



AK4355

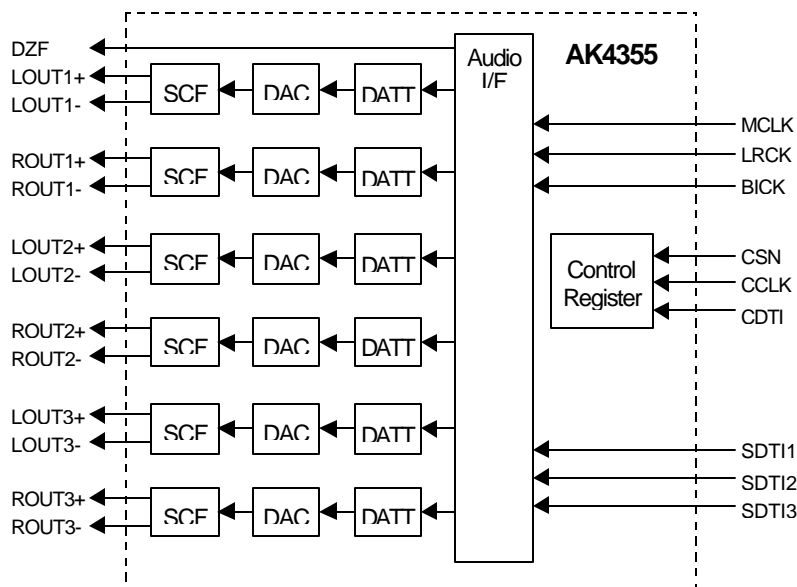
192kHz 24-Bit 6ch DAC for DVD-Audio

GENERAL DESCRIPTION

The AK4355 offers the perfect mix for cost and performance based multi-channel audio systems. AKM's advanced multi-bit architecture delivers a wide dynamic range and low outband noise. The AK4355 has full differential SCF outputs, removing the need for AC coupling capacitors and increasing performance for systems with excessive clock jitter. The 24 Bit word length and 192kHz sampling rate make this part ideal for a wide range of application including DVD-Audio.

FEATURES

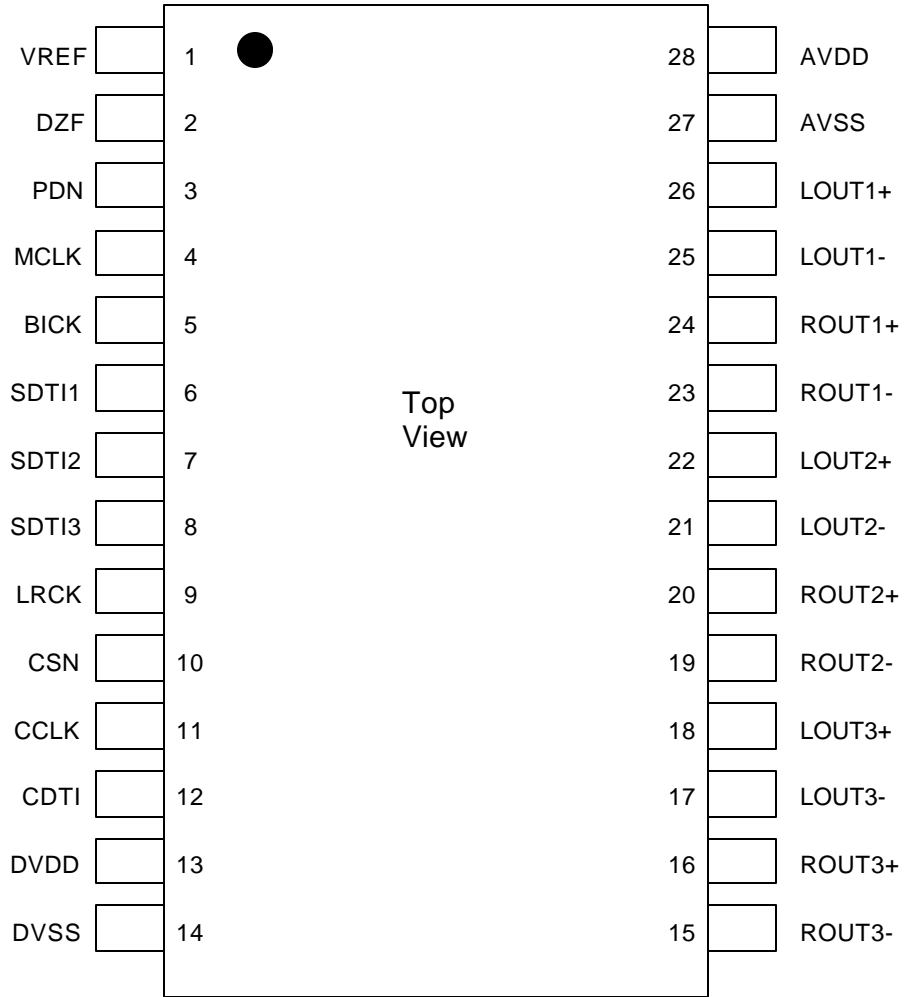
- Sampling Rate: 8kHz to 192kHz
- 24Bit 8 times Digital Filter with Slow roll-off option
- THD+N: -90dB
- DR, S/N: 106dB
- High Tolerance to Clock Jitter
- Low Distortion Differential Output
- Digital De-emphasis for 32, 44.1 & 48kHz sampling
- Zero Detect Pin
- Channel Independent Digital Attenuator with soft-transition
- Soft Mute
- I/F format: 24-Bit MSB justified, 24/20/16-Bit LSB justified or I²S
- Master Clock
 - Normal Speed: 256fs, 384fs, 512fs or 768fs
 - Double Speed: 128fs, 192fs, 256fs or 384fs
 - Quad Speed: 128fs, 192fs
- Power Supply: 4.75 to 5.25V
- 28pin VSOP Package



■ Ordering Guide

| | | |
|----------|-----------------------------|---------------------------|
| AK4355VF | -40 ~ +85°C | 28pin VSOP (0.65mm pitch) |
| AKD4355 | Evaluation Board for AK4355 | |

■ Pin Layout



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|---------------------|
| PIN/FUNCTION |
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| No. | Pin Name | I/O | Function |
|-----|----------|-----|--|
| 1 | VREF | I | Positive Voltage Reference Input Pin |
| 2 | DZF | O | Zero Input Detect Pin |
| 3 | PDN | I | Power-Down Mode Pin When at "L", the AK4355 is in the power-down mode and is held in reset. The AK4355 should always be reset upon power-up. |
| 4 | MCLK | I | Master Clock Input Pin An external TTL clock should be input on this pin. |
| 5 | BICK | I | Audio Serial Data Clock Pin |
| 6 | SDTI1 | I | DAC1 Audio Serial Data Input Pin |
| 7 | SDTI2 | I | DAC2 Audio Serial Data Input Pin |
| 8 | SDTI3 | I | DAC3 Audio Serial Data Input Pin |
| 9 | LRCK | I | L/R Clock Pin |
| 10 | CSN | I | Chip Select Pin |
| 11 | CCLK | I | Control Clock Pin |
| 12 | CDTI | I | Control Data Input Pin |
| 13 | DVDD | - | Digital Power Supply Pin |
| 14 | DVSS | - | Digital Ground Pin |
| 15 | ROUT3- | O | DAC3 Rch Negative Analog Output Pin |
| 16 | ROUT3+ | O | DAC3 Rch Positive Analog Output Pin |
| 17 | LOUT3- | O | DAC3 Lch Negative Analog Output Pin |
| 18 | LOUT3+ | O | DAC3 Lch Positive Analog Output Pin |
| 19 | ROUT2- | O | DAC2 Rch Negative Analog Output Pin |
| 20 | ROUT2+ | O | DAC2 Rch Positive Analog Output Pin |
| 21 | LOUT2- | O | DAC2 Lch Negative Analog Output Pin |
| 22 | LOUT2+ | O | DAC2 Lch Positive Analog Output Pin |
| 23 | ROUT1- | O | DAC1 Rch Negative Analog Output Pin |
| 24 | ROUT1+ | O | DAC1 Rch Positive Analog Output Pin |
| 25 | LOUT1- | O | DAC1 Lch Negative Analog Output Pin |
| 26 | LOUT1+ | O | DAC1 Lch Positive Analog Output Pin |
| 27 | AVSS | - | Analog Ground Pin |
| 28 | AVDD | - | Analog Power Supply Pin |

Note: All input pins should not be left floating.

