Enable Register 3	DTCEN3	00h
008Ch	DTC Activation Enable Register 4	DTCEN4	00h
008Dh			
008Eh	DTC Activation Enable Register 6	DTCEN6	00h
008Fh	, , , , , , , , , , , , , , , , , , ,		
0090h			
0091h			
0092h			
0093h			
0094h			
0095h			
0096h			
0097h			
0098h			
0099h			
009Ah			
009Bh			
009Ch			
009Dh			
009Dh			
009Fh			
00A0h	UART0 Transmit/Receive Mode Register	UOMR	00h
00A1h	UART0 Bit Rate Register	U0BRG	XXh
00A2h	UART0 Transmit Buffer Register	U0TB	XXh
00A3h			XXh
00A4h	UART0 Transmit/Receive Control Register 0	U0C0	00001000b
00A5h	UART0 Transmit/Receive Control Register 1	U0C1	00000010b
00A6h	UARTO Receive Buffer Register	UORB	XXh
00A7h		00112	XXh
	LUADTO Transmit/Density Made Denister	LIONE	00h
00A8h	UART2 Transmit/Receive Mode Register	U2MR	
00A9h	UART2 Bit Rate Register	U2BRG	XXh
00AAh	UART2 Transmit Buffer Register	U2TB	XXh
00ABh			XXh
00ACh	UART2 Transmit/Receive Control Register 0	U2C0	00001000b
00ADh	UART2 Transmit/Receive Control Register 1	U2C1	00000010b
00AEh	UART2 Receive Buffer Register	U2RB	XXh
00AFh	1 [~]		XXh
00B0h	UART2 Digital Filter Function Select Register	URXDF	00h
00B0h		610XB1	0011
00B1h			
00B3h			
00B4h			
00B5h			
00B6h			
00B7h			
00B8h		1	
00B9h			
00BAh			
00BAh	UART2 Special Mode Register 5	U2SMR5	00h
00BCh	UART2 Special Mode Register 4	U2SMR4	00h
00BDh	UART2 Special Mode Register 3	U2SMR3	000X0X0Xb
	UART2 Special Mode Register 2	U2SMR2	X000000b
00BEh 00BFh	UART2 Special Mode Register	U2SMR	X000000b



Table 4.4SFR Information (4) (1)

Address	Register	Symbol	After Reset
00C0h /	VD Register 0	AD0	XXh
00C1h			000000XXb
00C2h /	VD Register 1	AD1	XXh
00C3h	-		000000XXb
00C4h /	VD Register 2	AD2	XXh
00C5h			000000XXb
00C6h A	VD Register 3	AD3	XXh
00C7h		-	000000XXb
00C8h /	VD Register 4	AD4	XXh
00C9h			000000XXb
00CAh A	VD Register 5	AD5	XXh
00CBh	g		000000XXb
	VD Register 6	AD6	XXh
00CDh	g		000000XXb
	VD Register 7	AD7	XXh
00CFh	g		000000XXb
00D0h			
00D1h			
00D2h			
00D2h			
	A/D Mode Register	ADMOD	00h
00D4n /	VD Input Select Register	ADINSEL	1100000b
	A/D Control Register 0	ADINGEL	00h
00D6n /	VD Control Register 0	ADCON0 ADCON1	
00D7h /	VD Control Register 1	ADCON1	00h
00D8h			
00D9h			
00DAh			
00DBh			
00DCh			
00DDh			
00DEh			
00DFh			
00E0h			
00E1h F	Port P1 Register	P1	XXh
00E2h			
	Port P1 Direction Register	PD1	00h
00E4h			
00E5h F	Port P3 Register	P3	XXh
00E6h			
00E7h F	Port P3 Direction Register	PD3	00h
00E8h F	Port P4 Register	P4	XXh
00E9h			
	Port P4 Direction Register	PD4	00h
00EBh			
00ECh			
00EDh			
00EEh			
00EFh			
00F0h			
00F1h			
00F2h			
00F3h			
00F4h			
00F5h			
00F6h			
00F7h			
00F8h			
00F9h			
00FAh			
00FBh			
00FBh			
00FCh 00FDh			
00FEh			
00FFh			

X: Undefined



SFR Information (5)⁽¹⁾ Table 4.5

Address	Register	Symbol	After Reset
0100h	Timer RA Control Register	TRACR	00h
0101h	Timer RA I/O Control Register	TRAIOC	00h
0102h	Timer RA Mode Register	TRAMR	00h
0103h	Timer RA Prescaler Register	TRAPRE	FFh
0104h	Timer RA Register	TRA	FFh
0105h	LIN Control Register 2	LINCR2	00h
0106h	LIN Control Register	LINCR	00h
0107h	LIN Status Register	LINST	00h
0108h	Timer RB Control Register	TRBCR	00h
0109h	Timer RB One-Shot Control Register	TRBOCR	00h
010Ah	Timer RB I/O Control Register	TRBIOC	00h
010Bh	Timer RB Mode Register	TRBMR	00h
010Ch	Timer RB Prescaler Register	TRBPRE	FFh
010Dh	Timer RB Secondary Register	TRBSC	FFh
010Eh	Timer RB Primary Register	TRBPR	FFh
010Eh		THE THE	
0100 h			
0111h			
0112h			
0113h			
0114h			
0115h			
0116h			
0117h			
0118h			
0119h			
0119h			
-			
011Bh			
011Ch			
011Dh			
011Eh			
011Fh			
0120h	Timer RC Mode Register	TRCMR	01001000b
0121h	Timer RC Control Register 1	TRCCR1	00h
0122h	Timer RC Interrupt Enable Register	TRCIER	01110000b
0123h	Timer RC Status Register	TRCSR	01110000b
		TRCIOR0	
0124h	Timer RC I/O Control Register 0		10001000b
0125h	Timer RC I/O Control Register 1	TRCIOR1	10001000b
0126h	Timer RC Counter	TRC	00h
0127h			00h
0128h	Timer RC General Register A	TRCGRA	FFh
0129h			FFh
012Ah	Timer RC General Register B	TRCGRB	FFh
012Bh			FFh
012Dh	Timer RC General Register C	TRCGRC	FFh
012Ch		INCONC	FFh
	Timer DC Canaral Degister D	TROOPR	
012Eh	Timer RC General Register D	TRCGRD	FFh
012Fh			FFh
0130h	Timer RC Control Register 2	TRCCR2	00011000b
0131h	Timer RC Digital Filter Function Select Register	TRCDF	00h
0132h	Timer RC Output Master Enable Register	TRCOER	0111111b
0133h	Timer RC Trigger Control Register	TRCADCR	00h
0134h			
0135h	Timer RD Trigger Control Register	TRUVUCB	00h
0135h 0136h	Timer RD Trigger Control Register	TRDADCR	00h
0135h 0136h 0137h	Timer RD Start Register	TRDSTR	11111100b
0135h 0136h 0137h 0138h	Timer RD Start Register Timer RD Mode Register	TRDSTR TRDMR	11111100b 00001110b
0135h 0136h 0137h 0138h 0139h	Timer RD Start Register Timer RD Mode Register Timer RD PWM Mode Register	TRDSTR TRDMR TRDPMR	11111100b 00001110b 10001000b
0135h 0136h 0137h 0138h 0139h 0139h 013Ah	Timer RD Start Register Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register	TRDSTR TRDMR TRDPMR TRDFCR	11111100b 00001110b 10001000b 10000000b
0135h 0136h 0137h 0138h 0139h	Timer RD Start Register Timer RD Mode Register Timer RD PWM Mode Register	TRDSTR TRDMR TRDPMR	11111100b 00001110b 10001000b
0135h 0136h 0137h 0138h 0139h 0139h 013Ah	Timer RD Start Register Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register	TRDSTR TRDMR TRDPMR TRDFCR	11111100b 00001110b 10001000b 10000000b
0135h 0136h 0137h 0138h 0139h 013Ah 013Bh 013Ch	Timer RD Start Register Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register Timer RD Output Master Enable Register 1 Timer RD Output Master Enable Register 2	TRDSTR TRDMR TRDPMR TRDFCR TRDOER1 TRDOER2	11111100b 00001110b 10001000b 10000000b FFh
0135h 0136h 0137h 0138h 0139h 013Ah 013Bh 013Ch 013Dh	Timer RD Start Register Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register Timer RD Output Master Enable Register 1 Timer RD Output Master Enable Register 2 Timer RD Output Control Register	TRDSTR TRDMR TRDPMR TRDFCR TRDOER1 TRDOER2 TRDOCR	11111100b 00001110b 10001000b 10000000b FFh 01111111b 00h
0135h 0136h 0137h 0138h 0139h 013Ah 013Bh 013Ch	Timer RD Start Register Timer RD Mode Register Timer RD PWM Mode Register Timer RD Function Control Register Timer RD Output Master Enable Register 1 Timer RD Output Master Enable Register 2	TRDSTR TRDMR TRDPMR TRDFCR TRDOER1 TRDOER2	11111100b 00001110b 10001000b 10000000b FFh 01111111b

Table 4.6SFR Information (6) (1)

