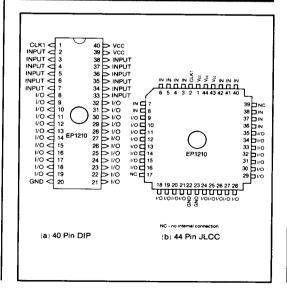
#### **FEATURES**

- High Density (over 1200 gates) replacement for TTL and 74HC.
- Advanced CHMOS EPROM technology allows for erasability and reprogrammability.
- Low power: 15 mW typical standby power dissipation.
- Programmable Macrocell & I/O Architecture: up to 36 inputs or 24 outputs, 28 Macrocells including 4 buried state registers.
- Programmable latch feature allows latching of all inputs.
- Programmable clock system for input latches and output registers.
- Product term sharing and local bus architecture for optimized array performance.
- 100% generically testable provides 100% programming yield.
- Programmable "Security Bit" allows total protection of proprietary designs.
- Advanced software support featuring Schematic Capture, Interactive Netlist, State Machine and Boolean Equation design entry methods.
- Package options include 40 pin DIP and 44 pin J-Leaded Chip Carrier.

#### **CONNECTION DIAGRAM**



#### **GENERAL DESCRIPTION**

The Altera EP1210 is an LSI logic circuit that can be programmed to provide logic replacement for conventional SSI and MSI logic circuits.

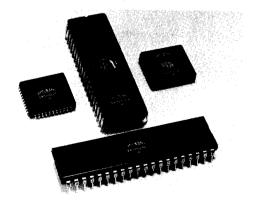
The EP1210 contains CMOS EPROM (floatinggate) elements that control the logical operation of the device. The device can typically provide equivalent performance to 1200 gates of SSI and MSI logic. The EPROM technology enables the logic designer to rapidly program the device and make design changes after erasing for just a few minutes. The same technology also permits 100% factory testing of all elements within the device.

The CMOS technology reduces power consumption to less than 10% of equivalent bipolar devices without sacrificing speed performance.

To implement general purpose logic the EP1210 contains the familiar sum-of-product PLA structure with a programmable AND and fixed OR array. The design uses a range of OR gate widths to accommodate logical functions without the overhead of unnecessary product-terms or the speed penalties of programmable OR structures.

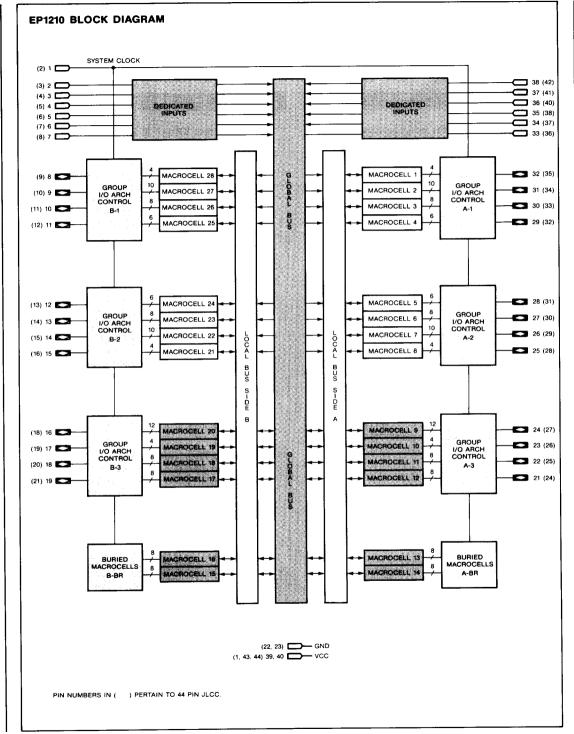
A segmented PLA design that provides local and global connectivity also optimizes the performance of the EP1210.

The EP1210 contains innovative architectural features that provide significant I/O flexibility and maximize performance within a conventional dual-inline package or a J-leaded chip carrier package for increased footprint efficiency.



**REV. 4.0** 





#### **FUNCTIONAL DESCRIPTION**

The EP1210 is an LSI erasable programmable logic device (EPLD) which uses EPROM technology to configure connections within a programmable logic array. The device has a programmable I/O architecture that provides options to change inputs, outputs and logical function of the device.

