



## M27C320

### 32 Mbit (4Mb x8 or 2Mb x16) OTP EPROM

- 5V  $\pm$  10% SUPPLY VOLTAGE in READ OPERATION
- ACCESS TIME: 80ns
- BYTE-WIDE or WORD-WIDE CONFIGURABLE
- 32 Mbit MASK ROM REPLACEMENT
- LOW POWER CONSUMPTION
  - Active Current 70mA at 8MHz
  - Stand-by Current 100mA
- PROGRAMMING VOLTAGE: 12V  $\pm$  0.25V
- PROGRAMMING TIME: 50 $\mu$ s/word
- ELECTRONIC SIGNATURE:
  - Manufacturer Code 20h
  - Device Code: 32h

#### DESCRIPTION

The M27C320 is a 32 Mbit EPROM offered in the OTP range (one time programmable). It is ideally suited for microprocessor systems requiring large data or program storage. It is organised as either 4 MWords of 8 bit or 2 MWords of 16 bit. The pin-out is compatible with the 32 Mbit Mask ROM.

The M27C320 is offered in SO44 and TSOP48 (12 x 20 mm) packages.

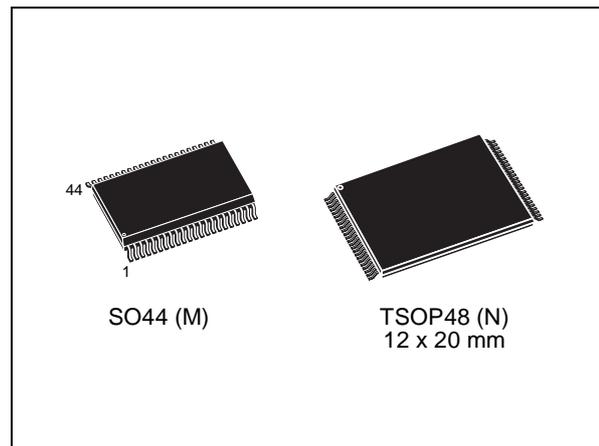
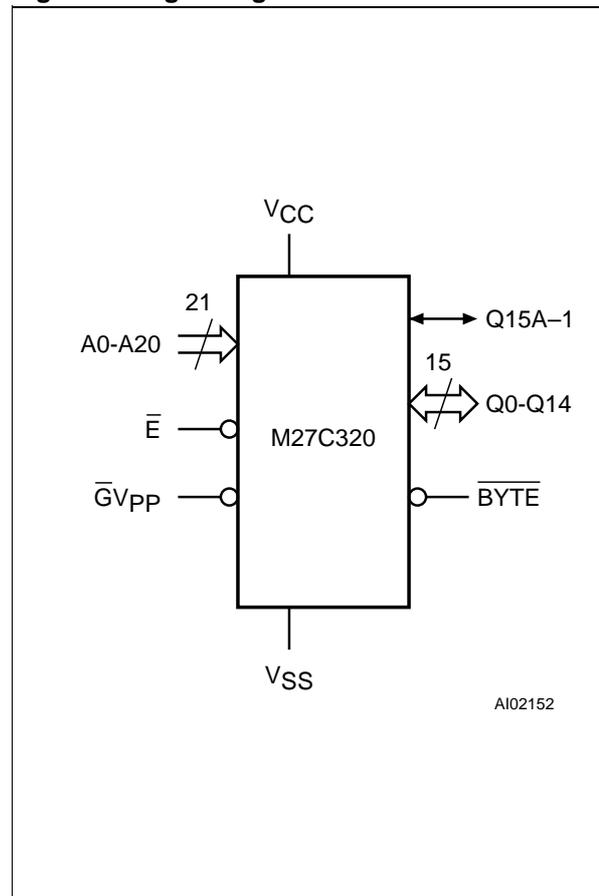


Figure 1. Logic Diagram





**Table 2. Absolute Maximum Ratings (1)**

Symbol	Parameter	Value	Unit
T <sub>A</sub>	Ambient Operating Temperature (3)	-40 to 125	°C
T <sub>BIAS</sub>	Temperature Under Bias	-50 to 125	°C
T <sub>STG</sub>	Storage Temperature	-65 to 150	°C
V <sub>IO</sub> (2)	Input or Output Voltage (except A9)	-2 to 7	V
V <sub>CC</sub>	Supply Voltage	-2 to 7	V
V <sub>A9</sub> (2)	A9 Voltage	-2 to 13.5	V
V <sub>PP</sub>	Program Supply Voltage	-2 to 14	V

Note: 1. Except for the rating "Operating Temperature Range", stresses above those listed in the Table "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics SURE Program and other relevant quality documents.

2. Minimum DC voltage on Input or Output is -0.5V with possible undershoot to -2.0V for a period less than 20ns. Maximum DC voltage on Output is V<sub>CC</sub> +0.5V with possible overshoot to V<sub>CC</sub> +2V for a period less than 20ns.
3. Depends on range.

**Table 3. Operating Modes**

Mode	$\bar{E}$	$\overline{GV}_{PP}$	$\overline{BYTE}$	A9	Q15A-1	Q14-Q8	Q7-Q0
Read Word-wide	V <sub>IL</sub>	V <sub>IL</sub>	V <sub>IH</sub>	X	Data Out	Data Out	Data Out
Read Byte-wide Upper	V <sub>IL</sub>	V <sub>IL</sub>	V <sub>IL</sub>	X	V <sub>IH</sub>	Hi-Z	Data Out
Read Byte-wide Lower	V <sub>IL</sub>	V <sub>IL</sub>	V <sub>IL</sub>	X	V <sub>IL</sub>	Hi-Z	Data Out
Output Disable	V <sub>IL</sub>	V <sub>IH</sub>	X	X	Hi-Z	Hi-Z	Hi-Z
Program	V <sub>IL</sub> Pulse	V <sub>PP</sub>	V <sub>IH</sub>	X	Data In	Data In	Data In
Program Inhibit	V <sub>IH</sub>	V <sub>PP</sub>	V <sub>IH</sub>	X	Hi-Z	Hi-Z	Hi-Z
Standby	V <sub>IH</sub>	X	X	X	Hi-Z	Hi-Z	Hi-Z
Electronic Signature	V <sub>IL</sub>	V <sub>IL</sub>	V <sub>IH</sub>	V <sub>ID</sub>	Code	Codes	Codes

Note: X = V<sub>IH</sub> or V<sub>IL</sub>, V<sub>ID</sub> = 12V ± 0.5V.