Address	Register	Symbol	After Reset
0140h	Timer RD Control Register 0	TRDCR0	00h
0141h	Timer RD I/O Control Register A0	TRDIORA0	10001000b
0142h	Timer RD I/O Control Register C0	TRDIORC0	10001000b
0143h	Timer RD Status Register 0	TRDSR0	11100000b
0144h	Timer RD Interrupt Enable Register 0	TRDIER0	11100000b
0145h	Timer RD PWM Mode Output Level Control Register 0	TRDPOCR0	11111000b
0146h	Timer RD Counter 0	TRD0	00h
0147h			00h
0148h	Timer RD General Register A0	TRDGRA0	FFh
0149h			FFh
014Ah	Timer RD General Register B0	TRDGRB0	FFh
014Bh			FFh
014Ch	Timer RD General Register C0	TRDGRC0	FFh
014Dh			FFh
014Eh	Timer RD General Register D0	TRDGRD0	FFh
014Fh			FFh
0150h	Timer RD Control Register 1	TRDCR1	00h
0151h	Timer RD I/O Control Register A1	TRDIORA1	10001000b
0152h	Timer RD I/O Control Register C1	TRDIORC1	10001000b
0153h	Timer RD Status Register 1	TRDSR1	1100000b
0154h	Timer RD Interrupt Enable Register 1	TRDIER1	11100000b
0155h	Timer RD PWM Mode Output Level Control Register 1	TRDPOCR1	11111000b
0156h	Timer RD Counter 1	TRD1	00h
0157h			00h
0158h	Timer RD General Register A1	TRDGRA1	FFh
0159h			FFh
015Ah	Timer RD General Register B1	TRDGRB1	FFh
015Bh			FFh
015Ch	Timer RD General Register C1	TRDGRC1	FFh
015Dh			FFh
015Eh	Timer RD General Register D1	TRDGRD1	FFh
015Fh		IT BOILD I	FFh
0160h			
0161h			
0162h			
0163h			
0164h			
0165h			
0166h			
0167h			
0168h			
0169h			
016Ah			
016Bh			
016Ch			
016Dh			
016Eh			
016Fh			
0170h			-
0171h			
0172h			
0173h			
0174h			
0175h			
0176h			
0177h			
0178h			
0179h			
017Ah			
017Bh			
017Ch			
017Dh			
017Eh			
017Fh			
X. I Indefined		•	

X: Undefined



SFR Information (7)⁽¹⁾ Table 4.7

Address	Register	Symbol	After Reset
0180h	Timer RA Pin Select Register	TRASR	00h
0181h	Timer RB/RC Pin Select Register	TRBRCSR	00h
0182h	Timer RC Pin Select Register 0	TRCPSR0	00h
0183h	Timer RC Pin Select Register 1	TRCPSR1	00h
0184h	Timer RD Pin Select Register 0	TRDPSR0	00h
0185h	Timer RD Pin Select Register 1	TRDPSR1	00h
0186h			
0187h			
0188h	UART0 Pin Select Register	U0SR	00h
0189h	6		
018Ah	UART2 Pin Select Register 0	U2SR0	00h
018Bh	UART2 Pin Select Register 1	U2SR1	00h
018Ch	SSU Pin Select Register	SSUIICSR	00h
018Dh			
018Eh	INT Interrupt Input Pin Select Register	INTSR	00h
018Fh	I/O Function Pin Select Register	PINSR	00h
0190h			0011
0191h			
0191h			
	SS Bit Counter Bagister	SSBR	11111000b
0193h	SS Bit Counter Register SS Transmit Data Register L	SSBR	11111000b
0194h			FFh
0195h	SS Transmit Data Register H	SSTDRH	FFh
0196h	SS Receive Data Register L	SSRDR	FFh
0197h	SS Receive Data Register H	SSRDRH	FFh
0198h	SS Control Register H	SSCRH	00h
0199h	SS Control Register L	SSCRL	01111101b
019Ah	SS Mode Register	SSMR	00010000b
019Bh	SS Enable Register	SSER	00h
019Ch	SS Status Register	SSSR	00h
019Dh	SS Mode Register 2	SSMR2	00h
019Eh			
019Fh			
01A0h			
01A1h			
01A2h			
01A3h			
01A4h			
01A5h			
01A6h			
01A7h			
01A8h			
01A9h			
01AAh			
01ABh			
01ACh			
01ADh			
01AEh			
01AFh			
01B0h			
01B1h			
01B1h	Flash Memory Status Register	FST	10000X00b
01B2h			100007000
01B3n	Flash Memory Control Register 0	FMR0	00h
01B4n	Flash Memory Control Register 1	FMR0	00h
01B5h	Flash Memory Control Register 2	FMR1	00h
	r iash wellioly control register 2		0011
01B7h			
01B8h			
01B9h			
01BAh			
01BBh			
01BCh			
01BDh			
01BEh 01BFh			



Table 4.8SFR Information (8) (1)

Address	Porietor	Symbol	After Reset
Address 01C0h	Register Address Match Interrupt Register 0	RMAD0	XXh
01C0h	Audress Mator Interrupt Register U	KWIADU	XXh
01C1h			0000XXXXb
01C2h 01C3h	Address Match Interrupt Enable Register 0	AIER0	0000XXXXD 00h
01C3h	Address Match Interrupt Enable Register 0 Address Match Interrupt Register 1	RMAD1	XXh
01C4n	Autoss mator miterrupt register i		XXh
01C5h			0000XXXXb
01C8h	Address Match Interrupt Enable Register 1	AIER1	000077770 00h
01C7h	Auress mater merupi Lindole Negister i		0011
01C9h			
01C9h		+	+
01CAn 01CBh		+	
01CCh			
01CDh			+
01CEh		+	+
01CEh			
01D0h			
01D1h			
01D2h			
01D2h			
01D3h			
01D4h			
01D6h			
01D7h			
01D8h			
01D9h			
01DAh			
01DBh		<u> </u>	<u> </u>
01DCh		<u> </u>	<u> </u>
01DDh		<u> </u>	<u> </u>
01DEh		<u> </u>	<u> </u>
01DFh		<u> </u>	<u> </u>
01E0h	Pull-Up Control Register 0	PUR0	00h
01E1h	Pull-Up Control Register 1	PUR1	00h
01E2h		1	
01E3h		1	
01E4h		1	
01E5h		1	
01E6h		1	
01E7h		1	† I
01E8h			
01E9h		1	
01EAh		1	† I
01EBh		1	† I
01ECh		1	† I
01EDh			
01EEh			
01EFh			
01F0h			
01F1h		1	
01F2h			
01F3h			
01F4h			
01F5h	Input Threshold Control Register 0	VLT0	00h
01F6h	Input Threshold Control Register 1	VLT1	00h
01F7h			
01F8h	Comparator B Control Register 0	INTCMP	00h
01F9h		1	
01FAh	External Input Enable Register 0	INTEN	00h
01FBh			
01FCh	INT Input Filter Select Register 0	INTF	00h
01FDh	· · · · · · · · · · · · · · · · · · ·	1	† I
01FEh	Key Input Enable Register 0	KIEN	00h
01FFh		1	

X: Undefined



R8C/32G Group, R8C/32H Group

SFR Information (9)⁽¹⁾ Table 4.9

Address	Register	Symbol	After Reset
2C00h	DTC Transfer Vector Area		XXh
2C01h	DTC Transfer Vector Area		XXh
2C02h	DTC Transfer Vector Area		XXh
2C03h	DTC Transfer Vector Area		XXh
2C04h	DTC Transfer Vector Area		XXh
2C05h	DTC Transfer Vector Area		XXh
2C06h	DTC Transfer Vector Area		XXh
2C07h	DTC Transfer Vector Area		XXh
2C08h	DTC Transfer Vector Area		XXh
2C09h	DTC Transfer Vector Area		XXh
2C0Ah	DTC Transfer Vector Area		XXh
:	DTC Transfer Vector Area		XXh
:	DTC Transfer Vector Area		XXh
2C3Ah	DTC Transfer Vector Area		XXh
2C3Bh	DTC Transfer Vector Area		XXh
2C3Ch	DTC Transfer Vector Area		XXh
2C3Dh	DTC Transfer Vector Area		XXh
2C3Eh	DTC Transfer Vector Area		XXh
2C3Fh	DTC Transfer Vector Area		XXh
2C40h	DTC Control Data 0	DTCD0	XXh
2C41h	1		XXh
2C42h	1		XXh
2C43h			XXh
2C44h			XXh
2C45h	1		XXh
2C46h			XXh
2C47h	1		XXh
2C48h	DTC Control Data 1	DTCD1	XXh
2C49h			XXh
2C4Ah	1		XXh
2C4Bh	1		XXh
2C4Ch	1		XXh
2C4Dh			XXh
2C4Eh	-		XXh
2C4Fh	-		XXh
2C50h	DTC Control Data 2	DTCD2	XXh
2C51h	4		XXh
2C52h			XXh
2C53h	-		XXh
2C54h	-		XXh
2C55h	-		XXh
2C56h	-		XXh
2C57h	-		XXh
2C58h	DTC Control Data 3	DTCD3	XXh
2C59h		51050	XXh
2C5Ah			XXh
2C5Bh	-		XXh
2C5Ch	-		XXh
2C5Dh			XXh
2C5Eh			XXh
2C5Fh	4		XXh
2C60h	DTC Control Data 4	DTCD4	XXh
2C61h			XXh
2C62h	4		XXh
2C63h	4		XXh
2C64h	4		XXh
2C65h	4		XXh
2C66h	4		XXh
2C67h	4		XXh
2C68h	DTC Control Data 5	DTCD5	XXh
2C68h			XXh
2C6911 2C6Ah	4		XXh
2C6An 2C6Bh	4		XXh
2C6Bn	4		XXh
	4		
2C6Dh	4		XXh XXh
2C6Eh 2C6Fh	4		
		1	XXh

X: Undefined Note: 1. The blank areas are reserved and cannot be accessed by users.

