

TOSHIBA CMOS DIGITAL INTEGRATED CIRCUIT SILICON MONOLITHIC

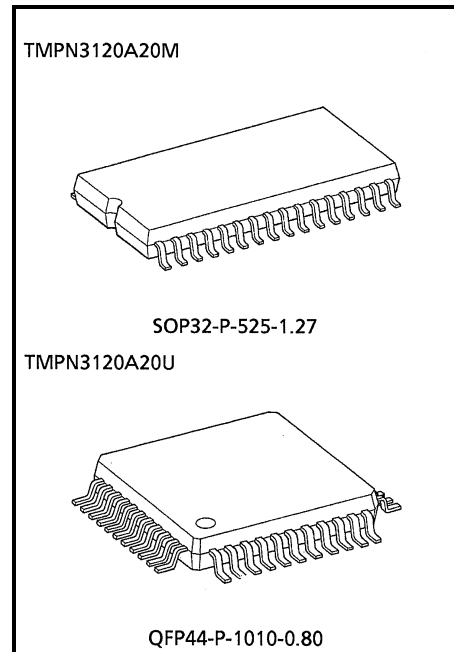
# TMPN3120A20M, TMPN3120A20U

Neuron<sup>®</sup> Chip  
For Distributed Intelligent Control Networks (LONWORKS<sup>®</sup>)

The Neuron Chip (TMPN3120A20M and TMPN3120A20U) provides double the performance of previous Neuron Chips. It supports a response time of 3 to 4 ms across a LONWORKS Network and has double the input / output (I / O) performance of the previous Neuron Chip in terms of both response time and data transmission speed. Neuron Chips have all the built-in communications and control functions required to implement LONWORKS nodes. These nodes may then be easily integrated into highly-reliable distributed intelligent control networks. The typical functions for this chip are explained below.

## FEATURES

- New features
  - ( In comparison with TMPN3120FE3M and TMPN3120A20M /U )
  - Enhanced communication port
  - The package is QFP44-P-1010-0.80 (TMPN3120A20U only)



Weight  
 SOP32-P-525-1.27 : 1.1g (Typ.)  
 QFP44-P-1010-0.80 : 0.6g (Typ.)

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- Main features of the 20MHz Neuron Chip  
(In comparison with the TMPN3120E1M and TMPN3120A20M / U)
  - Increased communication speed  
The maximum transmission speed has been increased two-fold.  
1.25 Mbps → 2.5 Mbps (\*1)  
\*1: This value applies to Single-Ended Mode only.
  - Shortened response time  
The amount of time required from I / O input to I / O output has been greatly reduced.  
Maximum speed 7ms → 3~4 ms
  - Increased IO object speed  
The execution time for all objects has been halved.  
Example) Serial I / O 9600bps  
Parallel I / O 1.2μs / byte
  - Development tool support  
The current LonBuilder® and NodeBuilder® development tools can be used to develop applications for the TMPN3120A20M and TMPN3120A20U (L.B ver. 3.0 or 3.01 is needed). Updated symbol table files for the Neuron Chip firmware are available from Echelon. If your application requires a 20MHz input clock, a utility program available from Echelon may be used to convert the programmer files.  
  
\* **The conversion utilities can be obtained from the Echelon Web Site at <http://www.echelon.com>.**
- I / O Functions
  - Eleven programmable I / O pins.
  - Two programmable 16-bit timers and counters built in.
  - 34 different types of I / O functions to handle a wide range of input and output.
  - ROM firmware image containing pre-programmed I / O drivers, greatly simplifying application programs.
- Network functions
  - Two CPUs for communication protocol processing built in.  
The communications and application CPUs execute in parallel.
  - Equipped with a built-in LonTalk protocol which supports all seven levels of the OSI reference model with ISO.
  - The ROM firmware image contains a complete network operating system, greatly simplifying application programs.
  - Built-in twisted-pair wire transceiver with improved common mode and drive current capabilities.
  - Equipped with communications modes and communication speeds which support various types of external transceivers.  
Supports twisted-pair wire, power line, radio ( RF ), infrared, coaxial cables, and fiber optics.
  - Communication port transceiver modes and logical addresses stored within the EEPROM.  
Can be amended via the network.

