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SPECIFICATION

Device Name : IGBT-IPM

Type Name : 6MBP50TEA060

Spec. No. : MS6M0700

Fuji Electric Co., Ltd.
Matsumoto Factory

	DATE	NAME	APPROVED	Fuji Electric Co.,Ltd.				
DRAWN	Nov -26-'02	K. Sekigawa	T. Fujikawa	DWG. NO.	MS6M0700	1/22		a
CHECKED	- -	Chishiro						
CHECKED	- -	K. Yamada						

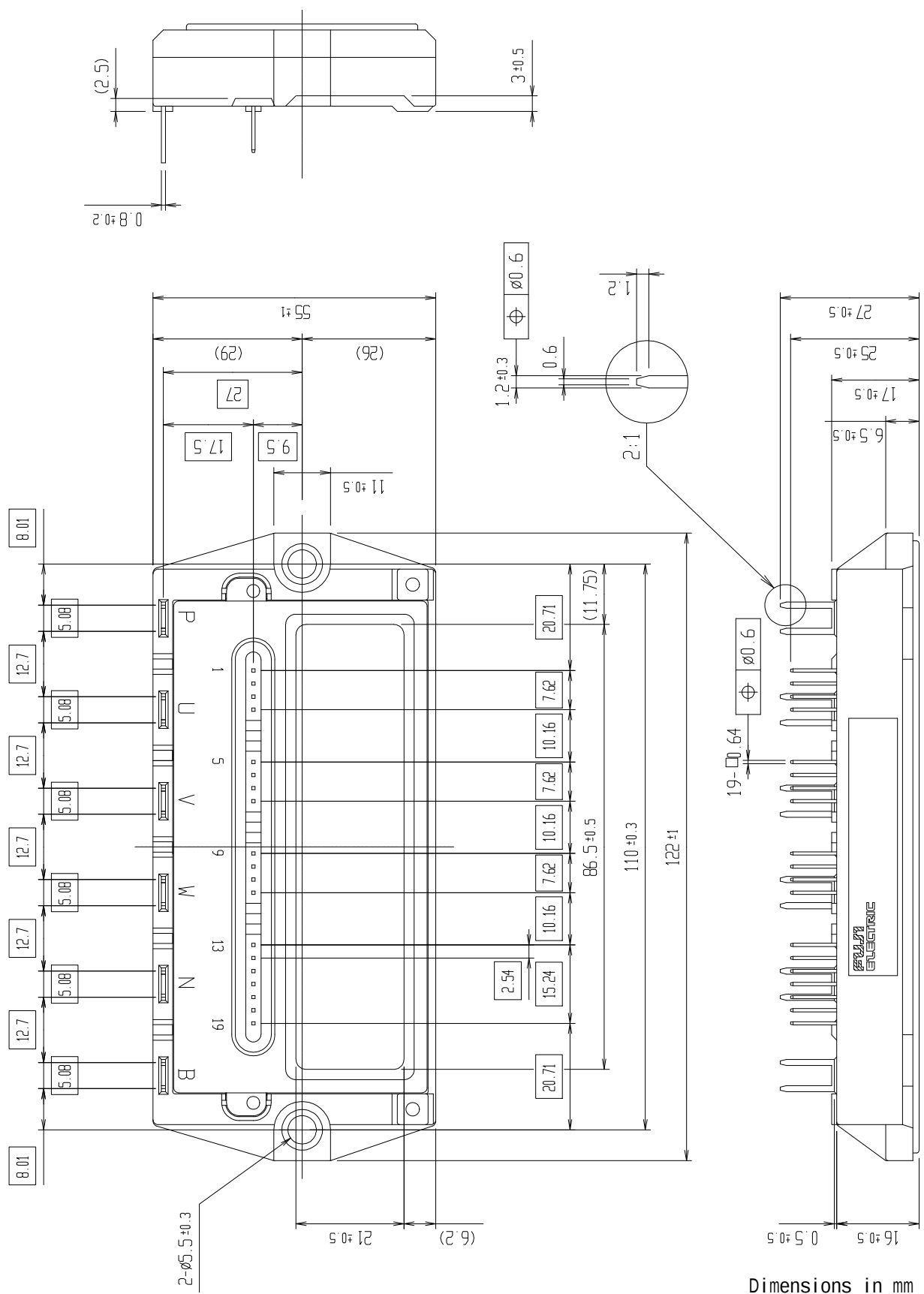
Revised Records

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1 .Package Outline Drawings ^(a)

Package type : P622



2 . Pin Descriptions

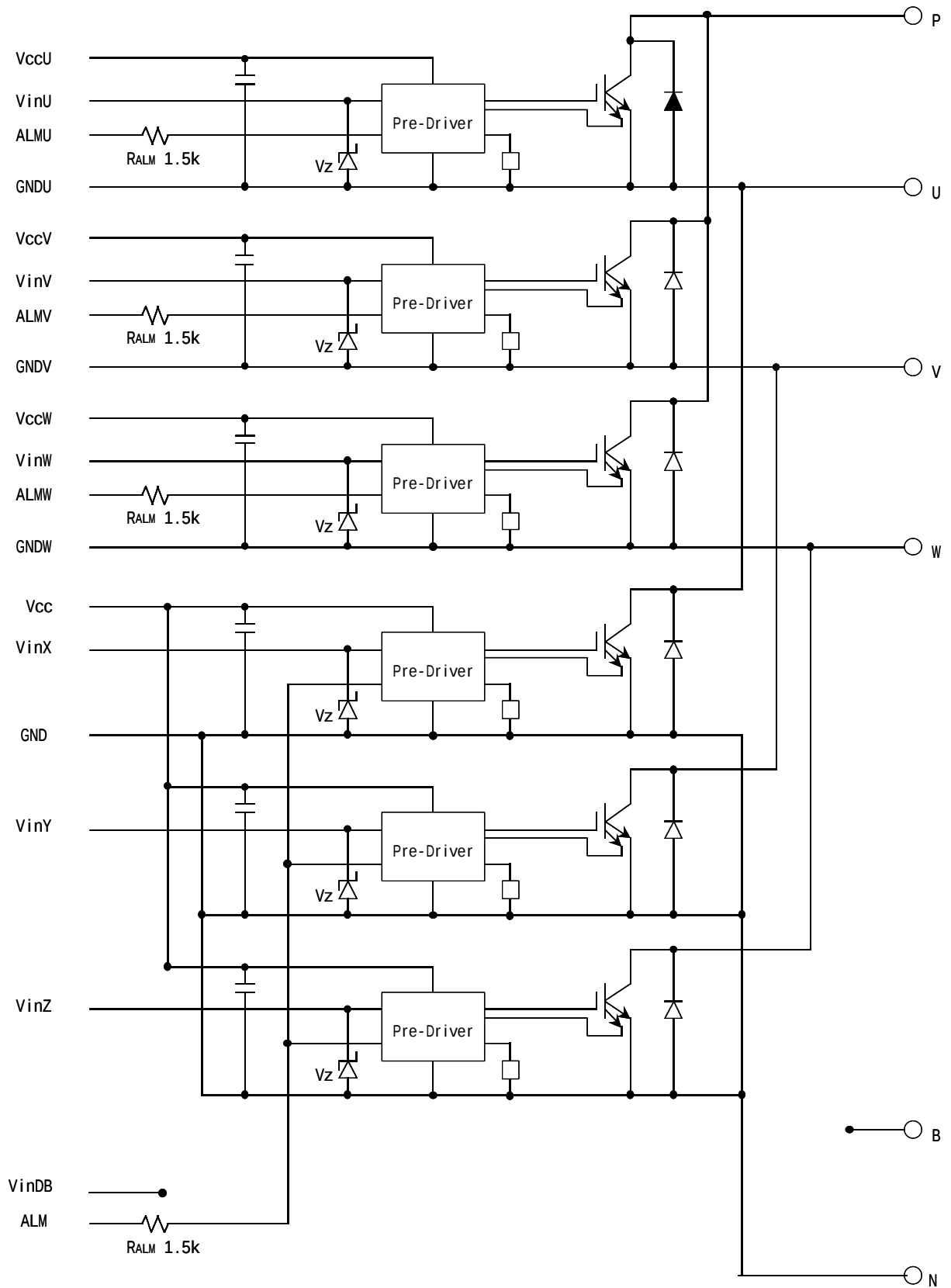
Main circuit

Symbol	Description
P	Positive input supply voltage.
U	Output (U).
V	Output (V).
W	Output (W).
N	Negative input supply voltage.
B	No contact.