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SFR Information (10)⁽¹⁾ Table 4.10

Aslahasas	De sietes	Ourseland	After Deest
Address	Register	Symbol	After Reset
2C70h	DTC Control Data 6	DTCD6	XXh
2C71h	4		XXh
2C72h	4		XXh
2C73h			XXh
2C74h			XXh
2C75h			XXh
2C76h			XXh
2C77h			XXh
2C78h	DTC Control Data 7	DTCD7	XXh
2C79h			XXh
2C7Ah			XXh
2C7Bh			XXh
2C7Ch			XXh
2C7Dh			XXh
2C7Eh			XXh
2C7Fh			XXh
2C80h	DTC Control Data 8	DTCD8	XXh
2C81h			XXh
2C82h	1		XXh
2C83h	1		XXh
2C84h	1		XXh
2C85h	4		XXh
2C86h	4		XXh
2C80h	4		XXh
2C87h	DTC Control Data 9	DTCD9	XXh
2C89h		DICD9	XXh
2C891	4		XXh
2C8Ah	4		XXh
2C8Ch	4		XXh
2C8Ch	4		XXh
2C8Dh 2C8Eh	-		XXh
	4		
2C8Fh	DTC Control Data 10	DTCD40	XXh
2C90h	DIC Control Data 10	DTCD10	XXh
2C91h	4		XXh
2C92h 2C93h	-		XXh XXh
2C93h 2C94h	-		XXh
	4		
2C95h	-		XXh
2C96h	4		XXh
2C97h		DT0D //	XXh
2C98h	DTC Control Data 11	DTCD11	XXh
2C99h			XXh
2C9Ah	4		XXh
2C9Bh	4		XXh
2C9Ch	4		XXh
2C9Dh	4		XXh
2C9Eh	4		XXh
2C9Fh			XXh
2CA0h	DTC Control Data 12	DTCD12	XXh
2CA1h			XXh
2CA2h			XXh
2CA3h			XXh
2CA4h			XXh
2CA5h			XXh
2CA6h			XXh
2CA7h]		XXh
2CA8h	DTC Control Data 13	DTCD13	XXh
2CA9h]		XXh
2CAAh	1		XXh
2CABh	1		XXh
2CACh	1		XXh
2CADh	1		XXh
2CAEh	1		XXh
2CAFh	1		XXh
X [.] Undefined			



Table 4.11	SFR Information (11) ⁽¹⁾
------------	-------------------------------------

Address	Register	Symbol	After Reset
2CB0h	DTC Control Data 14	DTCD14	XXh
2CB1h			XXh
2CB2h			XXh
2CB3h			XXh
2CB4h			XXh
2CB5h			XXh
2CB6h			XXh
2CB7h			XXh
2CB8h	DTC Control Data 15	DTCD15	XXh
2CB9h			XXh
2CBAh			XXh
2CBBh			XXh
2CBCh			XXh
2CBDh			XXh
2CBEh			XXh
2CBFh			XXh
2CC0h	DTC Control Data 16	DTCD16	XXh
2CC1h			XXh
2CC2h]		XXh
2CC3h			XXh
2CC4h			XXh
2CC5h			XXh
2CC6h			XXh
2CC7h			XXh
2CC8h	DTC Control Data 17	DTCD17	XXh
2CC9h			XXh
2CCAh			XXh
2CCBh			XXh
2CCCh			XXh
2CCDh			XXh
2CCEh			XXh
2CCFh			XXh
2CD0h	DTC Control Data 18	DTCD18	XXh
2CD1h			XXh
2CD2h			XXh
2CD3h			XXh
2CD4h			XXh
2CD5h			XXh
2CD6h			XXh
2CD7h			XXh
2CD8h	DTC Control Data 19	DTCD19	XXh
2CD9h			XXh
2CDAh			XXh
2CDBh	4		XXh
2CDCh	4		XXh
2CDDh	4		XXh
2CDEh	4		XXh
2CDFh	DTO Constant Data 00	DTODOO	XXh
2CE0h	DTC Control Data 20	DTCD20	XXh
2CE1h	4		XXh
2CE2h	4		XXh
2CE3h	4		XXh
2CE4h	4		XXh
2CE5h	4		XXh
2CE6h	4		XXh
2CE7h		DTODO	XXh
2CE8h	DTC Control Data 21	DTCD21	XXh
2CE9h	4		XXh
2CEAh	4		XXh
2CEBh	4		XXh
2CECh	4		XXh
2CEDh	4		XXh
2CEEh	4		XXh
2CEFh			XXh



Table 4.12 SFR Information (12)⁽¹⁾

Address	Register	Symbol	After Reset
2CF0h	DTC Control Data 22	DTCD22	XXh
2CF1h			XXh
2CF2h			XXh
2CF3h			XXh
2CF4h			XXh
2CF5h			XXh
2CF6h			XXh
2CF7h			XXh
2CF8h	DTC Control Data 23	DTCD23	XXh
2CF9h			XXh
2CFAh			XXh
2CFBh			XXh
2CFCh			XXh
2CFDh			XXh
2CFEh			XXh
2CFFh	7		XXh
2D00h			
:			
2FFFh			

X: Undefined

Note: 1. The blank areas are reserved and cannot be accessed by users.

ID Code Areas and Option Function Select Area Table 4.13

Address	Area Name	Symbol	After Reset
: FFDBh	Option Function Select Register 2	OFS2	(Note 1)
:			(
FFDFh	ID1		(Note 2)
:			
FFE3h	ID2		(Note 2)
:			
FFEBh	ID3		(Note 2)
:			
FFEFh	ID4		(Note 2)
			(Nists 0)
FFF3h	ID5		(Note 2)
FFF7h	ID6		(Note 2)
	IB0		(NOLE 2)
FFFBh	ID7		(Note 2)
:			(
FFFFh	Option Function Select Register	OFS	(Note 1)

Notes:

The option function select area is allocated in the flash memory, not in the SFRs. Set appropriate values as ROM data by a program. Do not write additions to the option function select area. If the block including the option function select area is erased, the option function select 1. area is set to FFh.

When blank products are shipped, the option function select area is set to FFh. It is set to the written value after written by the user. When factory-programming products are shipped, the value of the option function select area is the value programmed by the user. 2. The ID code areas are allocated in the flash memory, not in the SFRs. Set appropriate values as ROM data by a program.

Do not write additions to the ID code areas. If the block including the ID code areas is erased, the ID code areas are set to FFh. When blank products are shipped, the ID code areas are set to FFh. They are set to the written value after written by the user. When factory-programming products are shipped, the value of the ID code areas is the value programmed by the user.



5. **Electrical Characteristics**

Table 5.1 **Absolute Maximum Ratings**

Symbol	Parameter	Condition	Rated Value	Unit
Vcc/AVcc	Supply voltage		-0.3 to 6.5	V
Vi	Input voltage ⁽¹⁾		-0.3 to Vcc + 0.3	V
IIN	Input current ⁽¹⁾	(2, 3, 4)	-4 to 4	mA
Vo	Output voltage		-0.3 to Vcc + 0.3	V
Pd	Power dissipation	$-40^{\circ}C \le T_{opr} \le 85^{\circ}C$	300	mW
		$85^\circ C < T_{opr} \leq 125^\circ C$	125	
Topr	Operating ambient temperature		-40 to 85 (J version) / -40 to 125 (K version)	°C
Tstg	Storage temperature		-65 to 150	°C

Notes:

1. Meet the specified range for the input voltage or the input current.

Applicable ports: P1, P3_3 to P3_5, P3_7, P4_5
 The total input current must be 12 mA or less.

4. Even if no voltage is supplied to Vcc, the input current may cause the MCU to be powered on and operate. When a voltage is supplied to Vcc, the input current may cause the supply voltage to rise. Since operations in any cases other than above are not guaranteed, use the power supply circuit in the system to ensure the supply voltage for the MCU is stable within the specified range.



