

Preliminary Data

May 1995

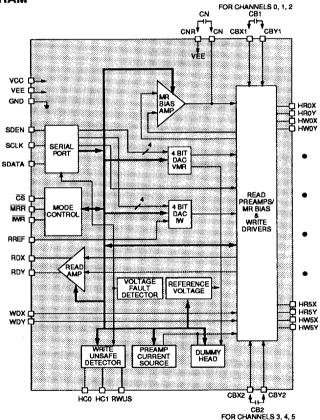
DESCRIPTION

The SSI 32R1550R is an integrated circuit designed for use with magneto-resistive recording heads. It provides a write driver and a low noise read amplifier for up to 6 channels. The device operates in -3V and +5V power supplies and comes in a 52-pin PLCC package and a 64-lead TQFP package.

FEATURES

- +5V, -3V ±10% supply
- Designed for four-terminal MR heads with minimum external components
- Truly differential voltage blas/voltage sense MR read Amp
- MR head bias current range = 5-20 mA
- MR read gain = 200 V/V (min)

BLOCK DIAGRAM



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for a static sensitive component.

CAUTION: Use handling procedures necessary

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FEATURES (continued)

- MR read input noise = 0.70 nV√Hz (Nom)
- MR read input resistance = 900Ω (Nom)
- Differential PECL write data input with optional flipflop
- Head voltage swing = 6.5 Vp-p (Min)
- Write current range = 12.5 50 mA
- Write unsafe detection
- Enhanced system write to read recovery time
- Power supply fault protection
- Head select, write current magnitude and MR bias voltage are controlled by serial interface

FUNCTIONAL DESCRIPTION

The SSI 32R1550R addresses up to 6 MR heads providing write drive or read bias and amplification. Mode control is accomplished with TTL pins MRR, IWR and CS. The TTL inputs have internal pull-up resistors so that when left opened, they will default to the TTL High state.

SERIAL PORT OPERATION

The write only serial data port is used to control head selection, write current magnitude, MR bias voltage, vendor query and MR head resistance measurement. It does this by writing data into two on board registers addressed E2 and F2.

A complete data transfer is sixteen (16) bits long and loaded LSB first. Addresses and data are loaded least significant bit (LSB) first, and addresses are loaded first. The first bit is the R/W bit and is always set to zero. The next three bits (S0-S2) are the device select bits and are always written S0=1, S1=0 and S2=0 for R/W amplifiers. The following four bits (A0-A3) are the address bits and the last eight (D0-D7) are the data bits.

Asserting the serial port enable line SDEN initiates a transfer. SDATA is clocked into the internal shift register by the rising edge of SCLK. A counter on the chip ensures that exactly 16 clock pulses occurred prior to SDEN being de-asserted otherwise the transfer will be aborted. Loading of the registers takes place on the falling edge of SDEN.

WRITE MODE

Taking both \overline{CS} and \overline{IWR} low with \overline{MRR} high selects the write mode which configures the 32R1550R as a current switch and activates the Write Unsafe (WUS) detect circuitry. Head current is toggled between the X (HWnX) and Y (HWnY) side of the selected head on each transition of the differential PECL signal WDX-WDY. With WDX>WDY lw will flow from the X to the Y pin, i.e., the X side of the head will be higher potential than the Y side. Write current magnitude is controlled by a four bit on-board digital to analog converter. This DAC is programmed via the serial port. The magnitude of the write current (0-pk) is given by:

$$lw = 12.5 \text{ mA} + 37.5 \text{ mA} (N/15)$$

where N = decimal value of WIMV0-WIMV3 (Digital input to write current DAC)

Note that the actual head current lx,y is given by:

$$Ix, y = \frac{Iw}{1+Rh/Rd}$$

where Rh is the head DC resistance and Rd is the damping resistance.

While in the write mode the voltages on CN and CB1/CB2 will be held to the values they were during the last read. This facilitates fast switching from write to read.