Control circuit

No	Symbol	Description
	GNDU	High side ground (U).
	ALMU	Alarm signal output (U).
	VinU	Logic input for IGBT gate drive (U).
	VccU	High side supply voltage (U).
	GNDV	High side ground (V).
	ALMV	Alarm signal output (V).
	VinV	Logic input for IGBT gate drive (V).
	VccV	High side supply voltage (V).
	GNDW	High side ground (W).
	ALMW	Alarm signal output (W).
	VinW	Logic input for IGBT gate drive (W).
	VccW	High side supply voltage (W).
	GND	Low side ground.
	Vcc	Low side supply voltage.
	VinDB	No contact.
	VinX	Logic input for IGBT gate drive (X).
	VinY	Logic input for IGBT gate drive (Y).
	VinZ	Logic input for IGBT gate drive (Z).
	ALM	Low side alarm signal output.

3. Block Diagram ^(a)



Pre-drivers include following functions

- 1.Amplifier for driver
- 2.Short circuit protection
- 3.Under voltage lockout circuit
- 4.Over current protection
- 5.IGBT chip over heating protection

4 . Absolute Maximum Ratings

Tc = 25 unless otherwise specified.

Items		Symbol	Min.	Max.	Units
Bus Voltage (between terminal P and N)	DC	V _{DC}	0	450	V
	Surge	V _{DC(surge)}	0	500	V
	Shortoperating	V _{sc}	200	400	V
Collector-Emitter Voltage *1		V _{ces}	0	600	V
Inverter	Collector Current	DC	—	50	A
		1ms	—	100	A
		Duty 76.1 % *2	—	50	A
	Collector Power Dissipation	One transistor *3	—	144	W
Supply Voltage of Pre-Driver *4		V _{cc}	-0.5	20	V
Input Signal Voltage *5		V _{in}	-0.5	V _{cc} +0.5	V
Input Signal Current		I _{in}	—	3	mA
Alarm Signal Voltage *6		V _{ALM}	-0.5	V _{cc}	V
Alarm Signal Current *7		I _{ALM}	—	20	mA
Junction Temperature		T _j	—	150	
Operating Case Temperature		T _{opr}	-20	100	
Storage Temperature		T _{stg}	-40	125	
Solder Temperature *8		T _{sol}	—	260	
Isolating Voltage (Terminal to base, 50/60Hz sine wave 1min.)		V _{iso}	—	AC2500	V
Screw Torque	Mounting (M5)	—	—	3.5	Nm

Note

- *1 : V_{ces} shall be applied to the input voltage between terminal P and U or V or W, N and U or V or W
- *2 : $125 / \text{FWD Rth(j-c)} / (\text{Ic} \times \text{VF MAX}) = 125 / 1.263 / (50 \times 2.6) \times 100 = 76.1\%$
- *3 : $\text{Pc} = 125 / \text{IGBT Rth(j-c)} = 125 / 0.87 = 144\text{W}$ [Inverter]
- *4 : V_{CC} shall be applied to the input voltage between terminal No.4 and 1, 8 and 5, 12 and 9, 14 and 13
- *5 : V_{in} shall be applied to the input voltage between terminal No.3 and 1, 7 and 5, 11 and 9, 16,17,18 and 13 .
- *6 : V_{ALM} shall be applied to the voltage between terminal No.2 and 1, No6 and 5, No10 and 9, No.19 and 13 .
- *7 : I_{ALM} shall be applied to the input current to terminal No.2,6,10 and 19 .
- *8 : Immersion time 10 ± 1sec.

5 . Electrical Characteristics

$T_j = 25$, $V_{cc} = 15V$ unless otherwise specified.

5.1 Main circuit

Item		Symbol	Conditions	Min.	Typ.	Max.	Units
Inverter	Collector Current at off signal input	ICES	VCE = 600V Vin terminal open.	-	-	1.0	mA
	Collector-Emitter saturation voltage	VCE(sat)	Ic = 50A Terminal	-	-	2.5	V
			Chip	-	2.0	-	V
	Forward voltage of FWD	VF	-Ic = 50A Terminal	-	-	2.6	V
Chip			-	1.6	-	V	
Turn-on time		ton	VDC = 300V\ Tj=125 Ic = 50A Fig.1 , Fig.6	1.2	-	-	us
Turn-off time		toff		-	-	3.6	
Reverse recovery time		trr	VDC = 300V\ Tj=25 IF = 50A Fig.1 , Fig.6	-	-	0.3	
Maximum Avalanche Energy (A non-repetition)		PAV	internal wiring inductance = 50nH Main circuit wiring inductance = 54nH	30	-	-	mJ

5.2 Control circuit

Item	Symbol	Conditions	Min.	Typ.	Max.	Units
Supply current of P-side pre-driver (one unit)	I_{ccp}	Switching Frequency: 0 ~ 15kHz	-	-	18	mA
Supply current of N-side pre-driver	I_{ccn}	$T_c = -20 \sim 125$ Fig.7	-	-	65	mA
Input signal threshold voltage	$V_{in(th)}$	ON	1.00	1.35	1.70	V
		OFF	1.25	1.60	1.95	
Input Zener Voltage	V_z	$R_{in} = 20k\Omega$	-	8.0	-	V
Alarm Signal Hold Time	t_{ALM}	$T_c = -20$ Fig.2	1.1	-	-	ms
		$T_c = 25$ Fig.2	-	2.0	-	ms
		$T_c = 125$ Fig.2	-	-	4.0	ms
Current Limit Resistor	R_{ALM}	Alarm terminal	1425	1500	1575	Ω

①

5.3 Protection Section (Vcc = 15V)

Item	Symbol	Conditions	Min.	Typ.	Max.	Units
Over Current Protection Level of Inverter circuit	loc	Tj=125	75	-	-	A
Over Current Protection Delay time	tdoc	Tj=125	-	5	-	us
SC Protection Delay time	tsc	Tj=125 Fig.4	-	-	8	us
IGBT Chips Over Heating Protection Temperature Level	TjOH	Surface of IGBT Chips	150	-	-	
Over Heating Protection Hysteresis	TjH		-	20	-	
Under Voltage Protection Level	VUV		11.0	-	12.5	V
Under Voltage Protection Hysteresis	VH		0.2	0.5	-	

6. Thermal Characteristics (Tc = 25 °C)

Item			Symbol	Min.	Typ.	Max.	Units
Junction to Case Thermal Resistance *10	Inverter	IGBT	Rth(j-c)	-	-	0.87	/W
		FWD	Rth(j-c)	-	-	1.263	
Case to Fin Thermal Resistance with Compound			Rth(c-f)	-	0.05	-	

7. Noise Immunity (Vdc=300V, Vcc=15V, Test Circuit Fig 5.)

Item	Conditions	Min.	Typ.	Max.	Units
Common mode rectangular noise	Pulse width 1us, polarity ±, 10 minutes Judge: no over-current, no miss operating	± 2.0	-	-	kV
Common mode lightning surge	Rise time 1.2us, Fall time 50us Interval 20s, 10 times Judge: no over-current, no miss operating	± 5.0	-	-	kV

8. Recommended Operating Conditions

Item	Symbol	Min.	Typ.	Max.	Units
DC Bus Voltage	Vdc	-	-	400	V
Power Supply Voltage of Pre-Driver	Vcc	13.5	15.0	16.5	V
Screw Torque (M5)	-	2.5	-	3.0	Nm

9. Weight

Item	Symbol	Min.	Typ.	Max.	Units
Weight	Wt	-	270	-	g

*10: (For 1device , Case is under the device)