## Other functions

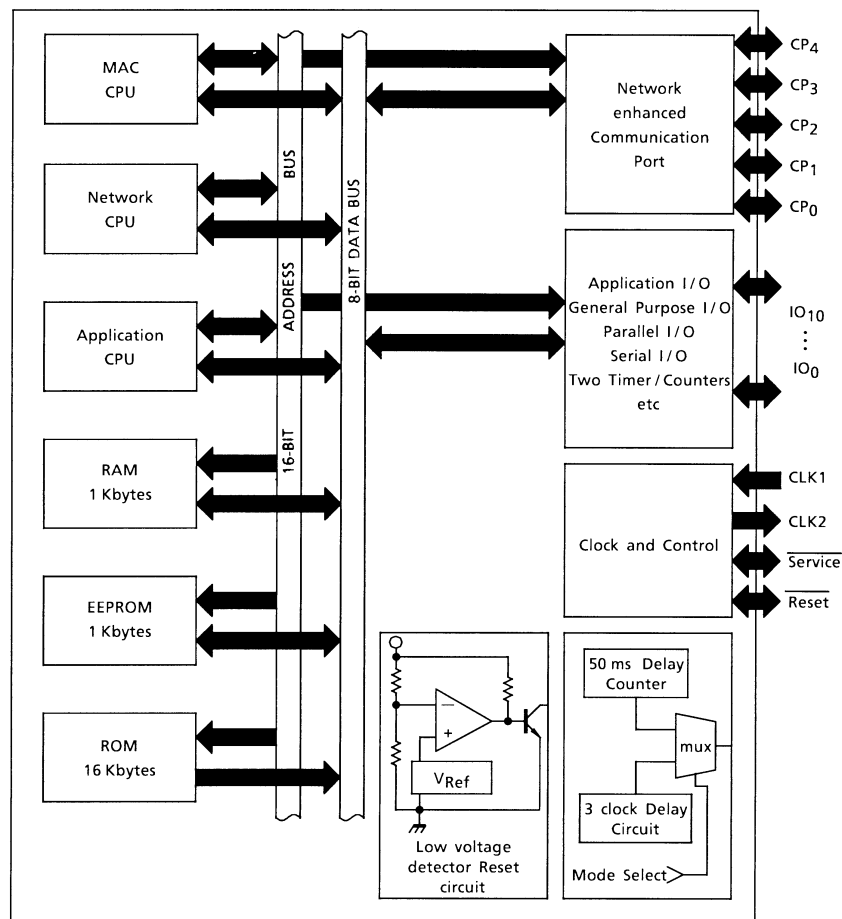
- Application programs are also stored within the EEPROM.  
Can be updated by downloading over the network.
- Built-in watch-dog timer.
- Each chip has a unique ID number.  
Effective during the logical installation of networks.
- Low electrical consumption mode supported with a sleep mode.
- Built in Selectable Reset time  
Prolongs the power-ON reset time for at least 50ms and keeps the operation stable during that time. The reset time can be selected 50ms delay mode or 3clock delay mode by program after the device is in power-ON.
- High-impedance communication port ( CP0 to CP3 )  
The Communication port pins ( CP0 to CP3 ) attain high impedance. This eliminates the need for an external relay.
- Built-in low-voltage detection circuit.  
Prevents in correct operations and writing errors in the EEPROM during drops in power voltage.  
An external LVD must be used to assert reset at power supply voltage below 4.5 V if Neuron Chip is operated at 20 MHz.
- Programmable LVD (Low Voltage Detection) circuit.  
LVDin pin is prepared in order to make it reset on arbitrary voltage.
- Firmware version 9.
- Timing for the main I / O objects during 20 MHz Neuron Chip operations

I / O MODEL	10 MHz TIMING	20 MHz TIMING
Parallel	2.4 $\mu$ s / byte	1.2 $\mu$ s / byte
Bitshift	1, 10 or 15 kbps	2, 20 or 30 kbps
Magcard	Up to 8334 bps	Up to 16668 bps
Magtrack1	Up to 7246 bps	Up to 14492 bps
Neurowire Master	1, 10 or 20 kbps	2, 20 or 40 kbps
Neurowire Slave	Up to 18 kbps	Up to 36 kbps
Serial	600, 1200, 2400 or 4800 bps	1200, 2400, 4800 or 9600 bps
Touch	Supported	Not supported
Frequency Output	Resolution0.4 to 51.2 $\mu$ s Max Range 26.21 to 3355 ms	Resolution0.2 to 25.6 $\mu$ s Max Range 13.1 to 1678 ms
Other Timer / Counter	Resolution0.2 to 25.6 $\mu$ s Max Range 13.1 to 1678 ms	Resolution0.1 to 12.8 $\mu$ s Max Range 6.55 to 839 ms