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| ABSOLUTE MAXIMUM RATINGS |
|---------------------------------|

(AVSS, DVSS=0V; Note 1)

| Parameter | | Symbol | min | max | Units |
|--|---------------------|--------|------|----------|-------|
| Power Supplies | Analog | A VDD | -0.3 | 6.0 | V |
| | Digital | DVDD | -0.3 | 6.0 | V |
| | AVSS-DVSS (Note 2) | ΔGND | - | 0.3 | V |
| Input Current (any pins except for supplies) | | IIN | - | ±10 | mA |
| Analog Input Voltage | | VINA | -0.3 | AVDD+0.3 | V |
| Digital Input Voltage | | VIND | -0.3 | DVDD+0.3 | V |
| Ambient Operating Temperature | | Ta | -40 | 85 | °C |
| Storage Temperature | | Tstg | -65 | 150 | °C |

Note: 1. All voltages with respect to ground.

2. AVSS and DVSS must be connected to the same analog ground plane.

WARNING: Operation at or beyond these limits may results in permanent damage to the device.

Normal operation is not guaranteed at these extremes.

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| RECOMMENDED OPERATING CONDITIONS |
|---|

(AVSS, DVSS=0V; Note 1)

| Parameter | | Symbol | min | typ | max | Units |
|----------------------------|---------|--------|----------|-----|------|-------|
| Power Supplies (Note 3) | Analog | A VDD | 4.75 | 5.0 | 5.25 | V |
| | Digital | DVDD | 4.75 | 5.0 | 5.25 | V |
| Voltage Reference | | VREF | AVDD-0.5 | - | AVDD | V |

Note: 1. All voltages with respect to ground.

3. The power up sequence between AVDD and DVDD is not critical.

*AKM assumes no responsibility for the usage beyond the conditions in this datasheet.

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| ANALOG CHARACTERISTICS |
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(Ta=25°C; AVDD, DVDD=5V; VREF=AVDD; fs=44.1kHz; BICK=64fs; Signal Frequency=1kHz; 24bit Input Data; Measurement frequency=20Hz ~ 20kHz; R_L ≥4kΩ; unless otherwise specified)

| Parameter | min | typ | max | Units | |
|---|------------|---------|------|-------|-----------------|
| Resolution | | | 24 | Bits | |
| Dynamic Characteristics (Note 4) | | | | | |
| THD+N | fs=44.1kHz | 0dBFS | -90 | -86 | dB |
| | BW=20kHz | -60dBFS | -42 | - | dB |
| | fs=96kHz | 0dBFS | -88 | -84 | dB |
| | BW=40kHz | -60dBFS | -39 | - | dB |
| | fs=192kHz | 0dBFS | -86 | - | dB |
| | BW=40kHz | -60dBFS | -39 | - | dB |
| Dynamic Range (-60dBFS with A-weighted) | (Note 5) | 100 | 106 | dB | |
| S/N (A-weighted) | (Note 6) | 100 | 106 | dB | |
| Interchannel Isolation (1kHz) | | 90 | 100 | dB | |
| Interchannel Gain Mismatch | | | 0.2 | 0.5 | dB |
| DC Accuracy | | | | | |
| Gain Drift | | | 100 | - | ppm/°C |
| Output Voltage | (Note 7) | ±3.0 | ±3.2 | ±3.4 | V _{pp} |
| Load Resistance | (Note 8) | 4 | | | kΩ |
| Power Supplies | | | | | |
| Power Supply Current (AVDD+DVDD) | | | | | |
| Normal Operation (PDN = "H", fs ≤96kHz) | | | 49 | 75 | mA |
| Normal Operation (PDN = "H", fs=192kHz) | | | 55 | 80 | mA |
| Power-Down Mode (PDN = "L") | (Note 9) | | 10 | 100 | μA |

- Notes: 4. Measured by Audio Precision (System Two) or UPD. Refer to the evaluation board manual.
 5. 100dB at 16bit data.
 6. S/N does not depend on input bit length.
 7. Full-scale voltage (0dB). Output voltage scales with the voltage of VREF,
 $AOUT (typ. @0dB) = (AOUT+) - (AOUT-) = \pm 3.2V_{pp} \times VREF/5$.
 8. For AC-load. 4kΩ for DC-load.
 9. All digital inputs including clock pins (MCLK, BICK and LRCK) are held DVDD or DVSS.

SHARP ROLL-OFF FILTER CHARACTERISTICS

($T_a = 25^\circ\text{C}$; AVDD, DVDD = 4.75 ~ 5.25V; $f_s = 44.1\text{kHz}$; DEM = OFF; SLOW='0')

| Parameter | Symbol | min | typ | max | Units | |
|-----------------------------|-------------------------------|----------------------|-------|------------|-----------|----|
| Digital filter | | | | | | |
| Passband | $\pm 0.05\text{dB}$ (Note 10) | PB | 0 | 20.0 | kHz | |
| | | | - | 22.05 | kHz | |
| Stopband | (Note 10) | SB | 24.25 | | kHz | |
| Passband Ripple | | PR | | ± 0.02 | dB | |
| Stopband Attenuation | | SA | 54 | | dB | |
| Group Delay | (Note 11) | GD | - | 20.5 | 1/ f_s | |
| Digital Filter + LPF | | | | | | |
| Frequency Response | 20.0kHz | $f_s=44.1\text{kHz}$ | FR | - | ± 0.2 | dB |
| | 40.0kHz | $f_s=96\text{kHz}$ | FR | - | ± 0.3 | dB |
| | 80.0kHz | $f_s=192\text{kHz}$ | FR | - | +0/-0.6 | dB |

Notes: 10. The passband and stopband frequencies scale with f_s (system sampling rate).

For example, $\text{PB}=0.4535 \times f_s$ ($\pm 0.05\text{dB}$), $\text{SB}=0.546 \times f_s$.

11. The calculating delay time which occurred by digital filtering. This time is from setting the 16/24bit data of both channels to input register to the output of analog signal.

SLOW ROLL-OFF FILTER CHARACTERISTICS

($T_a = 25^\circ\text{C}$; AVDD, DVDD = 4.75~5.25V; $f_s = 44.1\text{kHz}$; DEM = OFF; SLOW = "1")

| Parameter | Symbol | min | Typ | max | Units | |
|-----------------------------|-------------------------------|----------------------|------|-------------|----------|----|
| Digital Filter | | | | | | |
| Passband | $\pm 0.04\text{dB}$ (Note 12) | PB | 0 | 8.1 | kHz | |
| | | | - | 18.2 | kHz | |
| Stopband | (Note 12) | SB | 39.2 | | kHz | |
| Passband Ripple | | PR | | ± 0.005 | dB | |
| Stopband Attenuation | | SA | 72 | | dB | |
| Group Delay | (Note 11) | GD | - | 20.5 | 1/ f_s | |
| Digital Filter + SCF | | | | | | |
| Frequency Response | 20.0kHz | $f_s=44.1\text{kHz}$ | FR | - | +0/-5 | dB |
| | 40.0kHz | $f_s=96\text{kHz}$ | FR | - | +0/-4 | dB |
| | 80.0kHz | $f_s=192\text{kHz}$ | FR | - | +0/-5 | dB |

Note: 12. The passband and stopband frequencies scale with f_s .

For example, $\text{PB} = 0.185 \times f_s$ ($\pm 0.04\text{dB}$), $\text{SB} = 0.888 \times f_s$.

DC CHARACTERISTICS

($T_a=25^\circ\text{C}$; AVDD, DVDD = 4.75 ~ 5.25V)

| Parameter | Symbol | min | Typ | max | Units |
|---|-----------------|----------|-----|----------|---------|
| High-Level Input Voltage | V _{IH} | 2.2 | - | - | V |
| Low-Level Input Voltage | V _{IL} | - | - | 0.8 | V |
| High-Level Output Voltage (I _{out} =-80 μ A) | V _{OH} | DVDD-0.4 | - | - | V |
| Low-Level Output Voltage (I _{out} =80 μ A) | V _{OL} | - | - | 0.4 | V |
| Input Leakage Current | I _{in} | - | - | ± 10 | μ A |