**Table 4. Electronic Signature**

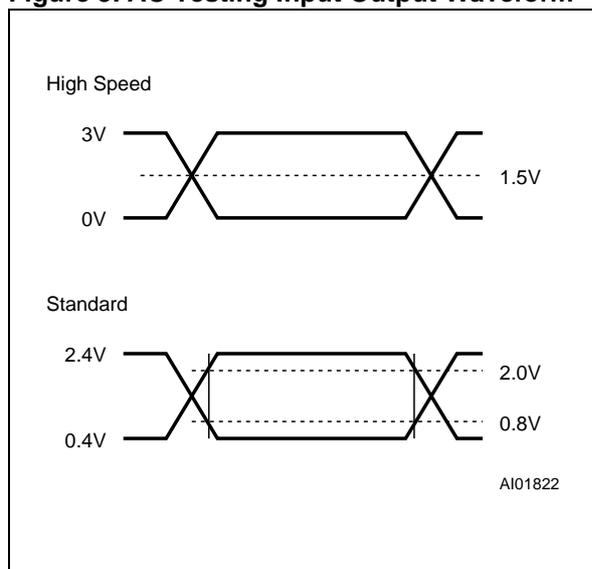
Identifier	A0	Q7	Q6	Q5	Q4	Q3	Q2	Q1	Q0	Hex Data
Manufacturer's Code	V <sub>IL</sub>	0	0	1	0	0	0	0	0	20h
Device Code	V <sub>IH</sub>	0	0	1	1	0	0	1	0	32h

Note: Outputs Q15-Q8 are set to '0'.

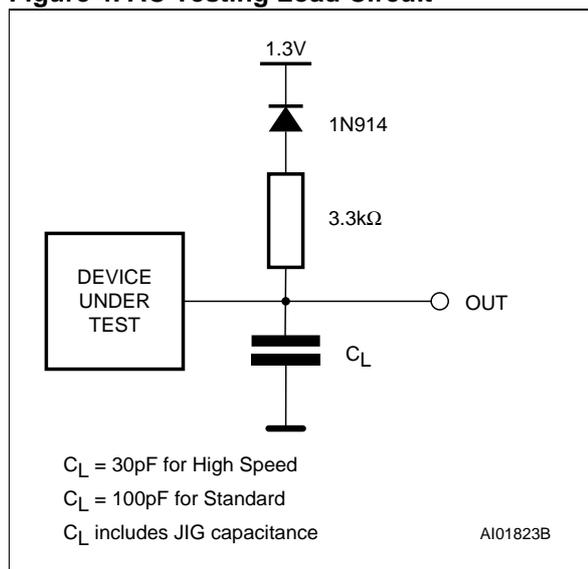
**Table 5. AC Measurement Conditions**

	High Speed	Standard
Input Rise and Fall Times	≤ 10ns	≤ 20ns
Input Pulse Voltages	0 to 3V	0.4V to 2.4V
Input and Output Timing Ref. Voltages	1.5V	0.8V and 2V

**Figure 3. AC Testing Input Output Waveform**



**Figure 4. AC Testing Load Circuit**



**Table 6. Capacitance (1)** (T<sub>A</sub> = 25 °C, f = 1 MHz)

Symbol	Parameter	Test Condition	Min	Max	Unit
C <sub>IN</sub>	Input Capacitance	V <sub>IN</sub> = 0V		10	pF
C <sub>OUT</sub>	Output Capacitance	V <sub>OUT</sub> = 0V		12	pF

Note: 1. Sampled only, not 100% tested.

The M27C320 has two control functions, both of which must be logically active in order to obtain data at the outputs. In addition the Word-wide or Byte-wide organisation must be selected.

Chip Enable ( $\bar{E}$ ) is the power control and should be used for device selection. Output Enable ( $\bar{G}$ ) is the output control and should be used to gate data to the output pins independent of device selection. Assuming that the addresses are stable, the address access time (t<sub>AVQV</sub>) is equal to the delay from  $\bar{E}$  to output (t<sub>ELQV</sub>). Data is available at the

output after a delay of t<sub>GLQV</sub> from the falling edge of  $\bar{G}$ , assuming that  $\bar{E}$  has been low and the addresses have been stable for at least t<sub>AVQV</sub>-t<sub>GLQV</sub>.

**Standby Mode**

The M27C320 has standby mode which reduces the supply current from 50mA to 100µA. The M27C320 is placed in the standby mode by applying a CMOS high signal to the  $\bar{E}$  input. When in the standby mode, the outputs are in a high impedance state, independent of the  $\bar{G}$  input.

**Table 7. Read Mode DC Characteristics (1)**(T<sub>A</sub> = 0 to 70 °C, -40 to 85 °C or -40 to 125 °C; V<sub>CC</sub> = 5V ± 10%)

Symbol	Parameter	Test Condition	Min	Max	Unit
I <sub>LI</sub>	Input Leakage Current	0V ≤ V <sub>IN</sub> ≤ V <sub>CC</sub>		±1	μA
I <sub>LO</sub>	Output Leakage Current	0V ≤ V <sub>OUT</sub> ≤ V <sub>CC</sub>		±10	μA
I <sub>CC</sub>	Supply Current	$\bar{E} = V_{IL}, \bar{G} = V_{IL}, I_{OUT} = 0\text{mA}, f = 8\text{MHz}$		70	mA
		$\bar{E} = V_{IL}, \bar{G} = V_{IL}, I_{OUT} = 0\text{mA}, f = 5\text{MHz}$		50	mA
I <sub>CC1</sub>	Supply Current (Standby) TTL	$\bar{E} = V_{IH}$		1	mA
I <sub>CC2</sub>	Supply Current (Standby) CMOS	$\bar{E} > V_{CC} - 0.2\text{V}$		100	μA
I <sub>PP</sub>	Program Current	V <sub>PP</sub> = V <sub>CC</sub>		10	μA
V <sub>IL</sub>	Input Low Voltage		-0.3	0.8	V
V <sub>IH</sub> (2)	Input High Voltage		2	V <sub>CC</sub> + 1	V
V <sub>OL</sub>	Output Low Voltage	I <sub>OL</sub> = 2.1mA		0.4	V
V <sub>OH</sub>	Output High Voltage TTL	I <sub>OH</sub> = -400μA	2.4		V

Note: 1. V<sub>CC</sub> must be applied simultaneously with or before V<sub>PP</sub> and removed simultaneously or after V<sub>PP</sub>.2. Maximum DC voltage on Output is V<sub>CC</sub> + 0.5V.

