

UT7R995 & UT7R995C RadClock™

RadHard 2.5V/3.3V 200MHz High-Speed Multi-phase PLL Clock Buffer



Advanced Data Sheet
November 29, 2005

FEATURES:

- ❑ +3.3V Core Power Supply
- ❑ +2.5V or +3.3V Clock Output Power Supply
 - Independent Clock Output Bank Power Supplies
- ❑ Output frequency range: 6 MHz to 200 MHz
- ❑ Output-output skew < 100 ps
- ❑ Cycle-cycle jitter < 100 ps
- ❑ ± 2% maximum output duty cycle
- ❑ Eight LVTTTL outputs with selectable drive strength
- ❑ Selectable positive- or negative-edge synchronization
- ❑ Selectable phase-locked loop (PLL) frequency range and lock indicator
- ❑ Phase adjustments in 625 to 1300 ps steps up to ± 7.8 ns
- ❑ (1-6,8,10,12) x multiply and (1/2,1/4) x divide ratios
- ❑ Compatible with Spread-Spectrum reference clocks
- ❑ Power-down mode
- ❑ Selectable reference input divider
- ❑ Radiation performance
 - Total-dose tolerance: 300 krad (Si) and 1 Mrad (Si)
 - SEL Immune to a LET of 109 MeV-cm²/mg
 - SEU Immune to a LET of 109 MeV-cm²/mg
 - SET: Contact factory for details
- ❑ Military temperature range: -55°C to +125°C
- ❑ Packaging options:
 - 48-Lead Ceramic Flatpack
- ❑ Standard Microcircuit Drawing: 5962-05214
 - QML-Q and QML-V compliant part

INTRODUCTION:

The UT7R995/UT7R995C is a low-voltage, low-power, eight-output, 6-to-200 MHz clock driver. It features output phase programmability which is necessary to optimize the timing of high-performance microprocessor and communication systems.

The user programs both the frequency and the phase of the output banks through nF[1:0] and DS[1:0] pins. The adjustable phase feature allows the user to skew the outputs to lead or lag the reference clock. Connect any one of the outputs to the feedback input to achieve different reference frequency multiplication and division ratios.

The devices also feature split output bank power supplies that enable banks 1 & 2, bank 3, and bank 4 to operate at a different power supply levels. The ternary PE/HD pin controls the synchronization of output signals to either the rising or the falling edge of the reference clock and selects the drive strength of the output buffers. The UT7R995 and UT7R995C both interface to a digital clock while the UT7R995C will also interface to a quartz crystal.

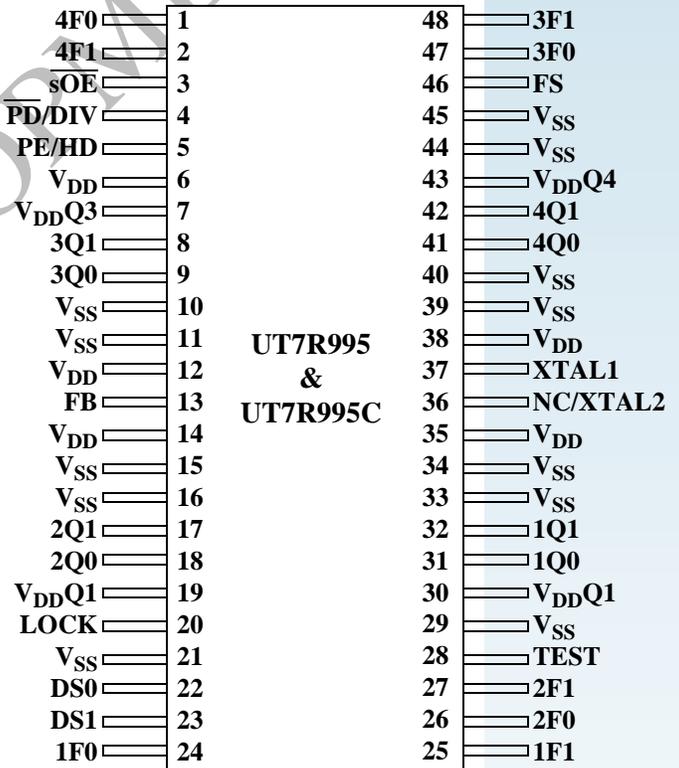


Figure 1. 48-Lead Ceramic Flatpack Pin Description

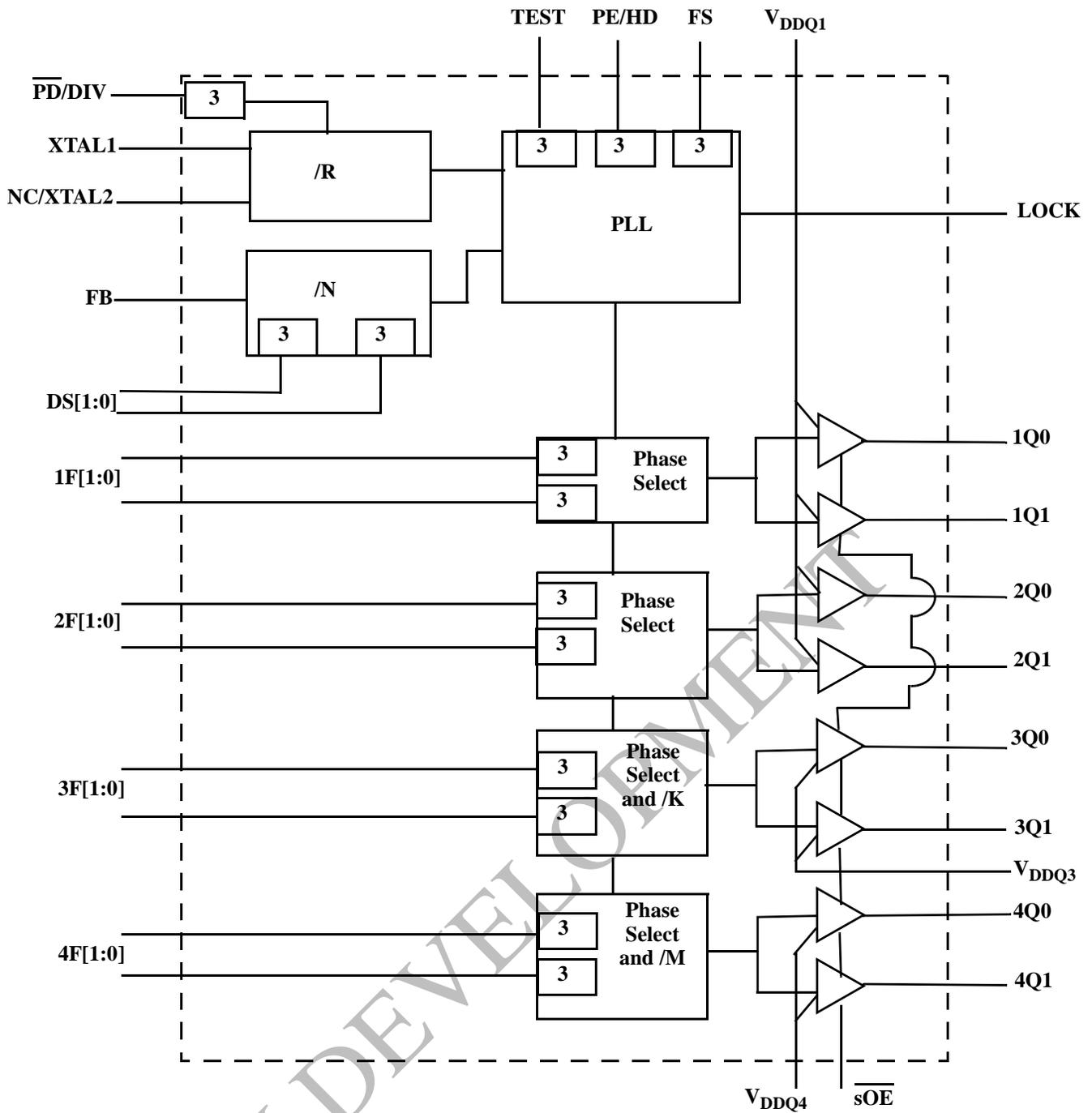


Figure 2. UT7R995 & UT7R995C Block Diagram

1.0 DEVICE CONFIGURATION:

The outputs of the UT7R995/C can be configured to run at frequencies ranging from 6 MHz to 200 MHz. Each output bank has the ability to run at separate frequencies and with various phase skews. Furthermore, numerous clock division and multiplication options exist.

The following discussion and list of tables will summarize the available configuration options for the UT7R995/C. Tables 1 through 11, are relevant to the following configuration discussions.

- Table 1. Feedback Divider Settings (N-factor)**
- Table 2. Reference Divider Settings (R-Factor)**
- Table 3. Output Divider Settings - Bank 3 (K-factor)**
- Table 4. Output Divider Settings - Bank 4 (M-Factor)**
- Table 5. Frequency Divider Summary**
- Table 6. Calculating Output Frequency Settings**
- Table 7. Frequency Range Select**
- Table 8. Multiplication Factor (MF) Calculation**
- Table 9. Signal Propagation Delays in Various Media**
- Table 10: Output Skew Settings**
- Table 11. PE/HD Settings**
- Table 12. Power Supply Constraints**

1.1 Divider Configuration Settings:

The feedback input divider is controlled by the 3-level DS[1:0] pins as indicated in Table 1 and the reference input divider is controlled by the 3-level $\overline{\text{PD}}/\text{DIV}$ pin as indicated in Table 2. Although the Reference divider will continue to operate when the UT7R995/C is in the standard TEST mode of operation, the Feedback Divider will not be available.