READ MODE

Taking $\overline{\text{CS}}$ and $\overline{\text{MRR}}$ low and $\overline{\text{IWR}}$ high selects the read mode which activates the MR bias voltage generator and low noise differential amplifier. The outputs of the read amplifier RDX and RDY are emitter followers and are in phase with the resistivity change at the selected input ports HRnX and HRnY where the respective MR head is attached. The voltage across the MR head is regulated by the chip and is adjustable from 100 mV to 400 mV. The magnitude of this voltage is controlled by an on board digital to analog converter. This DAC is programmed via the serial port. The actual magnitude is given by:

$$VMR = 100 \text{ mV} + (M/15)(300 \text{ mV})$$

where M = decimal value of MRB0-MRB3 (Digital input to MR bias DAC)

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An external capacitor connected from pin CN to CNR is used for reducing the noise from the MR bias current source. A low inductance capacitor with a value of 0.1 µF is recommended. Two external floating capacitors CB1 and CB2 connected between pins CBX1/CBY1 and CBX2/CBY2, respectively, are required for DC blocking. Care should be taken to use low inductance high frequency capacitors and to locate them as close to the pins as possible. The stray inductance will degrade amplifier's noise and frequency response performance. The value of the DC blocking capacitors CB1/CB2 will have direct effect on the write to read recovery time. For fast recovery time, the capacitor value should be kept as small as possible. The value of the capacitor CB1/CB2 also sets the low frequency cutoff of the read amplifier. The -3 dB lowfrequency corner is given by:

$$f_1 = 1/(2 \cdot \pi \cdot 15\Omega \cdot CB1/CB2)$$

For example, a $0.1\,\mu\text{F}$ capacitor for CB1/CB2 will result in the -3 dB low-frequency of about 106 kHz.

In read mode, the voltage at the midpoint of the selected MR head is forced to a virtual ground.

If either the X or Y side of the head is shorted to ground the head bias current will not exceed it's programmed value. For the unselected MR heads, the head ports become high impedance and thus will prevent the heads from conducting current in the event of head to disk contact.

RBAW MODE

Taking CS, IWR and MRR low selects the RBAW (read bias active in write) mode. In this mode the write driver is active just as in the write mode but the MR voltage bias circuitry is also active. The outputs of the read amplifier RDX/RDY remain inactive, i.e., high impedance. The purpose of this mode is to speed up the write to read transition times by selecting this mode just prior to switching to the read mode. To be effective it is suggested that RBAW be selected at least 5 μs prior to selecting read mode. Switching times from RBAW to read mode are guaranteed to be less than 1 μs.

STANDBY MODE

Taking \overline{CS} low and \overline{MRR} and \overline{IWR} high selects the standby mode. In this mode the write driver and read amplifier are both inactive. The voltages across CN and CB1/CB2 are held to the values they were during the last read. This facilitates fast switching from standby to read. The serial port is active in this mode and it is suggested for fastest performance that head switching be done in standby rather than IDLE.

IDLE MODE

Taking $\overline{\text{CS}}$ high selects Idle mode which deactivates both the write driver and read amp/MR bias circuitry. The pins RDX/RDY are switched into high impedance state to facilitate multiple device applications where these pins could be wire OR'ed. The serial port is active while in Idle mode.

VENDOR QUERY MODE

This mode is entered by selecting idle mode and setting bits D4=0 and D5=1 in register E2. The purpose of this mode is for the host system to interrogate the read/write IC for information regarding the specific vendor associated with the head and the read/write IC itself. Pins HC0 and HC1 are used to create a two-bit code unique to the particular head being used in this drive. They default to logic high if left open. The SSI 32R1550R is programmed at the factory to have the two-bit code CC0=0 and CC1=0. Bits WIMV0-WIMV3 of register E2 are used to guess the value of HC0,HC1, CC0,CC1. When the value of WIMV0-WIMV3 matches HC0,HC1,CC0,CC1, RWUS will go high

MR RESISTANCE MEASURE MODE

This mode is entered by selecting READ (\overline{CS} , \overline{MRR} =0 \overline{IWR} =1) and setting bits D4=1 and D5=0 in register E2. There are two purposes for using this mode. They are to measure MR head resistance and to test for an open MR head. The open head test can only be done in this mode, not in the normal read mode. It is not intended as a read unsafe monitor during read mode operation but as a means to verify the heads were installed properly and for two and four channel drives to verify head count and location.