### Two Line Output Control

Because EPROMs are usually used in larger memory arrays, this product features a 2 line control function which accommodates the use of multiple memory connection. The two line control function allows:

- the lowest possible memory power dissipation,
- complete assurance that output bus contention will not occur.

For the most efficient use of these two control lines,  $\bar{E}$  should be decoded and used as the primary device selecting function, while  $\bar{G}$  should be made a common connection to all devices in the array and connected to the  $\overline{\text{READ}}$  line from the system control bus. This ensures that all deselected memory devices are in their low power standby mode and that the output pins are only active when data is required from a particular memory device.

### System Considerations

The power switching characteristics of Advanced CMOS EPROMs require careful decoupling of the supplies to the devices. The supply current I<sub>CC</sub> has three segments of importance to the system designer: the standby current, the active current and the transient peaks that are produced by the falling and rising edges of  $\bar{E}$ .

The magnitude of the transient current peaks is dependent on the capacitive and inductive loading of the device outputs. The associated transient voltage peaks can be suppressed by complying with the two line output control and by properly selected decoupling capacitors. It is recommended that a 0.1μF ceramic capacitor is used on every device between V<sub>CC</sub> and V<sub>SS</sub>. This should be a high frequency type of low inherent inductance and should be placed as close as possible to the device. In addition, a 4.7μF electrolytic capacitor should be used between V<sub>CC</sub> and V<sub>SS</sub> for every eight devices. This capacitor should be mounted near the power supply connection point. The purpose of this capacitor is to overcome the voltage drop caused by the inductive effects of PCB traces.

## M27C320

**Table 8. Read Mode AC Characteristics (1)**

( $T_A = 0$  to  $70$  °C,  $-40$  to  $85$  °C or  $-40$  to  $125$  °C;  $V_{CC} = 5V \pm 10\%$ )

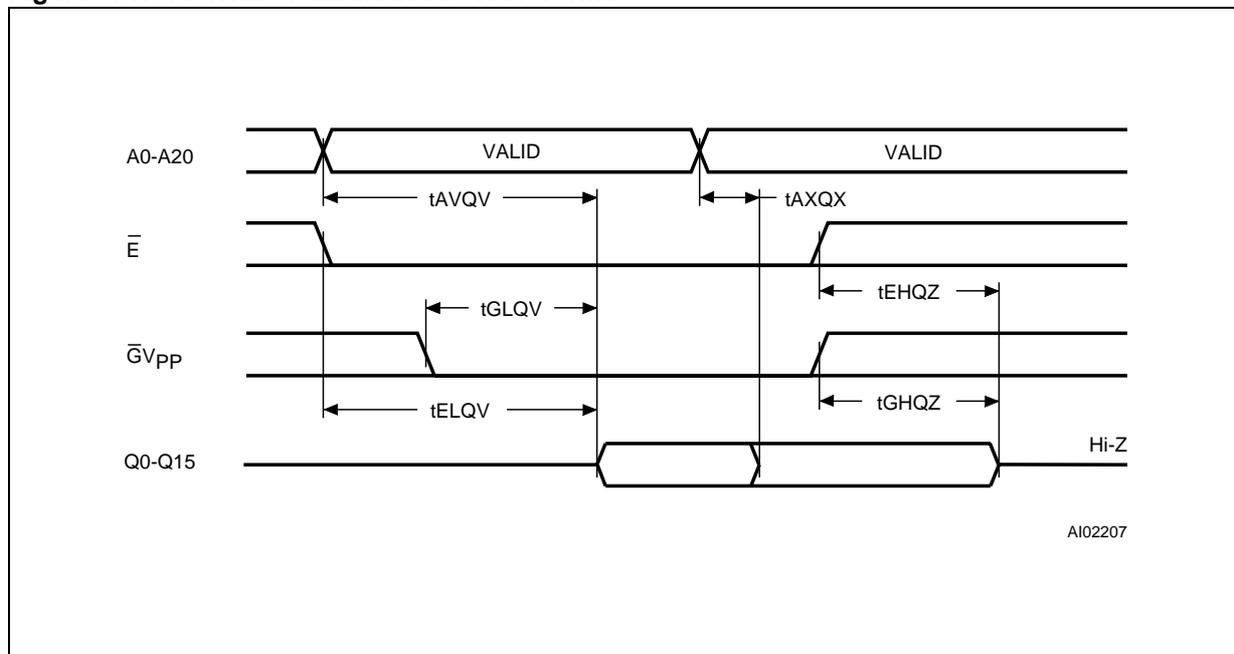
Symbol	Alt	Parameter	Test Condition	M27C320						Unit
				-80 (3)		-100		-120		
				Min	Max	Min	Max	Min	Max	
$t_{AVQV}$	$t_{ACC}$	Address Valid to Output Valid	$\bar{E} = V_{IL}, \bar{G} = V_{IL}$		80		100		120	ns
$t_{BHQV}$	$t_{ST}$	BYTE High to Output Valid	$\bar{E} = V_{IL}, \bar{G} = V_{IL}$		80		100		120	ns
$t_{ELQV}$	$t_{CE}$	Chip Enable Low to Output Valid	$\bar{G} = V_{IL}$		80		100		120	ns
$t_{GLQV}$	$t_{OE}$	Output Enable Low to Output Valid	$\bar{E} = V_{IL}$		40		50		60	ns
$t_{BLQZ}^{(2)}$	$t_{STD}$	BYTE Low to Output Hi-Z	$\bar{E} = V_{IL}, \bar{G} = V_{IL}$		40		40		50	ns
$t_{EHQZ}^{(2)}$	$t_{DF}$	Chip Enable High to Output Hi-Z	$\bar{G} = V_{IL}$	0	40	0	40	0	50	ns
$t_{GHQZ}^{(2)}$	$t_{DF}$	Output Enable High to Output Hi-Z	$\bar{E} = V_{IL}$	0	40	0	40	0	50	ns
$t_{AXQX}$	$t_{OH}$	Address Transition to Output Transition	$\bar{E} = V_{IL}, \bar{G} = V_{IL}$	5		5		5		ns
$t_{BLQX}$	$t_{OH}$	BYTE Low to Output Transition	$\bar{E} = V_{IL}, \bar{G} = V_{IL}$	5		5		5		ns

Note: 1.  $V_{CC}$  must be applied simultaneously with or before  $V_{PP}$  and removed simultaneously or after  $V_{PP}$ .