Table 1: Feedback Divider Settings (N-factor)

| DS[1:0] | Feedback Input Divider - (N) | Permitted Output Divider (K or M) Connected to FB |
|---------|------------------------------|---|
| LL | 2 | 1 or 2 |
| LM | 3 | 1 |
| LH | 4 | 1, 2, or 4 |
| ML | 5 | 1 or 2 |
| MM | 1 | 1, 2, or 4 |
| MH | 6 | 1 or 2 |
| HL | 8 | 1 or 2 |
| HM | 10 | 1 |
| HH | 12 | 1 |

Table 2: Reference Divider Settings (R-factor)

| $\overline{\text{PD}}/\text{DIV}$ | Operating Mode | Reference Input Divider - (R) |
|-----------------------------------|------------------|-------------------------------|
| LOW ¹ | Powered Down | Not Applicable |
| MID | Normal Operation | 2 |
| HIGH | Normal Operation | 1 |

Notes:

1. When $\overline{\text{PD}}/\text{DIV}$ = LOW, the device enters power-down mode.

In addition to the reference and feedback dividers, the UT7R995/C includes output dividers on Bank 3 and Bank 4, which are controlled by 3F[1:0] and 4F[1:0] as indicated in Tables 3 and 4, respectively.

Table 3: Output Divider Settings - Bank 3 (K-factor)

| 3F[1:0] | Bank 3 Output Divider - (K) |
|--------------------|-----------------------------|
| LL | 2 |
| HH | 4 |
| Other ¹ | 1 |

Notes:

1. These states are used to program the phase of the respective banks. Please see Equation 1 along with Tables 8 and 10.

Table 4: Output Divider Settings - Bank 4 (M-factor)

| 4F[1:0] | Bank 4 Output Divider (M) |
|--------------------|---------------------------|
| LL | 2 |
| Other ¹ | 1 |

Notes:

1. These states are used to program the phase of the respective banks. Please see Equation 1 along with Tables 8 and 10.

Each of the four divider options and their respective settings are summarized in Table 5. By applying the divider options in Table 5 to the calculations shown in Table 6, the user determines the proper clock frequency for every output bank.

Table 5: Frequency Divider Summary

| Division Factors | Available Divider Settings |
|------------------|-----------------------------|
| N | 1, 2, 3, 4, 5, 6, 8, 10, 12 |
| R | 1, 2 |
| K | 1, 2, 4 |
| M | 1, 2 |

Table 6: Calculating Output Frequency Settings

| Configuration | Output Frequency | | |
|------------------------------|---|----------------------------|----------------------------|
| Clock Output Connected to FB | 1Q[1:0] ¹ and 2Q[1:0] ¹ | 3Q[1:0] | 4Q[1:0] |
| 1Qn or 2Qn | $(N/R) * f_{XTAL}$ | $(N/R) * (1/K) * f_{XTAL}$ | $(N/R) * (1/M) * f_{XTAL}$ |
| 3Qn | $(N/R) * K * f_{XTAL}$ | $(N/R) * f_{XTAL}$ | $(N/R) * (K/M) * f_{XTAL}$ |
| 4Qn | $(N/R) * M * f_{XTAL}$ | $(N/R) * (M/K) * f_{XTAL}$ | $(N/R) * f_{XTAL}$ |

Notes:

1. These outputs are undivided copies of the VCO clock. Therefore, the formulas in this column can be used to calculate the nominal VCO operating frequency (f_{NOM}) at a given reference frequency (f_{XTAL}) and the divider and feedback configuration. The user must select a configuration and a reference frequency that will generate a VCO frequency that is within the range specified by FS pin. Please see Table 7.

1.2 Frequency Range and Skew Selection:

The PLL in the UT7R995/C operates within three nominal frequency ranges. Depending upon the desired PLL operating frequency, the user must define the state of the ternary FS control pin. Table 7 defines the required FS selections based upon the nominal PLL operating frequency ranges. Because the clock outputs on Bank 1 and Bank 2 do not include a divider option, they will always reflect the current frequency of the PLL. Reference the first column of equations in Table 6 to calculate the value of f_{NOM} for any given feedback clock.

Table 7: Frequency Range Select

| FS | Nominal PLL Frequency Range (f_{NOM}) |
|----|---|
| L | 24 to 50 MHz |
| M | 48 to 100MHz |
| H | 96 to 200 MHz |

Selectable output skew is in discrete increments of time unit (t_U). The value of t_U is determined by the FS setting and the PLL's operating frequency (f_{NOM}). Use the following equation to calculate the time unit (t_U):

Equation 1.
$$t_U = \frac{1}{(f_{NOM} * MF)}$$

The f_{NOM} term, which is calculated with the help of Table 6, must be compatible with the nominal frequency range selected by the FS signal as defined in Table 7. The multiplication factor (MF), also determined by FS, is shown in Table 8. The UT7R995/C output skew steps have a typical accuracy, based upon the calculated time unit, of +/- 100ps per skew step.

After calculating the time unit (t_U) based on the nominal PLL frequency (f_{NOM}) and multiplication factor (MF), the circuit designer plans routing requirements of each clock output and its respective destination receiver. With an understanding of signal propagation delays through a conductive medium (see Table 9), the designer specifies trace lengths which ensure a signal propagation delay that is equal to one of the t_U multiples show in Table 10. For each output bank, the t_U skew factors are selected with the tri-level, bank-specific, nF[1:0] pins.

Table 8: MF Calculation

| FS | MF | f_{NOM} examples that result in a t_U of 1.0ns |
|----|----|--|
| L | 32 | 31.25 MHz |
| M | 16 | 62.5 MHz |
| H | 8 | 125 MHz |

Table 9: Signal Propagation Delays in Various Media

| Medium | Propagation Delay (ps/inch) | Dielectric Constant |
|----------------------------|-----------------------------|---------------------|
| Air (Radio Waves) | 85 | 1.0 |
| Coax. Cable (75% Velocity) | 113 | 1.8 |
| Coax. Cable (66% Velocity) | 129 | 2.3 |
| FR4 PCB, Outer Trace | 140 - 180 | 2.8 - 4.5 |
| FR4 PCB, Inner Trace | 180 | 4.5 |
| Alumina PCB, Inner Trace | 240 - 270 | 8 - 10 |

Table 10: Output Skew Settings

| nF[1:0] | Skew 1Q[1:0], 2Q[1:0] | Skew 3Q[1:0] | Skew 4Q[1:0] |
|-------------------|--------------------------|------------------|-----------------------|
| LL ^{1,2} | -4t _U | Divide by 2 | Divide by 2 |
| LM | -3t _U | -6t _U | -6t _U |
| LH | -2t _U | -4t _U | -4t _U |
| ML | -1t _U | -2t _U | -2t _U |
| MM | Zero Skew | Zero Skew | Zero Skew |
| MH | +1t _U | +2t _U | +2t _U |
| HL | +2t _U | +4t _U | +4t _U |
| HM | +3t _U | +6t _U | +6t _U |
| HH ² | +4t _U | Divide by 4 | Inverted ³ |

Notes:

1. nF[1:0] = LL disables bank specific outputs if TEST=MID and sOE = HIGH.
2. When TEST=MID or HIGH, the Divide-by-2, Divide-by-4, and Inversion-options function as defined in Table 9.
3. When 4Q[1:0] are set to run inverted (4F[1:0] = HH), sOE disables these outputs HIGH when PE/HD = HIGH or MID, sOE disables them LOW when PE/HD = LOW.

A graphical summary of Table 10 is shown in Figure 3. The drawing assumes that the FB input is driven by a clock output programmed with zero skew. Depending upon the state of the nF[1:0] pins the respective clocks will be skewed, divided, or inverted relative to the feedback output as shown in Figure 3.

1.3 Output Drive, Synchronization, and Power Supplies:

The UT7R995/C employs flexible output buffers providing the user with selectable drive strengths, independent power supplies, and synchronization to either edge of the reference input. Using the 3-level PE/HD pin, the user selects the reference edge synchronization and the output drive strength for all clock outputs. The options for edge synchronization and output drive strength selected by the PE/HD pin are listed in Table 11.

Table 11: PE/HD Settings

| PE/HD | Synchronization | Output Drive Strength ¹ |
|-------|-----------------|------------------------------------|
| L | Negative | Low Drive |
| M | Positive | High Drive |
| H | Positive | Low Drive |

Notes:

1. Please refer to "DC Parameters" section for I_{OH}/I_{OL} specifications.

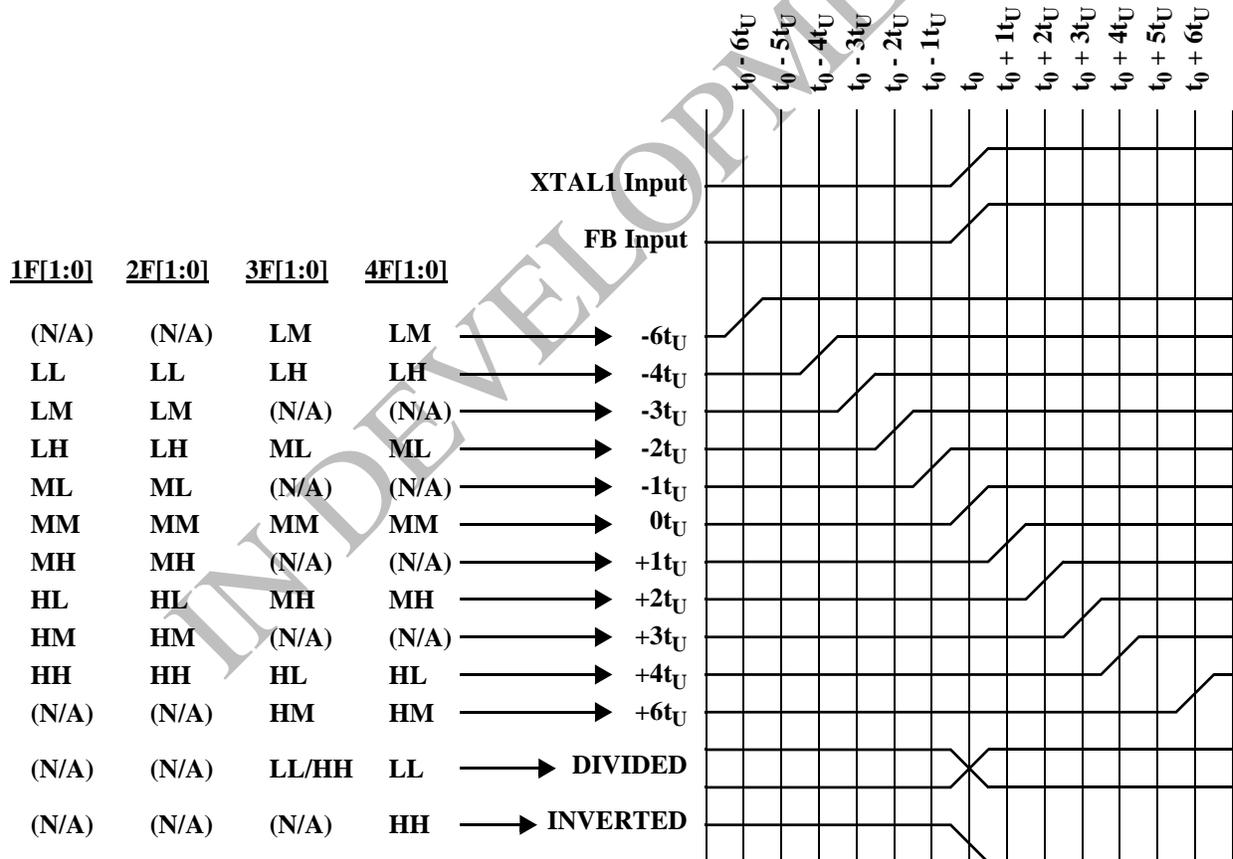


Figure 3. Typical Outputs with FB Connected to a Zero-Skewed Output

When the outputs are configured for low drive operation, they will provide a minimum 12mA of drive current regardless of the selected output power supply. If the outputs are configured for high drive operation, they will provide a minimum 24mA of drive current under a 3.3V power supply and 20mA when powered from a 2.5V supply.

The UT7R995/C features split power supply buses for Banks 1 and 2, Bank 3, and Bank 4. These independent power supplies enable the user to obtain both 3.3V and 2.5V output signals from one UT7R995/C device. The core power supply (V_{DD}) must run from a 3.3V power supply. Table 12 summarizes the various power supply options available with the UT7R995/C.

Table 12: Power Supply Constraints ¹

| V_{DD} | V_{DDQ1} | V_{DDQ3} | V_{DDQ4} |
|----------|--------------|--------------|--------------|
| 3.3V | 3.3V or 2.5V | 3.3V or 2.5V | 3.3V or 2.5V |

Notes:

- $V_{DDQ1/3/4}$ must not be set at a level higher than that of V_{DD} .

1.4 Reference Clock Interfaces

When an external, LVCMOS/LVTTL, digital clock is used to drive the UT7R995 and UT7R995C, the reference clock signal should drive the XTAL1 input of the RadClock, while the XTAL2 output should be left unconnected (see Figure 4). **Note**, for the UT7R995 only, the XTAL2 pin is defined as a no-connect.

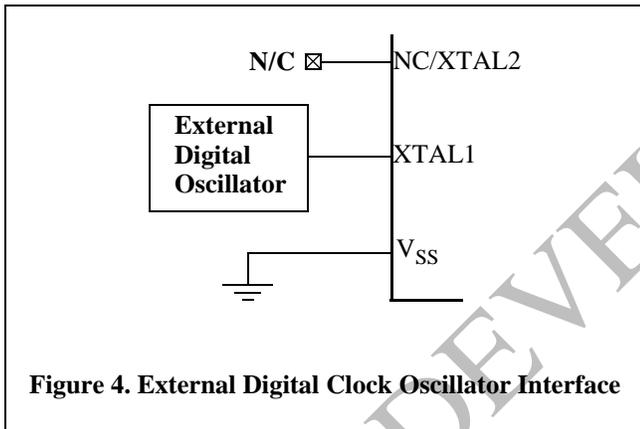
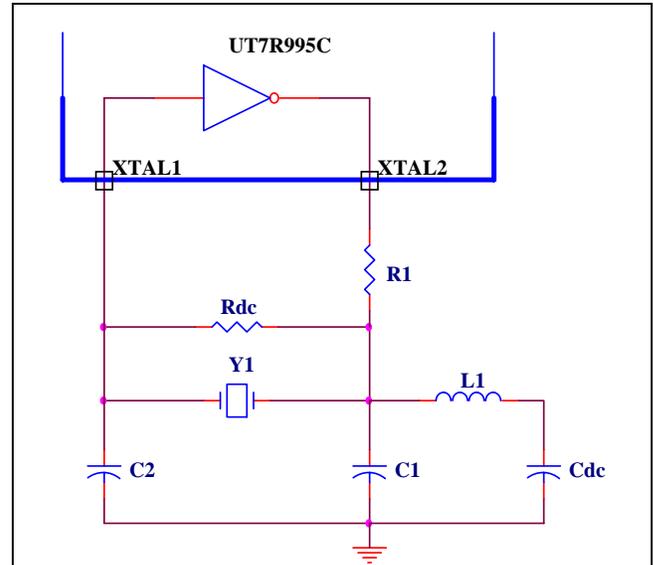


Figure 4. External Digital Clock Oscillator Interface

In addition to a digital clock reference, the UT7R995C can interface to a quartz crystal. When interfacing to a quartz crystal, XTAL1 and XTAL2 are the input and output, respectively, of an inverting amplifier within the RadClock. This inverting amplifier provides the initial 180° phase shift of the reference clock whose frequency, and subsequent 180° phase shift, is set by the quartz crystal and its surrounding RLC network. Figure 5 shows a typical pierce-oscillator with tank-circuit that will support reliable startup of fundamental and odd-harmonic, AT-cut, quartz crystals.



Fundamental Frequency Pierce Crystal Oscillator

$R_{dc} = \sim 10M\Omega$; $L1 = \text{Not Used}$; $C_{dc} = \text{Not Used}$

$C2$ is used to tune the circuit for stable oscillation. Typical values for $C2$ range from 30pF to 50pF.

$R1$ and $C1$ are selected to create a time constant that facilitates the fundamental frequency (f_F) of the quartz crystal as defined in equation 2.

$$\text{Equation 2. } f_F = \frac{1}{(2\pi * R1 * C1)}$$

As an example, selecting a value of 100Ω for $R1$ and 80pF for $C1$ would facilitate the reliable operation of a 20MHz, AT-cut, quartz crystal.

Higher Frequency Pierce Crystal Oscillator

$R_{dc} = \sim 10M\Omega$; $C_{dc} = \sim 1.5nF$; $C2 = \text{Tuning capacitor similar to prior example}$

$R1$ and $C1$ are selected to create a time constant that facilitates the overtone frequency (f_{OT}) of the quartz crystal as shown in equation 3.

$$\text{Equation 3. } f_{OT} = \frac{1}{(2\pi * R1 * C1)}$$

Additionally, $L1$ is selected such that its relationship with $C2$ facilitates a frequency falling between the fundamental frequency (f_F) and the specified overtone frequency (f_{OT}) of the quartz crystal as shown in equation 4.

$$\text{Equation 4. } f_M = \frac{1}{(2\pi * \sqrt{L1 * C1})}$$

As an example, selecting the following component values will result in a 50MHz Pierce Crystal Oscillator based upon an 3rd overtone, AT-cut, quartz crystal having a fundamental frequency of 16.6666MHz.

$R_{dc} = 10M\Omega$; $C_{dc} = 1.5nF$; $C2 = 30pF$;
 $R1 = 50\Omega$; $C1 = 55pF$; $L1 = 300nH$;
 $f_F = 16.6666MHz$; $f_{OT} = 50MHz$

Figure 5. Pierce Crystal Oscillator with Tank Circuit

2.0 RADIATION HARDNESS

Table 13: Radiation Hardness Design Specifications

| Parameter | Limit | Units |
|---|--------|-------------------------|
| Total Ionizing Dose (TID) | >1E6 | rads(Si) |
| Single Event Latchup (SEL) ^{1,2} | >109 | MeV-cm ² /mg |
| SEU Saturated Cross-Section (σ_{sat}) | 1.0E-8 | cm ² /device |
| Onset Single Event Upset (SEU) LET Threshold ³ | 109 | MeV-cm ² /mg |
| Neutron Fluence | 1.0E14 | n/cm ² |
| Dose Rate Upset | TBD | rads(Si)/sec |
| Dose Rate Survivability | TBD | rads(Si)/sec |

Notes:

1. The UT7R995/C are latchup immune to particle LETs >109 MeV-cm²/mg.
2. Worst case temperature and voltage of T_C = +125°C, V_{DD} = 3.6V, V_{DD}Q1/Q3/Q4 = 3.6V for SEL.
3. Worst case temperature and voltage of T_C = +25°C, V_{DD} = 3.0V, V_{DD}Q1/Q3/Q4 = 3.0V for SEU.
4. Adams 90% worst case particle environment, Geosynchronous orbit, 100mils of Aluminum shielding.

Table 14: Weibull and Device Parameters (256 Registers¹)

| Parameter | Limit | Units |
|---------------------------------------|--------|-------------------------|
| Shape Parameter | TBD | -- |
| Width Parameter | TBD | -- |
| Structural Cross-Section (σ) | 1.0E-8 | cm ² /device |
| Onset SEU LET ² | 109 | MeV-cm ² /mg |
| Depletion Depth | TBD | μm |
| Funnel Depth | TBD | μm |

Notes:

1. This SEU data is based on a test chip containing an array of 256 registers that are identical to the 30 registers used within the UT7R995/C.
2. All SEU data specified in this datasheet is based on the storage elements used in the UT7R995/C. Please contact the factory for details regarding SET performance of the UT7R995/C.