The internal architecture is based on 28 Macrocells each of which contains a PLA and a programmable I/O block that can be programmed to create many different logic structures. This powerful I/O architecture can be configured to support both active-high, active-low, 3-state, open-drain and bi-directional data ports or act as an input, all on a 4-bit wide basis.

All inputs to the circuit may be latched, including the 12 dedicated input pins.

The Macrocells share a common programmable clock system that controls clocking of all registers and input latches. The device contains 8 modes of clock operation that allow logic transitions to take place on either rising or falling edges of the clock signals.

The primary logic array of the EP1210 is segmented into two symmetrical halves that communicate via global bus signals. The main arrays contain some 15104 programmable elements representing 236 product terms each containing 64 input signals.

Macrocells in each half of the circuit are grouped together for architecture programming. These banks of four Macrocells can be further programmed on an individual Macrocell basis to generate active high or active low outputs of the logic function from the PLA.

The circuit further contains four Macrocells whose outputs are only fed back into the array to create buried-state functions. The feedback path may be either the registered or combinatorial result of the PLA output. The use of buried state Macrocells provides maximum equivalent logic density without demanding higher pincount packages which consume valuable board space.

#### I/O ARCHITECTURE

The Input/Output architecture of the EP1210 Macrocells can be programmed using both static and dynamic controls. The static controls remain fixed after the device is programmed whereas the dynamic controls may change state as a result of the signals applied to the device.

The static controls set the inversion logic, register by-pass and input feedback multiplexers. In the latter two cases these controls operate on four Macrocells as a bank. The buried-state registers have simpler controls which determine if the feedback is to be registered or combinatorial.

The dynamic controls consist of a programmable input latch-enable, as well as register clear and output-enable product terms. The latch-enable function is

common throughout the EP1210 and is programmed by the clock control block but may also be driven by input signals applied to pin 1 (see clock modes in Table 1). The register clear and output-enable controls are logically controlled by single product terms (the logic AND of programmed variables in the array). These terms have control over banks of four Macrocells

The output-enable control may be used to generate architecture types that include bi-directional, 3-state, open-drain or input only structures.

# **OUTPUT/FEEDBACK SELECTION**

The EP1210 Input/Output Architecture allows each group of Macrocells to be programmed for combinatorial or registered operation, with individual control over output polarity. In addition, the designer may configure the feedback path for combinatorial, registered, input (pin), and latched input feedback. All Macrocell groups have Asynchronous Clear control from a dedicated product term. When the product term is asserted to a logical "1", the registers within the respective Macrocell group will immediately be loaded with a logical "0" independently of the clock. On power up, the EP1210 performs the Clear function automatically.

Figure 2 shows the basic output configurations for the EP1210. In a combinatorial mode, the output is controlled via the group dedicated Output Enable product term. The Invert Select EPROM bit controls output polarity. The Feedback Select Multiplexer enables registered feedback, pin or latched pin feedback, or no feedback.

In a registered mode, 4 to 16 product terms are ORed together and made available to the D-type flipflop. The Output Enable product term allows registered or no output. The Invert Select EPROM bit determines output polarity. The Feedback Select Multiplexer can be configured for registered feedback, pin or latched pin feedback, or no feedback.

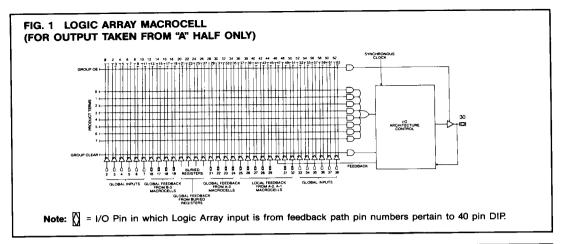
Any I/O group can be configured as a dedicated input group by selecting no output and pin feedback.