2. Sampled only, not 100% tested.

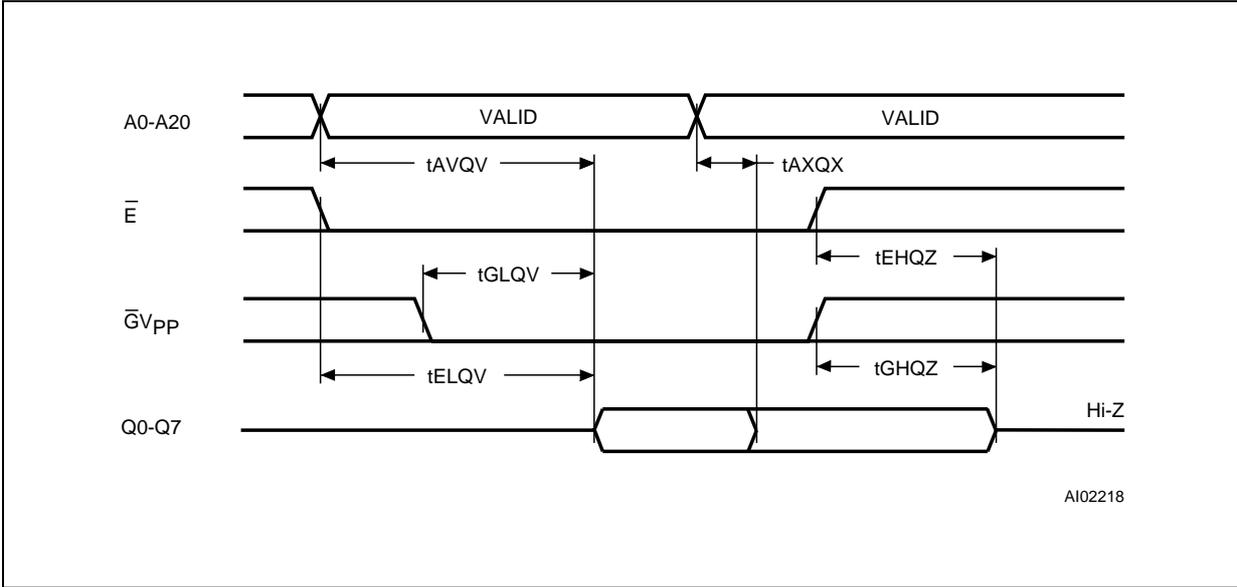
3. Speed obtained with High Speed AC measurement conditions.

**Figure 5. Word-Wide Read Mode AC Waveforms**



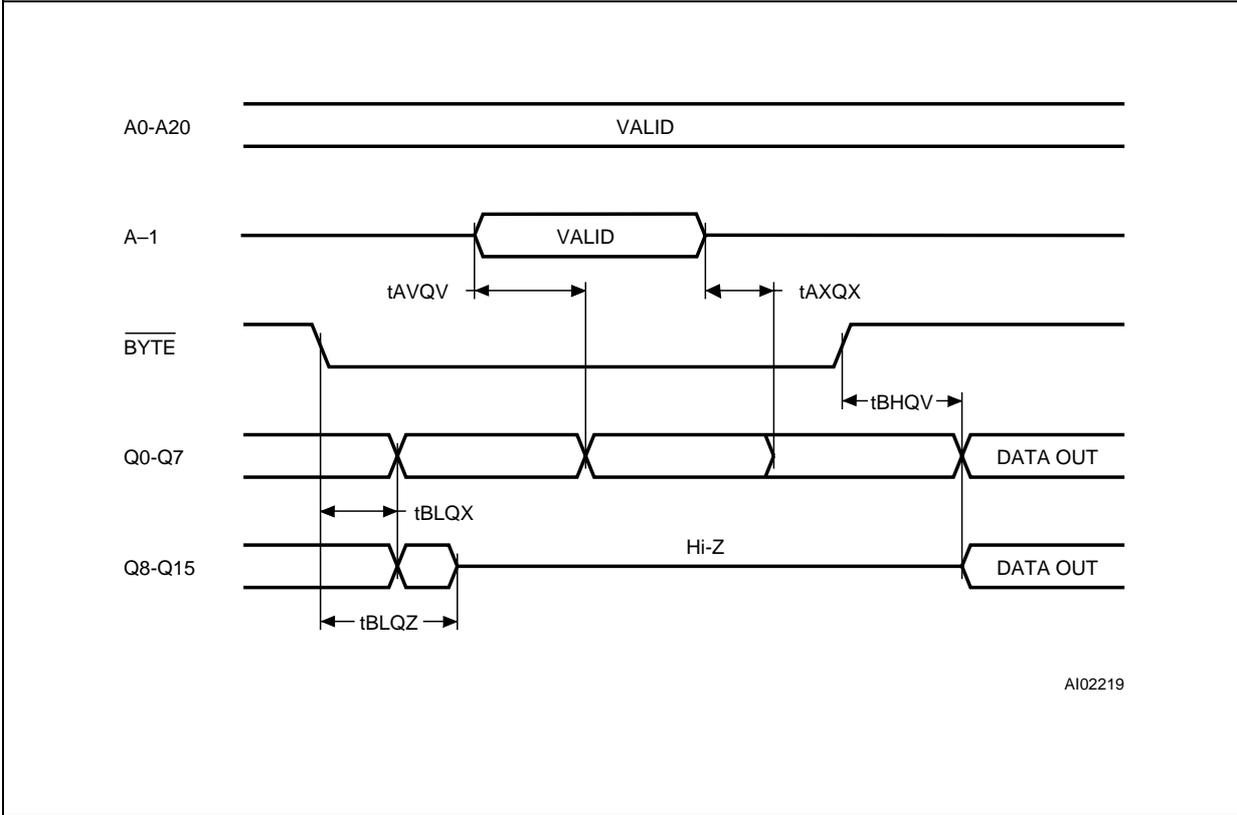
Note:  $\text{BYTE} = V_{IH}$ .

Figure 6. Byte-Wide Read Mode AC Waveforms



Note:  $\overline{BYTE} = V_{IL}$ .

Figure 7.  $\overline{BYTE}$  Transition AC Waveforms



Note:  $\overline{E} = V_{IL}$ ;  $\overline{GV_{PP}} = V_{IL}$ .