The specifications for the main timers during 20 MHz operations are as follows :

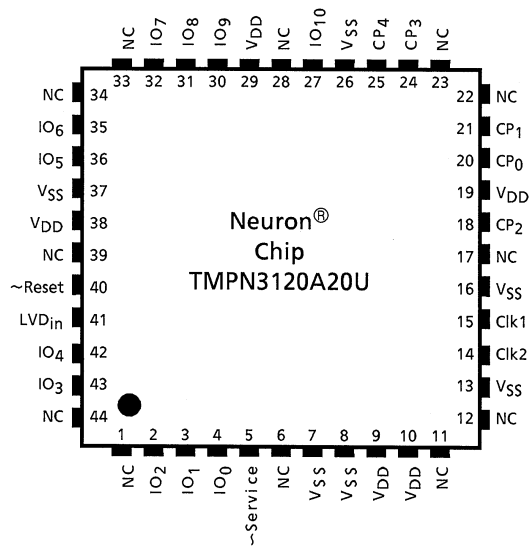
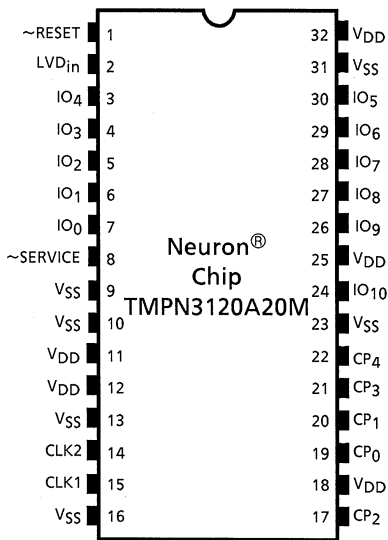
Watchdog Timer	420 ms
Millisecond Timers	1 to 32000 ms
Second Timers	1 to 65000 s
Delay ( ) Function	1 to 32767 counts
Get_Tick_Count ( ) Function	409.6 $\mu$ s per count

## BLOCK DIAGRAM



ITEM	TMPN3120A20M	TMPN3120A20U
CPU	8-bit CPU × 3	8-bit CPU × 3
RAM	1,024 bytes	1,024 bytes
ROM	16,384 bytes	16,384 bytes
EEPROM	1,024 bytes	1,024 bytes
16-bit Timer / Counter	2 channels	2 channels
External Memory Interface	No	No
Package	32-pin SOP	44-pin QFP

## PIN CONNECTION



\* : All NC pins should be open.

## PIN FUNCTION

PIN No.		PIN NAME	I / O	PIN FUNCTION
TMPN3120A20M	TMPN3120A20U			
15	15	CLK1	Input	Oscillator connection, or external clock input.
14	14	CLK2	Output	Oscillator connection. Leave open when external clock is input to CLK1.
1	40	~RESET	I / O (built-in pull-up)	Reset pin. ( Active low )
8	5	~SERVICE	I / O (built-in configurable pull-up)	Service pin. Indicator output during operation.
7~4	4~2, 43	IO <sub>0</sub> ~IO <sub>3</sub>	I / O	Large current sink capacity ( 20 mA ). General I / O port.
3, 30~28	42, 36, 35, 32	IO <sub>4</sub> ~IO <sub>7</sub>	I / O (built-in configurable pull-up)	General I / O port. One of IO <sub>4</sub> to IO <sub>7</sub> can be specified as No.1 timer / counter input. Output signal can be output to IO <sub>0</sub> . IO <sub>4</sub> can be used as the No.2 timer / counter input with IO <sub>1</sub> as output.
27, 26, 24	31, 30, 27	IO <sub>8</sub> ~IO <sub>10</sub>	I / O	General I / O port. Can be used for serial communication with other device.
11, 12, 18, 25, 32	9, 10, 19, 29, 38	V <sub>DD</sub>	Input	Power input ( 5.0 V Typ. )
9, 10, 13, 16, 23, 31	7, 8, 13, 16, 26, 37	V <sub>SS</sub>	Input	Power input ( 0 V GND )
2	41	LVD <sub>in</sub>	Input	Input pin for programmable LVD ( Normally connect to V <sub>DD</sub> )
19, 20, 17, 21, 22	20, 21, 18, 24, 25	CP <sub>0</sub> ~CP <sub>4</sub>	I / O	Bidirectional port for communications. Supports several communications protocols by specifying mode.
—	1, 6, 11, 12, 17, 22, 23, 28, 33, 34, 39, 44	NC	—	Do not connect anything. Leave pins open.