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| SWITCHING CHARACTERISTICS |
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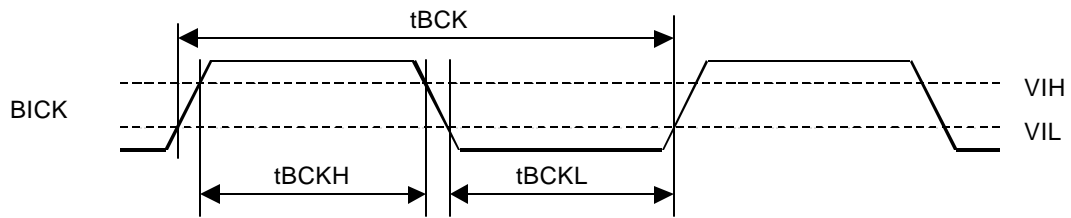
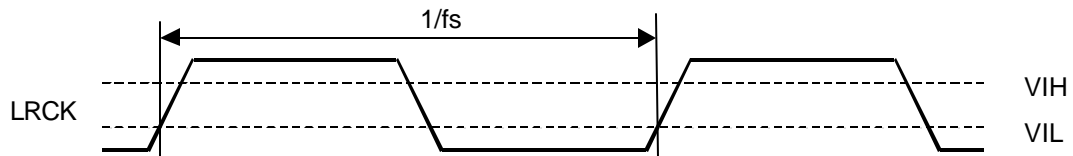
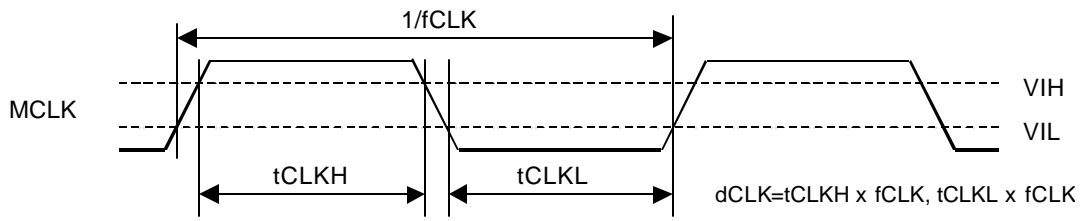
(Ta=25°C; AVDD, DVDD = 4.75 ~ 5.25V; C_I=20pF)

| Parameter | Symbol | min | typ | max | Units |
|------------------------------------|-------------------|---------|---------|--------|-------|
| Master Clock Frequency | fCLK | 2.048 | 11.2896 | 36.864 | MHz |
| Duty Cycle | dCLK | 40 | | 60 | % |
| LRCK Frequency | | | | | |
| Normal Speed Mode | f _{sn} | 8 | | 48 | kHz |
| Double Speed Mode | f _{sd} | 60 | | 96 | kHz |
| Quad Speed Mode | f _{sq} | 120 | | 192 | kHz |
| Duty Cycle | Duty | 45 | | 55 | % |
| Audio Interface Timing | | | | | |
| BICK Period | | | | | |
| Normal Speed Mode | t _{BCK} | 1/128fs | | | ns |
| Double/Quad Speed Mode | t _{BCK} | 1/64fs | | | ns |
| BICK Pulse Width Low | t _{BCKL} | 30 | | | ns |
| Pulse Width High | t _{BCKH} | 30 | | | ns |
| BICK rising to LRCK Edge (Note 13) | t _{BLR} | 20 | | | ns |
| LRCK Edge to BICK rising (Note 13) | t _{LRB} | 20 | | | ns |
| SDTI Hold Time | t _{SDH} | 20 | | | ns |
| SDTI Setup Time | t _{SDS} | 20 | | | ns |
| Control Interface Timing | | | | | |
| CCLK Period | t _{CCK} | 200 | | | |
| CCLK Pulse Width Low | t _{CCKL} | 80 | | | ns |
| Pulse Width High | t _{CCKH} | 80 | | | ns |
| CDTI Setup Time | t _{CDS} | 40 | | | ns |
| CDTI Hold Time | t _{CDH} | 40 | | | ns |
| CSN "H" Time | t _{CSW} | 150 | | | ns |
| CSN "↓" to CCLK "↑" | t _{CSS} | 50 | | | ns |
| CCLK "↑" to CSN "↑" | t _{CSH} | 50 | | | ns |
| Reset Timing | | | | | |
| PDN Pulse Width (Note 14) | t _{PD} | 150 | | | ns |

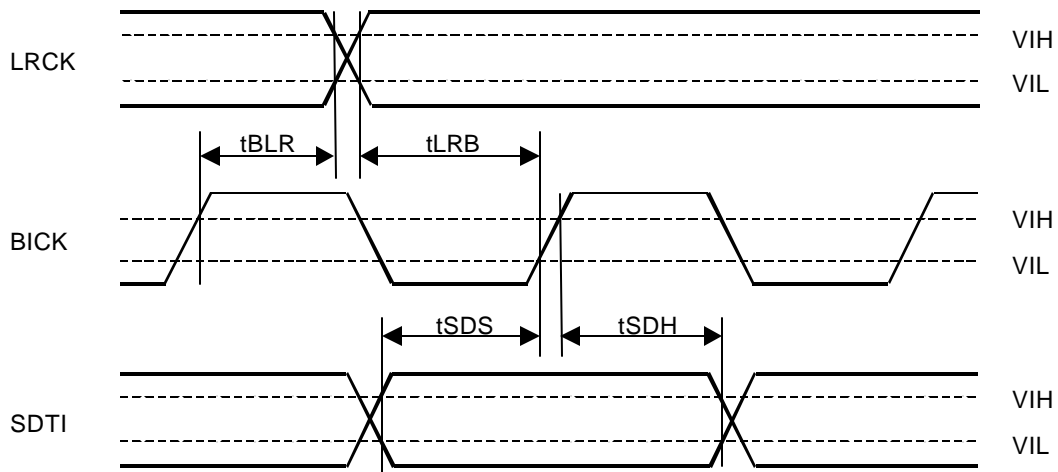
Notes: 13. BICK rising edge must not occur at the same time as LRCK edge.

14. The AK4355 can be reset by bringing PDN= "L".

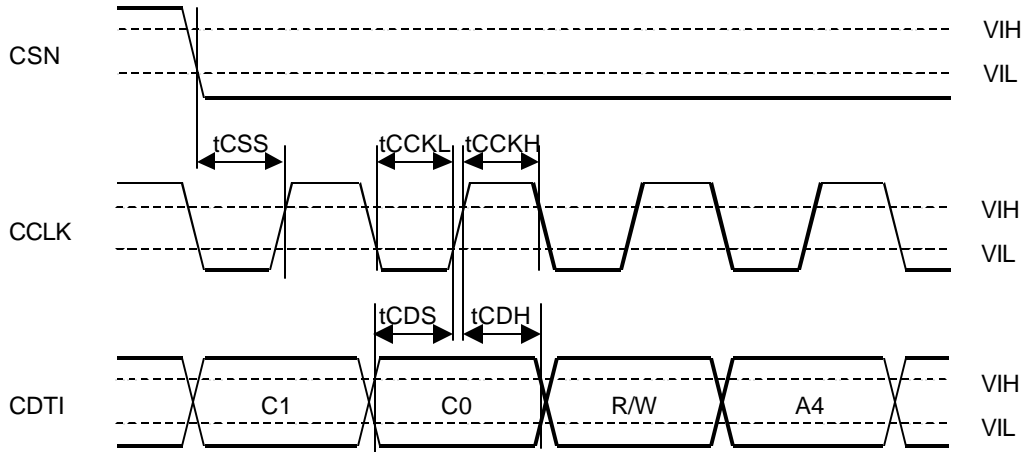
■ Timing Diagram



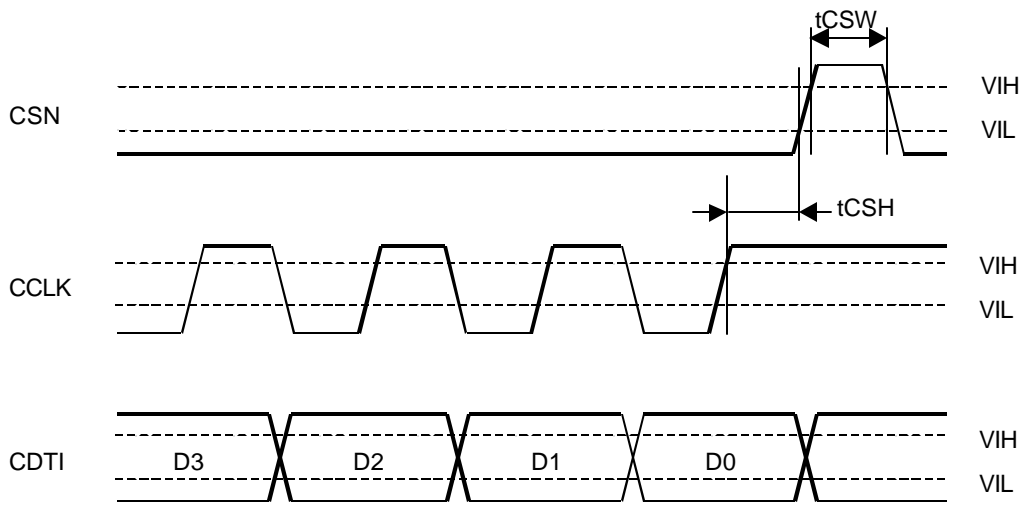
Clock Timing



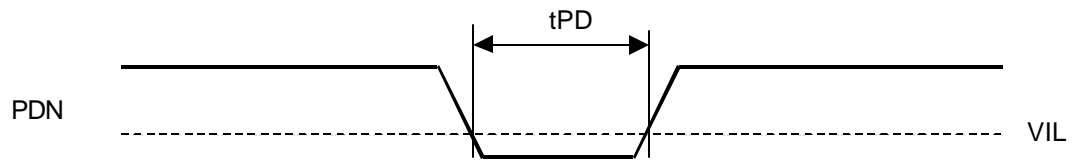
Serial Interface Timing



WRITE Command Input Timing



WRITE Data Input Timing



Power-down Timing

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| OPERATION OVERVIEW |
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■ System Clock

The external clocks, which are required to operate the AK4355, are MCLK, LRCK and BICK. The master clock (MCLK) should be synchronized with LRCK but the phase is not critical. The MCLK is used to operate the digital interpolation filter and the delta-sigma modulator. There are two methods to set MCLK frequency. In Manual Setting Mode (ACKS = "0": Register 00H), the sampling speed is set by DFS0/1 (Table 1). The frequency of MCLK at each sampling speed is set automatically. (Table 2~4). In Auto Setting Mode (ACKS = "1": Default), as MCLK frequency is detected automatically (Table 5), and the internal master clock becomes the appropriate frequency (Table 6), it is not necessary to set DFS0/1.