Symbol		Dor	ameter		Conditions		Standard		Unit
Symbol		Fal	ameter		Conditions	Min.	Тур.	Max.	Unit
Vcc/AVcc	Supply voltage					2.7	-	5.5	V
Vss/AVss	Supply voltage					-	0	-	V
Viн	Input "H" voltage	Other th	nan CMOS ii	nput		0.8 Vcc	-	Vcc	V
		CMOS	Input level	Input level selection	$4.0 \text{ V} \leq \text{Vcc} \leq 5.5 \text{ V}$	0.5 Vcc	-	Vcc	V
		input	switching	: 0.35 Vcc	$2.7~V \leq Vcc < 4.0~V$	0.55 Vcc	-	Vcc	V
			function (I/O port)	Input level selection	$4.0~V \leq Vcc \leq 5.5~V$	0.65 Vcc	-	Vcc	V
			(i/O port)	: 0.5 Vcc	$2.7~V \leq Vcc < 4.0~V$	0.7 Vcc	-	Vcc	V
				Input level selection	$4.0~V \leq Vcc \leq 5.5~V$	0.85 Vcc	-	Vcc	V
				: 0.7 Vcc	$2.7~V \leq Vcc < 4.0~V$	0.85 Vcc	-	Vcc	V
		Externa	I clock input	(XOUT)		1.2	-	Vcc	V
VIL	Input "L" voltage	Other th	nan CMOS ii	nput		0	-	0.2 Vcc	V
		CMOS	Input level		$4.0~V \leq Vcc \leq 5.5~V$	0	-	0.2 Vcc	V
		input	function	: 0.35 Vcc	$2.7~V \leq Vcc < 4.0~V$	0	-	0.2 Vcc	V
	(I/O port) Input level select	Input level selection	$4.0~V \leq Vcc \leq 5.5~V$	0	-	0.4 Vcc	V		
		(1/0 nort)	: 0.5 Vcc	$2.7~V \leq Vcc < 4.0~V$	0	-	0.3 Vcc	V	
				Input level selection	$4.0~V \leq Vcc \leq 5.5~V$	0	-	0.55 Vcc	V
				: 0.7 Vcc	$2.7~V \leq Vcc < 4.0~V$	0	-	0.45 Vcc	V
		Externa	I clock input	(XOUT)		0	-	0.4	V
IOH(sum)	Peak sum output "I	H" current	Sum of all	pins IOH(peak)		-	-	-80	mA
IOH(sum)	Average sum output	"H" current	Sum of all	pins IOH(avg)		-	-	-40	mA
IOH(peak)	Peak output "H" cu	rrent				-	-	-10	mA
IOH(avg)	Average output "H"	current				-	-	-5	mA
IOL(sum)	Peak sum output "I	" current	Sum of all	pins IOL(peak)		-	-	80	mA
IOL(sum)	Average sum output		Sum of all	pins IOL(avg)		-	-	40	mA
IOL(peak)	Peak output "L" cur	rent				-	-	10	mA
IOL(avg)	Average output "L"					-	-	5	mA
f(XIN)	XIN clock input osc	illation fre	quency		$2.7~V \leq Vcc \leq 5.5~V$	-	-	20	MHz
fOCO40M	When used as the	count sour	ce for timer	RC or timer RD ⁽³⁾	$2.7~V \leq Vcc \leq 5.5~V$	32	-	40	MHz
fOCO-F	fOCO-F frequency				$2.7~V \leq Vcc \leq 5.5~V$	-	-	20	MHz
_	System clock frequ	ency			$2.7~V \leq Vcc \leq 5.5~V$	-	-	20	MHz
f(BCLK)	CPU clock frequen	су			$2.7 \text{ V} \leq \text{Vcc} \leq 5.5 \text{ V}$	-	-	20	MHz

Table 5.2	Recommended	Operating	Conditions	(1)

Notes:

1. Vcc = 2.7 to 5.5 V and Topr = -40 to 85° C (J version) / -40 to 125° C (K version), unless otherwise specified.

2. The average output current indicates the average value of current measured during 100 ms.

3. fOCO40M can be used as the count source for timer RC or timer RD in the range of Vcc = 2.7 V to 5.5V.



Table 5.3	Recommended Operating Conditions (2))
-----------	--------------------------------------	---

Symbol	Parameter		Conditions		Unit		
Symbol Parameter		Conditions	Min.	Тур.	Max.	Onit	
IIC(H)	High input injection current	P1, P3_3 to P3_5, P3_7, P4_5	$V_{I} > V_{CC}$	-	-	2	mA
lic(L)	Low input injection current	P1, P3_3 to P3_5, P3_7, P4_5	$V_{I} < V_{SS}$	-	-	-2	mA
Σ IIC	Total injection current			-	-	8	mA

Note:

1. Vcc = 4.5 to 5.5 V and $T_{opr} = -40$ to 85°C (J version) / -40 to 125°C (K version), unless otherwise specified.

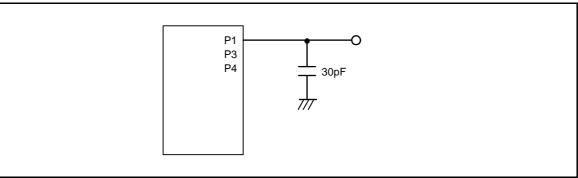


Figure 5.1 Ports P1, P3 and P4 Timing Measurement Circuit



Sumbol	Doromotor	Parameter		litiono	Standard		Unit		
Symbol	Parameter		Conc	Conditions		Тур.	Max.	Max.	
-	Resolution		Vref = AVCC		-	-	10	Bit	
-	Absolute accuracy	10-bit mode	Vref = AVCC = 5.0 V	AN8 to AN11 input	-	-	±3	LSB	
			Vref = AVCC = 3.0 V	AN8 to AN11 input	-	-	±5	LSB	
		8-bit mode	Vref = AVCC = 5.0 V	AN8 to AN11 input	-	-	±2	LSB	
			Vref = AVCC = 3.0 V	AN8 to AN11 input	-	-	±2	LSB	
φAD	A/D conversion clock		$4.0 \text{ V} \leq \text{Vref} = \text{AVcc} \leq 5.5 \text{ V}^{(2)}$		2	-	20	MHz	
			2.7 V \leq Vref = AVcc \leq 5.5 V ⁽²⁾		2	-	10	MHz	
			$2.2 \text{ V} \le \text{Vref} = \text{AVcc} \le$	5.5 V ⁽²⁾	2	-	5	MHz	
-	Tolerance level impedance	9			-	3	-	kΩ	
t CONV	Conversion time	10-bit mode	Vref = AVCC = 5.0 V, ¢	AD = 20 MHz	2.2	-	-	μS	
		8-bit mode	Vref = AVCC = 5.0 V, ¢	AD = 20 MHz	2.2	-	-	μS	
t SAMP	Sampling time		φAD = 20 MHz		0.80	-	-	μS	
IVref	Vref current		$Vcc = 5 V$, $XIN = f1 = \phi AD = 20 MHz$		-	45	-	μΑ	
Vref	Reference voltage				2.7	-	AVcc	V	
Via	Analog input voltage (3)				0	-	Vref	V	
OCVREF	On-chip reference voltage		$2 \text{ MHz} \le \phi \text{AD} \le 4 \text{ MH}$	lz	1.14	1.34	1.54	V	

Table 5.4 A/D Converter Characteristics

Notes:

1. Vcc/AVcc = Vref = 2.7 to 5.5 V, Vss = 0 V and Topr = -40 to 85° C (J version) / -40 to 125° C (K version), unless otherwise specified.

2. The A/D conversion result will be undefined in wait mode, stop mode, when the flash memory stops, and in low-currentconsumption mode. Do not perform A/D conversion in these states or transition to these states during A/D conversion.

3. When the analog input voltage is over the reference voltage, the A/D conversion result will be 3FFh in 10-bit mode and FFh in 8-bit mode.

Table 5.5 Comparator B Electrical Characteristics

Symbol	Parameter	Condition		Unit		
Symbol	Falameter	Condition	Min.	Тур.	Max.	Unit
Vref	IVREF1, IVREF3 input reference voltage		0	-	Vcc - 1.4	V
Vi	IVCMP1, IVCMP3 input voltage		-0.3	-	Vcc + 0.3	V
-	Offset		-	5	100	mV
td	Comparator output delay time (2)	VI = Vref ± 100 mV	-	0.1	-	μS
ICMP	Comparator operating current	Vcc = 5.0 V	-	17.5	-	μΑ

Notes:

1. Vcc = 2.7 to 5.5 V, T_{opr} = -40 to 85°C (J version) / -40 to 125°C (K version), unless otherwise specified.

2. When the digital filter is disabled.



Symbol	Parameter	Conditions		Unit		
Symbol	Falameter	Conditions	Min.	Тур.	Тур. Мах.	
_	Program/erase endurance (2)	R8C/32G Group	1,000 ⁽³⁾	-	-	times
		R8C/32H Group	100 (3)	-	-	times
-	Byte program time (program/erase endurance ≤ 100 times)		-	80	300	μS
-	Byte program time (program/erase endurance > 100 times)		_	80	500	μS
-	Block erase time		-	0.3	4	S
td(SR-SUS)	Time delay from suspend request until suspend		-	-	5+CPU clock × 3 cycles	ms
-	Interval from erase start/restart until following suspend request		0	-	-	μS
-	Time from suspend until erase restart		-	-	30+CPU clock × 1 cycle	μS
td(CMDRST- READY)	Time from when command is forcibly terminated until reading is enabled		-	-	30+CPU clock × 1 cycle	μS
-	Program, erase voltage		2.7	-	5.5	V
-	Read voltage		2.7	-	5.5	V
-	Program, erase temperature		-40	_	85 (J version) 125 (K version)	°C
-	Data hold time (7)	Ambient temperature = 55°C ⁽⁸⁾	20	-	_	year

Table 5.6 Flash Memory (Program ROM) Electrical Characteristics

Notes:

1. Vcc = 2.7 to 5.5 V at Topr = -40 to 85°C (J version) / -40 to 125°C (K version) (under consideration), unless otherwise specified.