- \* :
- The ~SERVICE and IO<sub>4</sub> to IO<sub>7</sub> terminals are programmable pull-ups.
  - All V<sub>DD</sub> terminals must be externally connected.
  - All V<sub>SS</sub> terminals must be externally connected.

**MAXIMUM RATINGS (  $V_{SS} = 0V$ ,  $V_{SS}$  typ.)**

ITEM	SYMBOL	RATING	UNIT
Power Supply Voltage	$V_{DD}$	-0.3~7.0	V
Input Voltage	$V_{IN}$	-0.3 to $V_{DD} + 0.3$ V	V
Input Voltage CP <sub>0</sub> -CP <sub>3</sub>	$V_{IN(2)}$	-0.5 to $V_{DD} + 1.3$ V $V_{IN(2)} < 7.3$	V
Power Dissipation	$P_D$	800	mW
Storage Temperature	$T_{stg}$	-65~150	°C

**OPERATING CONDITIONS**

ITEM	SYMBOL	MIN	TYP.	MAX	UNIT
Operating Voltage	$V_{DD}$	4.5	5.0	5.5	V
Input Voltage ( TTL )	$V_{IH}$	2.0	—	$V_{DD}$	V
	$V_{IL}$	$V_{SS}$	—	0.8	V
Input Voltage ( CMOS )	$V_{IH}$	$V_{DD} - 0.8$ V	—	$V_{DD}$	V
	$V_{IL}$	$V_{SS}$	—	0.8	V
Input Voltage CP <sub>0</sub> -CP <sub>3</sub> ( differential mode )	$V_{IH}$	—	—	$V_{DD} + 1.0$ V	V
	$V_{IL}$	-0.1	—	—	
Operating Frequency	$f_{osc}$	0.625	—	20	MHz
Operating Temperature	$T_{opr}$	-40	—	85	°C

**ELECTRICAL CHARACTERISTICS**
**DC characteristic (  $V_{DD} = 5.0 \text{ V} \pm 10\%$ ,  $V_{SS} = 0 \text{ V}$ ,  $T_a = -40 \sim 85^\circ\text{C}$  )**
**( Above operating conditions apply unless otherwise states. )**

ITEM	SYMBOL	PINS	TEST CONDITION	MIN	MAX	UNIT
LOW Level Input Voltage (1)	$V_{IL} (1)$	$IO_0 \sim IO_{10}$ CP <sub>0</sub> , CP <sub>3</sub> , CP <sub>4</sub> , ~SERVICE	—	0	0.8	V
LOW Level Input Voltage (2)	$V_{IL} (2)$	~RESET	—	0	$V_{DD} \times 0.3$	V
HIGH Level Input Voltage (1)	$V_{IH} (1)$	$IO_0 \sim IO_{10}$ CP <sub>0</sub> , CP <sub>3</sub> , CP <sub>4</sub> , ~SERVICE	—	2.0	$V_{DD}$	V
HIGH Level Input Voltage (2)	$V_{IH} (2)$	~RESET	—	$V_{DD} - 0.7 \text{ V}$	$V_{DD}$	V
LOW Output Voltage (1)	$V_{OL} (1)$	$IO_0 \sim IO_3$ ~SERVICE, ~RESET	$I_{OL} = 20\text{mA}$	0	0.8	V
			$I_{OL} = 10\text{mA}$	0	0.4	
LOW Output Voltage (2)	$V_{OL} (2)$	CP <sub>2</sub> , CP <sub>3</sub>	$I_{OL} = 40\text{mA}$	0	1.0	V
LOW Output Voltage (3)	$V_{OL} (3)$	Others ( Note 1 )	$I_{OL} = 1.4\text{mA}$	0	0.4	V
HIGH Output Voltage (1)	$V_{OH} (1)$	$IO_0 \sim IO_3$	$I_{OH} = -1.4\text{mA}$	$V_{DD} - 0.4 \text{ V}$	$V_{DD}$	V
HIGH Output Voltage (2)	$V_{OH} (2)$	~SERVICE	$I_{OH} = -1.4\text{mA}$	$V_{DD} - 0.4 \text{ V}$	$V_{DD}$	V
HIGH Output Voltage (3)	$V_{OH} (3)$	CP <sub>2</sub> , CP <sub>3</sub>	$I_{OH} = -40\text{mA}$	$V_{DD} - 1.0 \text{ V}$	$V_{DD}$	V
HIGH Output Voltage (4)	$V_{OH} (4)$	Others ( Note 1 )	$I_{OH} = -1.4\text{mA}$	$V_{DD} - 0.4 \text{ V}$	$V_{DD}$	V
Input Current	$I_{IN}$	( Note 2 )	$V_{IN} = V_{SS} \sim V_{DD}$	-10	10	$\mu\text{A}$
Pull-up Current	$I_{PU}$ (Note 3)	$IO_4 \sim IO_7$ ~SERVICE, ~RESET	$V_{IN} = 0\text{V}$	-30	-300	$\mu\text{A}$
Low-voltage Detection Level	$V_{LVD}$	$V_{DD}$	—	3.8	4.5	V