3.0 PIN DESCRIPTION

| Flatpack Pin No. | Name | I/O | Type | Description |
|------------------|-------------------|-----|---------|---|
| 37 | XTAL1 | I | LVTTL | Primary reference clock input. When interfacing a single-ended reference clock to the UT7R995 or UT7R995C, this input must be driven by an LVTTL/LVCMOS clock source. If a quartz crystal is used as the reference clock source (UT7R995C only), the second pin on the crystal must be connected to XTAL2. If a singled ended reference clock is supplied to this pin, then XTAL2 should be left unconnected. |
| 36 | N/C | -- | -- | No Connect. UT7R995 Only. |
| | XTAL2 | O | N/A | Feedback output from the on-board crystal oscillator. When a crystal is used to supply the reference clock for the UT7R995C, this pin must be connected to the second terminal of the quartz crystal. If a single-ended reference clock is supplied to XTAL1, then this output should be left unconnected. |
| 13 | FB | I | LVTTL | Feedback input for the PLL. When FB is not driven by an active clock output the PLL will run to its maximum frequency, unless the device is placed in power-down. |
| 28 | TEST ¹ | I | 3-Level | Built-in test control signal. When Test is set to the MID or HIGH level, it disables the PLL and the XTAL1 reference frequency is driven to all outputs (except for the conditions described in note 2). Set Test LOW for normal operation. |

| Flatpack Pin No. | Name | I/O | Type | Description | | | | | | | | | | | | | | | | |
|------------------------------|-------------------------|------------------------------|-------------|--|--------------|------------------------|------------------------------|------------|----------------------|------------------|------------|----------------------|-------------------|-------------|----------------------|------------------|-------------|-----------|-------------|-------------|
| 3 | $\overline{\text{sOE}}$ | I | LVTTL | <p>Synchronous Output Enable. The $\overline{\text{sOE}}$ input is used to synchronously enable/disable the output clocks. Each clock output that is controlled by the $\overline{\text{sOE}}$ pin is synchronously enabled/disabled by the individual output clock. When HIGH, $\overline{\text{sOE}}$ disables all clocks except 2Q0 and 2Q1. When disabled, 1Q0, 1Q1, 3Q0, and 3Q1 will always enter a LOW state when PE/HD is MID or HIGH, and they will disable into a HIGH state when PE/HD is LOW.</p> <p>The disabled state of 4Q0 and 4Q1 is dependent upon the state of PE/HD and 4F[1:0]. The following table illustrates the disabled state of bank 4 outputs as they are controlled by the state of PE/HD and 4F[1:0].</p> <table border="1"> <thead> <tr> <th><u>PE/HD</u></th> <th><u>4F[1:0]*</u></th> <th><u>4Q0</u></th> <th><u>4Q1</u></th> </tr> </thead> <tbody> <tr> <td>LOW</td> <td>HH</td> <td>LOW</td> <td>LOW</td> </tr> <tr> <td>MID</td> <td>HH</td> <td>HIGH</td> <td>HIGH</td> </tr> <tr> <td>HIGH</td> <td>HH</td> <td>HIGH</td> <td>HIGH</td> </tr> </tbody> </table> <p>*All other combinations of 4F[1:0] will result in 4Q0 and 4Q1 disabling into a LOW state when PE/HD is MID or HIGH, and they will disable into a HIGH state when PE/HD is LOW.</p> <p>When TEST is held at the MID level and $\overline{\text{sOE}}$ is HIGH, the nF[1:0] pins act as individual output enable/disable controls for each output bank, excluding bank 2. Setting both nF[1:0] signals LOW disables the corresponding output bank.</p> <p>Set $\overline{\text{sOE}}$ LOW to place the UT7R995/C RadClock™ outputs into their normal operating modes.</p> | <u>PE/HD</u> | <u>4F[1:0]*</u> | <u>4Q0</u> | <u>4Q1</u> | LOW | HH | LOW | LOW | MID | HH | HIGH | HIGH | HIGH | HH | HIGH | HIGH |
| <u>PE/HD</u> | <u>4F[1:0]*</u> | <u>4Q0</u> | <u>4Q1</u> | | | | | | | | | | | | | | | | | |
| LOW | HH | LOW | LOW | | | | | | | | | | | | | | | | | |
| MID | HH | HIGH | HIGH | | | | | | | | | | | | | | | | | |
| HIGH | HH | HIGH | HIGH | | | | | | | | | | | | | | | | | |
| 1, 2, 24, 25, 26, 27, 47, 48 | nF[1:0] | I | 3-Level | <p>Output divider and phase skew selection for each output bank. Please see Tables 3, 4, 5, 6, and 9 for a complete explanation of the nF[1:0] control functions and their effects on output frequency and skew.</p> | | | | | | | | | | | | | | | | |
| 46 | FS | I | 3-Level | <p>VCO operating frequency range selection. Please see Tables 7 and 8.</p> | | | | | | | | | | | | | | | | |
| 8, 9, 17, 18, 31, 32, 41, 42 | nQ[1:0] | O | LVTTL | <p>Four clock banks of two outputs each. Please see Table 6 for frequency settings and Table 9 for skew settings.</p> | | | | | | | | | | | | | | | | |
| 22, 23 | DS[1:0] | I | 3-Level | <p>Feedback input divider selection. Please see Table 1 for a summary of the feedback input divider settings.</p> | | | | | | | | | | | | | | | | |
| 5 | PE/HD | I | 3-Level | <p>Positive/negative edge control and high/low output drive strength selection. The PE portion of this pin controls which edge of the reference input synchronizes the clock outputs. The HD portion of this pin controls the drive strength of the output clock buffers. The following table summarizes the effects of the PE/HD pin during normal operation.</p> <table border="1"> <thead> <tr> <th><u>PE/HD</u></th> <th><u>Synchronization</u></th> <th><u>Output Drive Strength</u></th> </tr> </thead> <tbody> <tr> <td>LOW</td> <td>Negative Edge</td> <td>Low Drive</td> </tr> <tr> <td>MID</td> <td>Positive Edge</td> <td>High Drive</td> </tr> <tr> <td>HIGH</td> <td>Positive Edge</td> <td>Low Drive</td> </tr> </tbody> </table> <p>Low drive strength outputs provide 12mA of drive strength while the high drive condition results in 24mA of current drive. Output banks operating from a 2.5V power supply guarantee a high drive of 20mA.</p> | <u>PE/HD</u> | <u>Synchronization</u> | <u>Output Drive Strength</u> | LOW | Negative Edge | Low Drive | MID | Positive Edge | High Drive | HIGH | Positive Edge | Low Drive | | | | |
| <u>PE/HD</u> | <u>Synchronization</u> | <u>Output Drive Strength</u> | | | | | | | | | | | | | | | | | | |
| LOW | Negative Edge | Low Drive | | | | | | | | | | | | | | | | | | |
| MID | Positive Edge | High Drive | | | | | | | | | | | | | | | | | | |
| HIGH | Positive Edge | Low Drive | | | | | | | | | | | | | | | | | | |

| Flatpack Pin No. | Name | I/O | Type | Description | | | | | | | | | | | | |
|--|----------------------------|-------------------------|---------|--|----------------------------|-----------------|-------------------------|---------------|--------------|---------------|-----|------------------|----------|------|------------------|----------|
| 4 | $\overline{\text{PD/DIV}}$ | I | 3-Level | <p>Power down and reference divider control. This dual function pin controls the power down operation and selects the input reference divider. The following table summarizes the operating states controlled by the PD/DIV pin.</p> <table border="1"> <thead> <tr> <th>$\overline{\text{PD/DIV}}$</th> <th>Operating Mode</th> <th>Input Reference Divider</th> </tr> </thead> <tbody> <tr> <td>LOW</td> <td>Powered Down</td> <td>N/A</td> </tr> <tr> <td>MID</td> <td>Normal Operation</td> <td>$\div 2$</td> </tr> <tr> <td>HIGH</td> <td>Normal Operation</td> <td>$\div 1$</td> </tr> </tbody> </table> | $\overline{\text{PD/DIV}}$ | Operating Mode | Input Reference Divider | LOW | Powered Down | N/A | MID | Normal Operation | $\div 2$ | HIGH | Normal Operation | $\div 1$ |
| $\overline{\text{PD/DIV}}$ | Operating Mode | Input Reference Divider | | | | | | | | | | | | | | |
| LOW | Powered Down | N/A | | | | | | | | | | | | | | |
| MID | Normal Operation | $\div 2$ | | | | | | | | | | | | | | |
| HIGH | Normal Operation | $\div 1$ | | | | | | | | | | | | | | |
| 20 | LOCK | O | LVTTL | <p>PLL lock indication signal. A HIGH state indicates that the PLL is in a locked condition. A LOW state indicates that the PLL is not locked and the outputs may not be synchronized to the input. As the following table indicates, the level of phase alignment between XTAL1 and FB that will cause the LOCK pin to change states is dependent upon the frequency range selected by the FS input.</p> <table border="1"> <thead> <tr> <th>FS</th> <th>LOCK Resolution</th> </tr> </thead> <tbody> <tr> <td>L</td> <td>1.6ns typical</td> </tr> <tr> <td>M</td> <td>1.6ns typical</td> </tr> <tr> <td>H</td> <td>800ps typical</td> </tr> </tbody> </table> <p>** Note: When the RadClock is in a power-down mode or the reference clock is removed, the LOCK pin will transition to its HIGH state.</p> | FS | LOCK Resolution | L | 1.6ns typical | M | 1.6ns typical | H | 800ps typical | | | | |
| FS | LOCK Resolution | | | | | | | | | | | | | | | |
| L | 1.6ns typical | | | | | | | | | | | | | | | |
| M | 1.6ns typical | | | | | | | | | | | | | | | |
| H | 800ps typical | | | | | | | | | | | | | | | |
| 43 | V_{DDQ4}^2 | PWR | Power | <p>Power supply for Bank 4 output buffers. Please see Table 12 for supply level constraints.</p> | | | | | | | | | | | | |
| 7 | V_{DDQ3}^2 | PWR | Power | <p>Power supply for Bank 3 output buffers. Please see Table 12 for supply level constraints.</p> | | | | | | | | | | | | |
| 19, 30 | V_{DDQ1}^2 | PWR | Power | <p>Power supply for Bank 1 and Bank 2 output buffers. Please see Table 12 for supply level constraints.</p> | | | | | | | | | | | | |
| 6, 12, 14, 35, 38 | V_{DD}^2 | PWR | Power | <p>Power supply for internal circuitry. Please see Table 12 for supply level constraints.</p> | | | | | | | | | | | | |
| 10, 11, 15, 16, 21, 29, 33, 34, 39, 40, 44, 45 | V_{SS} | PWR | Power | <p>Ground</p> | | | | | | | | | | | | |

Notes:

- When TEST = MID and $\overline{\text{sOE}} = \text{HIGH}$, the PLL remains active with nF[1:0] = LL functioning as an output disable control for individual output banks. Skew selections remain in effect unless nF[1:0] = LL.
- A bypass capacitor (0.1 μF) should be placed as close as possible to each positive power pin (<0.2"). An additional 1 μF capacitor should be located within 0.2" of the output bank power supplies (V_{DDQ1} , V_{DDQ3} , and V_{DDQ4}). If these bypass capacitors are not close to the pins, their high frequency filtering characteristics will be cancelled by the parasitic inductance of the traces. Additionally, it is recommend that wide traces (0.025" or wider) be used when connecting the decoupling capacitors to their respective power pins on the RadClock.