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Referring to the equation below, the MR resistance measurement is done by setting VMR to a known value by programming MRB0-MRB3. A scaled version of the actual MR bias current is then compared to a scaled version of the write DAC output current. This current is set by WIMV0-WIMV3. When used this way the write DAC is switched out of the write circuit and into the measure circuit. The write driver is not active. WIMV0-WIMV3 are adjusted until RWUS toggles low to high or high to low (depending on whether the initial guess was less than or greater than the actual RMR). RMR is determined by:

$$RMR = \frac{VMR}{(N+5)mA}$$

where: N = decimal value of WIMV0-WIMV3 at RWUS toggle. Note: The level of RWUS can take up to 1µs to settle after WIMV0-WIMV3 are changed.

There are limitations to the range of resistance that can be measured. They are determined by the operating range of VMR and IMR.

For example with VMR set to 100 mV, the range of resistance it is possible to measure is 5 to 20Ω . With VMR set to 400 mV the range is 20 to 80Ω .

For open head testing it should be noted that there is $7~k\Omega$ internal resistance in parallel with the head. This is for biasing purposes. With open head conditions IMR can't exceed 5 mA and RWUS will be low for all values of VMR.

POWER SUPPLY FAULT PROTECTION

A voltage fault detection circuit improves data security by disabling the write current generator and the MR bias current/read amplifier during a voltage fault or power startup regardless of mode.

RWUS OPERATION

RWUS pin behavior can be divided into four categories:

- write and RBAW
- idle, read and standby
- MR resistance measure
- vendor query

When in the Write or RBAW modes the following faults will cause RWUS to be latched high:

- WDX/WDY frequency low
- no head current
- open head
- write head lead short to ground
- low supply voltage

RWUS will remain high even if the fault has been cleared before leaving the write mode. To clear RWUS it is necessary to exit the write mode and enter either idle, read or standby then re-enter the write mode with the fault removed. RWUS will then go low after two transitions of WDX-WDY (following the required 500 ns mode transition time). It should be noted that for write head lead short to ground and low supply voltage faults that in addition to RWUS going high the write driver will be disabled.

When in idle, read or standby modes RWUS is high.

RWUS behavior for the MR resistance measure and vendor query modes has been described in previous sections.

TABLE 1: Mode Select

| ĊŚ | MRR | ĪWR | REG E2 D4 | REG E2 D5 | MODE | RDX/RDY | MR BIAS | WRITE DRIVER |
|----|-----|-----|--------------|--------------|-----------------------------|---------|------------|-----------------|
| 0 | 1 | 0 | 0 | 0 | Write | Hi-Z | OFF | ON |
| 0 | 0 | 1 | 0 | 0 | Read | ON | ON | OFF |
| 0 | 0 | 0 | 0 | 0 | RBAW | Hi-Z | ON | ON |
| 0 | 1 | 1 | Х | Х | Standby | Hi-Z | OFF | OFF |
| 1 | Х | х | 0 | 0 | ldle | Hi-Z | OFF | OFF |
| 1 | х | Х | 0 | 1 | VENDOR QUERY | Hi-Z | OFF | OFF |
| 0 | 0 | 1 | 1 | 0 | MR RESISTANCE MEASURE | Hi-Z | ON | OFF |

SERIAL INTERFACE OPERATION

The serial interface is a CMOS port for writing programming data to the internal registers. For data transfers, the SDEN pin is brought high, serial data is presented at the SDATA pin, and a serial clock is applied to the SCLK pin. The data is clocked in on the rising edge of the clock LSB first. After SDEN goes high, an internal counter requires exactly 16 clock pulses before SDEN goes low or no data is transferred. The data in the shift register is latched when SDEN goes low.