Note1 : Output voltage characteristics exclude the CLK2 pin.

Note2 : Excludes pull-up input pins.

 Note3 : The  $IO_4$  to  $IO_7$  and ~SERVICE pins have programmable pull-ups. ~RESET has a fixed pull-up.



ITEM		SYMBOL	TYP.	MAX	UNIT
Operating Mode Current Consumption	20 MHz Clock	$I_{DD} (OP)$	33	55	mA
	10 MHz Clock		15	30	
	5 MHz Clock		7	15	
	2.5 MHz Clock		4	8	
	1.25 MHz Clock		2.2	5	
	0.625 MHz Clock		1.2	3	
Sleep Mode Current Consumption		$I_{DD} (SLP)$	16	100	$\mu A$

Note: Test conditions for current dissipation

VDD = 5V, all output = with no load, all input = 0.2V or below or VDD - 0.2 V, programmable pull-up = off, crystal oscillator clock input, differential receiver disabled.

The current value ( typ. ) is a typical value when Ta = 25.°C

The current value ( max ) applies to the rated temperature range at VDD = 5.5 V.

200A $\mu$  ( typ. ) to 600 $\mu A$  ( max ) is added to the current of the differential receiver when the receiver is enabled.

The differential receiver is enabled by either of the following conditions :

- When the Neuron Chip is in Run mode and the communication ports are in Differential mode.
- When the Neuron Chip is in Sleep mode, the communication ports are in Differential mode, and the Comm Port Wakeup is not masked.

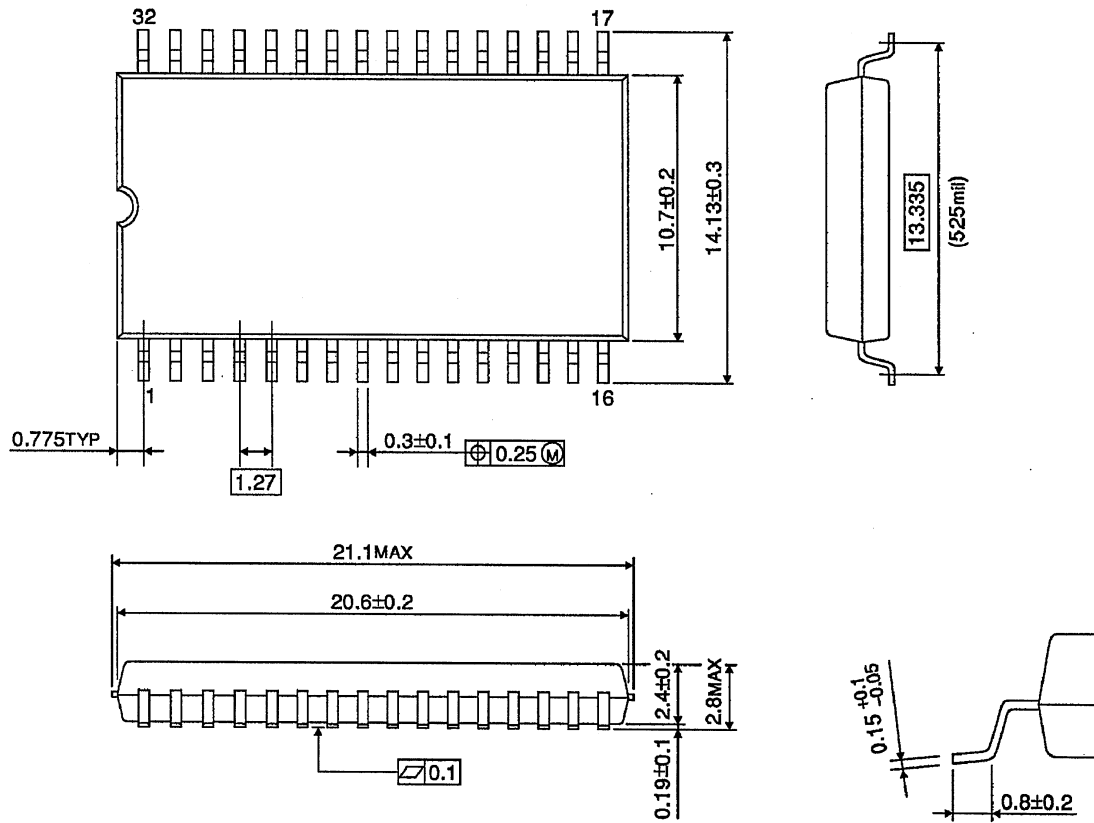
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## PACKAGE DIMENSIONS