4.0 ABSOLUTE MAXIMUM RATINGS:¹

(Referenced to V_{SS})

| Symbol | Description | Limits | Units |
|--|--|--------------------------|-------|
| V_{DD} | Core Power Supply Voltage | -0.3 to 4.0 | V |
| V_{DDQ1} , V_{DDQ3} , and V_{DDQ4} | Output Bank Power Supply Voltage | -0.3 to 4.0 | V |
| V_{IN} | Voltage Any Input Pin | -0.3 to $V_{DD} + 0.3$ | V |
| V_{OUT} | Voltage Any Clock Bank Output | -0.3 to $V_{DDQn} + 0.3$ | V |
| V_O | Voltage on XTAL2 and LOCK Outputs | -0.3 to $V_{DD} + 0.3$ | V |
| I_I | DC Input Current | ± 10 | mA |
| P_D | Maximum Power Dissipation | 1 | W |
| T_{STG} | Storage Temperature | -65 to +150 | °C |
| T_J | Maximum Junction Temperature ² | +150 | °C |
| Θ_{JC} | Thermal Resistance, Junction to Case | 15 | °C/W |
| ESD_{HBM} | ESD Protection (Human Body Model) - Class II | >3000 | V |

Notes:

- Stresses outside the listed absolute maximum ratings may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions beyond limits indicated in the operational sections of this specification is not recommended. Exposure to absolute maximum rating conditions for extended periods may affect device reliability and performance.
- Maximum junction temperature may be increased to +175°C during burn-in and steady-static life.

5.0 RECOMMENDED OPERATING CONDITIONS:

| Symbol | Description | Limits | Units |
|--|---|-----------------|-------|
| V_{DD} | Core Operating Voltage | 3.0 to 3.6 | V |
| V_{DDQ1} , V_{DDQ3} , and V_{DDQ4} | Output Bank Operating Voltage | 2.25 to 3.6 | V |
| V_{IN} | Voltage Any Configuration and Control Input | 0 to V_{DD} | V |
| V_{OUT} | Voltage Any Bank Output | 0 to V_{DDQn} | V |
| T_C | Case Operating Temperature | -55 to +125 | °C |

6.0 DC INPUT ELECTRICAL CHARACTERISTICS (Pre- and Post-Radiation)*

($V_{DD} = +3.3V \pm 0.3V$; $T_C = -55^\circ C$ to $+125^\circ C$)

| Symbol | Description | Conditions | Min. | Max. | Units |
|-----------------|---|---|-----------------------|-----------------------|---------|
| V_{IH}^1 | High-level input voltage (XTAL1, FB and \overline{sOE} inputs) | | 2.0 | -- | V |
| V_{IL}^1 | Low-level input voltage (XTAL1, FB and \overline{sOE} inputs) | | -- | 0.8 | V |
| $V_{IHH}^{1,2}$ | High-level input voltage | | $V_{DD} - 0.6$ | -- | V |
| $V_{IMM}^{1,2}$ | Mid-level input voltage | | $V_{DD} \div 2 - 0.3$ | $V_{DD} \div 2 + 0.3$ | V |
| $V_{ILL}^{1,2}$ | Low-level input voltage | | -- | 0.6 | V |
| I_{IL} | Input leakage current (XTAL1, FB and \overline{sOE} inputs) | $V_{IN} = V_{DD}$ or V_{SS} ; $V_{DD} = \text{Max}$ | -5 | 5 | μA |
| I_{3L}^2 | 3-Level input DC current | HIGH, $V_{IN} = V_{DD}$ | -- | 200 | μA |
| | | MID, $V_{IN} = V_{DD}/2$ | -50 | 50 | μA |
| | | LOW, $V_{IN} = V_{SS}$ | -200 | -- | μA |
| I_{DDQ} | Quiescent supply current | $V_{DD} = +3.0V$; $V_{DDQn} = +3.0V$; TEST & $\overline{sOE} = \text{HIGH}$; XTAL1, FB, FS, & PE/HD = LOW; All other inputs are floated; Outputs are not loaded | -- | 4 | mA |
| I_{DDPD} | Power-down current | $V_{DD} = +3.0V$; $V_{DDQn} = +3.0V$; TEST & $\overline{sOE} = \text{HIGH}$; XTAL1, \overline{PD}/DIV , FB, FS, & PE/HD = LOW; All other inputs are floated; Outputs are not loaded | -- | 100 | μA |
| C_{IN-2L}^3 | Input pin capacitance 2-level inputs | $f = 1\text{MHz}$ @ 0V; $V_{DD} = \text{Max}$ | 8.5 | | pF |
| C_{IN-3L}^3 | Input pin capacitance 3-level inputs | $f = 1\text{MHz}$ @ 0V; $V_{DD} = \text{Max}$ | 15 | | pF |

Notes:

* Post-radiation performance guaranteed at $25^\circ C$ per MIL-STD-883 Method 1019, Condition A up to a TID level of $1.0E6$ rad(Si).

- Functional tests are conducted in accordance with MIL-STD-883 with the following input test conditions: $V_{IH} = V_{IH(\min)} + 20\%$, -0% ; $V_{IL} = V_{IL(\max)} + 0\%$, -50% , as specified herein for LVTTTL and LVCOS inputs. For 3-level inputs, $V_{IH} = V_{IHH(\min)} + 50\%$, -0% ; $V_{IL} = V_{ILL(\max)} + 0\%$, -50% ; $V_{IM} = V_{IMM(\text{nom})} + 0.1V$, $-0.1V$. Devices may be tested using any input voltage within the above specified range, but are guaranteed to $V_{IH(\min)}$, $V_{IL(\max)}$, $V_{IHH(\min)}$, $V_{ILL(\max)}$, and $V_{IMM(\text{nom})}$.
- These inputs are normally wired to V_{DD} , V_{SS} , or left unconnected. Internal termination resistors bias unconnected inputs to $V_{DD}/2 \pm 0.3V$. The 3-level inputs include: TEST, \overline{PD}/DIV , PE/HD, FS, nF[1:0], DS[1:0].
- Capacitance is measured for initial qualification and when design changes may affect the input/output capacitance. Capacitance is measured between the designated terminal and V_{SS} at frequency of 1MHz and a signal amplitude of 50mV rms maximum.

7.0 DC OUTPUT ELECTRICAL CHARACTERISTICS (Pre- and Post-Radiation)*

($V_{DDQn} = +2.5V \pm 10\%$; $V_{DD} = +3.3V \pm 0.3V$; $T_C = -55^\circ C$ to $+125^\circ C$) (Note 1)

| Symbol | Description | Conditions | Min. | Max. | Units |
|--------------|------------------------------|---|------|------|-------|
| V_{OL} | Output low voltage | $I_{OL} = 12mA$ (PE/HD = LOW or HIGH); (Pins: nQ[1:0]) | -- | 0.4 | V |
| | | $I_{OL} = 20mA$ (PE/HD = MID); (Pins: nQ[1:0]) | -- | 0.4 | V |
| | | $I_{OL} = 2mA$ (Pins: LOCK) | -- | 0.4 | V |
| V_{OH} | High-level output voltage | $I_{OH} = 8mA$ (PE/HD = LOW or HIGH); (Pins: nQ[1:0]); $V_{DDQn} = +2.25V$ | 2.0 | -- | |
| | | $I_{OH} = -12mA$ (PE/HD = LOW or HIGH); (Pins: nQ[1:0]) | 2.0 | -- | V |
| | | $I_{OH} = -16mA$ (PE/HD = MID); (Pins: nQ[1:0]); $V_{DDQn} = +2.25V$ | 2.0 | -- | V |
| | | $I_{OH} = -20mA$ (PE/HD = MID); (Pins: nQ[1:0]); $V_{DDQn} = +2.375V$ | 2.0 | -- | V |
| | | $I_{OH} = -2mA$ (Pins: LOCK) | 2.4 | -- | V |
| I_{OSQn}^2 | Short-circuit output current | $V_O = V_{DDQn}$ or V_{SS} ; $V_{DDQn} = +2.75V$; PE/HD = MID | -500 | 500 | mA |
| | | $V_O = V_{DDQn}$ or V_{SS} ; $V_{DDQn} = +2.75V$; PE/HD = LOW or HIGH | -300 | 300 | mA |
| I_{DDOP}^3 | Dynamic supply current | @200MHz (FS = HIGH); $V_{DD} = \text{Max}$; $V_{DDQn} = +2.75V$; $C_L = 40pF/\text{output}$ | -- | 250 | mA |
| | | @100MHz (FS = MID); $V_{DD} = \text{Max}$; $V_{DDQn} = +2.75V$; $C_L = 40pF/\text{output}$ | -- | 150 | mA |
| | | @50MHz (FS = LOW); $V_{DD} = \text{Max}$; $V_{DDQn} = +2.75V$; $C_L = 40pF/\text{output}$ | -- | 100 | mA |
| C_{OUT}^4 | Output pin capacitance | $f = 1MHz @ 0V$; $V_{DD} = \text{Max}$; $V_{DDQn} = +2.75V$ | 15 | | pF |