## M27C320

**Table 9. Programming Mode DC Characteristics (1)**

( $T_A = 25\text{ }^\circ\text{C}$ ;  $V_{CC} = 6.25\text{V} \pm 0.25\text{V}$ ;  $V_{PP} = 12\text{V} \pm 0.25\text{V}$ )

Symbol	Parameter	Test Condition	Min	Max	Unit
$I_{LI}$	Input Leakage Current	$V_{IL} \leq V_{IN} \leq V_{IH}$		$\pm 10$	$\mu\text{A}$
$I_{CC}$	Supply Current			50	mA
$I_{PP}$	Program Current	$\bar{E} = V_{IL}$		50	mA
$V_{IL}$	Input Low Voltage		-0.3	0.8	V
$V_{IH}$	Input High Voltage		2.4	$V_{CC} + 0.5$	V
$V_{OL}$	Output Low Voltage	$I_{OL} = 2.1\text{mA}$		0.4	V
$V_{OH}$	Output High Voltage TTL	$I_{OH} = -2.5\text{mA}$	3.5		V
$V_{ID}$	A9 Voltage		11.5	12.5	V

Note: 1.  $V_{CC}$  must be applied simultaneously with or before  $V_{PP}$  and removed simultaneously or after  $V_{PP}$ .

**Table 10. MARGIN MODE AC Characteristics (1)**

( $T_A = 25\text{ }^\circ\text{C}$ ;  $V_{CC} = 6.25\text{V} \pm 0.25\text{V}$ ;  $V_{PP} = 12\text{V} \pm 0.25\text{V}$ )

Symbol	Alt	Parameter	Test Condition	Min	Max	Unit
$t_{A9HVPH}$	$t_{AS9}$	$V_{A9}$ High to $V_{PP}$ High		2		$\mu\text{s}$
$t_{VPHEL}$	$t_{VPS}$	$V_{PP}$ High to Chip Enable Low		2		$\mu\text{s}$
$t_{A10HEH}$	$t_{AS10}$	$V_{A10}$ High to Chip Enable High (Set)		1		$\mu\text{s}$
$t_{A10LEH}$	$t_{AS10}$	$V_{A10}$ Low to Chip Enable High (Reset)		1		$\mu\text{s}$
$t_{EXA10X}$	$t_{AH10}$	Chip Enable Transition to $V_{A10}$ Transition		1		$\mu\text{s}$
$t_{EXVPX}$	$t_{VPH}$	Chip Enable Transition to $V_{PP}$ Transition		2		$\mu\text{s}$
$t_{VPXA9X}$	$t_{AH9}$	$V_{PP}$ Transition to $V_{A9}$ Transition		2		$\mu\text{s}$

Note: 1.  $V_{CC}$  must be applied simultaneously with or before  $V_{PP}$  and removed simultaneously or after  $V_{PP}$ .

### Programming

When delivered, all bits of the M27C320 are in the '1' state. Data is introduced by selectively programming '0's into the desired bit locations. Although only '0's will be programmed, both '1's and '0's can be present in the data word. The

M27C320 is in the programming mode when  $V_{PP}$  input is at 12.5V,  $\bar{G}$  is at  $V_{IH}$  and  $\bar{E}$  is pulsed to  $V_{IL}$ . The data to be programmed is applied to 16 bits in parallel to the data output pins. The levels required for the address and data inputs are TTL.  $V_{CC}$  is specified to be  $6.25\text{V} \pm 0.25\text{V}$ .

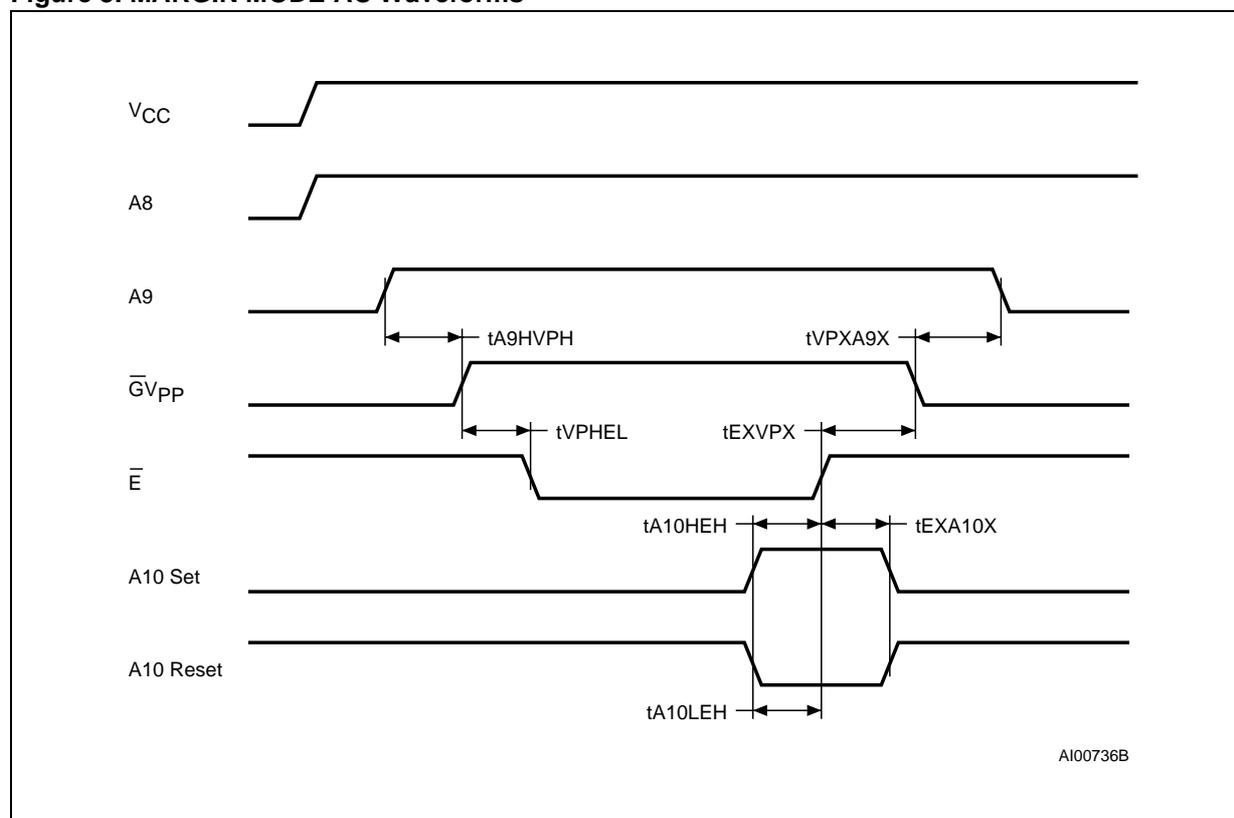
**Table 11. Programming Mode AC Characteristics <sup>(1)</sup>**  
 ( $T_A = 25\text{ }^\circ\text{C}$ ;  $V_{CC} = 6.25\text{V} \pm 0.25\text{V}$ ;  $V_{PP} = 12\text{V} \pm 0.25\text{V}$ )