2. Definition of programming/erasure endurance

The programming and erasure endurance is defined on a per-block basis. If the programming and erasure endurance is n (n = 100, 1,000), each block can be erased n times. For example, if 4,096 1byte writes are performed to different addresses in block, a 4 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one.

However, the same address must not be programmed more than once per erase operation (overwriting prohibited).

3. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).

4. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. It is also advisable to retain data on the erasure endurance of each block and limit the number of erase operations to a certain number.

5. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.

6. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.

7. The data hold time includes time that the power supply is off or the clock is not supplied.

8. This data hold time includes 3,000 hours in Ta = 125° C and 7,000 hours in Ta = 85° C.



Sumbol	Parameter	Conditions		Standard			
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit	
_	Program/erase endurance (2)		10,000 (3)	-	-	times	
-	Byte program time (program/erase endurance ≤ 1,000 times)		-	160	950	μS	
-	Byte program time (program/erase endurance > 1,000 times)		-	300	950	μS	
_	Block erase time (program/erase endurance ≤ 1,000 times)		-	0.2	1	S	
_	Block erase time (program/erase endurance > 1,000 times)		-	0.3	1	S	
td(SR-SUS)	Time delay from suspend request until suspend		-	Í	3+CPU clock × 3 cycles	ms	
-	Interval from erase start/restart until following suspend request		0	Í	-	μS	
_	Time from suspend until erase restart		-	-	30+CPU clock × 1 cycle	μS	
td(CMDRST- READY)	Time from when command is forcibly terminated until reading is enabled		-	-	30+CPU clock × 1 cycle	μS	
-	Program, erase voltage		2.7	-	5.5	V	
-	Read voltage		2.7	-	5.5	V	
_	Program, erase temperature		-40	-	85°C (J version), 125°C (K version)	°C	
_	Data hold time ⁽⁷⁾	Ambient temperature = 55 °C ⁽⁸⁾	20	_	-	year	

Table 5.7 Flash Memory (Data flash Block A to Block D) Electrical Characteristics

Notes:

1. Vcc = 2.7 to 5.5 V and Topr = -40 to 85°C (J version) / -40 to 125°C (K version), unless otherwise specified.

2. Definition of programming/erasure endurance

The programming and erasure endurance is defined on a per-block basis. If the programming and erasure endurance is n (n = 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to different addresses in block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one.

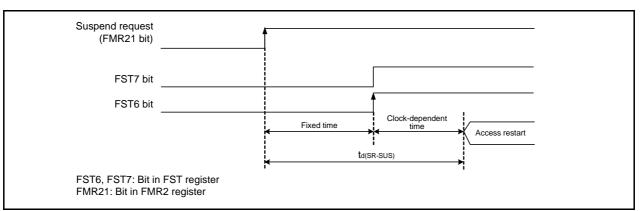
However, the same address must not be programmed more than once per erase operation (overwriting prohibited).

3. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).

4. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. In addition, averaging the erasure endurance between blocks A to D can further reduce the actual erasure endurance. It is also advisable to retain data on the erasure endurance of each block and limit the number of erase operations to a certain number.

5. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.

- 6. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
- 7. The data hold time includes time that the power supply is off or the clock is not supplied.
- 8. This data hold time includes 3,000 hours in Ta = 125° C and 7,000 hours in Ta = 85° C.



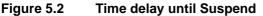




Table 5.8 Voltage Detection 0 Circuit Electrical Character
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Symbol	Parameter	Condition		Unit		
Symbol	Faranieter	Condition	Min.	Тур.	Max.	Unit
Vdet0	Voltage detection level	At the falling of Vcc	2.70	2.85	3.05	V
-	Voltage detection 0 circuit response time (3)	At the falling of Vcc from 5 V to (Vdet0_0 – 0.1) V	-	6	150	μS
_	Voltage detection circuit self power consumption	VCA25 = 1, Vcc = 5.0 V	-	1.5	-	μΑ
td(E-A)	Waiting time until voltage detection circuit operation starts ⁽²⁾		-	=	100	μS

Notes:

1. The measurement condition is Vcc = 2.7 V to 5.5 V and $T_{opr} = -40$ to $85^{\circ}C$ (J version) / -40 to $125^{\circ}C$ (K version).

2. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA25 bit in the VCA2 register to 0.

3. Time until the voltage monitor 0 reset is generated after the voltage passes Vdet0.

 Table 5.9
 Voltage Detection 1 Circuit Electrical Characteristics

Cumbal	Deremeter	Condition		Unit		
Symbol	Parameter	Condition	Min.	Тур.	Max.	Offic
Vdet1	Voltage detection level Vdet1_7 ⁽²⁾	At the falling of Vcc	2.95	3.25	3.55	V
	Voltage detection level Vdet1_8 ⁽²⁾	At the falling of Vcc	3.10	3.40	3.70	V
	Voltage detection level Vdet1_9 ⁽²⁾	At the falling of Vcc	3.25	3.55	3.85	V
	Voltage detection level Vdet1_A (2)	At the falling of Vcc	3.40	3.70	4.00	V
	Voltage detection level Vdet1_B (2)	At the falling of Vcc	3.55	3.85	4.15	V
	Voltage detection level Vdet1_C (2)	At the falling of Vcc	3.70	4.00	4.30	V
	Voltage detection level Vdet1_D (2)	At the falling of Vcc	3.80	4.15	4.45	V
	Voltage detection level Vdet1_E (2)	At the falling of Vcc	4.00	4.30	4.60	V
-	Hysteresis width at the rising of Vcc in voltage detection 1 circuit		-	0.10	-	V
_	Voltage detection 1 circuit response time ⁽³⁾	At the falling of Vcc from 5 V to (Vdet1_7 – 0.1) V	-	60	150	μS
-	Voltage detection circuit self power consumption	VCA26 = 1, Vcc = 5.0 V	-	1.7	-	μA
td(E-A)	Waiting time until voltage detection circuit operation starts ⁽⁴⁾		-	_	100	μS

Notes:

1. The measurement condition is Vcc = 2.7 V to 5.5 V and T_{opr} = -40 to 85°C (J version) / -40 to 125°C (K version).

2. Select the voltage detection level with bits VD1S0 to VD1S3 in the VD1LS register.

3. Time until the voltage monitor 1 interrupt request is generated after the voltage passes Vdet1.

4. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA26 bit in the VCA2 register to 0.



Table 5.10 Voltage Detection 2 Circuit Electrical Characteristics

Symbol	Parameter	Condition		Unit		
Symbol	Falameter	Condition	Min.	Тур.	Max.	Unit
Vdet2	Voltage detection level Vdet2	At the falling of Vcc	3.70	4.00	4.30	V
-	Hysteresis width at the rising of Vcc in voltage detection 2 circuit		-	0.10	-	V
-	Voltage detection 2 circuit response time ⁽²⁾	At the falling of Vcc from 5 V to (Vdet2_0 – 0.1) V	-	20	150	μS
-	Voltage detection circuit self power consumption	VCA27 = 1, Vcc = 5.0 V	-	1.7	-	μA
td(E-A)	Waiting time until voltage detection circuit operation starts ⁽³⁾		_	-	100	μS

Notes:

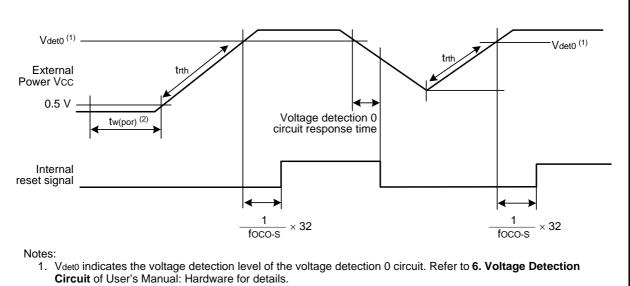
- 1. The measurement condition is Vcc = 2.7 V to 5.5 V and T_{opr} = -40 to 85°C (J version) / -40 to 125°C (K version).
- 2. Time until the voltage monitor 2 interrupt request is generated after the voltage passes Vdet2.
- 3. Necessary time until the voltage detection circuit operates after setting to 1 again after setting the VCA27 bit in the VCA2 register to 0.

Table 5.11 Power-on Reset Circuit ⁽²⁾

Symbol	Parameter	Condition		Standard	Unit	
	Falameter	Condition	Min.	Тур.	Max.	Unit
trth	External power Vcc rise gradient	(1)	0	-	50,000	mV/msec

Notes:

- 1. The measurement condition is $T_{opr} = -40$ to $85^{\circ}C$ (J version) / -40 to $125^{\circ}C$ (K version), unless otherwise specified.
- 2. To use the power-on reset function, enable voltage monitor 0 reset by setting the LVDAS bit in the OFS register to 0.



 tw(por) indicates the duration the external power Vcc must be held below the valid voltage (0.5 V) to enable a power-on reset. When turning on the power after it falls with voltage monitor 0 reset disabled, maintain tw(por) for 1 ms or more.