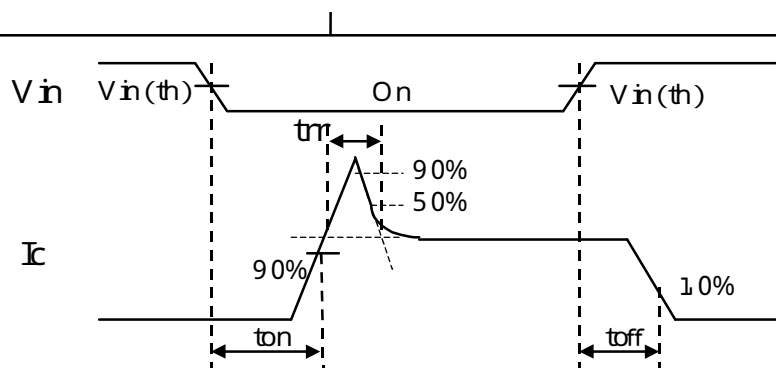
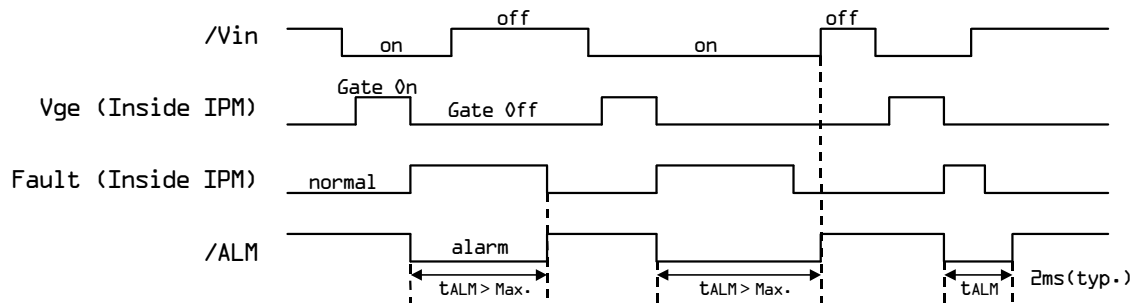


Figure 1. Switching Time Waveform Definitions



Fault : Over-current, Over-heat or Under-voltage

Figure 2. Input/Output Timing Diagram

Necessary conditions for alarm reset (refer to to in figure2.)

This represents the case when a failure-causing Fault lasts for a period more than t_{ALM} . The alarm resets when the input V_{in} is OFF and the Fault has disappeared.

This represents the case when the ON condition of the input V_{in} lasts for a period more than t_{ALM} . The alarm resets when the V_{in} turns OFF under no Fault conditions.

This represents the case when the Fault disappears and the V_{in} turns OFF within t_{ALM} . The alarm resets after lasting for a period of the specified time t_{ALM} .

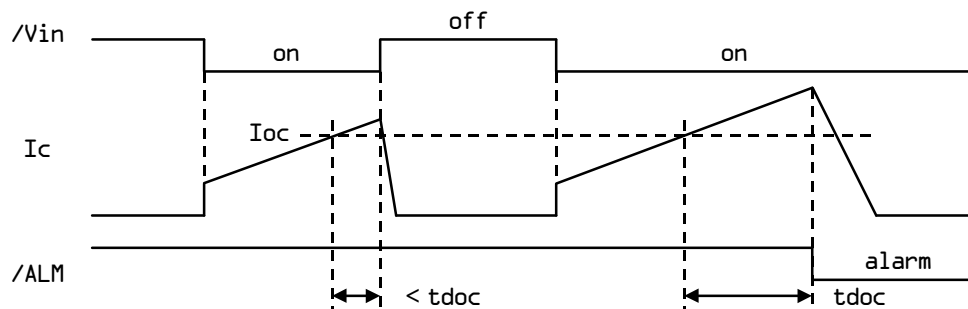


Figure 3. Over-current Protection Timing Diagram

Period : When a collector current over the OC level flows and the OFF command is input within a period less than the trip delay time t_{doc} , the current is hard-interrupted and no alarm is output.

Period : When a collector current over the OC level flows for a period more than the trip delay time t_{doc} , the current is soft-interrupted. If this is detected at the lower arm IGBTs, an alarm is output.

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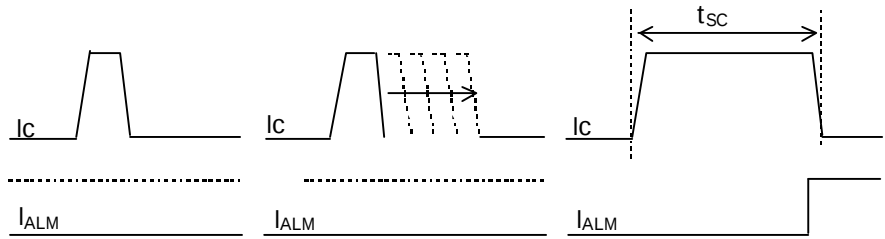


Figure.4 Definition of tsc

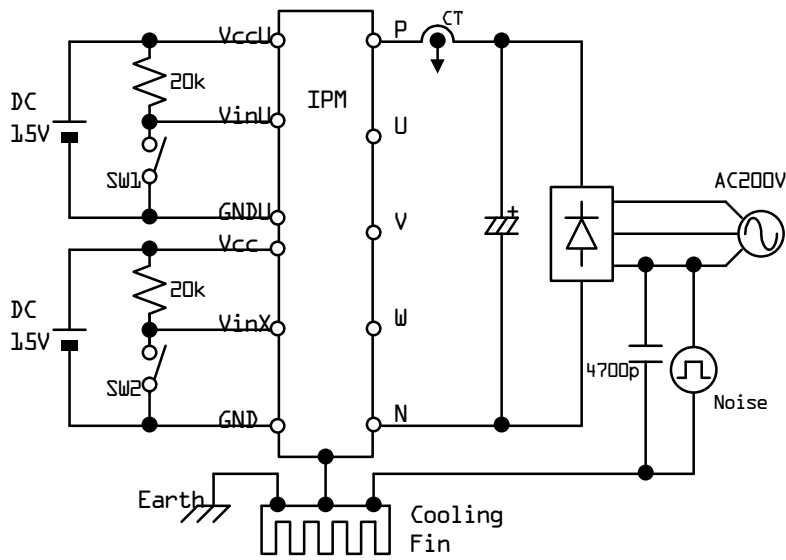


Figure 5. Noise Test Circuit

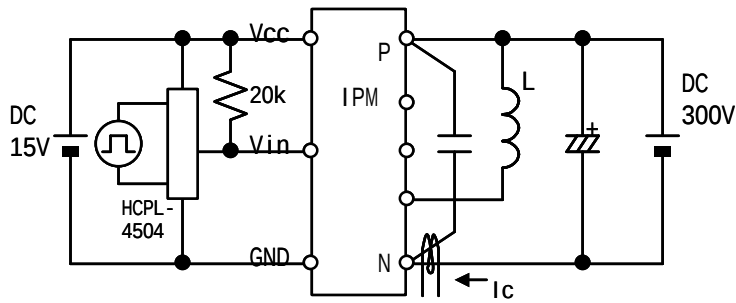


Figure 6. Switching Characteristics Test Circuit

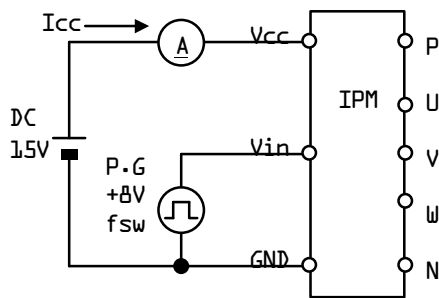


Figure 7. Icc Test Circuit

10. Truth table

10.1 IGBT Control

The following table shows the IGBT ON/OFF status with respect to the input signal Vin.
The IGBT turn-on when Vin is at “Low” level under no alarm condition.

Input (Vin)	Output (IGBT)
Low	ON
High	OFF

10.2 Fault Detection

- (1) When a fault is detected at the high side, only the detected arm stops its output. At that time the IPM outputs detected arm's alarm.
- (2) When a fault is detected at the low side, all the lower arms stop their outputs and the IPM outputs an alarm of the low side.

	Fault	IGBT				Alarm Output			
		U-phase	V-phase	W-phase	Low side	ALM-U	ALM-V	ALM-W	ALM
High side U-phase	OC	OFF	*	*	*	L	H	H	H
	UV	OFF	*	*	*	L	H	H	H
	TjOH	OFF	*	*	*	L	H	H	H
High side V-phase	OC	*	OFF	*	*	H	L	H	H
	UV	*	OFF	*	*	H	L	H	H
	TjOH	*	OFF	*	*	H	L	H	H
High side W-phase	OC	*	*	OFF	*	H	H	L	H
	UV	*	*	OFF	*	H	H	L	H
	TjOH	*	*	OFF	*	H	H	L	H
Low side	OC	*	*	*	OFF	H	H	H	L
	UV	*	*	*	OFF	H	H	H	L
	TjOH	*	*	*	OFF	H	H	H	L

* : Depend on input logic.