All external clocks (MCLK, BICK and LRCK) should always be present whenever the AK4355 is in the normal operation mode (PDN="H"). If these clocks are not provided, the AK4355 may draw excess current may fall into unpredictable operation. This is because the device utilizes dynamic refreshed logic internally. The AK4355 should be reset by PDN="L" after these clocks are provided. If the external clocks are not present, the AK4355 should be in the power-down mode (PDN="L"). After exiting reset at power-up etc., the AK4355 is in the power-down mode until MCLK and LRCK are input.

| DFS1 | DFS0 | Sampling Rate (fs) | | Default |
|------|------|--------------------|---------------|---------|
| 0 | 0 | Normal Speed Mode | 8kHz~48kHz | |
| 0 | 1 | Double Speed Mode | 60kHz~96kHz | |
| 1 | 0 | Quad Speed Mode | 120kHz~192kHz | |

Table 1. Sampling Speed (Manual Setting Mode)

| LRCK | MCLK | | | | BICK |
|---------|------------|------------|------------|------------|-----------|
| | fs | 256fs | 384fs | 512fs | |
| 32.0kHz | 8.1920MHz | 12.2880MHz | 16.3840MHz | 24.5760MHz | 2.0480MHz |
| 44.1kHz | 11.2896MHz | 16.9344MHz | 22.5792MHz | 33.8688MHz | 2.8224MHz |
| 48.0kHz | 12.2880MHz | 18.4320MHz | 24.5760MHz | 36.8640MHz | 3.0720MHz |

Table 2. System Clock Example (Normal Speed Mode @Manual Setting Mode)

| LRCK | MCLK | | | | BICK |
|---------|------------|------------|------------|------------|-----------|
| | fs | 128fs | 192fs | 256fs | |
| 88.2kHz | 11.2896MHz | 16.9344MHz | 22.5792MHz | 33.8688MHz | 5.6448MHz |
| 96.0kHz | 12.2880MHz | 18.4320MHz | 24.5760MHz | 36.8640MHz | 6.1440MHz |

Table 3. System Clock Example (Double Speed Mode @Manual Setting Mode)

| LRCK | MCLK | | BICK |
|----------|------------|------------|------------|
| | fs | 128fs | |
| 176.4kHz | 22.5792MHz | 33.8688MHz | 11.2896MHz |
| 192.0kHz | 24.5760MHz | 36.8640MHz | 12.2880MHz |

Table 4. System Clock Example (Quad Speed Mode @Manual Setting Mode)

| MCLK | | Sampling Speed |
|-------|-------|----------------|
| 512fs | 768fs | Normal |
| 256fs | 384fs | Double |
| 128fs | 192fs | Quad |

Table 5. Sampling Speed (Auto Setting Mode)

| LRCK | MCLK (MHz) | | | | | | Sampling Speed | |
|----------|------------|---------|---------|---------|-------|---------|----------------|--------|
| | fs | 128fs | 192fs | 256fs | 384fs | 512fs | | 768fs |
| 32.0kHz | - | - | - | - | - | 16.3840 | 24.5760 | Normal |
| 44.1kHz | - | - | - | - | - | 22.5792 | 33.8688 | |
| 48.0kHz | - | - | - | - | - | 24.5760 | 36.8640 | |
| 88.2kHz | - | - | 22.5792 | 33.8688 | - | - | - | Double |
| 96.0kHz | - | - | 24.5760 | 36.8640 | - | - | - | |
| 176.4kHz | 22.5792 | 33.8688 | - | - | - | - | - | Quad |
| 192.0kHz | 24.5760 | 36.8640 | - | - | - | - | - | |

Table 6. System Clock Example (Auto Setting Mode)

■ Audio Serial Interface Format

Data is shifted in via these SDTI1, SDTI2, and SDTI3 pins using BICK and LRCK inputs. The DIF0-2 as shown in Table 7 can select five serial data modes. In all modes the serial data is MSB-first, 2's complement format and is latched on the rising edge of BICK. Mode 2 can be used for 16/20 MSB justified formats by zeroing the unused LSBs.

| Mode | DIF2 | DIF1 | DIF0 | SDTI Format | BICK | Figure |
|------|------|------|------|-----------------------------------|-------|----------|
| 0 | 0 | 0 | 0 | 16bit LSB Justified | ≥32fs | Figure 1 |
| 1 | 0 | 0 | 1 | 20bit LSB Justified | ≥40fs | Figure 2 |
| 2 | 0 | 1 | 0 | 24bit MSB Justified | ≥48fs | Figure 3 |
| 3 | 0 | 1 | 1 | 24bit I ² S Compatible | ≥48fs | Figure 4 |
| 4 | 1 | 0 | 0 | 24bit LSB Justified | ≥48fs | Figure 2 |

