5V, 750mA Low Dropout Linear Regulator with Delayed RESET

Description

The CS8126 is a low dropout, high current 5V linear regulator. It is an improved replacement for the CS8156. Improvements include higher accuracy, tighter saturation control, better supply rejection, and enhanced RESET circuitry. Familiar PNP regulator features such as reverse battery protection, overvoltage shutdown, thermal shutdown, and current limit make the CS8126 suitable for use in automotive and battery operated equipment. Additional onchip filtering has been included to enhance rejection of high frequency transients on all external leads.

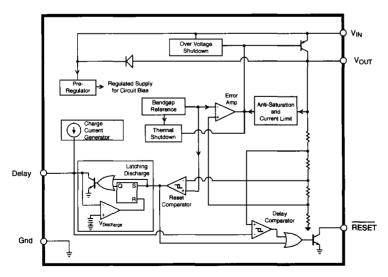
An active microprocessor RESET function is included on-chip with externally programmable delay time. During power-up, or after detection of any error in the regulated output, the RESET lead will remain in the low

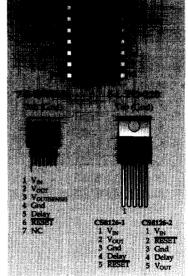
state for the duration of the delay. Types of errors include short circuit, low input voltage, overvoltage shutdown, thermal shutdown, or others that cause the output to become unregulated. This function is independent of the input voltage and will function correctly with an output voltage as low as 1V. Hysteresis is included in both the reset and Delay comparators for enhanced noise immunity. A latching discharge circuit is used to discharge the Delay capacitor, even when triggered by a relatively short fault condition. This circuit improves upon the commonly used SCR structure by providing full capacitor discharge (0.2V type).

Note:The CS8126 is lead compatible with the LM2925, TLE4260, L4947, LM2927, and LM2926.

Features

Block Diagram







Cherry Semiconductor Corporation 2000 South County Trail, East Greenwich, RI 02818 Tel: (401)885-3600 Fax: (401)885-5786 Email: info@cherry-semi.com Web Site: www.cherry-semi.com

Absolute Maximum Ratings

Power Dissipation	Internally Limited
Peak Transient Voltage (46V Load Dump)	50V, 60V
Output Current	Internally Limited
ESD Susceptibility (Human Body Model)	
Junction Temperature	40°C to 150°C
Storage Temperature	55°C to 150°C
Lead Temperature Soldering Wave Solder (through hole styles only)	10 sec. max, 260°C peak
Reflow (SMD styles only)	

Tlectrical Characteristics:	$T_{\Lambda} = -40$ C	to ±125 C,	$I_1 = -40 \text{ C to } + 150$	C, $V_{1N} = 6$ to $26V$, $I_{13} = 5$ to 500 m/A .
	$R_{R1S1.1} = 4$	$4.7 \mathrm{k}\Omega$ to V_{GC}	-unless otherwise	noted