11. Cautions for design and application

1. Trace routing layout should be designed with particular attention to least stray capacity between the primary and secondary sides of optical isolators by minimizing the wiring length between the optical isolators and the IPM input terminals as possible.

フォトカブラとIPMの入力端子間の配線は極力短くし、フォトカブラの一次側と二次側の浮遊容量を小さくしたパターンレイアウトにして下さい。

2. Mount a capacitor between Vcc and GND of each high-speed optical isolator as close to as possible. 高速フォトカブラの Vcc-GND 間に、コンデンサを出来るだけ近接して取り付けて下さい。

3. For the high-speed optical isolator, use high-CMR type one with tpHL, tpLH 0.8μs.

高速フォトカブラは tpHL, tpLH 0.8us、高 CMR タイプをご使用ください。

4. For the alarm output circuit, use low-speed type optical isolators with CTR 100%.

アラーム出力回路は、低速フォトカブラ CTR 100%のタイプをご使用ください。

5. For the control power Vcc, use four power supplies isolated each. And they should be designed to reduce the voltage variations.

制御電源 Vcc は、絶縁された4電源を使用してください。また、電圧変動を抑えた設計として下さい。

6. Suppress surge voltages as possible by reducing the inductance between the DC bus P and N, and connecting some capacitors between the P and N terminals

P-N 間の直流母線は出来るだけ低インダクタンス化し、P-N 端子間にコンデンサを接続するなどしてサージ電圧を低減して下さい。

7. To prevent noise intrusion from the AC lines, connect a capacitor of some 4700pF between the three-phase lines each and the ground.

AC ラインからのノイズ侵入を防ぐために、3相各線 - アース間に4700pF程のコンデンサを接続して下さい。

8. At the external circuit, never connect the control terminal GNDU to the main terminal U-phase, GNDV to V-phase, GNDW to W-phase, and GND to N-phase. Otherwise, malfunctions may be caused.

制御端子 GNDUと主端子U相、制御端子 GNDVと主端子V相、制御端子 GNDWと主端子W相

制御端子 GNDと主端子Nを外部回路で接続しないで下さい。誤動作の原因になります。

9. Take note that an optical isolator's response to the primary input signal becomes slow if a capacitor is connected between the input terminal and GND.

入力端子-GND 間にコンデンサを接続すると、フォトカブラ一次側入力信号に対する応答時間が長くなりますのでご注意ください。

10. Taking the used isolator's CTR into account, design with a sufficient allowance to decide the primary forward current of the optical isolator.

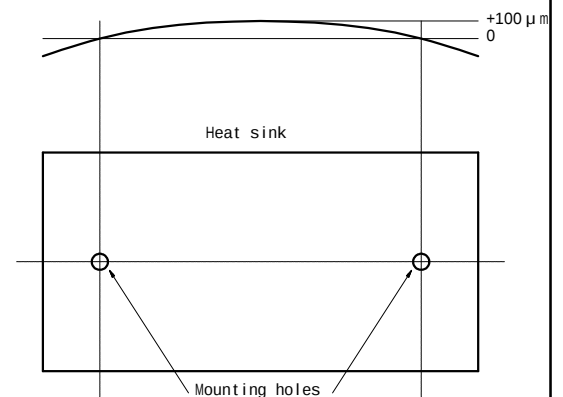
フォトカプラの一次側電流は、お使いのフォトカプラの CTR を考慮し十分に余裕をもった設計にしてください。

11. Apply thermal compound to the surfaces between the IPM and its heat sink to reduce the thermal contact resistance.

接触熱抵抗を小さくするために、IPMとヒートシンクの上にサーマルコンパウンド塗布して下さい。

12. Finish the heat sink surface within roughness of 10 μ m and flatness (camber) between screw positions of 0 to +100 μ m. If the flatness is minus, the heat radiation becomes worse due to a gap between the heat sink and the IPM. And, if the flatness is over +100 μ m, there is a danger that the IPM copper base may be deformed and this may cause a dielectric breakdown.

ヒートシンク表面の仕上げは、粗さ 10 μ m 以下、ネジ位置間での平坦度(反り)は 0 ~ 100 μ m として下さい。平坦度がマイナスの場合、ヒートシンクと IPM の間に隙間ができ放熱が悪化します。また、平坦度が +100 μ m 以上の場合 IPM の銅ベースが変形し絶縁破壊を起こす危険性があります。



13. This product is designed on the assumption that it applies to a servo use. Sufficient examination is required when applying to a general purpose inverter or converter use. Please contact Fuji Electric Co., Ltd if you would like to applying to general purpose inverter or converter use.

本製品は、サーボ用途への適用を前提に設計されております。汎用インバータやコンバータ用途へ適用される場合は、十分な検討が必要です。もし、汎用インバータやコンバータへ適用される場合は御連絡ください。

14. Please see the 『Fuji IGBT-IPM R SERIES APPLICATION MANUAL』 and 『Fuji IGBT MODULES N SERIES APPLICATION MANUAL』.

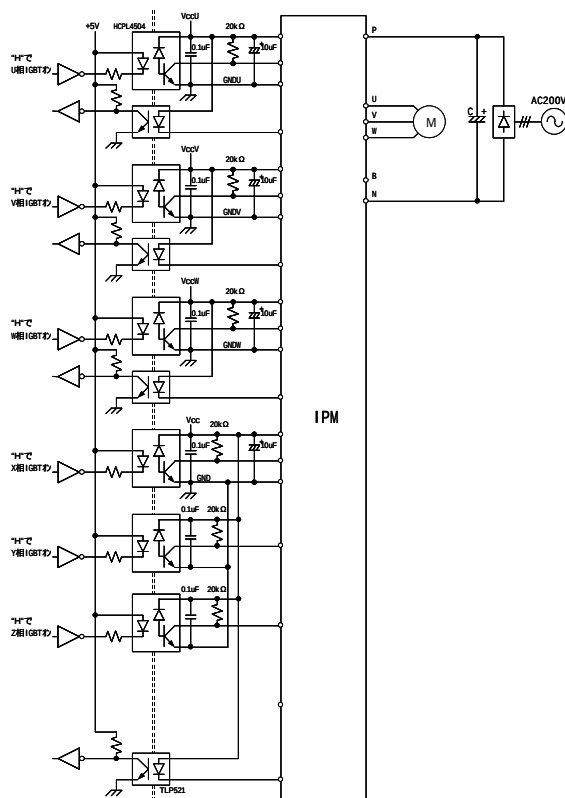
『富士 IGBT-IPM R シリーズ アプリケーションマニュアル』及び『IGBT モジュール N シリーズ アプリケーションマニュアル』を御参照ください。

- ① 15. There is thermal interference between nearby power devices, because the Econo IPM is a compact package. Therefore you measure the case temperature just under the IGBT chips that showed in report MT6M04545, and estimate the chip temperature.

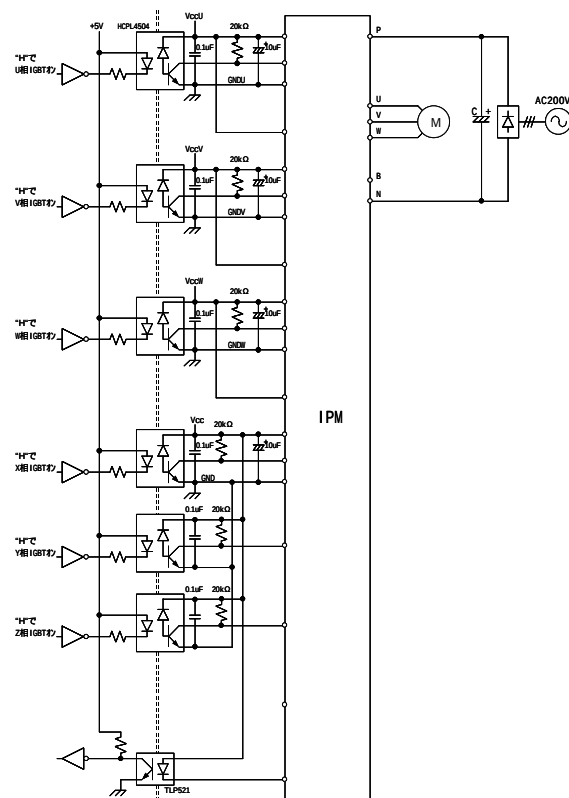
Econo IPM はパッケージ小型化のため、パワー素子の熱干渉が考えられます。

その為、チップ温度推定は必ず MT6M04545 に示すチップ直下のケース温度を測定して行って下さい。

① 1 2 . Example of applied circuit 応用回路例



(a) In case of use of High side alarm
上アームアラーム使用の場合



(b) In case of no use of High side alarm
上アームアラーム不使用の場合

1 3 . Package and Marking 梱包仕様

Please see the MT6M04140 which is packing specification of IPM .