Default

Table 7. Audio Data Formats

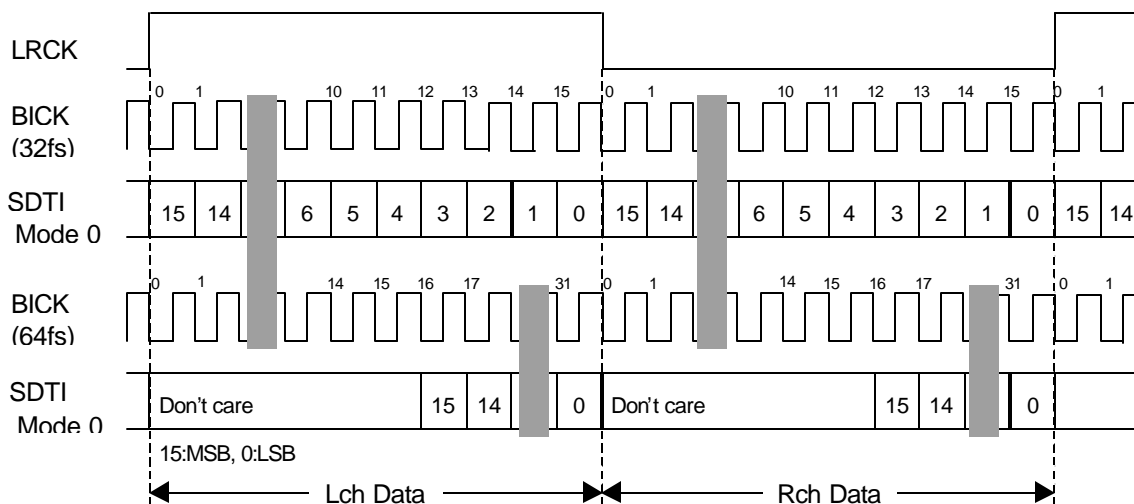


Figure 1. Mode 0 Timing

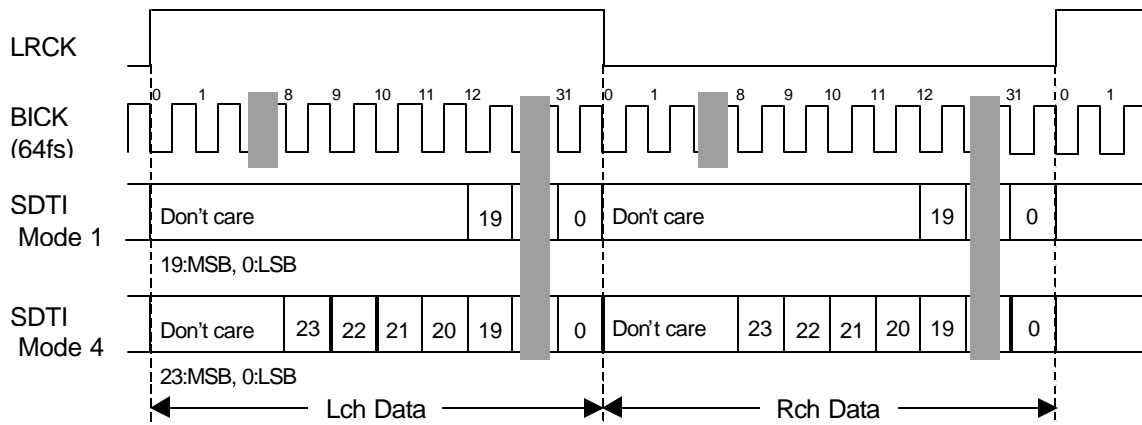


Figure 2. Mode 1,4 Timing

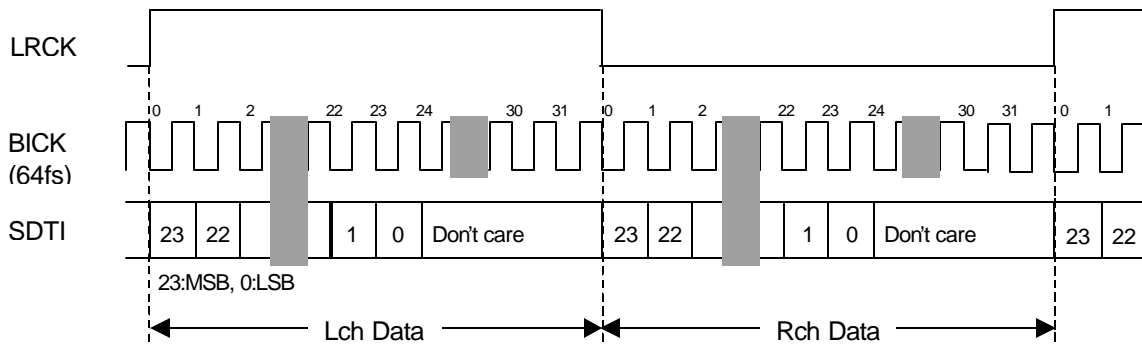


Figure 3. Mode 2 Timing

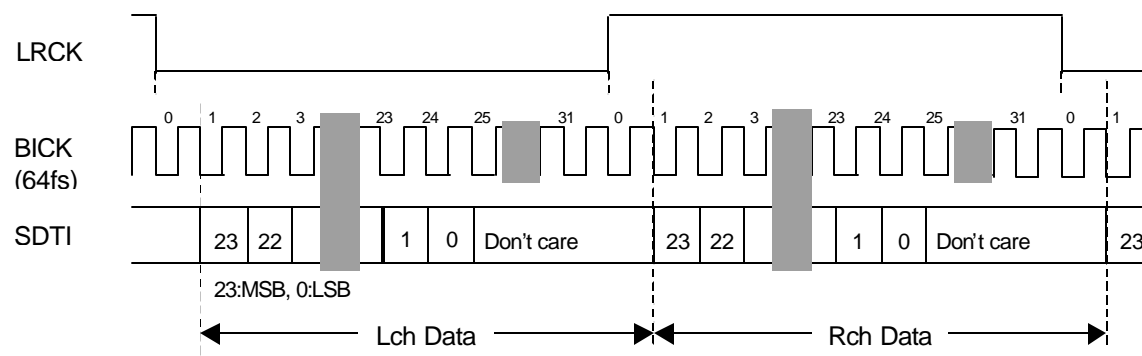


Figure 4. Mode 3 Timing

■ De-emphasis Filter

A digital de-emphasis filter is available for 32, 44.1 or 48kHz sampling rates ($t_c = 50/15\mu s$) and is enabled or disabled with DEM0 and DEM1. In case of double speed and quad speed mode, the digital de-emphasis filter is always off.

| DEM1 | DEM0 | Mode |
|------|------|---------|
| 0 | 0 | 44.1kHz |
| 0 | 1 | OFF |
| 1 | 0 | 48kHz |
| 1 | 1 | 32kHz |

Default

Table 8. De-emphasis Filter Control (Normal Speed Mode)

■ Output Volume

The AK4355 includes channel independent digital output volumes (ATT) with 256 levels including MUTE and 0.5dB step. These volumes are in front of the DAC and can attenuate the input data from 0dB to -127dB and mute. Transition time is set by AST1-0 bits (Table 10). In Mode0 and Mode1, when changing levels, transitions are executed via soft changes; thus no switching noise occurs during these transitions.

| ATT7-0 | Attenuation Level |
|--------|-------------------|
| FFH | 0dB |
| FEH | -0.5dB |
| FDH | -1.0dB |
| : | : |
| 02H | -126.5dB |
| 01H | -127.0dB |
| 00H | MUTE (∞) |

Default

Table 9. Attenuation Level of Output Volume

| Mode | ATS1 | ATS0 | ATT speed |
|------|------|------|-----------|
| 0 | 0 | 0 | 7424/fs |
| 1 | 0 | 1 | 1061/fs |
| 2 | 1 | 0 | 256/fs |
| 3 | 1 | 1 | Reserved |

Default

Table 10. Transition time of output volume

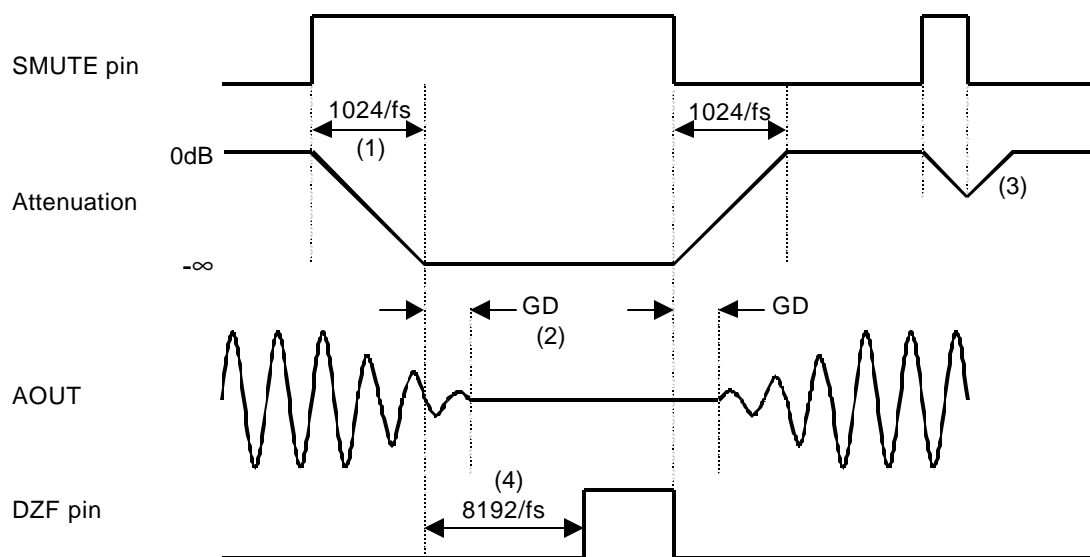
In case of Mode0, it takes $7424/fs$ ($168ms@fs=44.1k$) to transit from FFH(0dB) to 00H(MUTE). In case of Mode1, it takes $1061/fs$ ($24ms@fs=44.1k$) to transit from FFH(0dB) to 00H(MUTE). In case Mode2 and 3, it takes $256/fs$ ($6ms@fs=44.1k$) to transit from FFH(0dB) to 00H(MUTE). If PDN pin goes to "L", ATT7-0 registers are initialized to FFH. ATTN7-0 registers go to FFH when RSTN bit is set to "0". When RSTN bit returns to "1", ATT7-0 registers go to the set value. Digital output volume function is independent of soft mute function.

■ Zero Detection

When the input data at all channel is continuously zeros for 8192 LRCK cycles, DZF pin goes to “H”. DZF pin immediately goes to “L” if input data of each channel is not zero after going DZF “H”. If RSTN bit is “0”, DZF pin goes to “H”. DZF pin goes to “L” at 4~5LRCK if input data of each channel is not zero after RSTN bit returns to “1”. Zero detect function can be disabled by DZFE bit. In this case, DZF pins of both channels are always “L”. DZFB bit can invert the polarity of DZF pin. When one of PW1-3 bit is set to “0”, the input data of DAC which the PW bit is set to “0” should be zero in order to enable zero detection of the other channels. When all PW1-3 bits are set to “0”, DZF pin fixes “L”.

■ Soft Mute Operation

Soft mute operation is performed at digital domain. When the SMUTE bit goes to “1”, the output signal is attenuated by $-\infty$ during 1024 LRCK cycles. When the SMUTE bit is returned to “0”, the mute is cancelled and the output attenuation gradually changes to 0dB during 1024 LRCK cycles. If the soft mute is cancelled within 1024 LRCK cycles after starting the operation, the attenuation is discontinued and returned to 0dB. The soft mute is effective for changing the signal source without stopping the signal transmission.



Notes:

- (1) The output signal is attenuated by $-\infty$ during 1024 LRCK cycles ($1024/f_s$).
- (2) The analog output corresponding to the digital input has a group delay, GD.
- (3) If the soft mute is cancelled within 1024 LRCK cycles, the attenuation is discontinued and returned to 0dB.
- (4) When the input data at each channel is continuously zeros for 8192 LRCK cycles, DZF pin of each channel goes to “H”. DZF pin immediately goes to “L” if input data are not zero after going DZF “H”.