Symbol	Alt	Parameter	Test Condition	Min	Max	Unit
$t_{AVEL}$	$t_{AS}$	Address Valid to Chip Enable Low		1		$\mu\text{s}$
$t_{QVEL}$	$t_{DS}$	Input Valid to Chip Enable Low		1		$\mu\text{s}$
$t_{VCHEL}$	$t_{VCS}$	$V_{CC}$ High to Chip Enable Low		2		$\mu\text{s}$
$t_{VPHEL}$	$t_{OES}$	$V_{PP}$ High to Chip Enable Low		1		$\mu\text{s}$
$t_{VPLVPH}$	$t_{PRT}$	$V_{PP}$ Rise Time		50		ns
$t_{ELEH}$	$t_{PW}$	Chip Enable Program Pulse Width (Initial)		45	55	$\mu\text{s}$
$t_{EHQX}$	$t_{DH}$	Chip Enable High to Input Transition		2		$\mu\text{s}$
$t_{EHVPX}$	$t_{OEH}$	Chip Enable High to $V_{PP}$ Transition		2		$\mu\text{s}$
$t_{VPLEL}$	$t_{VR}$	$V_{PP}$ Low to Chip Enable Low		1		$\mu\text{s}$
$t_{ELQV}$	$t_{DV}$	Chip Enable Low to Output Valid			1	$\mu\text{s}$
$t_{EHQZ}^{(2)}$	$t_{DFP}$	Chip Enable High to Output Hi-Z		0	130	ns
$t_{EHAX}$	$t_{AH}$	Chip Enable High to Address Transition		0		ns

Note: 1.  $V_{CC}$  must be applied simultaneously with or before  $V_{PP}$  and removed simultaneously or after  $V_{PP}$ .

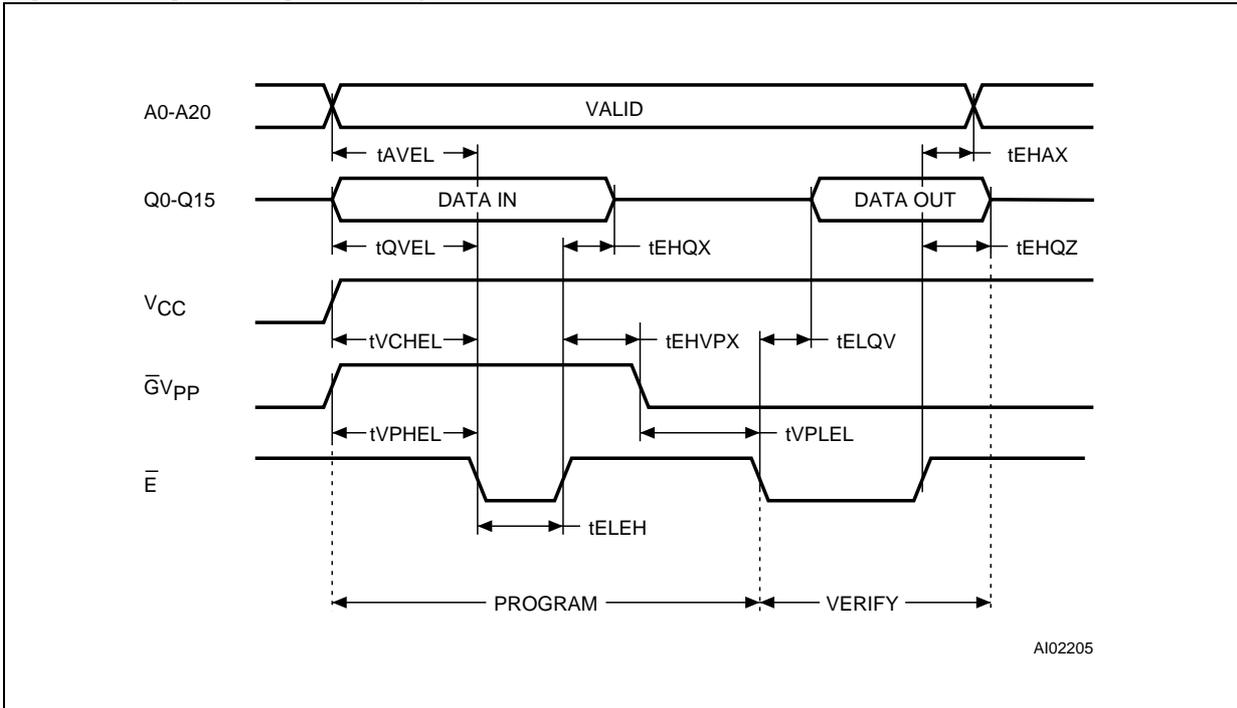
2. Sampled only, not 100% tested.

**Figure 8. MARGIN MODE AC Waveforms**



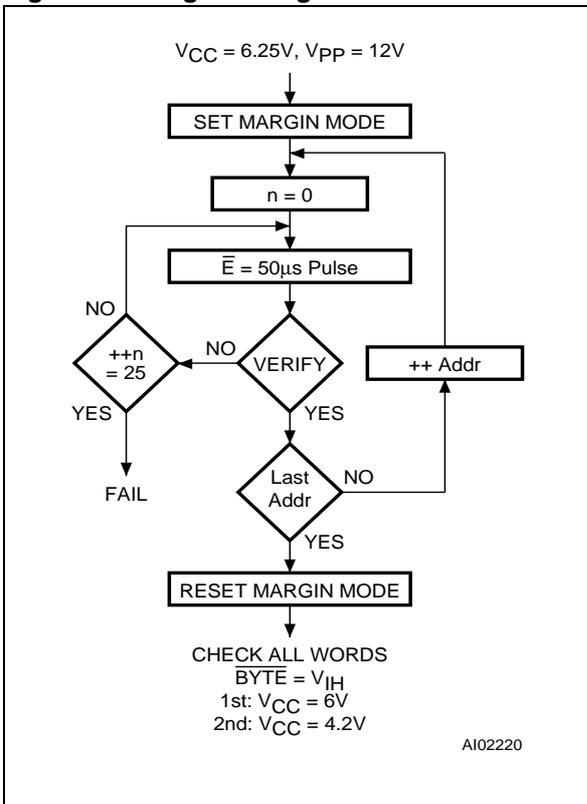
Note:  $A_8$  High level = 5V;  $A_9$  High level = 12V.

