# **AN6612, AN6612S**

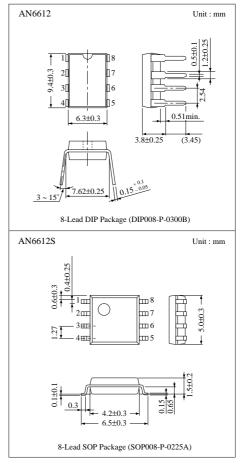
## Motor Control Circuits

#### ■ Overview

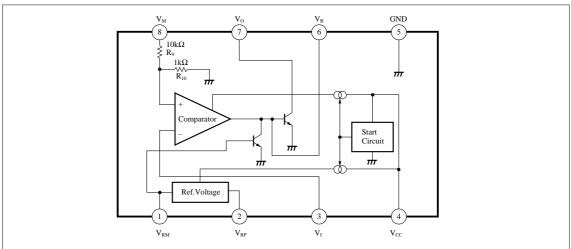
The AN6612 and the AN6612S are the electronic governor circuits suitable for the rotating speed control of a low voltage and compact DC motor which is used for a small tape recorder, etc.

#### ■ Features

- Wide range of operating voltage : V<sub>CC (opr)</sub> =1.8V ~ 8V
- 2 package types
- Fewer external parts
- Speed control in steps with linear fine control
- Output current limiting circuit is built-in



#### ■ Block Diagram



### ■ Pin Descriptions

Pin No.	Pin Name	Pin No.	Pin Name
1	Current Sensor	5	GND
2	Reference Voltage	6	Base
3	Control	7	Output Base
4	V <sub>CC</sub>	8	Motor pin

### ■ Absolute Maximum Ratings (Ta= 25°C)

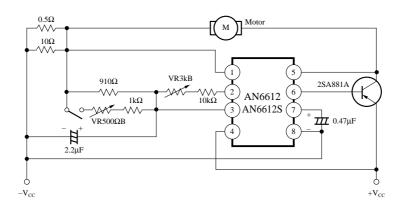
Param	eter	Symbol	Rating	Unit	
Supply Voltage		V <sub>CC</sub>	10	V	
Supply Current		$I_4$	5	mA	
D D' ' '	AN6612	- P <sub>D</sub>	400	***	
Power Dissipation	AN6612S		200	mW	
Operating Ambient Temperature		$T_{\mathrm{opr}}$	-20 ~ + 75	°C	
C. T.	AN6612	$T_{ m stg}$	-40 ~ +150		
Storage Temperature	AN6612S		-40 ~ +125	°C	

## ■ Electrical Characteristics (Ta = 25°C)

Parameter	Symbol	Condition	min.	typ.	max.	Unit
Supply Current	$I_4$	$V_{CC} = 3V$		1.9	3	mA
Reference Voltage	V <sub>2-1</sub>	$V_{CC} = 3V, R_{2-1} = 10k\Omega$	1.24	1.32	1.40	V
Starting Current	$I_a$	$V_{CC} = 1.8V, Ra = 4.9\Omega$	250			mA
Voltage Variable Characteristics for Rotating Speed	$ \Delta N_{\rm V} $	$V_{CC} = 1.8V \sim 4V,$ $I_{L} = 72mA (1.7g \cdot cm)$			10	rpm/V
Time Drift Characteristics for Rotating Speed	$ \Delta N_T $	$V_{CC} = 3V, I_L = 72mA,$ $t = 15s \sim 10min.$		0.1		%
Temperature Variation Characteristics for Rotating Speed	$\Delta N_A^*$	$V_{CC} = 3V, I_L = 72mA,$ $Ta = -20^{\circ}C \sim +60^{\circ}C$		- 0.035	_	%/°C
Output Current Limit Voltage	V <sub>t (1-5)</sub>	$V_{CC} = 3V$	0.6	0.7	0.8	V

<sup>\*</sup> In case that only IC temperature is changed.

### ■ Application Circuit



Motor Constants

 $\begin{cases} R_a: \text{ Internal resistor} = 4.9\Omega \\ K_a: \text{ Electromotive force constant} = 0.4\text{mV/rpm} \\ K_T: \text{ Torque constant} = 29\text{g} \cdot \text{cm/A} \end{cases}$ 

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