Figure 5. Soft Mute and Zero Detection

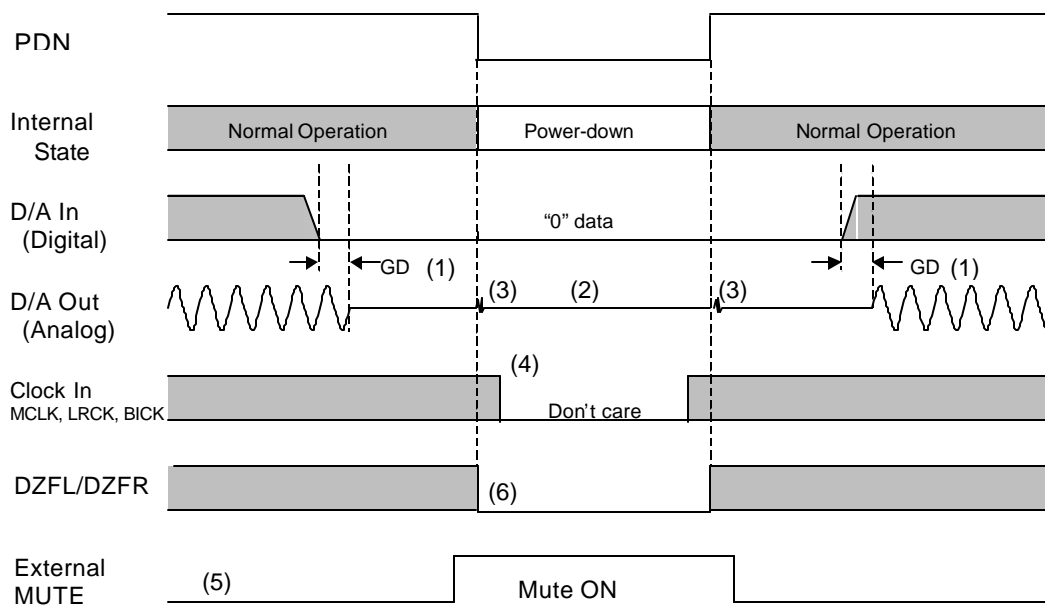
■ System Reset

The AK4355 should be reset once by bringing PDN="L" upon power-up. The AK4355 is powered up and the internal timing starts clocking by LRCK "↑" after exiting reset and power down state by MCLK. The AK4355 is in the power-down mode until MCLK and LRCK are input.

■ Power-down

The AK4355 is placed in the power-down mode by bringing PDN pin "L" and the analog outputs are floating (Hi-Z). Figure 6 shows an example of the system timing at the power-down and power-up.

Each DAC can be powered down by each power-down bit (PW1-3) "0". In this case, the internal register values are not initialized and the analog output is Hi-Z. Because some click noise occurs, the analog output should be muted externally if the click noise influences system application.



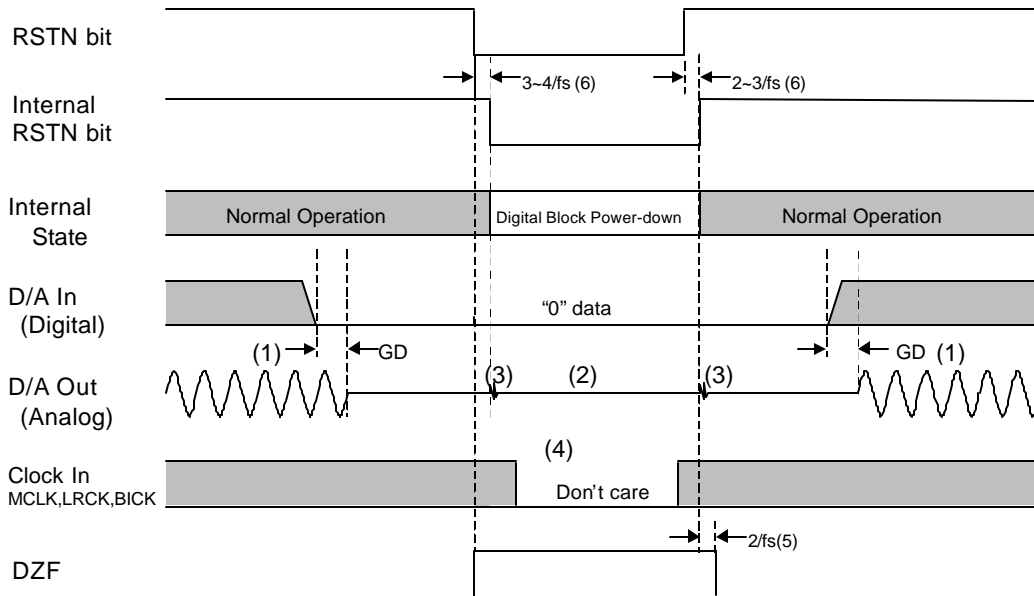
Notes:

- (1) The analog output corresponding to digital input has the group delay (GD).
- (2) Analog outputs are floating (Hi-Z) at the power-down mode.
- (3) Click noise occurs at the edge of PDN signal. This noise is output even if "0" data is input.
- (4) The external clocks (MCLK, BICK and LRCK) can be stopped in the power-down mode (PDN = "L").
- (5) Please mute the analog output externally if the click noise (3) influences system application.
The timing example is shown in this figure.
- (6) DZF pins are "L" in the power-down mode (PDN = "L").

Figure 6. Power-down/up Sequence Example

■ Reset Function

When RSTN=0, DAC is powered down but the internal register values are not initialized. The analog outputs go to AVDD/2 voltage and DZF pin goes to "H". Figure 7 shows the example of reset by RSTN bit.



Notes:

- (1) The analog output corresponding to digital input has the group delay (GD).
- (2) Analog outputs go to AVDD/2
- (3) Click noise occurs at the edges ("↑↓") of the internal timing of RSTN bit. This noise is output even if "0" data is input.
- (4) The external clocks (MCLK, BICK and LRCK) can be stopped in the reset mode (RSTN = "L").
- (5) DZF pins go to "H" when the RSTN bit becomes "0", and go to "L" at $2/f_s$ after RSTN bit becomes "1".
- (6) There is a delay, $3\sim 4/f_s$ from RSTN bit "0" to the internal RSTN bit "0", and $2\sim 3/f_s$ from RSTN bit "1" to the internal RSTN "1".

Figure 7. Reset Sequence Example

■ Mode Control Interface

Internal registers may be written by 3-wire μ P interface pins, CSN, CCLK and CDTI. The data on this interface consists of Chip Address (2bits, C1/0; fixed to “11”), Read/Write (1bit; fixed to “1”, Write only), Register Address (MSB first, 5bits) and Control Data (MSB first, 8bits). The AK4355 latches the data on the rising edge of CCLK, so data should be clocked in on the falling edge. The writing of data becomes valid by CSN “ \uparrow ”. The clock speed of CCLK is 5MHz (max).

PDN = “L” resets the registers to their default values. The internal timing circuit is reset by RSTN bit, but the registers are not initialized.

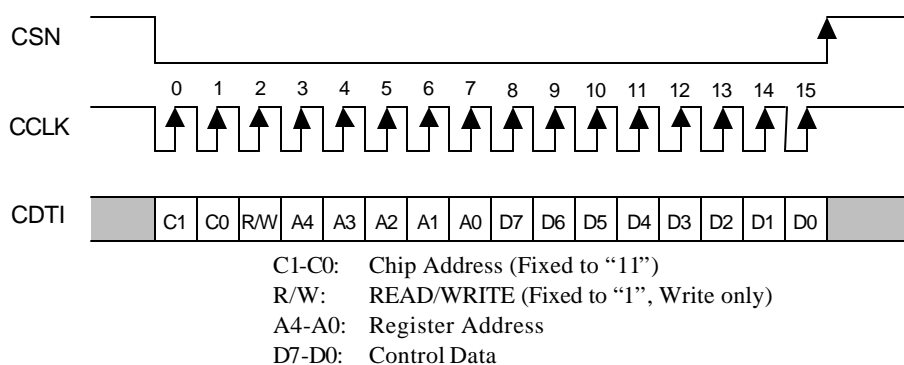


Figure 8. Control I/F Timing

*AK4355 does not support the read command and chip address. C1/0 and R/W are fixed to “11”

*When the AK4355 is in the power down mode (PDN = “L”) or the MCLK is not provided, writing into the control register is inhibited.