($V_{DDQn} = +3.3V \pm 0.3V$; $V_{DD} = +3.3V \pm 0.3V$; $T_C = -55^\circ C$ to $+125^\circ C$)

| Symbol | Description | Conditions | Min. | Max. | Units |
|--------------|------------------------------|--|------|------|-------|
| V_{OL} | Output low voltage | $I_{OL} = 12mA$ (PE/HD = LOW or HIGH); (Pins: nQ[1:0]) | -- | 0.4 | V |
| | | $I_{OL} = 24mA$ (PE/HD = MID); (Pins: nQ[1:0]) | -- | 0.4 | V |
| | | $I_{OL} = 2mA$ (Pins: LOCK) | -- | 0.4 | V |
| V_{OH} | High-level output voltage | $I_{OH} = -12mA$ (PE/HD = LOW or HIGH); (Pins: nQ[1:0]) | 2.4 | -- | V |
| | | $I_{OH} = -24mA$ (PE/HD = MID); (Pins: nQ[1:0]) | 2.4 | -- | V |
| | | $I_{OH} = -2mA$ (Pins: LOCK) | 2.4 | -- | V |
| I_{OSQn}^2 | Short-circuit output current | $V_O = V_{DDQn}$ or V_{SS} ; $V_{DDQn} = +3.6V$; PE/HD = MID | -600 | 600 | mA |
| | | $V_O = V_{DDQn}$ or V_{SS} ; $V_{DDQn} = +3.6V$; PE/HD = LOW or HIGH | -300 | 300 | mA |
| I_{DDOP}^3 | Dynamic supply current | @200MHz (FS = HIGH); $V_{DD} = \text{Max}$; $V_{DDQn} = +3.6V$; $C_L = 40pF/\text{output}$ | -- | 400 | mA |
| | | @100MHz (FS = MID); $V_{DD} = \text{Max}$; $V_{DDQn} = +3.6V$; $C_L = 40pF/\text{output}$ | -- | 230 | mA |
| | | @50MHz (FS = LOW); $V_{DD} = \text{Max}$; $V_{DDQn} = +3.6V$; $C_L = 40pF/\text{output}$ | -- | 150 | mA |
| C_{OUT}^4 | Output pin capacitance | $f = 1MHz @ 0V$; $V_{DD} = \text{Max}$; $V_{DDQn} = +3.6V$ | 15 | | pF |

Notes: * Post-radiation performance guaranteed at $25^\circ C$ per MIL-STD-883 Method 1019, Condition A up to a TID level of $1.0E6$ rad(Si).

1. Unless otherwise noted, these tests are performed with V_{DD} and V_{DDQn} at their minimum levels.
2. Supplied as a design limit. Neither guaranteed nor tested.
3. When measuring the dynamic supply current, all outputs are loaded in accordance with the equivalent test load defined in figure 10.
4. Capacitance is measured for initial qualification and when design changes may affect the input/output capacitance. Capacitance is measured between the designated terminal and V_{SS} at frequency of 1MHz and a signal amplitude of 50mV rms maximum.

8.0 AC INPUT ELECTRICAL CHARACTERISTICS (Pre- and Post-Radiation)*

($V_{DD} = +3.3V \pm 0.3V$; $T_C = -55^\circ C$ to $+125^\circ C$) ($V_{DDQn} = +3.3V$ nominal unless otherwise noted) (Note 1)

| Symbol | Description | Condition | Min. | Max. | Unit |
|------------------|---------------------------|---------------------------------------|------|------|------|
| $t_R, t_F^{2,3}$ | Input rise/fall time | $V_{IH}(\min) - V_{IL}(\max)$ | -- | 20 | ns/V |
| t_{PWC} | Input clock pulse | HIGH or LOW | 2 | -- | ns |
| t_{XTAL} | Input clock period | $1 \div F_{XTAL}$ | 5 | 500 | ns |
| t_{DCIN} | Input clock duty cycle | HIGH or LOW | 10 | 90 | % |
| f_{XTAL}^4 | Reference input frequency | FS = LOW; $\overline{PD}/DIV = HIGH$ | 2 | 50 | MHz |
| | | FS = LOW; $\overline{PD}/DIV = MID$ | 4 | 100 | MHz |
| | | FS = MID; $\overline{PD}/DIV = HIGH$ | 4 | 100 | MHz |
| | | FS = MID; $\overline{PD}/DIV = MID$ | 8 | 200 | MHz |
| | | FS = HIGH; $\overline{PD}/DIV = HIGH$ | 8 | 200 | MHz |
| | | FS = HIGH; $\overline{PD}/DIV = MID$ | 16 | 200 | MHz |

Notes:

* Post-radiation performance guaranteed at $25^\circ C$ per MIL-STD-883 Method 1019.

1. Reference Figure 11 for clock output loading circuit that is equivalent to the load circuit used for all AC testing.

2. Supplied only as a design guideline, neither tested nor guaranteed.

3. When driving the UT7R995C with a crystal, the XTAL1 pin does not define maximum input rise/fall time.

4. Although the input reference frequencies are defined as-low-as 2MHz, the N and R dividers must be selected to ensure the PLL operates from 24MHz-50MHz when FS = LOW, 48MHz-100MHz when FS = MID, and 96MHz-200MHz when FS = HIGH.

9.0 AC OUTPUT ELECTRICAL CHARACTERISTICS (Pre- and Post-Radiation)*

($V_{DD} = +3.3V \pm 0.3V$; $T_C = -55^\circ C$ to $+125^\circ C$) (Note 1)

| Symbol | Description | Condition | Min. | Max. | Unit |
|------------------|------------------------|--|------|------|------|
| f_{OR} | Output frequency range | $V_{DDQn} = +3.3V$ | 6 | 200 | MHz |
| $V_{CO_{LR}}$ | VCO lock range | $V_{DDQn} = +3.3V$ | 24 | 200 | MHz |
| $V_{CO_{LBW}}^2$ | VCO loop bandwidth | $V_{DD} = V_{DDQn} = +3.3V$; $T_C = \text{Room Temperature}$ | 0.25 | 3.5 | MHz |
| t_{SKEWPR}^3 | Matched-pair skew | Skew between the earliest and the latest output transitions within the same bank. | -- | 100 | ps |
| t_{SKEW0}^3 | Output-output skew | Skew between the earliest and the latest output transitions among all outputs at $0t_U$. | -- | 200 | ps |
| t_{SKEW1}^3 | | Skew between the earliest and the latest output transitions among all outputs for which the same phase delay has been selected. | -- | 200 | ps |
| t_{SKEW2}^3 | | Skew between the nominal output rising edge to the inverted output falling edge | -- | 500 | ps |
| t_{SKEW3}^3 | | Skew between non-inverted outputs running at different frequencies. | -- | 500 | ps |
| t_{SKEW4}^3 | | Skew between nominal to inverted outputs running at different frequencies. | -- | 500 | ps |
| t_{SKEW5}^3 | | Skew between nominal outputs at different power supply levels. | -- | 650 | ps |
| t_{PART}^8 | Part-part skew | Skew between the outputs of any two devices under identical settings and conditions (V_{DDQn} , V_{DD} , temp, air flow, frequency, etc). | -- | 750 | ps |

| Symbol | Description | Condition | Min. | Max. | Unit | |
|---------------------------------|-------------------------------------|---|------------------------|------|------|----|
| t_{PD0} ^{4, 8} | XTAL1 to FB propagation delay | $V_{DD} = V_{DDQn} = +3.3V$; $T_C = \text{Room Temperature}$ | -250 | +250 | ps | |
| t_{ODCV} | Output duty cycle | $f_{out} < 100 \text{ MHz}$, measured at $V_{DD} \div 2$ | 48 | 52 | % | |
| | | $f_{out} > 100 \text{ MHz}$, measured at $V_{DD} \div 2$ | 45 | 55 | % | |
| t_{PWH} | Output high time deviation from 50% | Measured at 2.0V; $V_{DDQn} = +3.3V$ | -- | 1.5 | ns | |
| t_{PWL} | Output low time deviation from 50% | Measured at 0.8V; $V_{DDQn} = +3.3V$ | -- | 2.0 | ns | |
| t_{ORISE} & t_{OFALL} | Output rise/fall time | Measured as transition time between $V_{OH} = +1.7V$ and $V_{OL} = +0.7V$ for $V_{DDQn} = +2.5V$; $C_L = 40pF$ | PE/HD = HIGH | 0.5 | 1.5 | ns |
| | | | PE/HD = MID | 0.25 | 1.25 | ns |
| | | Measured as transition time between $V_{OH} = +2.0V$ and $V_{OL} = +0.8V$ for $V_{DDQn} = +3.3V$; $C_L = 40pF$ | PE/HD = HIGH | 0.20 | 1.25 | ns |
| | | | PE/HD = MID | 0.10 | 1.0 | ns |
| t_{LOCK} ⁵ | PLL lock time | | -- | 1 | ms | |
| $t_{LOCKRES}$ ^{2, 6} | LOCK Pin Resolution | FS = LOW | 1.6ns \pm 200ps typ. | | ns | |
| | | FS = MID | 1.6ns \pm 200ps typ. | | ns | |
| | | FS = HIGH | 800ps \pm 100ps typ. | | ps | |
| t_{CCI} ⁷ | Cycle-cycle jitter | Divide by 1 output frequency, FS = LOW, FB = divide by 12 | -- | 100 | ps | |
| | | Divide by 1 output frequency FS = MID or HIGH, FB = divide by 12 | -- | 150 | ps | |

Notes:

- Reference Figure 11 for clock output loading circuit that is equivalent to the load circuit used for all AC testing.
- Supplied as a design guideline. Neither guaranteed nor tested.
- Test load = 40pF, terminated to $V_{DD} \div 2$. All outputs are equally loaded. See figure 11.
- t_{PD} is measured at 1.5V for $V_{DD} = 3.3V$ with XTAL1 rise/fall times of 1ns between 0.8V-2.0V.
- t_{LOCK} is the time that is required before outputs synchronize to XTAL1 as determined by the phase alignment between the XTAL1 and FB inputs. This specification is valid with stable power supplies which are within normal operating limits.
- Lock detector circuit will monitor the phase alignment between the XTAL1 and FB inputs. When the phase separation between these two inputs is greater than the amount listed, then the LOCK pin will drop low signaling that the PLL is out of lock.
- This parameter is guaranteed by measuring cycle-cycle jitter on 2¹⁶, back-to-back clock cycles.
- Guaranteed by characterization, but not tested.