IPM 梱包仕様書 MT 6 M 0 4 1 4 0 を御参照ください。

1 4 . Cautions for storage and transportation 保管、運搬上の注意

- Store the modules at the normal temperature and humidity (5 to 35°C, 45 to 75%).
常温常湿(5～35℃、45～75%)で保存して下さい。
- Avoid a sudden change in ambient temperature to prevent condensation on the module surfaces. モジュールの表面が結露しないよう、急激な温度変化を避けて下さい。
- Avoid places where corrosive gas generates or much dust exists.
腐食性ガスの発生場所、粉塵の多い場所は避けて下さい。
- Store the module terminals under unprocessed conditions
モジュールの端子は未加工の状態での保管すること。
- Avoid physical shock or falls during the transportation.
運搬時に衝撃を与えたり落下させないで下さい。

1 5 . Scope of application 適用範囲

This specification is applied to the IGBT-IPM (type: 6MBP50TEA060).

本仕様書は、IGBT-IPM (型式：6MBP50TEA060)に適用する。

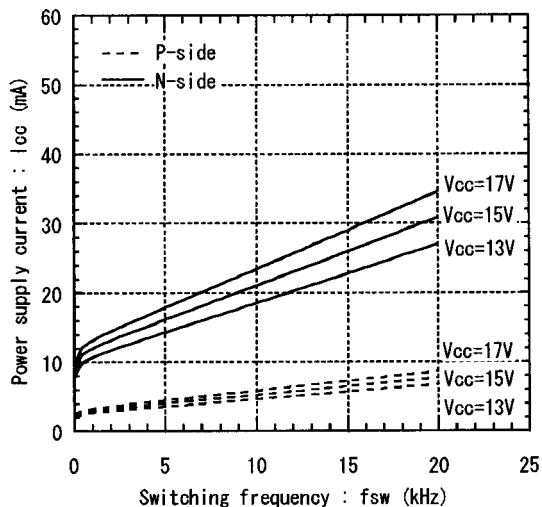
1 6 . Based safety standards 準拠安全規格

UL1557

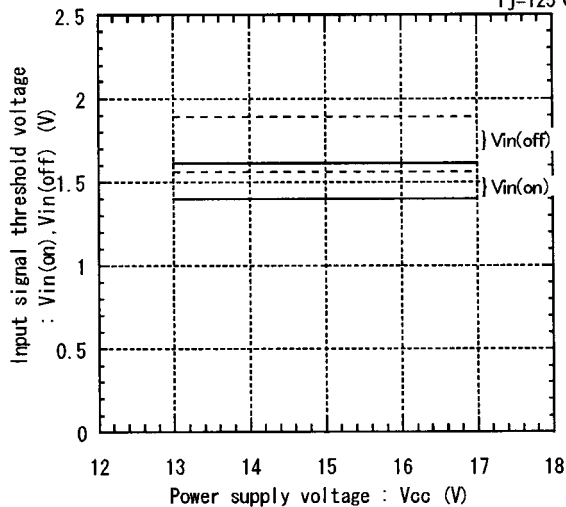
17. Characteristics

17-1. Control Circuit Characteristics (Representative)

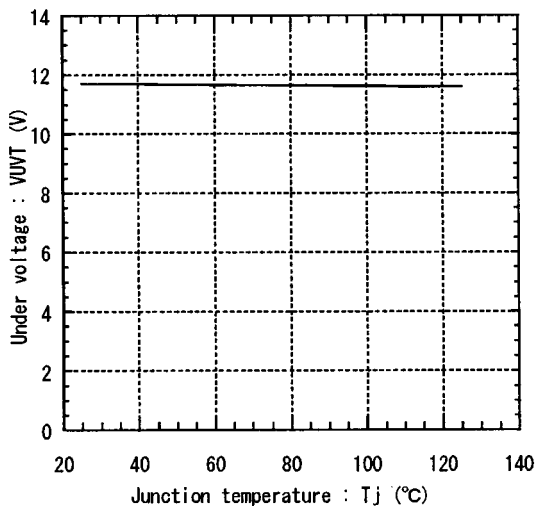
Power supply current vs. Switching frequency
 $T_c=125^\circ\text{C}$



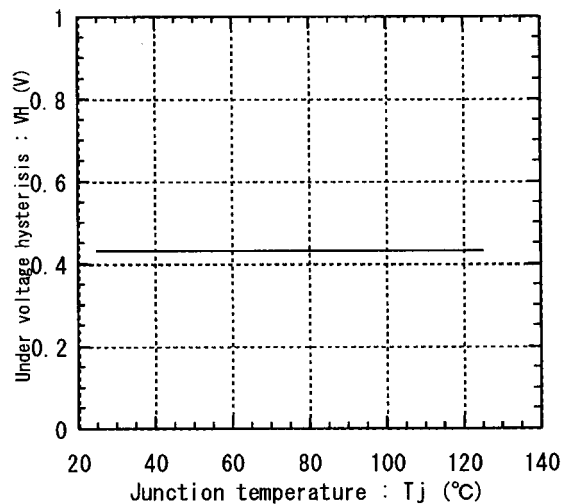
Input signal threshold voltage vs. Power supply voltage
 $T_j=25^\circ\text{C}$ (solid line)
 $T_j=125^\circ\text{C}$ (dashed line)



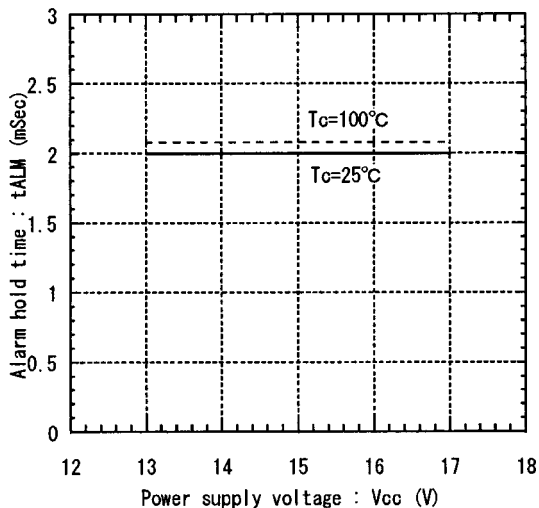
Under voltage vs. Junction temperature



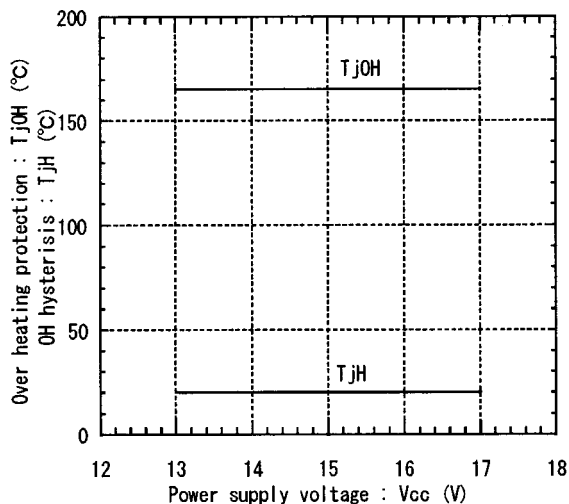
Under voltage hysteresis vs. Junction temperature