■ Register Map

| Addr | Register Name | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|----------------------------|------|------|------|------|------|------|-------|------|
| 00H | Control 1 | ACKS | SLOW | 0 | DZFE | DIF2 | DIF1 | DIF0 | RSTN |
| 01H | Control 2 | 0 | 0 | 0 | 0 | 0 | 0 | SMUTE | RSTN |
| 02H | Speed & Power Down Control | 0 | 0 | DFS1 | DFS0 | PW3 | PW2 | PW1 | RSTN |
| 03H | De-emphasis Control | 0 | 0 | 0 | 0 | 0 | 0 | DEM1 | DEM0 |
| 04H | LOUT1 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 05H | ROUT1 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 06H | LOUT2 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 07H | ROUT2 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 08H | LOUT3 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 09H | ROUT3 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 0AH | Control 3 | 0 | 0 | 0 | 0 | 0 | DZFB | ATS1 | ATS0 |

Notes:

For addresses from 0BH to 1FH, data must not be written.

When PDN pin goes “L”, the registers are initialized to their default values.

When RSTN bit goes to “0”, the internal timing is reset, DZF pin go to “H” but registers are not initialized to their default values.

■ Register Definitions

| Addr | Register Name | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|------|------|----|------|------|------|------|------|
| 00H | Control 1 | ACKS | SLOW | 0 | DZFE | DIF2 | DIF1 | DIF0 | RSTN |
| | Default | 1 | 0 | 0 | 1 | 0 | 1 | 0 | 1 |

RSTN: Internal timing reset

0: Reset. DZF pin goes to “H” and registers are not initialized.

1: Normal operation

When MCLK frequency or DFS changes, the AK4355 should be reset by PDN pin or RSTN bit.

DIF2-0: Audio data interface modes (See Table 7)

Initial: “010”, Mode 2

DZFE: Data Zero Detect Enable

0: Disable

1: Enable

Zero detect function can be disabled by DZFE bit.

SLOW: Slow roll-off response enable

0: Disable

1: Enable

ACKS: Master Clock Frequency Auto Setting Mode Enable

0: Disable, Manual Setting Mode

1: Enable, Auto Setting Mode

Master clock frequency is detected automatically at ACKS bit “1”. In this case, the setting of DFS1-0 are ignored. When this bit is “0”, DFS1-0 set the sampling speed mode.

| Addr | Register Name | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|----|----|----|----|----|----|-------|------|
| 01H | Control 2 | 0 | 0 | 0 | 0 | 0 | 0 | SMUTE | RSTN |
| | Default | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

RSTN: Internal timing reset

0: Reset. DZF pin goes to “H” and registers are not initialized.

1: Normal operation

When MCLK frequency or DFS changes, the AK4355 should be reset by PDN pin or RSTN bit.

SMUTE: Soft Mute Enable

0: Normal operation

1: All DAC outputs soft -muted

| Addr | Register Name | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|----------------------------|----|----|------|------|-----|-----|-----|------|
| 02H | Speed & Power Down Control | 0 | 0 | DFS1 | DFS0 | PW3 | PW2 | PW1 | RSTN |
| | Default | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 |

RSTN: Internal timing reset

0: Reset. DZF pin goes to "H" and registers are not initialized.

1: Normal operation

When MCLK frequency or DFS changes, the AK4355 should be reset by PDN pin or RSTN bit.

PW3-1: Power-down control (0: Power-down, 1: Power-up)

PW1: Power down control of DAC1

PW2: Power down control of DAC2

PW3: Power down control of DAC3

All sections are powered-down by PW1=PW2=PW3=0.

DFS1-0: Sampling speed control (See Table 1)

00: Normal speed

01: Double speed

10: 4 times speed

| Addr | Register Name | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------------|----|----|----|----|----|----|------|------|
| 03H | De-emphasis Control | 0 | 0 | 0 | 0 | 0 | 0 | DEM1 | DEM0 |
| | Default | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

DEM1-0: De-emphasis response control for DAC1/2/3 data on SDTI1/2/3/ (See Table 8)

Initial: "01", OFF

| Addr | Register Name | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|-------------------|------|------|------|------|------|------|------|------|
| 04H | LOUT1 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 05H | ROUT1 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 06H | LOUT2 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 07H | ROUT2 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 08H | LOUT3 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| 09H | ROUT3 ATT Control | ATT7 | ATT6 | ATT5 | ATT4 | ATT3 | ATT2 | ATT1 | ATT0 |
| | Default | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

ATT7-0: Attenuation Level

256 levels, 0.5dB step (See Table 9)

| Addr | Register Name | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|---------------|----|----|----|----|----|------|------|------|
| 0AH | Control 3 | 0 | 0 | 0 | 0 | 0 | DZFB | ATS1 | ATS0 |
| | Default | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ATS1-0: DATT Speed Setting (See Table 10)

Initial: "00", mode 0

DZFB: Inverting Enable of DZF

0: DZF goes "H" at Zero Detection

1: DZF goes "L" at Zero Detection

SYSTEM DESIGN

Figure 9 shows the system connection diagram. An evaluation board (AKD4355) is available in order to allow an easy study on the layout of a surrounding circuit.

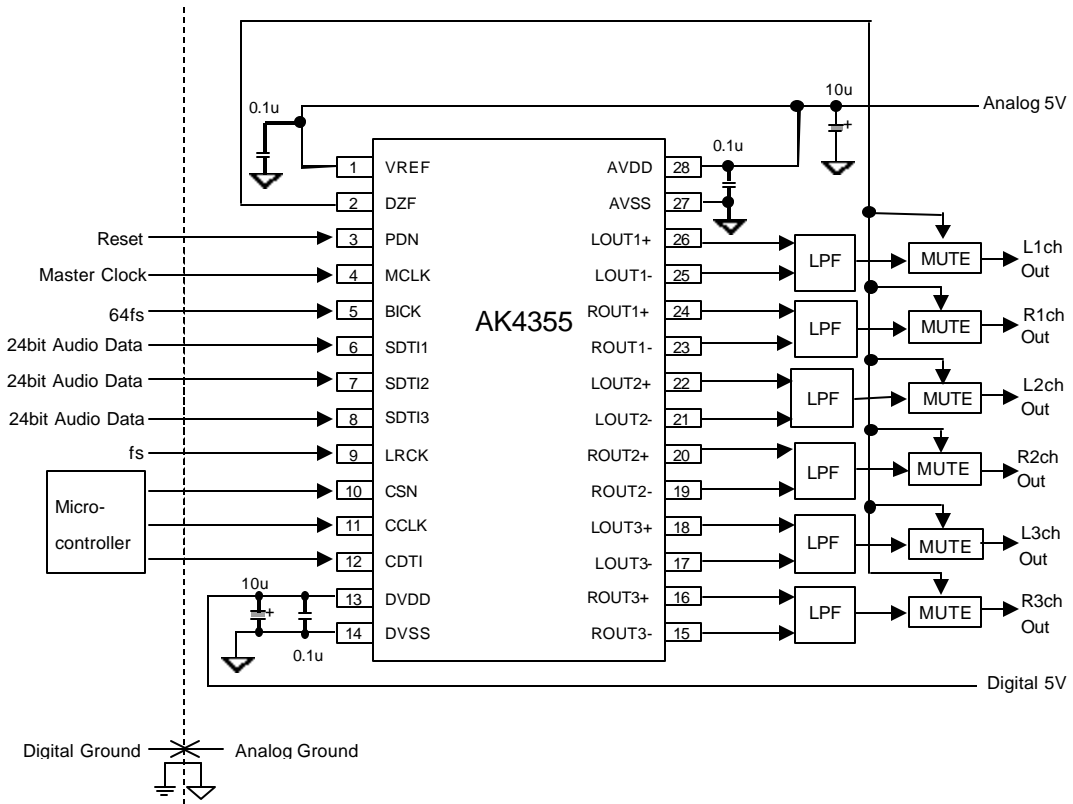


Figure 9. Typical Connection Diagram

Notes:

- LRCK = fs, BICK = 64fs.
- When AOUT drives some capacitive load, some resistor should be added in series between AOUT and capacitive load.
- All input pins should not be left floating.

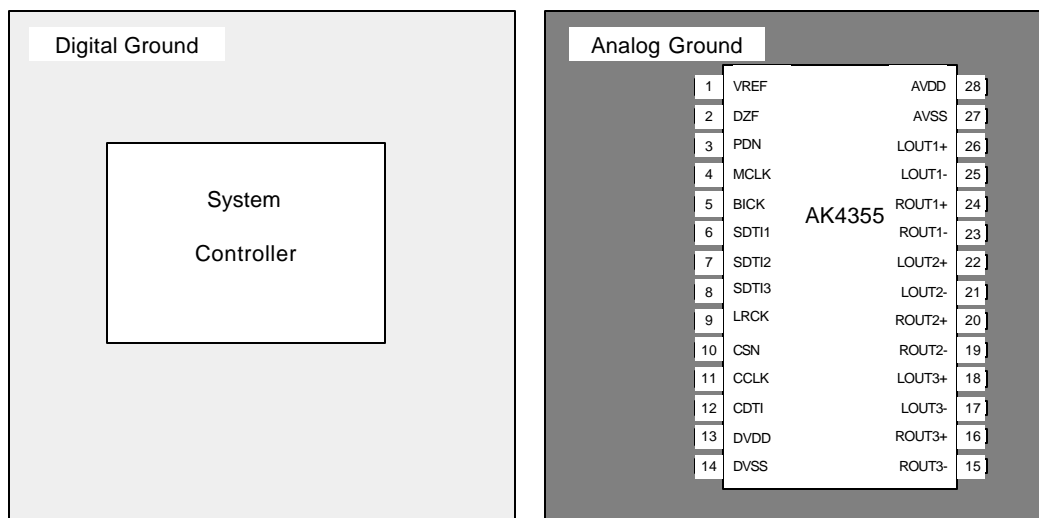


Figure10. Ground Layout

Note: AVSS and DVSS must be connected to the same analog ground plane.