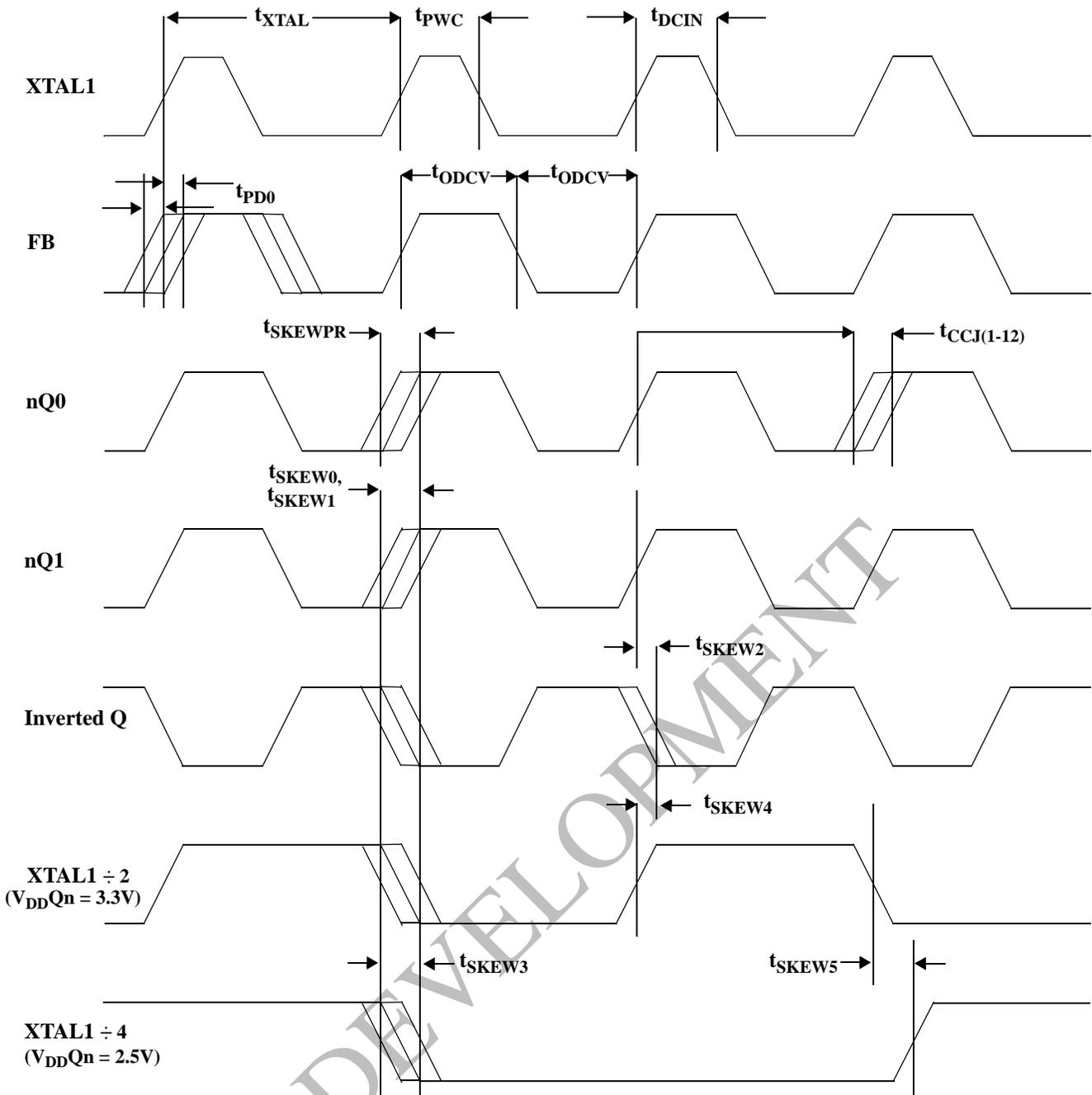


Figure 6. AC Timing Diagram

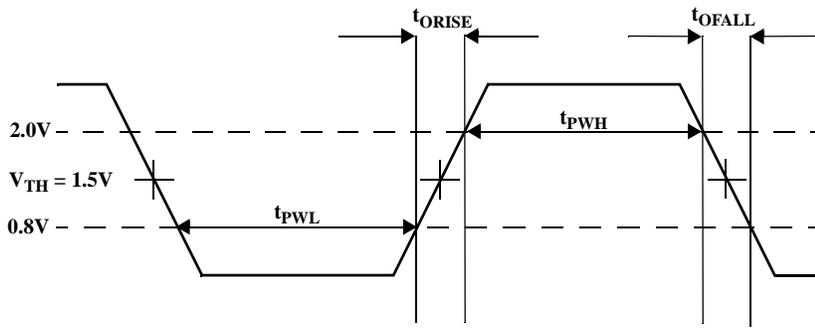


Figure 7. +3.3V LVTTL Output Waveform

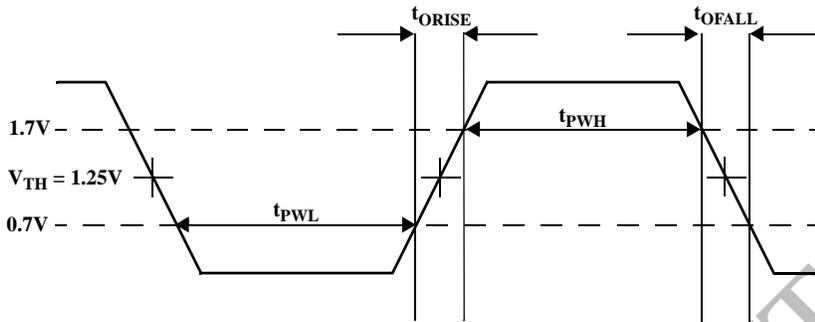


Figure 8. +2.5V LVTTL Output Waveform

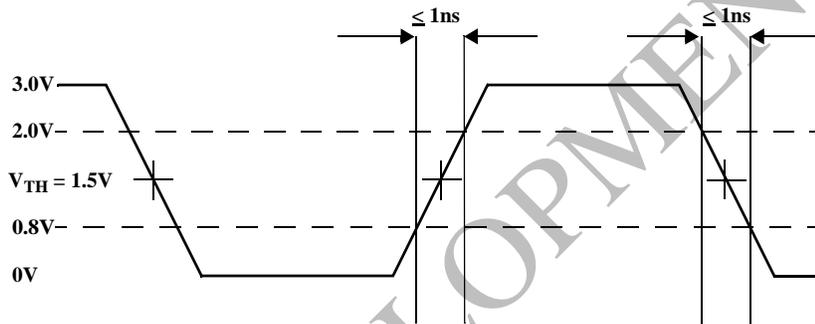


Figure 9. +3.3V LVTTL Input Test Waveform



Figure 10.
Output Test Load Circuit for LOCK and
Dynamic Power Supply Current Measurements

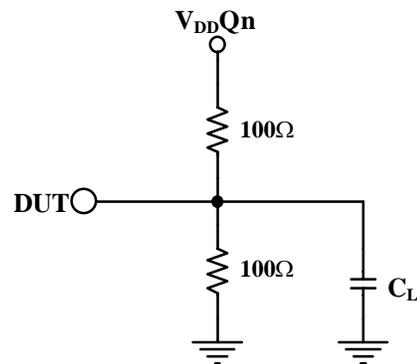
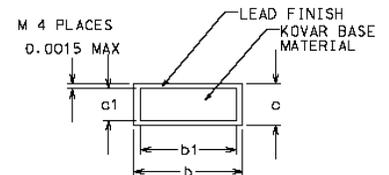
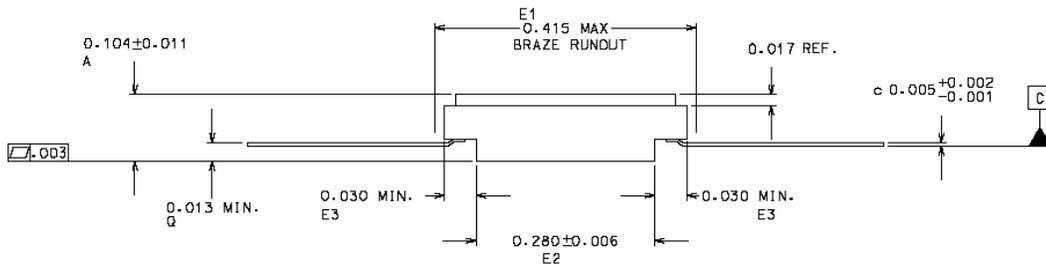
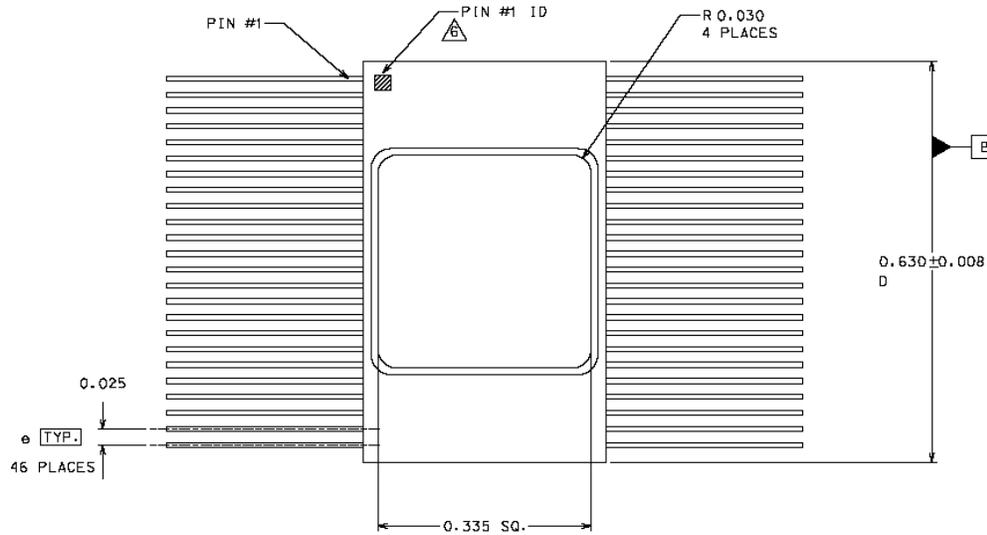