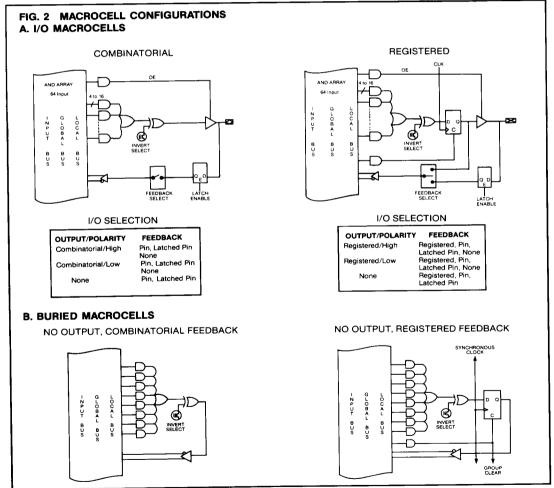
In the erased state, the EP1210 I/O is configured for active low combinatorial output and latched pin feedback.

### SHARED PRODUCT TERMS

Macrocells 9, 10, 11, 12, 17, 18, 19 and 20 have the facility to share a total of 16 additional product terms. The sharing takes place between pairs of adjacent macrocells. This capability enables, for example, Macrocells 9 and 10 to expand to 16 and 8 effective product terms respectively and for Macrocells 11 and 12 both to expand to 12 effective product terms. This facility is primarily of use in state machine and counter applications where common product-terms are frequently required among output functions.







ANDIERA

The two identical halves of the EP1210 communicate via a series of buses. The local bus structure that is used for communication within each half of the chip contains 16 conductors that carry the

The global bus is comprised of 48 conductors that span the entire chip which carry the TRUE and COMPLEMENT of primary inputs (pins 2 through 7 and 33 through 38), signals from 4 Buried Registers, as well as the global outputs of 8 Macrocells in groups A-3 and B-3.

TRUE and COMPLEMENT of 8 local Macrocells.

#### MACRO - BUS INTERFACE

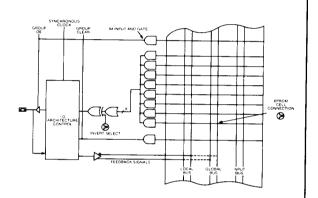
The Macrocells within an EP1210 are interconnected to other Macrocells and inputs to the device via three internal data buses.

The product-terms span the entire bus structure that is adjacent to their Macrocell so that they may produce a logical AND of any of the variables (or their complements) that are present on the buses.

Macrocells all have the ability to return data to the local or global bus. Feedback data may originate from the output of the Macrocell or from the I/O pin. Feedback to the global bus communicates throughout the part. Macrocells that feedback to the local bus communicate to only half the EP1210. Connections to and from the signal buses are made with EPROM

# FIG. 3 MACROCELL BUS STRUCTURE

At each intersecting point in the logic array there exists an EPROM-type programmable connection. Initially, all connections are complete. This means that both the true and complement of all inputs are connected to each product-term. Connections are opened during the programming process. Therefore any product term can be connected to the true or complement of any input. When both the true and complement connections of any input are left intact, a logical false results on the output of the AND gate. If both the true and complement connections of any input are programmed open, then a logical "don't care" results for that input. If all inputs for a product term are programmed open, then a logical true results on the output of the AND gate.



# FIG. 4 A. I/O MACROCELL B. BURIED MACROCELL SYNCHRONOUS ORCUP OUTENT HONEY GLOBA OCA SELECT OF SELEC

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switches that provide the reprogrammable logic capability of the circuit.

Macrocells in groups A-3 and B-3 and the buried registers all have global bus connections while Macrocells in groups A-1, A-2, and B-1, B-2 have local bus connections. Figure 3 illustrates the local and global bus connections. Advanced features of the ALTERA development system will, if desired, automatically select an appropriate Macrocell to meet both the logic requirements and the connection to an appropriate signal bus to achieve the interconnection to other Macrocells.

### **CLOCK MODE CONTROL**

The EP1210 contains two internal clock data paths that drive the input latches (transparent 7475 type) and the output registers. These clocks may be

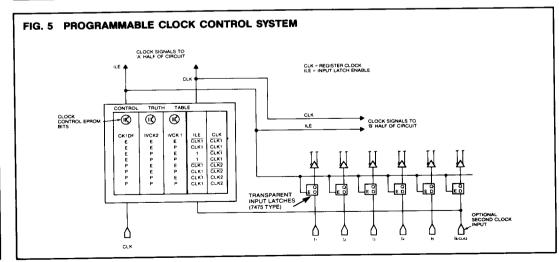
programmed into one of eight operating modes. Input latches may be enabled on either the high or low level of CLK1 (pin1). Once latched, the input signal keeps its value until the next transition of the chosen clock. Output registers can be programmed to be positive or negative edge-triggered with respect to CLK1 or CLK2. Table 1 shows the operation of each programming mode.