The first bit transferred on SDATA is the R/W bit which is always set to zero. The next three bits (SO - S2) are the device select bits and are always written as S0 = 1, S1 = 0, and S2 = 0 for R/W amplifiers. The following four bits (A0 - A3) are the register address bits and the last eight are the data bits. The serial port diagram and bit map are shown below.

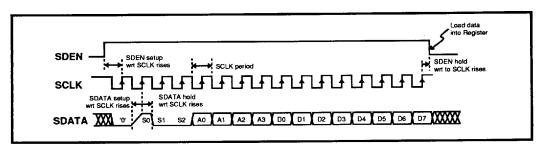


FIGURE 1: Serial Interface Timing Diagram - Writing Control Register

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TABLE 2: Serial Port Bit Map

| FUNCTION | REG | R/W | S0 | S1 | S3 | A0 | A1 | A2 | А3 | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 |
|---------------|-----|-----|----|----|----|----|----|----|----|-------|-------|-------|-------|------|------|------|----|
| Head Select | F2 | 0 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | HS0 | HS1 | HS2 | х | X | Х | Х | Х |
| MR Bias Set | F2 | 0 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | × | х | х | MRB0 | MRB1 | MRB2 | MRB3 | x |
| Write Current | E2 | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 1 | WIMVO | WIMV1 | WIMV2 | WIMV3 | 0 | 0 | х | х |
| MR Measure | E2 | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 1 | WIMVO | WIMV1 | WIMV2 | WIMV3 | 1 | 0 | х | Х |
| Vendor Query | E2 | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 1 | WIMVO | WIMV1 | WIMV2 | WIMV3 | 0 | 1 | х | х |

X = Don't Care

TABLE 3: Head Select

| HS2 | HS1 | HS0 | Channels |
|-----|-----|-----|-------------------------|
| | | | Selected |
| 0 | 0 | 0 | CH0, head 0 is selected |
| 0 | 0 | 1 | CH1, head 1 is selected |
| 0 | 1 | 0 | CH2, head 2 is selected |
| 0 | 1 | 1 | CH3, head 3 is selected |
| 1 | 0 | 0 | CH4, head 4 is selected |
| 1 | 0 | 1 | CH5, head 5 is selected |

Conditions following power up or power supply fault:

HS0, HS1, HS2 = "1" No channels selected

MRB0 - MRB3 = "0" VMR = 100 mV

D4, D5 (Reg. E2) = "0"

WIMV0 - WIMV3 = "0" lw = 12.5 mA

The definition of WIMV0 - WIMV3 is determined by bits D4 & D5 of register E2.

| D4 | D5 | Definition of WIMV0 - WIMV3 |
|----|----|---|
| 0 | 0 | Write current magnitude (LSB = 2.5 mA) |
| 0 | 1 | Chip and Head Vendor Query/Identification |
| 1 | 0 | MR resistance measurement/Open Head Detection |

MRB0 - MRB3 set the MR bias voltage, LSB = 20 mV

PIN DESCRIPTION

CONTROL INPUT PINS

| NAME | TYPE | DESCRIPTION |
|-----------|------|---|
| HR0X-HR5X | ı | MR read head input X and Y connections |
| HR0Y-HR5Y | | |
| HW0X-HW5X | 0 | Inductive write head X and Y connections |
| HW0Y-HW5Y | | |
| CN | 1 | Noise filter Cap |
| CNR | l | Noise filter cap return |
| CBX1/CBY1 | 1 | Floating DC blocking cap CB1; for head 0 to head 2 |
| CBX2/CBY2 | 1 | Floating DC blocking cap CB2: for head 3 to head 5 |
| WDX, WDY | Ī | Differential PECL Write Data Input |
| RDX, RDY | 0 | Differential MR head Read Data Output |
| RREF | 1 | 8 kΩ resistor to ground sets reference current for write DAC |
| RWUS | 0 | Write Unsafe; open collector; a high level indicates an unsafe writing condition or outcome of vendor query or MR head resistance measurement |
| CS | l | Chip Select; a high inhibits the chip; TTL |
| MRR | - 1 | Mode control, TTL |
| ĪWR | 1 | Mode control, TTL |
| SDATA | ı | Serial data used for head selection, setting write current magnitude and MR bias voltage, vendor query and MR head resistance measurement, CMOS |
| SCLK | 1 | Serial clock, CMOS |
| SDEN | 1 | Serial data enable, CMOS |
| HC0, HC1 | I | Head code bit 0 and bit 1 |
| VCC | 1 | +5V Supply |
| VEE | 1 | -3V Supply |
| GND | 1 | Ground |