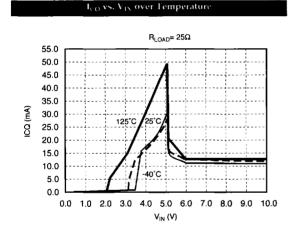
PARAMETER TEST CONDITIONS		MIN	ΓΥP	MAX	UNIT
Output Stage (V _{OUT})					
Output Voltage		4.85	5.00	5.15	v
Dropout Voltage	I _{OUT} = 500mA		0.35	0.60	V
Supply Current	I _{OUT} ≤ 10mA	2.00	2	7	mA
	$I_{OUT} \le 100 \text{mA}$		6	12	
The Manual William Control of the August 1999	I _{OUT} ≤ 500mA	The state of the s	55	100	
Line Regulation	$V_{IN} = 6 \text{ to } 26V, I_{OUT} = 50\text{mA}$		5	50	mV
Load Regulation	$I_{OUT} = 50 \text{ to } 500\text{mA}, V_{IN} = 14\text{V}$		10	50	mV
Ripple Rejection	$f = 120$ Hz, $V_{IN} = 7$ to 17V, $I_{OUT} = 250$ mA	54	75		dB
Current Limit		0.75	1.20		Α
Overvoltage Shutdown		32		40	V
Maximum Line Transient	$V_{OUT} \le 5.5V$		95		V
Reverse Polarity Input Voltage DC	$V_{OUT} \ge -0.6V$, 10Ω Load	- 15	-30		V
Reverse Polarity Input Voltage Transient	1% Duty Cycle, T < 100ms, 10Ω Load		-80		V
Thermal Shutdown	Guaranteed by Design	150	180	210	°C
■ RESET and Delay Functions					
Delay Charge Current	$V_{Delay} = 2V$	5	10	15	μA
RESET Threshold	V _{OUT} Increasing, V _{RT(ON)} V _{OUT} Decreasing, V _{RT(OFF)}	4.65 4.50	4,90 4,70	V _{OUT} - 0.01 V _{OUT} - 0.15	V V
RESET Hysteresis	$V_{RH} = V_{RT(ON)} - V_{RT(OFF)}$	150	200	250	mV
Delay Threshold	Charge, V _{DC(HI)} Discharge, V _{DC(LO)}	3.25 2.85	3.50 3.10	3.75 3.35	v V
Delay Hysteresis		200	400	800	mV
RESET Output Voltage Low	$1V < V_{OUT} < V_{RTL}$, $3k\Omega$ to V_{OUT}	654:8705B	0.1	0.4	v
	The state of the s		0	10	μA
RESET Output Leakage Current	$V_{OUT} > V_{RT(ON)}$,
RESET Output Leakage	Vout > V _{RT(ON)} Discharge Latched "ON", Vout > V _{RT}		0.2	0.5	Y

Delay Time =
$$\frac{C_{Delay} \times V_{Delay} \text{ Threshold Charge}}{I_{Charge}} = C_{Delay} \times 3.2 \times 10^5 \text{ (typ)}$$

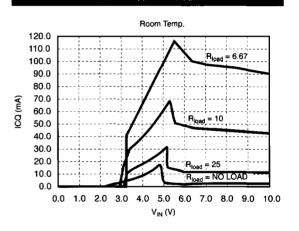
Note 1: assumes ideal capacitor

Package Lead Description					
	PA	CKAGE LEA	1)#	LEAD SYMBOL	FUNCTION
	TO-220 8126-2	7Lead D²PAK	16 Lead SOIC Wide		
1	1	1	1	V_{IN}	Unregulated supply voltage to IC.
2	5	2	16	Vour	Regulated 5V output.
3	3	4	11	Gnd	Ground connection.
4	. 4	5	8	Delay	Timing capacitor for RESET function.
5	2	6	6	RESET	CMOS/TTL compatible output lead. RESET goes low after detection of any error in the regulated output or during power up.
galla		3	14	Vout(sense)	Remote sensing of output voltage.
		7	2, 3, 4, 5, 7, 9, 10, 12, 13, 15	NC	No Connection.