SOP32-P-525-1.27

Unit : mm

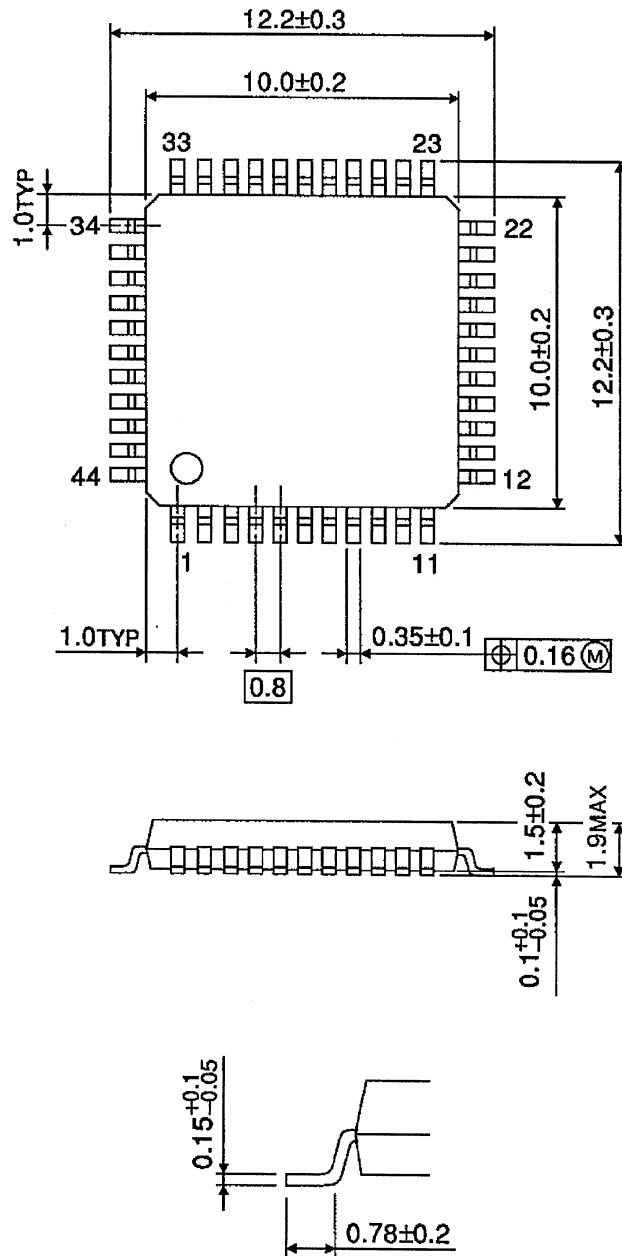


Weight : 1.1 g (Typ.)

## PACKAGE DIMENSIONS

QFP44-P-1010-0.80

Unit : mm



Weight : 0.6 g (Typ.)