In the erased state, the EP1210 clocking operation is set for mode 0. This means inputs are latched on a high level of CLK1. The high to low transition of CLK1 causes the input latches to become disabled, allowing input values to propagate into the logic array without being latched. In addition, CLK1 drives the output registers which are negative edgetriggered.

Care is required when using any of the two-clock modes to ensure that timing hazards are not created.

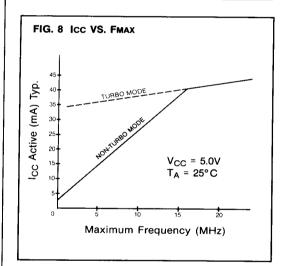
TABLE 1 CLOCK PROGRAMMING

PROGRAMMED MODE	INPUT SIGNALS ARE PASSED (a) AND DATA IS LATCHED (b) WHEN	OUTPUT REGISTERS CHANGE STATE WHEN:	CLOCK CONFIGURATION
0	CLK1 (PIN1) a 7b	CLK1 (PIN1)	1 CLOCK
1	CLK1 a b	CLK1 (PIN1)	1 CLOCK
2	INPUTS NOT LATCHED	CLK1 (PIN1)	1 CLOCK
3	INPUTS NOT LATCHED	CLK1 (PIN1)	1 CLOCK
4	CLK1 (PIN1) a 16	CLK2 (PIN38)	2 CLOCKS
5	CLK1 Photos	CLK2 (PIN38)	2 CLOCKS
6	CLK1 (PIN1) a	CLK2 (PIN38)	2 CLOCKS
7	CLK1 a b	CLK2 (PIN38)	2 CLOCKS



# DEVICE OUTPUT DEVICE INPUT RISE AND FALL TIMES < 6ns

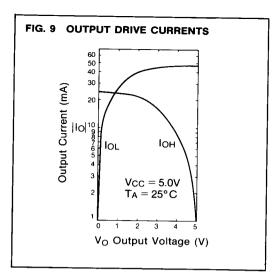
Power supply transients can affect AC measurements, simultaneous transitions of multiple outputs should be avoided for accurate measurement. Do not attempt to perform threshold tests under AC conditions. Large amplitude, fast ground current transients normally occur as the device outputs discharge the load capacitances. These transients flowing through the parasitic inductance between the device ground pin and the test system ground can create significant reductions in observable input noise immunity.



#### **FUNCTIONAL TESTING**

The EP1210 is fully functionally tested and guaranteed through complete testing of each programmable EPROM bit and all internal logic elements thus ensuring 100% programming yield.

As a result, traditional problems associated with fuse-programmed circuits are eliminated. The erasable nature of the EP1210 allows test program patterns to be used and then erased. This facility to use application-independent, general purpose tests is called generic testing and is unique among user-defined LSI logic devices.



# TURBO-BIT

Some EPLDs contain a programmable option to control the automatic power down feature that enables the low standby power mode of the device. This option is controlled by a TURBO-BIT which can be set using A+PLUS. When the TURBO-BIT is programmed (Turbo = ON), the low standby power mode (lcc1) is disabled. This renders the circuit less sensitive to Vcc noise transients which can be created by the power-up/power-down cycle when operating in the low power mode. The typical lcc vs frequency data for both Turbo and Non-Turbo (low power) mode is shown in each EPLD data sheet. All AC values are tested with the TURBO-BIT programmed.

If the design requires low power operation then the TURBO-BIT should be disabled (Turbo = OFF). When operating in this mode, some AC parameters are subject to increase. Values given in the AC specifications section under "Non-Turbo Adder" must be added to the respective AC parameter to determine worst-case timing.