Alarm hold time vs. Power supply voltage



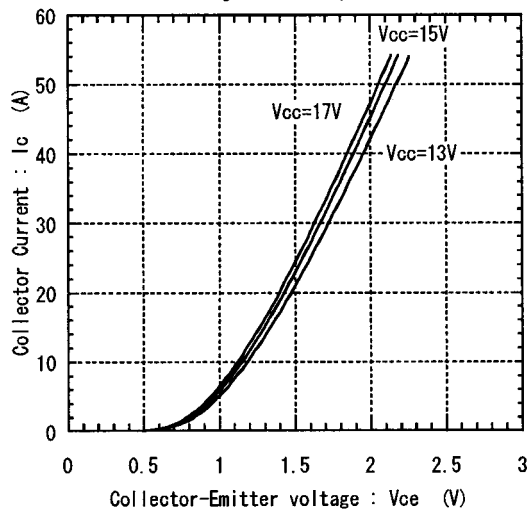
Over heating characteristics
 T_{jOH} , T_{jH} vs. V_{cc}



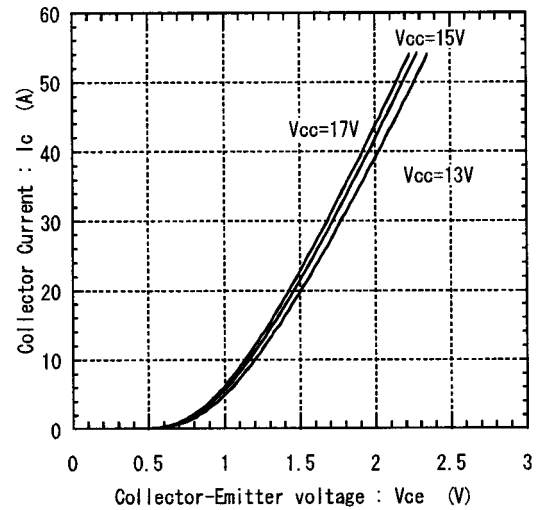
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17-2. Main Circuit Characteristics (Representative)

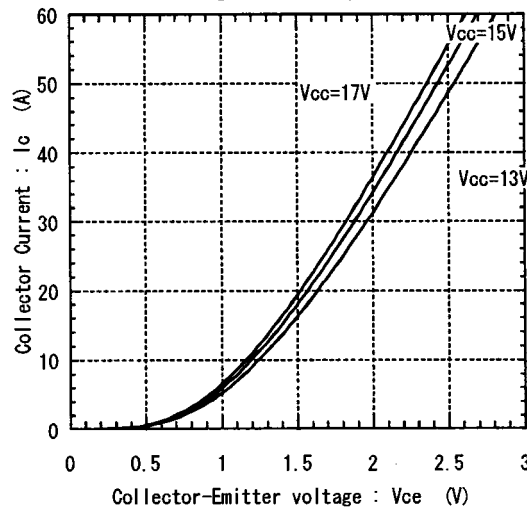
Collector current vs. Collector-Emitter voltage
 $T_j=25^\circ\text{C}$ (Chip)



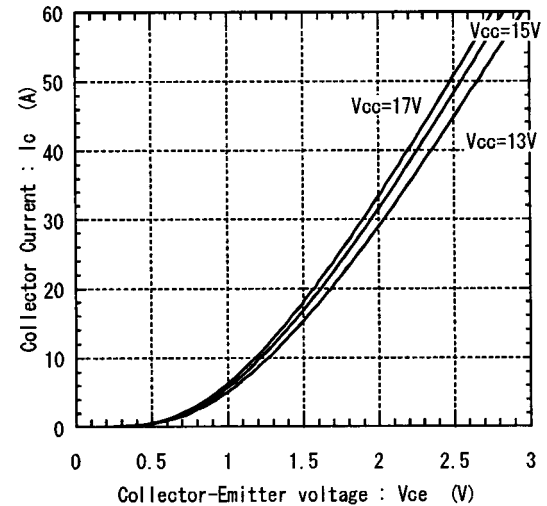
Collector current vs. Collector-Emitter voltage
 $T_j=25^\circ\text{C}$ (Terminal)



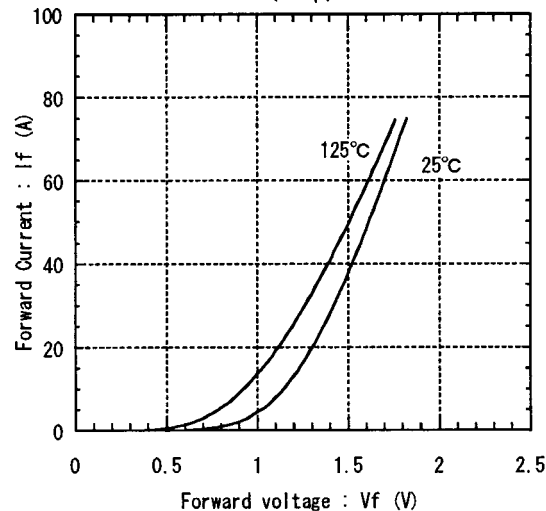
Collector current vs. Collector-Emitter voltage
 $T_j=125^\circ\text{C}$ (Chip)



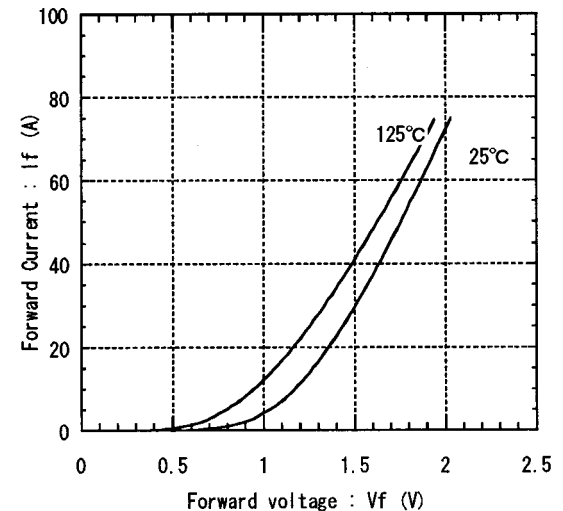
Collector current vs. Collector-Emitter voltage
 $T_j=125^\circ\text{C}$ (Terminal)



Forward current vs. Forward voltage
(Chip)

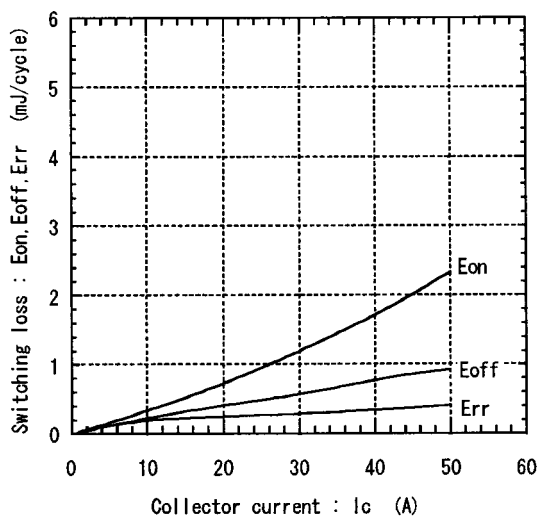


Forward current vs. Forward voltage
(Terminal)

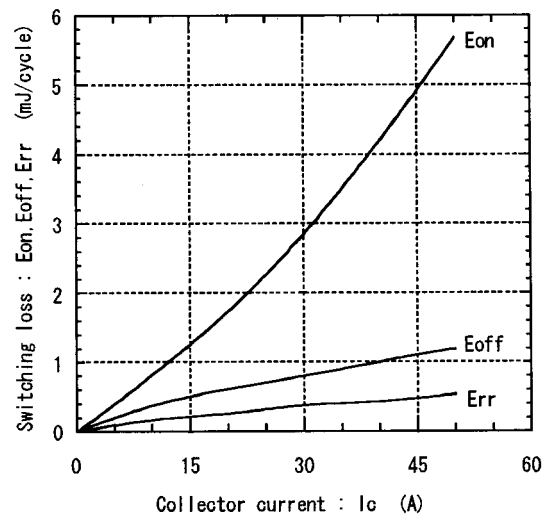


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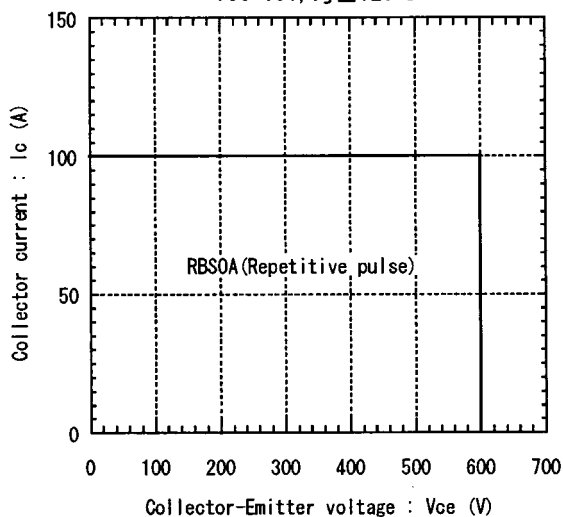
Switching Loss vs. Collector Current
 $E_{dc}=300V, V_{cc}=15V, T_j=25^\circ C$