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ELECTRICAL SPECIFICATIONS

Recommended conditions apply unless otherwise specified.

ABSOLUTE MAXIMUM RATINGS

Operation outside these maximum ratings may cause permanent damage to this device.

| PARAMETER | | RATING |
|--------------------------------|------------------|--------------------------------------|
| DC Supply Voltage | VCC VEE | +6 VDC -6 VDC |
| Logic Input Voltage | CMOS/TTL PECL | -0.3 to VCC +0.3 VDC 0 to VCC VDC |
| Write Current | lw | 75 mA |
| MR Bias Current | lr | 30 mA |
| Output Current | RWUS RDX/RDY | +8 mA -5 mA |
| Operating Junction Temperature | Tj | +135°C |
| Storage Temperature | Tstg | -65°C to +150°C |

RECOMMENDED OPERATING CONDITIONS

| DC Supply Voltage | VCC VEE | 4.5V to 5.5V -3.3V to -2.7V |
|-------------------------------|------------|--------------------------------|
| Operating Ambient Temperature | Ta | 0 to 70°C |

DC CHARACTERISTICS

Recommended operating conditions apply unless otherwise specified

| PARAMETER | | CONDITION | MIN | NOM | MAX | UNIT |
|----------------|-----|--------------|-----|----------------------|-----|------|
| Supply Current | VCC | read mode | | 31+lmr | | mA |
| | | write mode | | 21+1.13(lw) | | mA |
| | | RBAW mode | | 28+1.13(lw) + lmr | | mA |
| | | standby mode | | 10 | | mA |
| | | idle mode | | 2.3 | | mA |
| Supply Current | VEE | read mode | | 15 + lmr | | mA |
| | | write mode | | 4 + (lw/20) | | mA |
| | | RBAW mode | | 16 + lmr +(lw/20) | | mA |
| | | standby mode | | 2 | | mA |
| | | idle mode | | 0.5 | | mA |

DC CHARACTERISTICS
Recommended operating conditions apply unless otherwise specified

| PARAMETER | CONDITION | MIN | МОМ | MAX | UNIT |
|-------------------|------------------------------------|-------|-------|-------|------|
| Power Dissipation | read mode, lmr = 10 mA | | 280 | 420 | mW |
| | write mode, lw = 40 mA | | 355 | 525 | mW |
| | RBAW mode, Iw = 40 mA, Imr = 10 mA | | 530 | 800 | mW |
| | standby mode, lmr = 10 mA | | 56 | 85 | mW |
| | idle mode | | 13 | 20 | mW |
| VCC Fault Voltage | lw < 0.2 mA, Imr < 0.2 mA | 3.5 | 3.85 | 4.2 | VDC |
| VEE Fault Voltage | lw < 0.2 mA, Imr < 0.2 mA | -2.52 | -2.31 | -2.10 | VDC |