Figure 5.3

Power-on Reset Circuit Electrical Characteristics



Table 5.12	High-speed On-Chip Oscillator Circuit Electrical Characteristics
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Symbol	Parameter	Condition		Unit			
Symbol	Farameter	Condition	Min.	Тур.	Max.	Unit	
-	High-speed on-chip oscillator frequency after reset	Vcc = 2.7 V to 5.5 V, -40°C \leq Topr \leq 85°C (J) /	-	40	-	MHz	
	High-speed on-chip oscillator frequency when the FRA4 register correction value is written into the FRA1 register and the FRA5 register correction value into the FRA3 register ⁽³⁾	–40°C ≤ Topr ≤ 125°C (K)	_	36.864	-	MHz	
	High-speed on-chip oscillator frequency when the FRA6 register correction value is written into the FRA1 register and the FRA7 register correction value into the FRA3 register		_	32	_	MHz	
	High-speed on-chip oscillator frequency temperature • supply voltage dependence ⁽²⁾		-5	-	5	%	
-	Oscillation stability time		_	200	_	μs	
-	Self power consumption at oscillation	VCC = 5.0 V, Topr = 25°C	-	400	-	μA	

Notes:

1. The measurement condition is Vcc = 2.7 to 5.5 V, T_{opr} = -40 to 85°C (J version) / -40 to 125°C (K version).

2. This indicates the precision error for the oscillation frequency of the high-speed on-chip oscillator.

3. This enables the setting errors of bit rates such as 9600 bps and 38400 bps to be 0% when the serial interface is used in UART mode.

Table 5.13 Low-speed On-Chip Oscillator Circuit Electrical Characteristics

Symbol	Parameter	Condition		Unit		
Symbol	Falanetei	Condition	Min.	Тур.	Max.	Onit
fOCO-S	Low-speed on-chip oscillator frequency	$2.7~V \leq Vcc < 4.2~V$	106.25	125	143.75	kHz
		$4.2~V \leq Vcc \leq 5.5~V$	112.5	125	137.5	
fOCO-WDT	Low-speed on-chip oscillator frequency for watchdog	$2.7~V \leq Vcc < 4.2~V$	106.25	125	143.75	kHz
	timer	$4.2~V \leq Vcc \leq 5.5~V$	112.5	125	137.5	
-	Oscillation stability time	Vcc = 5.0 V, Topr = 25°C	-	30	100	μS
-	Self power consumption at oscillation	VCC = 5.0 V, Topr = $25^{\circ}C$	-	3	-	μA

Note:

1. The measurement condition is Vcc = 2.7 to 5.5 V, $T_{opr} = -40$ to $85^{\circ}C$ (J version) / -40 to $125^{\circ}C$ (K version).

Table 5.14 Power Supply Circuit Timing Characteristics

Symbol	Parameter	Condition		Standard	4	Unit
Symbol	Falanetei	Condition	Min.	Тур.	Max.	Unit
td(P-R)	Time for internal power supply stabilization during power-on ⁽²⁾		-	-	2,000	μS

Notes:

1. The measurement condition is VCC = 2.7 V to 5.5 V and Topr = -40 to 85°C (J version) / -40 to 125°C (K version).

2. Waiting time until the internal power supply generation circuit stabilizes during power-on.



Table 5.15	Timing Requirements of Synchronous Serial Communication Unit (SSU) ⁽¹⁾

Cumbal	Parameter		Conditions		Stand	Linit	
Symbol			Conditions	Min.	Тур.	Max.	Unit
tsucyc	SSCK clock cycle tim	SSCK clock cycle time		4	-	-	tcyc ⁽²⁾
tнı	SSCK clock "H" width	SSCK clock "H" width		0.4	I	0.6	tsucyc
tlo	SSCK clock "L" width	SSCK clock "L" width		0.4	-	0.6	tsucyc
trise	SSCK clock rising	Master		-	-	1	tcyc (2)
	time	Slave		-	-	1	μs
t FALL	SSCK clock falling time	Master		-	-	1	tCYC ⁽²⁾
		Slave		_	I	1	μs
tsu	SSO, SSI data input s	setup time		100	-	-	ns
tн	SSO, SSI data input h	nold time		1	-	-	tcyc (2)
tlead	SCS setup time	Slave		1tcyc + 50	-	_	ns
tlag	SCS hold time	Slave		1tcyc + 50	-	-	ns
top	SSO, SSI data output	t delay time		-	I	1	tcyc (2)
tSA	SSI slave access time	e	$2.7~V \leq Vcc \leq 5.5~V$	-	I	1.5tcyc + 100	ns
tor	SSI slave out open tir	ne	$2.7 \text{ V} \le \text{Vcc} \le 5.5 \text{ V}$	-	_	1.5tcyc + 100	ns

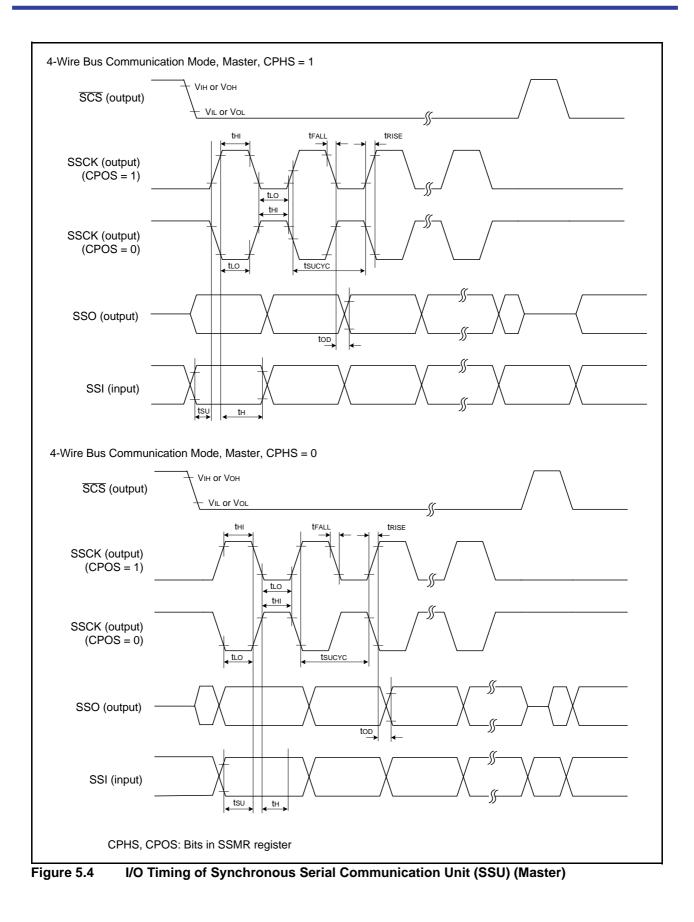
Notes:

1. Vcc = 2.7 to 5.5 V, Vss = 0 V and $T_{opr} = -40$ to 85°C (J version) / -40 to 125°C (K version), unless otherwise specified.

2. 1tCYC = 1/f1(s)

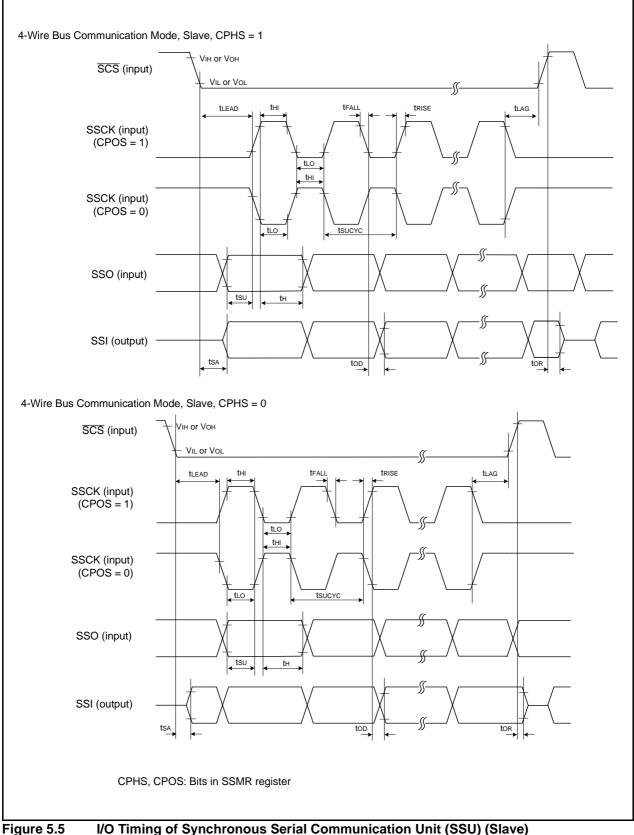


R8C/32G Group, R8C/32H Group





R8C/32G Group, R8C/32H Group



I/O Timing of Synchronous Serial Communication Unit (SSU) (Slave)



R8C/32G Group, R8C/32H Group

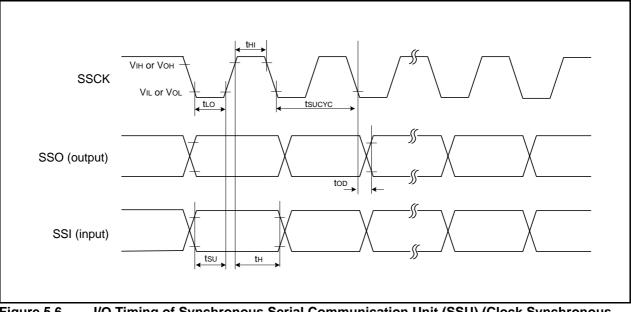


Figure 5.6 I/O Timing of Synchronous Serial Communication Unit (SSU) (Clock Synchronous Communication Mode)