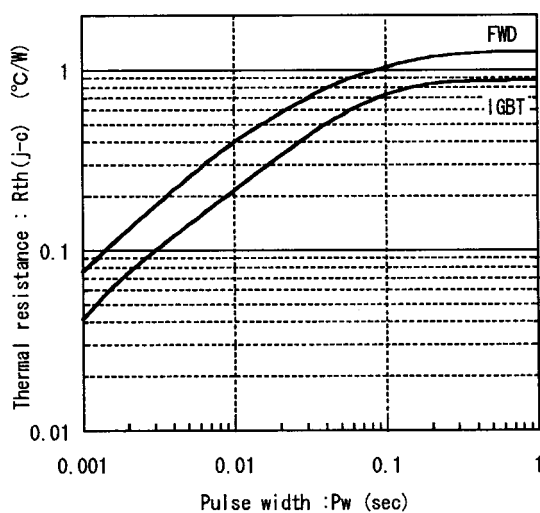
Switching Loss vs. Collector Current
 $E_{dc}=300V, V_{cc}=15V, T_j=125^\circ C$



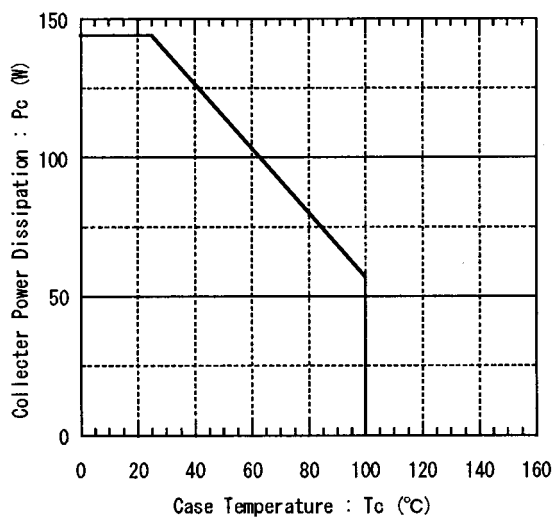
Reversed biased safe operating area
 $V_{cc}=15V, T_j \leq 125^\circ C$



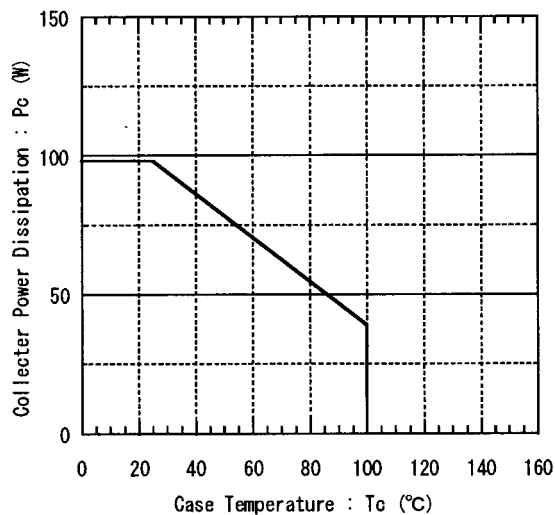
Transient thermal resistance



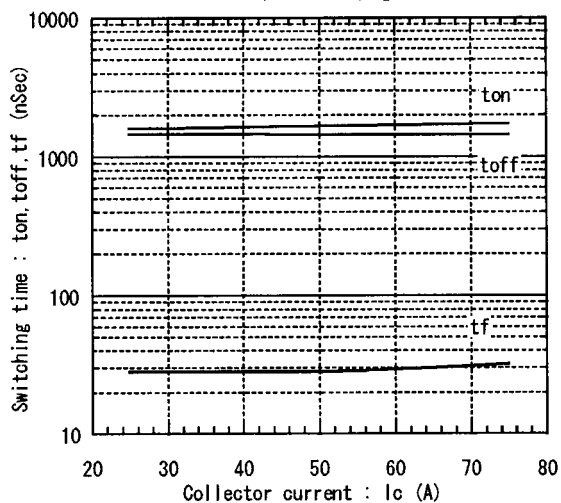
Power derating for IGBT
(per device)



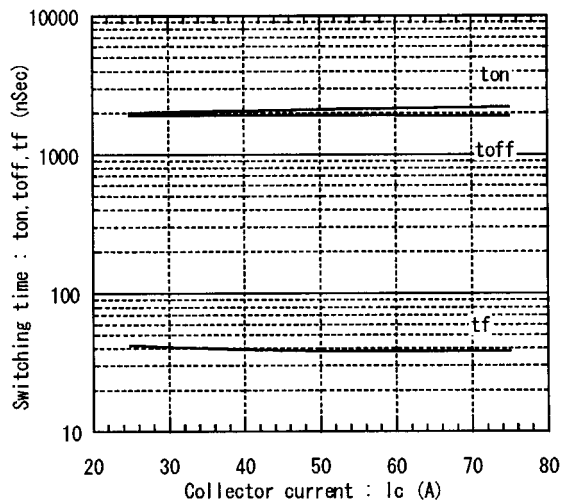
Power derating for FWD
(per device)



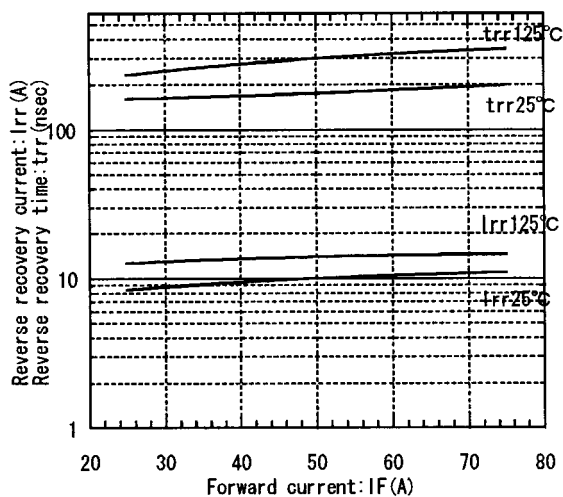
Switching time vs. Collector current
 $E_{dc}=300V, V_{cc}=15V, T_j=25^{\circ}C$



Switching time vs. Collector current
 $E_{dc}=300V, V_{cc}=15V, T_j=125^{\circ}C$