LOGIC INPUTS AND OUTPUTS

| Input low voltage | Vil | TTL | -0.3 | | 0.8 | VDC |
|--|------|----------------|---------|------|-----------|------------|
| Input high voltage | Vih | TTL | 2 | | Vcc+0.3 | VDC |
| input low current | lil | Vil = 0.8V | -0.4 | -0.2 | | mA |
| Input high current | lih | Vih = 2V | | | 100 | μΑ |
| Input low Voltage (WDX, WDY) | Vil2 | | Vcc-2 | | Vih2-0.25 | VDC |
| Input high Voltage (WDX, WDY) | Vih2 | | Vcc-1.1 | | Vcc-0.4 | VDC |
| Input Differential Voltage V(WDX, WDY) |) | | 0.3 | | | VDC |
| Input low Current | Lil2 | Vil = Vcc-1.4V | | | 50 | μ A |
| Input High Current | Lih2 | Vih = Vcc-0.4V | | | 50 | μΑ |
| Output High Current (RWUS) | Loh | | | | 50 | μА |
| Output Low Current (RWUS) | Lol | | | | 4 | mA |
| Output low Voltage (RWUS) | Vol | Lol = 4 mA | | | 0.5 | VDC |

SERIAL PORT TIMING

| SCLK Data Clock Perio | d TC | 100 | ns |
|-----------------------|-------|-----|----|
| SCLK Low Time | TCKL | 40 | ns |
| SCLK High Time | TCKH | 40 | ns |
| Enable to SCLK | TSENS | 30 | ns |
| SCLK to Disable | TSENH | 30 | ns |
| Data Set-up Time | TDS | 15 | ns |
| Data Hold Time | TDH | 15 | ns |
| SDEN Min. Low Time | Tsl | 200 | ns |

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ELECTRICAL SPECIFICATIONS (continued)

READ CHARACTERISTICS, MR HEAD AMPLIFIER

Recommended operating conditions apply unless otherwise specified

 $Rmr = 24\Omega$

CL (RDX, RDY) < 20 pF, RL (RDX, RDY) > 1K

| PARAMETER | CONDITIONS | MIN | NOM | MAX | UNIT |
|-------------------------------------|---|------|-----|------|--------|
| MR Head Resistance | | 12 | 24 | 35 | Ω |
| MR Current Range | | 5 | | 20 | mA |
| MR Head Voltage | selected Head (differential) | 100 | | 400 | mV |
| | unselected Heads (single ended) | -0.6 | 1 | -0.4 | V |
| MR Head Voltage Resolution (LSB) | | | 20 | | m∨ |
| MR Head Voltage Accuracy | | -10 | | +10 | % |
| Unselected MR Current | | | 0.1 | | mA |
| Differential Voltage Gain | Vin = 1 mVp-p @ 5 MHz Rmr = 24Ω; | 200 | 240 | 280 | V/V |
| Voltage BW | Lmr = 20 nH -1 dB | 40 | | | MHz |
| | Vin = 1 mVp-p -3 dB Upper | 72 | | | MHz |
| | CB1/CB2 = 0.1 μF -3 dB Lower | | | 150 | kHz |
| Input Noise Voltage | exclude head noise | | 0.7 | | nV/√Hz |
| Differential input Resistance | Vin = 1 mVp-p @ 5 MHz CB1/CB2 = 0.1 μF | | 1.5 | | kΩ |
| Differential input Capacitance | Vin = 1 mVp-p @ 5 MHz CB1/CB2 = 0.1 μF | | 13 | 20 | pF |
| CMRR | Vin = 100 mVp-p @ 5 MHz | 55 | | | dB |
| PSRR | 100 mVp-p @ 5 MHz on VCC or VEE | 50 | | | dB |
| Channel Separation | unselected channels driven with 100 mVp-p @ 5 MHz | 45 | | | dB |
| Output offset Voltage | | -300 | | 300 | mV |
| Output Resistance | single ended | | | 100 | Ω |

READ CHARACTERISTICS, MR HEAD AMPLIFIER (continued)

| PARAMETER | CONDITIONS | MIN | NOM | MAX | UNIT |
|---------------------------------------|--|-----|----------|-----|------|
| Output Current | | 1.5 | | | mA |
| RDX/RDY Common Mode Output Voltage | | | VCC-1.65 | | ٧ |
| Input Dynamic Range | AC input voltage where gain falls to 90% of its small signal value, @ 5 MHz | 3 | | | m∨ |
| Total Harmonic Distortion | Vin ≤ 2 mV @ 5 MHz | | | 1 | % |
| Amplifier Saturation Recovery Time | Vin = 20 mV step | | 2 | 3 | μs |