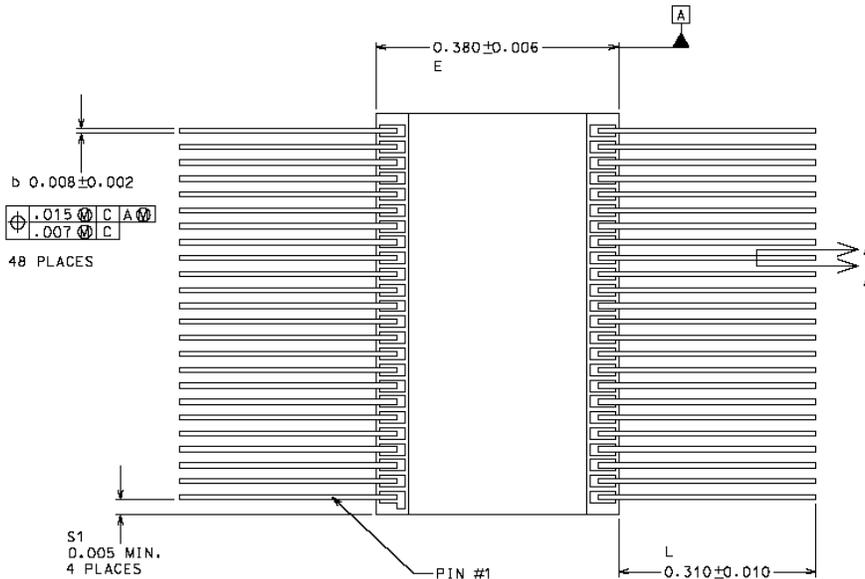
Figure 11.
Clock Output AC Test Load Circuit

Note: This is not the recommended termination
for normal user operation.



SECTION A-A

| | |
|----|-----------------|
| c1 | 0.005 +/- 0.001 |
| b1 | 0.017 +/- 0.002 |

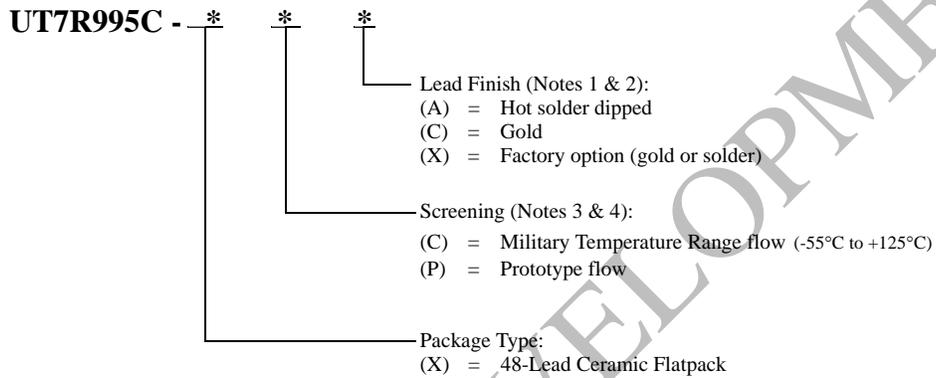
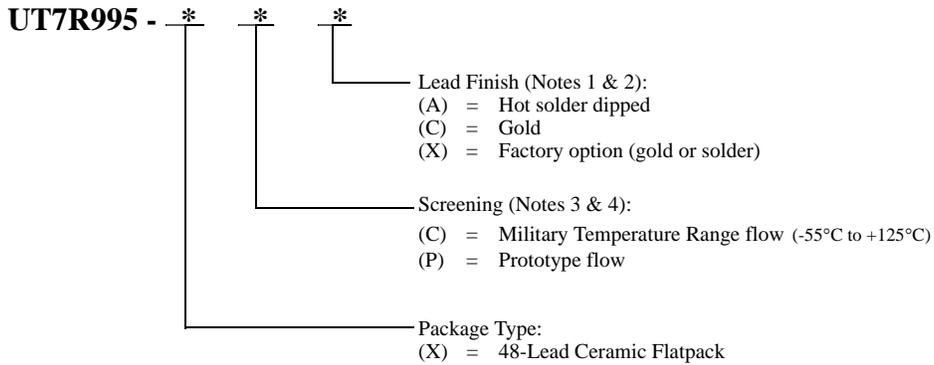


NOTES:

1. ALL EXPOSED METALIZED AREAS MUST BE GOLD PLATED OVER ELECTRICALLY PLATED NICKEL PER MIL-PRF-38535.
 2. THE LID IS ELECTRICALLY CONNECTED TO VSS.
 3. LEAD FINISHES ARE IN ACCORDANCE WITH MIL-PRF-38535.
 4. DIMENSION SYMBOLOGY IS IN ACCORDANCE WITH MIL-PRF-38535.
 5. LEAD POSITION AND COPLANARITY ARE NOT MEASURED
- △ ID MARK SYMBOL IS VENDOR OPTION; NO ALPHANUMERICS.

ORDERING INFORMATION

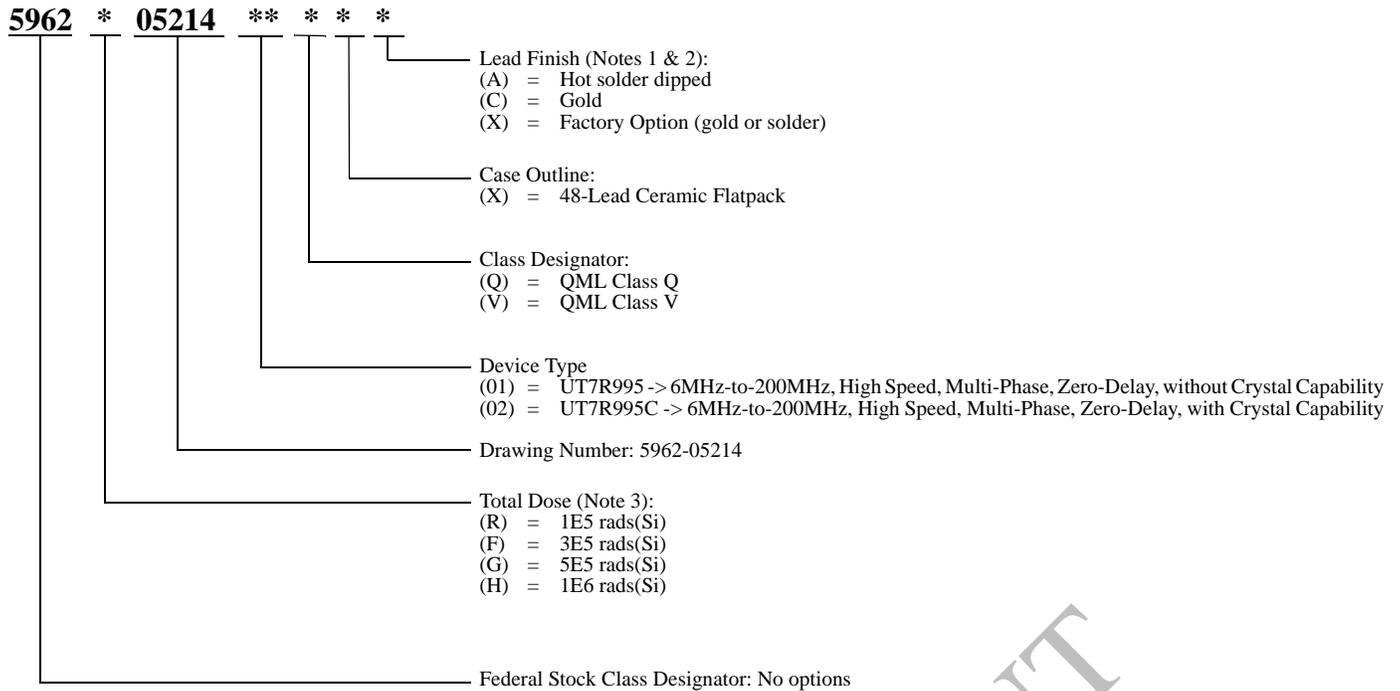
UT7R995 and UT7R995C:



Notes:

1. Lead finish (A,C, or X) must be specified.
2. If an "X" is specified when ordering, then the part marking will match the lead finish and will be either "A" (solder) or "C" (gold).
3. Prototype flow per UTMC Manufacturing Flows Document. Tested at 25°C only. Lead finish is GOLD ONLY. Radiation neither tested nor guaranteed.
4. Military Temperature Range flow per Aeroflex Colorado Springs Manufacturing Flows Document. Devices are tested at -55°C, room temp, and 125°C. Radiation neither tested nor guaranteed.

UT7R995 and UT7R995C: SMD



Notes:

1. Lead finish (A,C, or X) must be specified.
2. If an "X" is specified when ordering, part marking will match the lead finish and will be either "A" (solder) or "C" (gold).
3. Total dose radiation must be specified when ordering. QML Q and QML V are not available without radiation hardening.

IN DEVELOPMENT

NOTES:

IN DEVELOPMENT

NOTES:

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Our passion for performance is defined by three attributes represented by these three icons: solution-minded, performance-driven and customer-focused