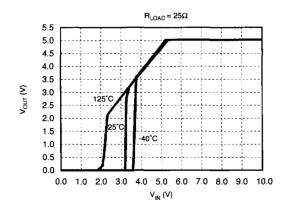
Lypical Performance Characteristics



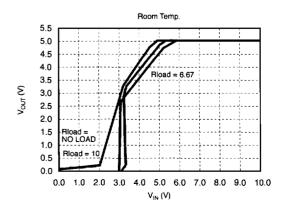
ICD vs. VIX over RIOXD

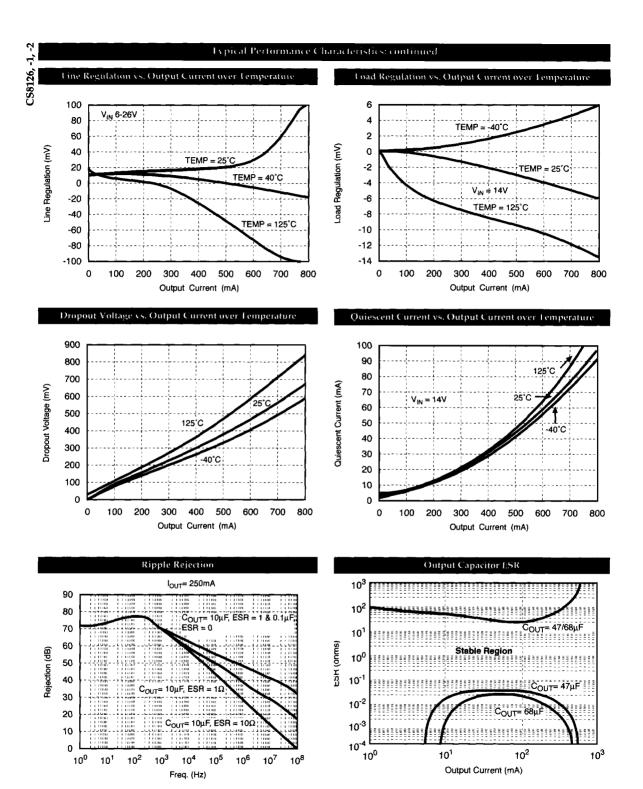


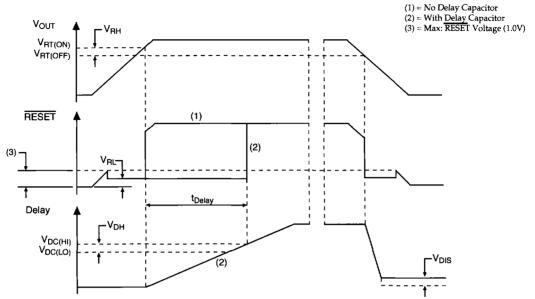




$V_{\rm OLH}$ vs. $V_{\rm IN}$ over $R_{\rm LOAD}$







Circuit Description

The CS8126 RESET function, has hysteresis on both the Reset and Delay comparators, a latching Delay capacitor discharge circuit, and operates down to 1V.

The RESET circuit output is an open collector type with ON and OFF parameters as specified. The RESET output NPN transistor is controlled by the two circuits described (see Block Diagram).

Low Voltage Inhibit Circuit

This circuit monitors output voltage, and when the output voltage falls below $V_{RT(OFF)}$, causes the RESET output transistor to be in the ON (saturation) state. When the output voltage rises above $V_{RT(ON)}$, this circuit permits the RESET output transistor to go into the OFF state if allowed by the RESET Delay circuit.

RESET Delay Circuit

This circuit provides a programmable (by external capacitor) delay on the RESET output lead. The Delay lead provides source current to the external delay capacitor only when the "Low Voltage Inhibit" circuit indicates that output voltage is above $V_{RT(ON)}$. Otherwise, the Delay lead sinks current to ground (used to discharge the delay capacitor). The discharge current is latched ON when the

output voltage falls below $V_{RT(OFF)}$. The Delay capacitor is fully discharged anytime the output voltage falls out of regulation, even for a short period of time. This feature ensures a controlled RESET pulse is generated following detection of an error condition. The circuit allows the RESET output transistor to go to the OFF (open) state only when the voltage on the Delay lead is higher than $V_{DC(HI)}$.

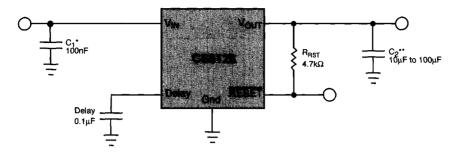
The Delay time for the RESET function is calculated from the formula:

$$Delay time = \frac{C_{Delay} \times V_{Delay} Threshold}{I_{Charge}}$$

Delay time =
$$C_{Delay} \times 3.2 \times 10^5$$

If $C_{Delay} = 0.1 \mu F$, Delay time (ms) = 32ms \pm 50%: i.e. 16ms to 48ms. The tolerance of the capacitor must be taken into account to calculate the total variation in the delay time.

Application Diagram



C₁* is required if the regulator is far from the power source filter.

C2** is required for stability

Application Notes

Stability Considerations

The output or compensation capacitor helps determine three main characteristics of a linear regulator: start-up delay, load transient response and loop stability.