WRITE CHARACTERISTICS

Recommended operating conditions apply unless otherwise specified lw = 40 mA, Lh = 250 nH, Rh = 17 Ω

| Write Current Range | | | 12.5 | | 50 | mA(0-pk) |
|--------------------------------------|-------|-----------|------|-----|-----|----------|
| Write Current Resolution | | | | 2.5 | | mA |
| Write Current Accuracy | | | -15 | | +15 | % |
| Differential Head Voltage Swing | ** | open head | 6.5 | | | Vp-p |
| Unselected Head Current | DC | | | | 0.1 | mA |
| - | AC | | | | 1 | mApk |
| Head Differential Damping Resistance | | | 360 | 450 | 540 | Ω |
| Head Differential Load Capacit | tance | | | | 15 | pF |
| Write DAC Reference Resistor | | | | 8 | | kΩ |

Note: Write Current accuracy can be increased to ± 10 % for 30 mA < lw < 50 mA & RREF = 7.5 k Ω

SWITCHING CHARACTERISTICS

Recommended operating conditions apply unless otherwise specified

 12Ω < Rmr < 35Ω ; CL (RDX, RDY) < 20 pF; Iw = 40 mA

RL (RDX, RDY) > 1K; Lh = 250 nH, Rh = 17Ω ; F (WDX/WDY) = 5 MHz

| PARAMETE | R | CONDITION | MIN | NOM | MAX | UNIT |
|------------------------------------|-------------------------|---|------|-----|-----|------|
| Read to Writ | te | To 90% of write current | 1 | 100 | 500 | ns |
| Write/Standby to Read | | To 90% of 100 mV, 5 MHz read signal envelope | | 2 | 5 | μs |
| RBAW to Re | ead | Same as above RBAW selected at least 5 µs prior to read | | 0.5 | 1 | μs |
| idle to Read | _ | Same as above | | | 50 | μs |
| Head switch | to Read | Same as above. Switch done in standby mode. | | | 30 | μs |
| RWUS | Safe to Unsafe (TD1) | Write mode, from loss of WDX-WDY transitions | 0.25 | | 1 | μs |
| | Unsafe to Safe (TD2) | Fault cleared from second WDX-WDY transition. | | | 500 | ns |
| Head Curren (WDX - WDY (TD3) | | From 50% point | | | 30 | ns |
| Rise/Fall Tim | ne | With head, 10% to 90% | | | 8 | ns |
| Write Current Asymmetry | | | | | 0.5 | ns |

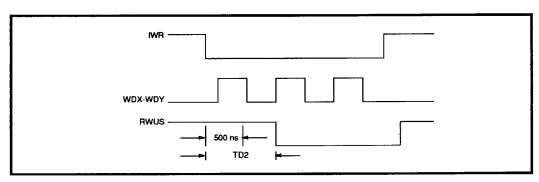


FIGURE 2: Normal Write Conditions

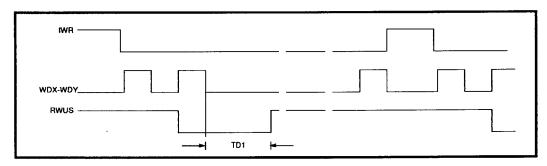
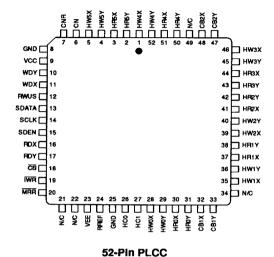
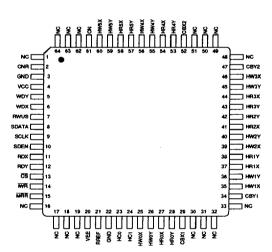


FIGURE 3: WUS Timing

PACKAGE PIN DESIGNATIONS (Top View)

CAUTION: Use handling procedures necessary for a static sensitive component.





64-Lead TQFP

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