# **DESIGN SECURITY**

The EP1210 contains a programmable design security feature that controls the access to the data programmed into the device. If this programmable feature is used, a proprietary design implemented in the device cannot be copied or retrieved. This enables a high level of design control to be obtained since programmed data within EPROM cells is invisible. The bit that controls this function, along with all other program data, may be reset simply by erasing the device.



# ABSOLUTE MAXIMUM RATINGS

# COMMERCIAL, INDUSTRIAL, MILITARY **OPERATING RANGES**

Note: See Design Recommendations

SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	UNIT
V <sub>CC</sub>	Supply voltage		-2.0	7.0	V
V <sub>PP</sub>	Programming supply voltage	With respect to GND note (3)	-2.0	13.5	٧
V.	DC INPUT voltage	to divid note (3)	-2.0	7.0	V
I <sub>MAX</sub>	DC V <sub>CC</sub> or GND current		-150	+150	mA
lout	DC OUTPUT current, per pin		-25	+25	mA
P <sub>D</sub>	Power dissipation			650	mW
T <sub>STG</sub>	Storage temperature	No bias	-65	+150	°C
T <sub>AMB</sub>	Ambient temperature	Under bias	-65	+135	°C
ESD .	ElectroStatic Discharge Voltage		±900		V

# RECOMMENDED OPERATING CONDITIONS

SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	UNIT
V <sub>CC</sub>	Supply Voltage	note (6)	4.75 (4.5)	5.25 (5.5)	٧
V <sub>i</sub>	INPUT voltage		0	V <sub>CC</sub>	٧
V <sub>0</sub>	OUTPUT voltage		0	V <sub>CC</sub>	٧
T <sub>A</sub>	Operating temperature	For Commercial	0	70	°C
TA	Operating temperature	For Industrial	-40	85	°C
Tc	Case temperature	For Military	-55	125	°C
To	INPUT rise time			500	ns
Te	INPUT fall time			500	ns

# DC OPERATING CHARACTERISTICS

(V<sub>CC</sub> = 5V  $\pm$  5%, T<sub>A</sub> = 0°C to 70°C for Commercial) (V<sub>CC</sub> = 5V  $\pm$  10%, T<sub>A</sub> = -40°C to 85°C for Industrial) (V<sub>CC</sub> = 5V  $\pm$  10%, T<sub>C</sub> = -55°C to 125°C for Military) \*

Note (1) and (6)

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>IH</sub>	HIGH level input voltage		2.0		V <sub>CC</sub> + 0.3	٧
V <sub>IL</sub>	LOW level input voltage		-0.3		0.8	٧
V <sub>OH</sub>	HIGH level TTL output voltage	I <sub>OH</sub> = -4mA DC	2.4			٧_
V <sub>OH</sub>	HIGH level CMOS output voltage	I <sub>OH</sub> = -2mA DC	3.84			V
V <sub>OL</sub>	LOW level output voltage	I <sub>OI</sub> = 4mA DC			0.45	V
I.	Input leakage current	Vo = Vcc or GND	-10		+10	μΑ
loz	3-state output off-state current	V <sub>I</sub> = V <sub>CC</sub> or GND	-10		+10	μA
I <sub>CC1</sub>	V <sub>CC</sub> supply current (standby)	V <sub>I</sub> = V <sub>CC</sub> or GND No load note (8)		3	6 (9)	mA
I <sub>CC2</sub>	V <sub>CC</sub> supply current (non-turbo)	V <sub>I</sub> = V <sub>CC</sub> or GND No load, f = 1.0 MHz note (7)		6	10 (13)	mA
I <sub>CC3</sub>	V <sub>CC</sub> supply current (turbo)	V <sub>I</sub> = V <sub>CC</sub> or GND No load, f = 1.0 MHz note (7)		35	65 (75)	mA

#### CAPACITANCE

### Note (4)

SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	UNIT
C <sub>IN</sub>	Input Capacitance	V <sub>IN</sub> = 0V f = 1.0 MHz		30	pF
C <sub>OUT</sub>	Output Capacitance	V <sub>OUT</sub> = 0V f = 1.0 MHz		40	pF
C <sub>CLK</sub>	Clock Pin Capacitance	V <sub>IN</sub> = 0V f = 1.0 MHz		30	pF