Figure 9. Programming and Verify Modes AC Waveforms



Note:  $\overline{\text{BYTE}} = V_{IH}$ ;  $\overline{\text{VPP}}$  High level = 12V.

Figure 10. Programming Flowchart



**PRESTO III Programming Algorithm**

The PRESTO III Programming Algorithm allows the whole array to be programmed with a guaranteed margin in a typical time of 100 seconds. Programming with PRESTO III consists of applying a sequence of 50µs program pulses to each word until a correct verify occurs (see Figure 10). During programming and verify operation a MARGIN MODE circuit must be activated to guarantee that each cell is programmed with enough margin. No overprogram pulse is applied since the verify in MARGIN MODE provides the necessary margin to each programmed cell.

**Program Inhibit**

Programming of multiple M27C320s in parallel with different data is also easily accomplished. Except for E-bar, all like inputs including G-bar of the parallel M27C320 may be common. A TTL low level pulse applied to a M27C320's E-bar input and VPP at 12V, will program that M27C320. A high level E-bar input inhibits the other M27C320s from being programmed.

**Program Verify**

A verify (read) should be performed on the programmed bits to determine that they were correctly programmed. The verify is accomplished with G-bar at VIL. Data should be verified with tELQV after the falling edge of E-bar.



**Electronic Signature**

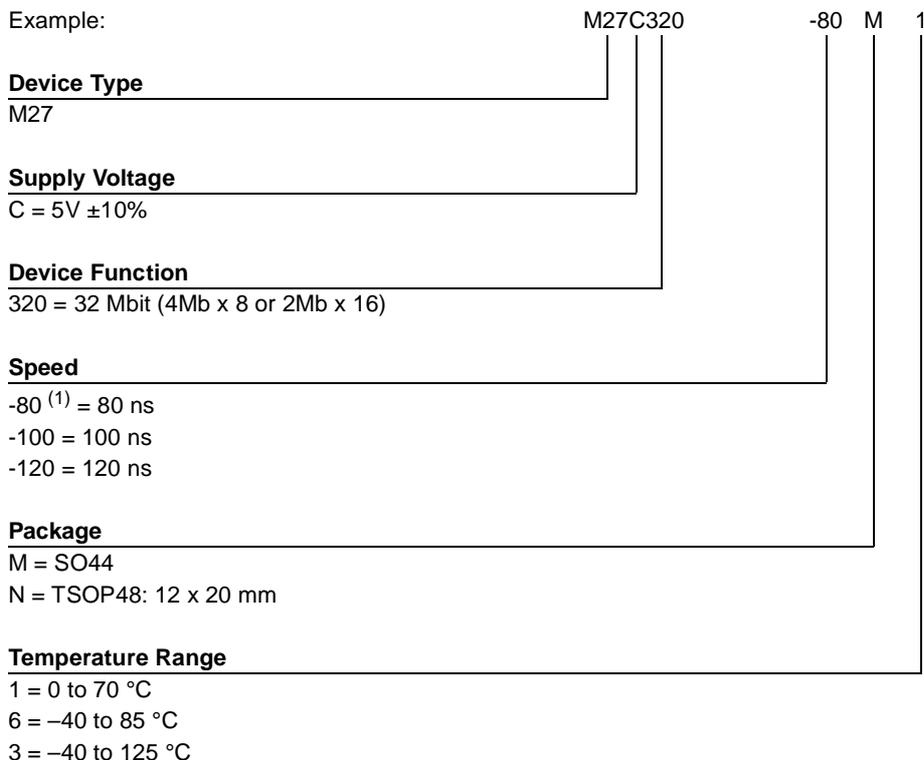
The Electronic Signature (ES) mode allows the reading out of a binary code from an EPROM that will identify its manufacturer and type. This mode is intended for use by programming equipment to automatically match the device to be programmed with its corresponding programming algorithm. The ES mode is functional in the  $25^{\circ}\text{C} \pm 5^{\circ}\text{C}$  ambient temperature range that is required when programming the M27C320. To activate the ES mode, the programming equipment must force

11.5V to 12.5V on address line A9 of the M27C320, with  $V_{PP} = V_{CC} = 5\text{V}$ . Two identifier bytes may then be sequenced from the device outputs by toggling address line A0 from  $V_{IL}$  to  $V_{IH}$ . All other address lines must be held at  $V_{IL}$  during Electronic Signature mode.

Byte 0 ( $A0 = V_{IL}$ ) represents the manufacturer code and byte 1 ( $A0 = V_{IH}$ ) the device identifier code. For the STMicroelectronics M27C320, these two identifier bytes are given in Table 4 and can be read-out on outputs Q7 to Q0.

## M27C320

**Table 12. Ordering Information Scheme**



Note: 1. High Speed, see AC Characteristics section for further information.

For a list of available options (Speed, Package, etc...) or for further information on any aspect of this device, please contact the STMicroelectronics Sales Office nearest to you.