Reverse recovery characteristics
 t_{rr}, I_{rr} vs. I_F



① 18-1 . Reliability Test Items

Test categories	Test items	Test methods and conditions	Reference norms EIAJ ED-4701	Number of sample	Acceptance number
Mechanical Tests	1 Terminal strength 端子強度 (Pull test)	Pull force : 20 N (main terminal) 10 N (control terminal) Test time : 10 ±1 sec.	Test Method 401 Method	5	(1 : 0)
	2 Mounting Strength 締付け強度	Screw torque : 2.5 ~ 3.5 N・m (M5) Test time : 10 ±1 sec.	Test Method 402 method	5	(1 : 0)
	3 Vibration 振動	Range of frequency : 10 ~ 500 Hz Sweeping time : 15 min. Acceleration : 100 m/s ² Sweeping direction : Each X,Y,Z axis Test time : 6 hr. (2hr./direction)	Test Method 403 Condition code B	5	(1 : 0)
	4 Shock 衝撃	Maximum acceleration : 5000 m/s ² Pulse width : 1.0 ms Direction : Each X,Y,Z axis Test time : 3 times/direction	Test Method 404 Condition code B	5	(1 : 0)
	5 Solderability はんだ付け性	Solder temp. : 235 ±5 Immersion duration : 5.0 ±0.5 sec. Test time : 1 time Each terminal should be Immersed in solder within 1~1.5mm from the body.	Test Method 303 Condition code A	5	(1 : 0)
	6 Resistance to soldering heat はんだ耐熱性	Solder temp. : 260 ±5 Immersion time : 10 ±1sec. Test time : 1 time Each terminal should be Immersed in solder within 1~1.5mm from the body.	Test Method 302 Condition code A	5	(1 : 0)
Environment Tests	1 High temperature storage 高温保存	Storage temp. : 125 ±5 Test duration : 1000 hr.	Test Method 201	5	(1 : 0)
	2 Low temperature storage 低温保存	Storage temp. : -40 ±5 Test duration : 1000 hr.	Test Method 202	5	(1 : 0)
	3 Temperature humidity storage 高温高湿保存	Storage temp. : 85 ±2 Relative humidity : 85 ±5% Test duration : 1000hr.	Test Method 103 Test code C	5	(1 : 0)
	4 Unsaturated pressure cooker プレッシャークッカー	Test temp. : 120 ±2 Atmospheric pressure : 1.7x10 ⁵ Pa Test humidity : 85 ±5% Test duration : 96 hr.	Test Method 103 Test code E	5	(1 : 0)
	5 Temperature cycle 温度サイクル	Test temp. : Minimum storage temp. -40 ±5 Maximum storage temp. 125 ±5 Normal temp. 5 ~ 35 Dwell time : Tmin ~ TN ~ Tmax ~ TN 1hr. 0.5hr. 1hr. 0.5hr. Number of cycles : 100 cycles	Test Method 105	5	(1 : 0)
	6 Thermal shock 熱衝撃	Test temp. : High temp. side 100 ⁺⁰ ₋₅ Low temp. side 0 ⁺⁵ ₋₀ Fluid used : Pure water (running water) Dipping time : 5 min. par each temp. Transfer time : 10 sec. Number of cycles : 10 cycles	Test Method 307 method Condition code A	5	(1 : 0)

① 18 - 2 . Reliability Test Items

Test categories	Test items	Test methods and conditions	Reference norms EIAJ ED-4701	Number of sample	Acceptance number
Endurance Tests	1 High temperature reverse bias 高温逆バイアス	Test temp. : $T_a = 125 \pm 5$ ($T_j \ 150$) Bias Voltage : $V_C = 0.8 \times V_{CES}$ Bias Method : Applied DC voltage to C-E $V_{cc} = 15V$ Test duration : 1000 hr.	Test Method 101	5	(1 : 0)
	2 Temperature humidity bias 高温高湿バイアス	Test temp. : 85 ± 2 Relative humidity : $85 \pm 5 \%$ Bias Voltage : $V_C = 0.8 \times V_{CES}$ $V_{cc} = 15V$ Bias Method : Applied DC voltage to C-E Test duration : 1000 hr.	Test Method 102 Condition code C	5	(1 : 0)
	3 Intermittent operating life (Power cycle) 断続動作	ON time : 2 sec. OFF time : 18 sec. Test temp. : $\Delta T_j = 100 \pm 5 \text{deg}$ $T_j \ 150$, $T_a = 25 \pm 5$ Number of cycles : 15000 cycles	Test Method 106	5	(1 : 0)

19 . Failure Criteria

Item	Characteristic	Symbol	Failure criteria		Unit	Note
			Lower limit	Upper limit		
Electrical characteristic	Leakage current	ICES	-	USL×2	mA	
	Saturation voltage	VCE(sat)	-	USL×1.2	V	
	Forward voltage	VF	-	USL×1.2	V	
	Thermal resistance	IGBT Rth(j-c)	-	USL×1.2	/W	
		FWD Rth(j-c)	-	USL×1.2	/W	
	Over Current Protection	Ioc	LSL×0.8	USL×1.2	A	
	Alarm signal hold time	tALM	LSL×0.8	USL×1.2	ms	
Visual inspection	Isolation voltage	Viso	Broken insulation		-	
	Visual inspection Peeling Plating and the others	-	The visual sample		-	

LSL : Lower specified limit.

USL : Upper specified limit.

Note : Each parameter measurement read-outs shall be made after stabilizing the components at room ambient for 2 hours minimum, 24 hours maximum after removal from the tests. And in case of the wetting tests, for example, moisture resistance tests, each component shall be made wipe or dry completely before the measurement.

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Warnings

1. This product shall be used within its absolute maximum rating (voltage, current, and temperature). This product may be broken in case of using beyond the ratings.
製品の絶対最大定格(電圧, 電流, 温度等)の範囲内で御使用下さい。絶対最大定格を超えて使用すると、素子が破壊する場合があります。
2. Connect adequate fuse or protector of circuit between three-phase line and this product to prevent the equipment from causing secondary destruction.
万一の不慮の事故で素子が破壊した場合を考慮し、商用電源と本製品の間に適切な容量のヒューズ又はブレーカーを必ず付けて2次破壊を防いでください。
3. When studying the device at a normal turn-off action, make sure that working paths of the turn-off voltage and current are within the RBSOA specification. And, when studying the device duty at a short-circuit current non-repetitive interruption, make sure that the paths are also within the avalanche proof (PAV) specification which is calculated from the snubber inductance, the IPM inner inductance and the turn-off current. In case of use of IGBT-IPM over these specifications, it might be possible to be broken.
通常のターンオフ動作における素子責務の検討の際には、ターンオフ電圧・電流の動作軌跡がRBSOA仕様内にあることを確認して下さい。また、非繰返しの短絡電流遮断における素子責務の検討に際しては、スナバーインダクタンスとIPM内部インダクタンス及びターンオフ電流から算出されるアバランシェ耐量(PAV)仕様内である事を確認して下さい。これらの仕様を越えて使用すると、素子が破壊する場合があります。
4. Use this product after realizing enough working on environment and considering of product's reliability life. This product may be broken before target life of the system in case of using beyond the product's reliability life.
製品の使用環境を十分に把握し、製品の信頼性寿命が満足できるか検討の上、本製品を適用して下さい。製品の信頼性寿命を超えて使用した場合、装置の目標寿命より前に素子が破壊する場合があります。
5. If the product had been used in the environment with acid, organic matter, and corrosive gas (For example : hydrogen sulfide, sulfurous acid gas), the product's performance and appearance can not be ensured easily.
酸・有機物・腐食性ガス(硫化水素, 亜硫酸ガス等)を含む環境下で使用された場合、製品機能・外観などの保証は致しかねます。
6. Use the product within the power cycle curve (Technical Rep.No. : MT6M4057)
本製品は、パワーサイクル寿命カーブ以下で使用下さい(技術資料 No.: MT6M4057)

7. Never add mechanical stress to deform the main or control terminal. The deformed

terminal may cause poor contact problem.

主端子及び制御端子に応力を与えて変形させないで下さい。端子の変形により、接触不良などを引き起こす場合があります。

8. If excessive static electricity is applied to the control terminals, the devices can be broken. Implement some countermeasures against static electricity.

制御端子に過大な静電気が印加された場合、素子が破壊する場合があります。取り扱い時は静電気対策を実施して下さい。

Caution

1. Fuji Electric is constantly making every endeavor to improve the product quality and reliability. However, semiconductor products may rarely happen to fail or malfunction. To prevent accidents causing injury or death, damage to property like by fire, and other social damage resulted from a failure or malfunction of the Fuji Electric semiconductor products, take some measures to keep safety such as redundant design, spread-fire-preventive design, and malfunction-protective design.

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2. The application examples described in this specification only explain typical ones that used the Fuji Electric products. This specification never ensure to enforce the industrial property and other rights, nor license the enforcement rights.

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3. The product described in this specification is not designed nor made for being applied to the equipment or systems used under life-threatening situations. When you consider applying the product of this specification to particular used, such as vehicle-mounted units, shipboard equipment, aerospace equipment, medical devices, atomic control systems and submarine relaying equipment or systems, please apply after confirmation of this product to be satisfied about system construction and required reliability.

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