# AC CHARACTERISTICS Note (5)

 $(V_{CC} = 5V \pm 5\%, T_A = 0^{\circ}C$  to  $70^{\circ}C$  for Commercial)  $(V_{CC} = 5V \pm 10\%, T_A = -40^{\circ}C$  to  $85^{\circ}C$  for Industrial)  $(V_{CC} = 5V \pm 10\%, T_C = -55^{\circ}C$  to  $125^{\circ}C$  for Military)\*

			EP1	210-1	EP1210-2		EP1210		NON-TURBO ADDER note (5)		
SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	UNIT
t <sub>PD1</sub>	Input to non-registered output			55		65		90		10	ns
t <sub>PD2</sub>	I/O input to non-registered output	C <sub>1</sub> = 30pF		58		68		93		10	ns
t <sub>PZX</sub>	Input to output enable	7 ' '		55		65	· · · · · ·	90		10	ns
t <sub>PXZ</sub>	Input to output disable	C <sub>1</sub> = 5pF note (2)		55		65		90		10	ns
t <sub>CLR</sub>	Asynchronous output clear time	C <sub>1</sub> = 30pF		90		110		150		10	ns
t <sub>IO</sub>	I/O input buffer delay			3		3		3		0	ns

#### SYNCHRONOUS CLOCK MODE

			EP1	210-1	EP1:	210-2	EP1210		NON-TURBO ADDER		1
SYMBOL	PARAMETER	CONDITIONS	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	UNIT
f <sub>MAX</sub>	Maximum frequency	note (9)	26.2		23.2		17.5		0		MHz
t <sub>SU</sub>	Input setup time		38		43		57	<b>†</b>	10		ns
t <sub>H</sub>	Input hold time		0		0		0		0	-	ns
t <sub>CH</sub>	Clock high time		19		21		28		0		ns
t <sub>CL</sub>	Clock low time		19		21		28		0		ns
t <sub>CO1</sub>	Clock to output delay			35		40		53	<del>-</del>	0	ns
t <sub>CNT</sub>	Minimum clock period (register output feedback to register input - internal path)	note (7)		50		58		80		0	ns
f <sub>CNT</sub>	Internal maximum frequency (1/t <sub>CNT</sub> )	note (7)	20.0		17.2		12.5		0		MHz
tils	Set up time for latching inputs		0		0		0		0		ns
t <sub>ILH</sub>	Hold time for latching inputs		17		20		25		0		ns
t <sub>C1C2</sub>	Minimum clock 1 to Clock 2 delay			44		50		65		0	ns
t <sub>P3</sub>	Minimum period for a 2-clock system (t <sub>C1C2</sub> + t <sub>C01</sub> )			79		90		118		0	пѕ
f <sub>3</sub>	Maximum frequency (1/t <sub>P3</sub> )		12.6		11		8.5		0		MHz

#### Notes:

1. Typical values are for T<sub>A</sub> = 25°C, V<sub>CC</sub> = 5V

2. Sample tested only for an output change of 500mV.

 Minimum DC input is -0.3V. During transitions, the inputs may undershoot to -2.0V for periods less than 20ns.

- 4. Capacitance measured at 25°C. Sample tested only.
- 5. See TURBO-BIT, page 2-21.
- 6. Figures in ( ) pertain to military temperature version.
- . Measured with device programmed as a 26-Bit Counter.
- EPLD automatically goes into standby mode if logic transitions do not occur when in non-turbo mode (approximately 100 ns after last transition).
- 9. The  $f_{\text{MAX}}$  values shown represent the highest frequency for pipelined data.

GRADE	AV	AILABILITY
Commercial (0°C to 70°C)	EP1210-1	EP1210-2 EP1210
Industrial (-40°C to 85°C)		EP1210
Military (-55°C to 125°C)		EP1210

<sup>\*</sup> Specifications for Mil.-STO-883 device may vary from those above. A Military Product Drawing, prepared in accordance with appropriate military specification formats, is available to provide guidance for the preparation of Source Centrol Brawings (SCD). Please contact Altera Marketing at (408) 984-2800 x 101 to obtain 883 Product drawings.