Symbol	Parameter		Condition		Standard			
Symbol	Fai	ameter	Condition	Min.	Тур.	Max.	Unit	
Vон	Output "H" voltage	Other than XOUT	Iон = –5 mA	Vcc - 2.0	-	Vcc	V	
			Іон = –200 μА	Vcc - 0.3	-	Vcc	V	
		XOUT	Іон = –200 μА	1.0	-	Vcc	V	
Vol	Output "L" voltage	Other than XOUT	IoL = 5 mA	-	-	2.0	V	
			Ιοι = 200 μΑ	-	-	0.45	V	
		XOUT	IOL = 200 μA	-	-	0.5	V	
VT+-VT-	Hysteresis	INTO, INT1, INT3, KIO, KI1, KI2, KI3, TRAIO, TRBO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, TRDIOA0, TRDIOB0, TRDIOC0, TRDIOD0, TRDIOC1, TRDIOD1, TRDIOC1, TRDIOD1, TRCTRG, TRCCLK, ADTRG, RXD0, RXD2, CLK0, CLK2, SSI, SCL, SDA, SSO RESET	Vcc = 5.0 V Vcc = 5.0 V	0.1	1.2	-	V	
Ін	Input "H" current		VI = 5 V, Vcc = 5.0 V	-	-	1.0	μA	
lil	Input "L" current		VI = 0 V, Vcc = 5.0 V	-	-	-1.0	μA	
Rpullup	Pull-up resistance		VI = 0 V, Vcc = 5.0 V	25	50	100	kΩ	
Rfxin	Feedback resistance	XIN		-	0.3	-	MΩ	
Vram	RAM hold voltage	•	During stop mode	2.0	_	-	V	

Table 5.16	Electrical Characteristics (1) [4.2 V \leq Vcc \leq 5.5 V]
------------	--

Note:

1. $4.2 \text{ V} \le \text{Vcc} \le 5.5 \text{ V}$ and $\text{T}_{opr} = -40$ to 85°C (J version) / -40 to 125°C (K version), f(XIN) = 20 MHz, unless otherwise specified.



Table 5.17Electrical Characteristics (2) $[3.3 V \le Vcc \le 5.5 V]$
(Topr = -40 to 85°C (J version), unless otherwise specified.)

Symbol	Parameter	Condition			Standard	4	Unit
Symbol	Falameter		Condition	Min.	Тур.	Max.	Unit
Icc	Power supply current (Vcc = 3.3 to 5.5 V)	High-speed clock mode	XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	_	7.0	15	mA
Single-chip mode, output pins are open, other pins are Vss		XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	5.6	12.5	mA	
		XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	3.6	-	mA	
			XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	3.0	-	mA
			XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	2.2	-	mA
			XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	1.5	-	mA
		High-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz No division	-	7.0	15	mA
			XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	3.0	-	mA
		Low-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR27 = 1, VCA20 = 0	-	90	180	μA
		Wait mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	15	110	μA
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	-	5.0	100	μΑ
		Stop mode	XIN clock off, Topr = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	_	2.0	5.0	μΑ
			XIN clock off, Topr = 85°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	-	15.0	-	μA

Note:

1. The typical value (Typ.) indicates the current value when the CPU and the memory operate.

Table 5.18Electrical Characteristics (3) $[3.3 V \le Vcc \le 5.5 V]$
(Topr = -40 to 125°C (K version), unless otherwise specified.)

Symbol	Parameter	Condition			Standard	ł	Unit
Symbol	Parameter		Condition	Min.	Тур.	Max.	Unit
Icc	Power supply current (Vcc = 3.3 to 5.5 V)	High-speed clock mode	XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	7.0	15	mA
Single-chip mode, output pins are open, other pins are Vss			XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	5.6	12.5	mA
		XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	3.6	-	mA	
			XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	3.0	-	mA
			XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	2.2	-	mA
			XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	1.5	-	mA
		High-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz No division	-	7.0	15	mA
			XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	3.0	-	mA
		Low-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR27 = 1, VCA20 = 0	-	90	400	μA
		Wait mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	15	330	μA
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	-	5.0	320	μΑ
		Stop mode	XIN clock off, Topr = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	-	2.0	5.0	μA
			XIN clock off, Topr = 125°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	-	60	_	μA

Note:

1. The typical value (Typ.) indicates the current value when the CPU and the memory operate.



Timing Requirements (Unless Otherwise Specified: Vcc = 5 V, Vss = 0 V at Topr = -40°C to 85°C (J ver)/-40°C to 125°C (K ver))

Table 5.19 External Clock Input (XOUT)

Symbol	Parameter	Stan	Unit	
		Min.	Max.	Unit
tc(XOUT)	XOUT input cycle time	50	-	ns
twh(xout)	XOUT input "H" width	24	-	ns
twl(xout)	XOUT input "L" width	24	-	ns

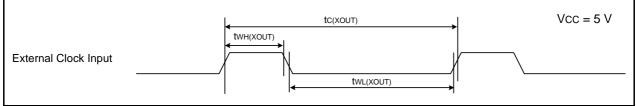


Figure 5.7 External Clock Input Timing Diagram when VCC = 5 V

Table 5.20 TRAIO Input

Symbol	Parameter	Stan	Unit	
		Min.	Max.	Unit
tc(TRAIO)	TRAIO input cycle time	100	-	ns
twh(traio)	TRAIO input "H" width	40	-	ns
twl(traio)	TRAIO input "L" width	40	-	ns

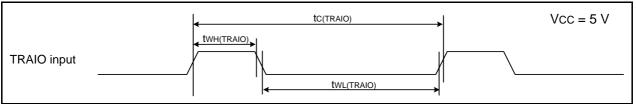


Figure 5.8 TRAIO Input Timing Diagram when Vcc = 5 V



Table 5.21 Serial Interface

Symbol	Boromotor	Parameter Condition	Standard		Unit
,	Parameter	Condition	Min.	Max.	Unit
tc(CK)	CLKi input cycle time		200	-	ns
tW(CKH)	CLKi input "H" width		100	-	ns
tW(CKL)	CLKi input "L" width	1	100	-	ns
td(C-Q)	TXDi output delay time	When external clock selected	-	90	ns
th(C-Q)	TXDi hold time		0	-	ns
tsu(D-C)	RXDi input setup time		10	-	ns
th(C-D)	RXDi input hold time		90	-	ns
td(C-Q)	TXDi output delay time		-	10	ns
tsu(D-C)	RXDi input setup time	When internal clock selected	90	-	ns
th(C-D)	RXDi input hold time		90	-	ns



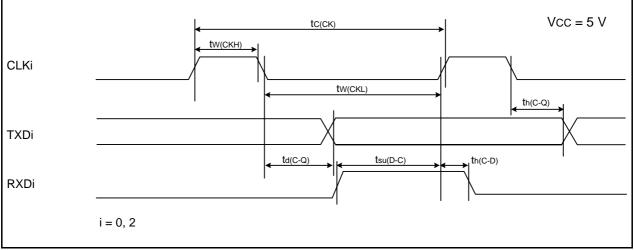


Figure 5.9 Serial Interface Timing Diagram when Vcc = 5 V

Table 5.22 External Interrupt INTi (i = 0 to 1, 3) Input, Key Input Interrupt Kli (i = 0 to 3)

Symbol	Parameter		Standard		
	Falanielei	Min.	Max.	Unit	
tw(INH)	INTi input "H" width, Kli input "H" width	250 (1)	-	ns	
tw(INL)	INTi input "L" width, Kli input "L" width	250 ⁽²⁾	-	ns	

Notes:

1. When selecting the digital filter by the INTi input filter select bit, use an INTi input HIGH width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

2. When selecting the digital filter by the INTi input filter select bit, use an INTi input LOW width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

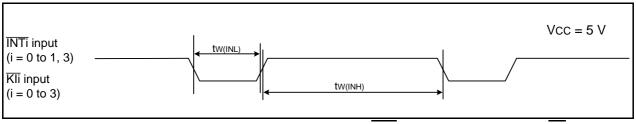


Figure 5.10 Input Timing Diagram for External Interrupt INTi and Key Input Interrupt Kli when Vcc = 5 V

Symbol	Parameter	Condition		Standard			
,			Min.	Тур.	Max.	Unit	
Vон	Output "H" voltage	Other than XOUT	Iон = –1 mA	Vcc - 0.5	-	Vcc	V
		XOUT	Іон = –200 μА	1.0	-	Vcc	V
Vol	Output "L" voltage	Other than XOUT	IOL = 1 mA	-	-	0.5	V
		XOUT	ΙΟL = 200 μΑ	-	-	0.5	V
VT+-VT-	Hysteresis	INTO, INT1, INT3, KIO, KI1, KI2, KI3, TRAIO, TRBO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, TRDIOA0, TRDIOB0, TRDIOC0, TRDIOD0, TRDIOC1, TRDIOD1, TRDIOC1, TRDIOD1, TRCTRG, TRCCLK, ADTRG, RXD0, RXD2, CLK0, CLK2, SSI, SCL, SDA, SSO	Vcc = 3.0 V	0.1	0.4	_	V
		RESET	Vcc = 3.0 V	0.1	0.5	-	V
Ін	Input "H" current		VI = 3 V, Vcc = 3.0 V	-	-	1.0	μA
lı∟	Input "L" current		VI = 0 V, Vcc = 3.0 V	-	-	-1.0	μA
Rpullup	Pull-up resistance		VI = 0 V, Vcc = 3.0 V	42	84	168	kΩ
Rfxin	Feedback resistance	XIN		_	0.3	-	MΩ
RfxCIN	Feedback resistance	XCIN		-	8	-	MΩ
Vram	RAM hold voltage	•	During stop mode	2.0	-	-	V

Table 5.23	Electrical Characteristics (4) [2.7 V \leq Vcc $<$ 4.2 V]
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Note:

1. 2.7 V \leq Vcc < 4.2 V and T_{opr} = -40 to 85°C (J version) / -40 to 125°C (K version), f(XIN) = 10 MHz, unless otherwise specified.