1. Grounding and Power Supply Decoupling

The AK4355 requires careful attention to power supply and grounding arrangements. AVDD and DVDD are usually supplied from analog supply in system. Alternatively if AVDD and DVDD are supplied separately, the power up sequence is not critical. **AVSS and DVSS of the AK4355 must be connected to analog ground plane.** System analog ground and digital ground should be connected together near to where the supplies are brought onto the printed circuit board. Decoupling capacitors should be near to the AK4355 as possible, with the small value ceramic capacitors being the nearest.

2. Voltage Reference Inputs

VREF sets the analog output range. VREF pin is normally connected to AVDD with a 0.1 μ F ceramic capacitor. All signals, especially clocks, should be kept away from the VREF pin in order to avoid unwanted coupling into the AK4355

3. Analog Outputs

The analog outputs are full-differential outputs and $0.64 \times VREFH$ V_{pp} (typ) centered around the internal common voltage (about AVDD/2). The differential outputs are summed externally, $V_{AOUT} = (AOUT+) - (AOUT-)$ between AOUT+ and AOUT-. If the summing gain is 1, the output range is 6.4V_{pp} (typ @ VREFH=5V). The bias voltage of the external summing circuit is supplied externally. The input data format is 2's complement. The output voltage (V_{AOUT}) is a positive full scale for 7FFFFFFF (@24bit) and a negative full scale for 800000H (@24bit). The ideal V_{AOUT} is 0V for 000000H (@24bit).

The internal switched-capacitor filter and external low pass filter attenuate the noise generated by the delta-sigma modulator beyond the audio passband. DC offset on AOUT+/- is eliminated without AC coupling since the analog outputs are differential. Figure 11 and 12 show the example of external op-amp circuit summing the differential outputs.

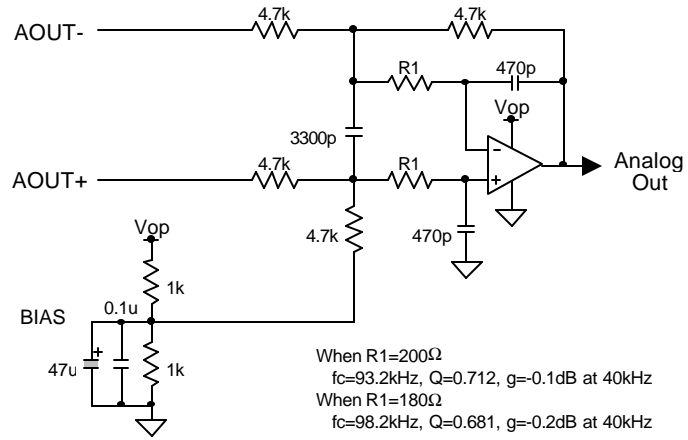


Figure 11 External 2nd order LPF Circuit Example (using op-amp with single power supply)

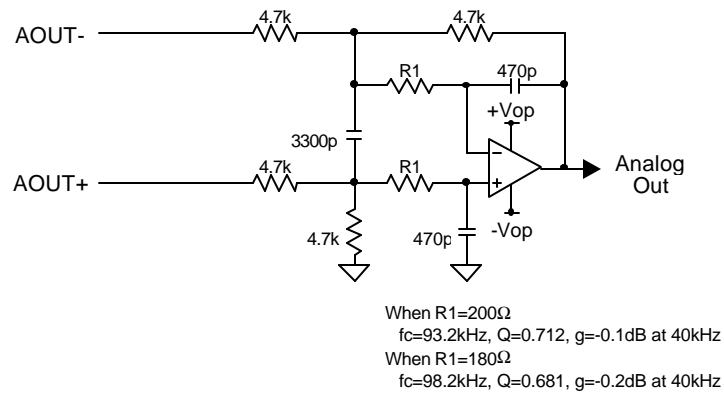
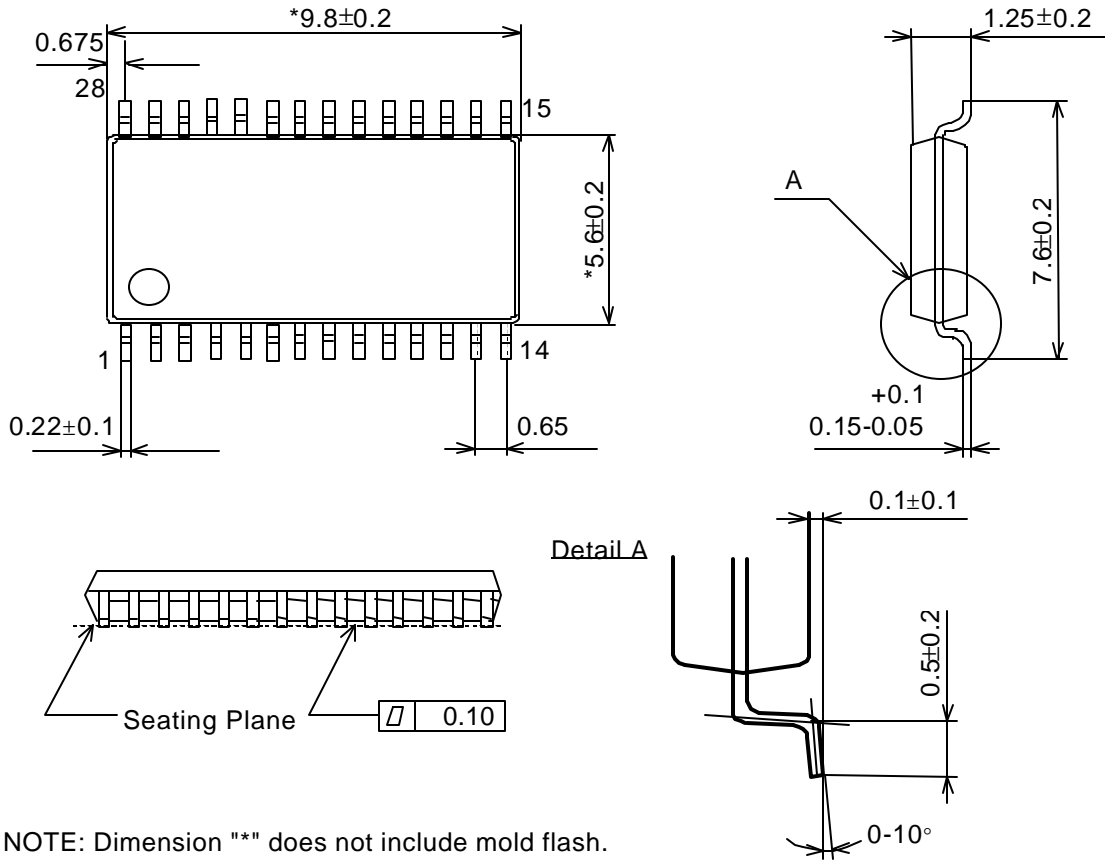


Figure 12 External 2nd order LPF Circuit Example (using op-amp with dual power supplies)

PACKAGE

28pin VSOP (Unit: mm)

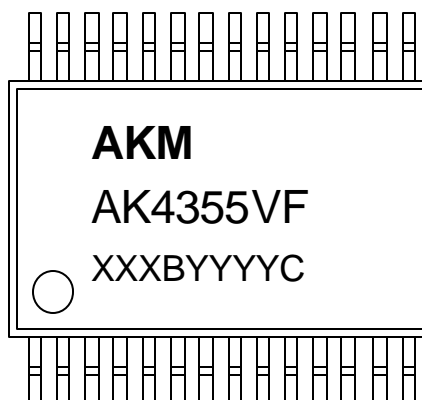


NOTE: Dimension "*" does not include mold flash.

■ **Package & Lead frame material**

- Package molding compound: Epoxy
- Lead frame material: Cu
- Lead frame surface treatment: Solder (Pb free) plate

| |
|----------------|
| MARKING |
|----------------|



XXXXBYYYYC date code identifier

XXXB: Lot number (X : Digit number, B : Alpha character)

YYYYC: Assembly date (Y : Digit number, C : Alpha character)

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