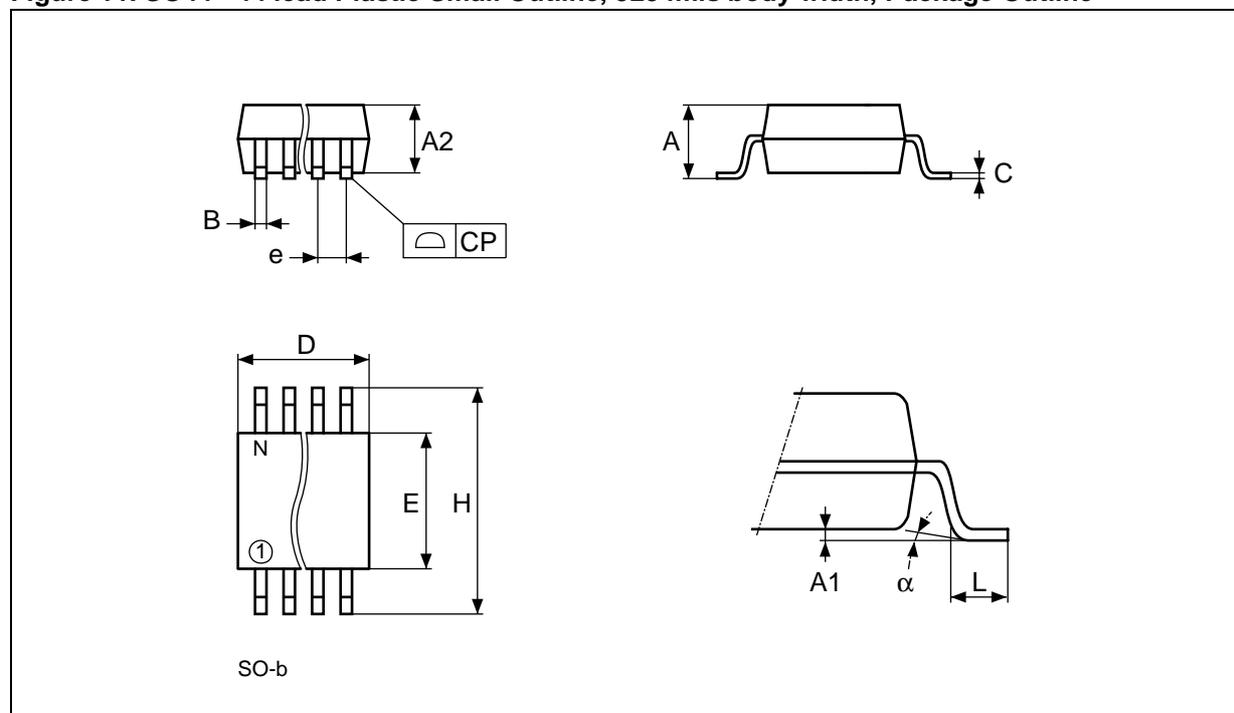
**Table 13. Revision History**

Date	Revision Details
September 1998	First Issue
09/20/00	AN620 Reference removed
11/29/00	From Preliminary Data to data Sheet -40 to 85 °C and -40 to 125 °C temperature ranges added (Tables 7, 8 and 12) 80ns speed class in High Speed AC measurement conditions (Tables 8 and 12) Note changed (Figures 6 and 9) Programming Flowchart change (Figure 10) Presto III Programming Algorithm paragraph changed

Table 14. SO44 - 44 lead Plastic Small Outline, 525 mils body width, Package Mechanical Data

Symb	mm			inches		
	Typ	Min	Max	Typ	Min	Max
A		2.42	2.62		0.095	0.103
A1		0.22	0.23		0.009	0.010
A2		2.25	2.35		0.089	0.093
B			0.50			0.020
C		0.10	0.25		0.004	0.010
D		28.10	28.30		1.106	1.114
E		13.20	13.40		0.520	0.528
e	1.27	–	–	0.050	–	–
H		15.90	16.10		0.626	0.634
L	0.80	–	–	0.031	–	–
$\alpha$	3°	–	–	3°	–	–
N		44			44	
CP			0.10			0.004

Figure 11. SO44 - 44 lead Plastic Small Outline, 525 mils body width, Package Outline



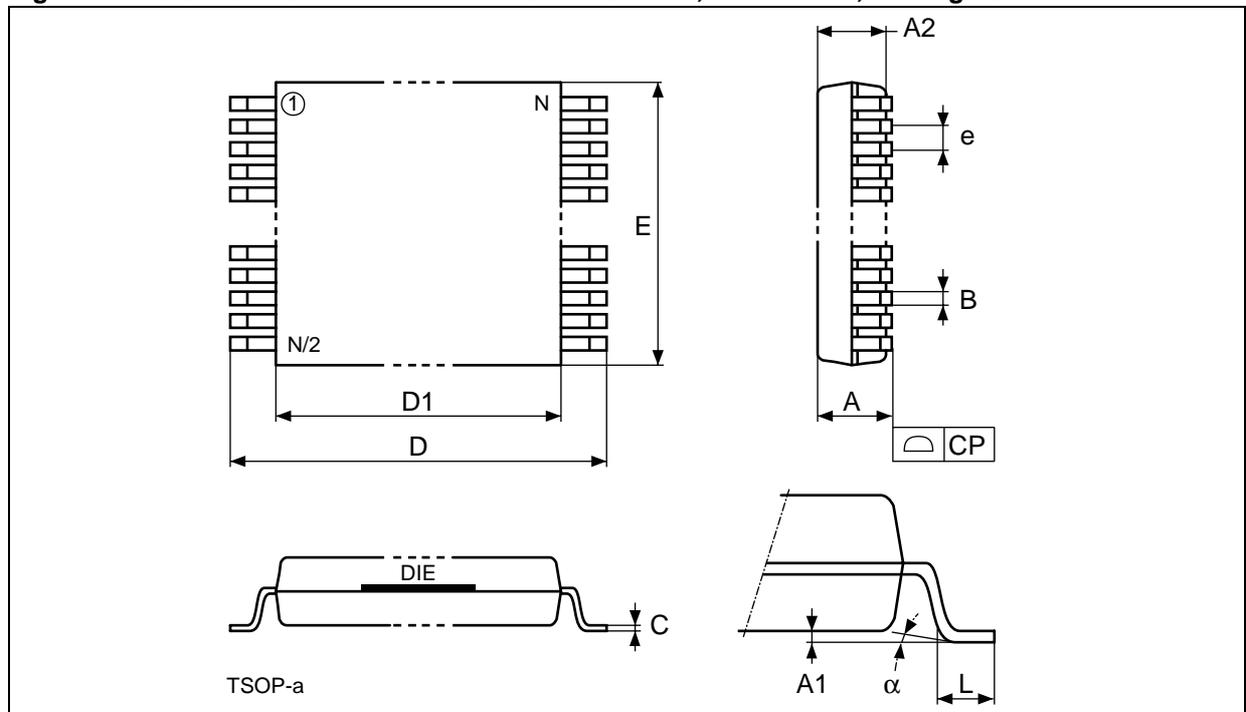
Drawing is not to scale.

**M27C320**

**Table 15. TSOP48 - 48 lead Plastic Thin Small Outline, 12 x 20 mm, Package Mechanical Data**

Symb	mm			inches		
	Typ	Min	Max	Typ	Min	Max
A			1.20			0.047
A1		0.05	0.15		0.002	0.006
A2		0.95	1.05		0.037	0.041
B		0.17	0.27		0.007	0.011
C		0.10	0.21		0.004	0.008
D		19.80	20.20		0.780	0.795
D1		18.30	18.50		0.720	0.728
E		11.90	12.10		0.469	0.476
e	0.50	-	-	0.020	-	-
L		0.50	0.70		0.020	0.028
$\alpha$		0°	5°		0°	5°
N	48			48		
CP			0.10			0.004

**Figure 12. TSOP48 - 48 lead Plastic Thin Small Outline, 12 x 20 mm, Package Outline**



Drawing is not to scale.

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