Table 5.24Electrical Characteristics (5) $[2.7 V \le Vcc < 3.3 V]$
(Topr = -40 to 85°C (J version), unless otherwise specified.)

Symbol	Parameter	Parameter Condition	Standard			Unit	
-				Min.	Тур.	Max.	
lcc	Power supply current (Vcc = 2.7 to 3.3 V) Single-chip mode, output pins are open,	High-speed clock mode (1)	XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	_	7.0	14.5	mA
	other pins are Vss		XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	_	5.6	12.0	mA
		XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	3.6	-	mA	
			XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	3.0	-	mA
			XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	2.2	-	mA
			XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	1.5	-	mA
	High-speed on-chip oscillator	XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz No division	-	7.0	14.5	mA	
	mode ⁽¹⁾	XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	3.0	-	mA	
		Low-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR27 = 1, VCA20 = 0	_	85	180	μA
		Wait mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	15	110	μΑ
		XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	5	100	μΑ	
		Stop mode	XIN clock off, Topr = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	_	2.0	5.0	μA
			XIN clock off, $T_{opr} = 85^{\circ}C$ High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	_	13.0	_	μA

Note:

1. The typical value (Typ.) indicates the current value when the CPU and the memory operate.

Table 5.25Electrical Characteristics (6) $[2.7 V \le Vcc < 3.3 V]$
(Topr = -40 to 125°C (K version), unless otherwise specified.)

Symbol	bol Parameter	Condition		Standard			
0,11001				Min.	Тур.	Max.	Unit
Icc	Power supply current (Vcc = 2.7 to 3.3 V) Single-chip mode, output pins are open,	High-speed clock mode (1)	XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	_	7.0	14.5	mA
	other pins are Vss		XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	_	5.6	12.0	mA
			XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	3.6	-	mA
			XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	_	3.0	-	mA
			XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	_	2.2	-	mA
			XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	_	1.5	-	mA
	High-speed on-chip oscillator mode ⁽¹⁾	on-chip oscillator	XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz No division	_	7.0	14.5	mA
		mode (1)	XIN clock off High-speed on-chip oscillator on fOCO-F = 20 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8	_	3.0	-	mA
		Low-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR27 = 1, VCA20 = 0	_	85	390	μA
		Wait mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	15	320	μA
		XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	5	310	μA	
		Stop mode	XIN clock off, $T_{opr} = 25^{\circ}C$ High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	-	2.0	5.0	μA
			XIN clock off, $T_{opr} = 125^{\circ}C$ High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	-	55.0	_	μA

Note:

1. The typical value (Typ.) indicates the current value when the CPU and the memory operate.



Timing Requirements (Unless Otherwise Specified: Vcc = 3 V, Vss = 0 V at Topr = -40°C to 85°C (J ver)/-40°C to 125°C (K ver))

Table 5.26 External Clock Input (XOUT)

Symbol	Parameter	Stan	Unit	
		Min.	Max.	Unit
tc(XOUT)	XOUT input cycle time	50	-	ns
twh(xout)	XOUT input "H" width	24	-	ns
twl(xout)	XOUT input "L" width	24	-	ns

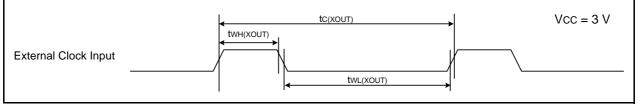


Figure 5.11 External Clock Input Timing Diagram when VCC = 3 V

Table 5.27 TRAIO Input

Symbol	Parameter	Stan	Unit	
Symbol	Falalletei			Max.
tc(TRAIO)	TRAIO input cycle time	300	-	ns
twh(traio)	TRAIO input "H" width	120	-	ns
twl(traio)	TRAIO input "L" width	120	-	ns

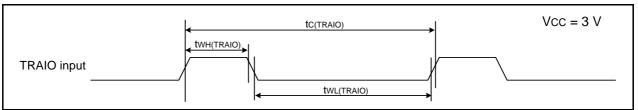


Figure 5.12 TRAIO Input Timing Diagram when Vcc = 3 V



Table 5.28 Serial Interface

Sympol	Parameter	Condition	Standard		Unit
Symbol	Parameter	Condition	Min.	Max.	Unit
tc(CK)	CLKi input cycle time		300	-	ns
tw(CKH)	CLKi input "H" width		150	-	ns
tW(CKL)	CLKi Input "L" width	1	150	-	ns
td(C-Q)	TXDi output delay time	When external clock selected	-	120	ns
th(C-Q)	TXDi hold time		0	-	ns
tsu(D-C)	RXDi input setup time		30	-	ns
th(C-D)	RXDi input hold time		90	-	ns
td(C-Q)	TXDi output delay time		-	30	ns
tsu(D-C)	RXDi input setup time	When internal clock selected	120	-	ns
th(C-D)	RXDi input hold time		90	-	ns

i = 0, 2

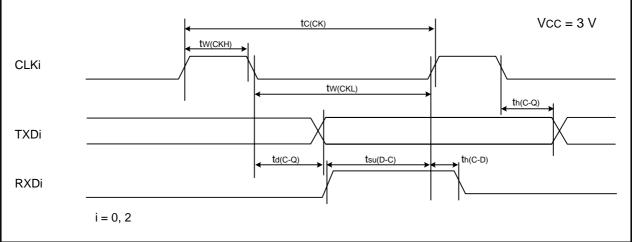




Table 5.29 External Interrupt INTi (i = 0 to 1, 3) Input, Key Input Interrupt Kli (i = 0 to 3)

Symbol	Parameter		Standard		
	Falanielei	Min.	Max.	Unit	
tw(INH)	INTi input "H" width, Kli input "H" width	380 (1)	-	ns	
tw(INL)	INTi input "L" width, Kli input "L" width	380 (2)	-	ns	

Notes:

1. When selecting the digital filter by the INTi input filter select bit, use an INTi input HIGH width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

2. When selecting the digital filter by the INTi input filter select bit, use an INTi input LOW width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

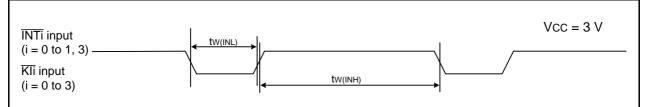
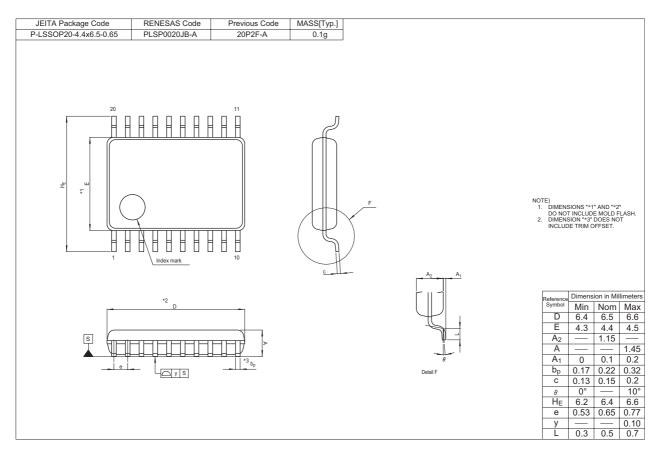


Figure 5.14 Input Timing Diagram for External Interrupt \overline{INTi} and Key Input Interrupt \overline{KIi} when Vcc = 3 V

Package Dimensions

Diagrams showing the latest package dimensions and mounting information are available in the "Packages" section of the Renesas Electronics website.





R8C/32G Group, R8C/32H Group Datasheet

Rev.	Date	Description	
		Page	Summary
0.01	Sep 30, 2010	_	First Edition issued
0.10	Feb 08, 2011	9	Figure 1.4 P3_3 "CTS2/RTS2" \rightarrow "CTS2/RTS2
		16	3.1 "The internal ROM with address 0FFFFh." deleted
		21	Table 4.4 "00E0h", "00E2h", "00E9h", "00EBh" deleted
		30 to 52	"5. Electrical Characteristics" added

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General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.
- 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
 - In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do
 not access these addresses; the correct operation of LSI is not guaranteed if they are
 accessed.
- 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.
- 5. Differences between Products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

— The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

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