The capacitor value and type should be based on cost, availability, size and temperature constraints. A tantalum or aluminum electrolytic capacitor is best, since a film or ceramic capacitor with almost zero ESR, can cause instability. The aluminum electrolytic capacitor is the least expensive solution, but, if the circuit operates at low temperatures (-25°C to -40°C), both the value and ESR of the capacitor will vary considerably. The capacitor manufacturers data sheet usually provides this information.

The value for the output capacitor C_2 shown in the test and applications circuit should work for most applications, however it is not necessarily the optimized solution.

To determine an acceptable value for C_2 for a particular application, start with a tantalum capacitor of the recommended value and work towards a less expensive alternative part.

Step 1: Place the completed circuit with a tantalum capacitor of the recommended value in an environmental chamber at the lowest specified operating temperature and monitor the outputs with an oscilloscope. A decade box connected in series with the capacitor will simulate the higher ESR of an aluminum capacitor. Leave the decade box outside the chamber, the small resistance added by the longer leads is negligible.

Step 2: With the input voltage at its maximum value, increase the load current slowly from zero to full load while observing the output for any oscillations. If no oscillations are observed, the capacitor is large enough to ensure a stable design under steady state conditions.

Step 3: Increase the ESR of the capacitor from zero using the decade box and vary the load current until oscillations appear. Record the values of load current and ESR that cause the greatest oscillation. This represents the worst case load conditions for the regulator at low temperature.

Step 4: Maintain the worst case load conditions set in step 3 and vary the input voltage until the oscillations increase.

This point represents the worst case input voltage conditions.

Step 5: If the capacitor is adequate, repeat steps 3 and 4 with the next smaller valued capacitor. A smaller capacitor will usually cost less and occupy less board space. If the output oscillates within the range of expected operating conditions, repeat steps 3 and 4 with the next larger standard capacitor value.

Step 6: Test the load transient response by switching in various loads at several frequencies to simulate its real working environment. Vary the ESR to reduce ringing.

Step 7: Remove the unit from the environmental chamber and heat the IC with a heat gun. Vary the load current as instructed in step 5 to test for any oscillations.

Once the minimum capacitor value with the maximum ESR is found, a safety factor should be added to allow for the tolerance of the capacitor and any variations in regulator performance. Most good quality aluminum electrolytic capacitors have a tolerance of +/- 20% so the minimum value found should be increased by at least 50% to allow for this tolerance plus the variation which will occur at low temperatures. The ESR of the capacitor should be less than 50% of the maximum allowable ESR found in step 3 above.

Calculating Power Dissipation in a Single Output Linear Regulator

The maximum power dissipation for a single output regulator (Figure 1) is:

$$P_{D(max)} = \{V_{IN(max)} - V_{OUT(min)}\}I_{OUT(max)} + V_{IN(max)}I_{Q}$$
(1)

where:

V_{IN(max)} is the maximum input voltage,

V_{OUT(min)} is the minimum output voltage,

 $I_{OUT(max)}$ is the maximum output current for the application, and

 I_Q is the quiescent current the regulator consumes at $I_{\text{OUT}(\text{max})}.$

Application Notes: continued

Once the value of $P_{\text{D(max)}}$ is known, the maximum permissible value of $R_{\Theta IA}$ can be calculated:

$$R_{\Theta JA} = \frac{150^{\circ} \text{C} - \text{T}_A}{P_D} \tag{2}$$

The value of $R_{\Theta | A}$ can then be compared with those in the package section of the data sheet. Those packages with $R_{\Theta | A}$'s less than the calculated value in equation 2 will keep the die temperature below 150°C.

In some cases, none of the packages will be sufficient to dissipate the heat generated by the IC, and an external heatsink will be required.

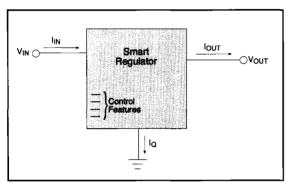


Figure 1. Single output regulator with key performance parameters labeled.

Heat Sinks

A heat sink effectively increases the surface area of the package to improve the flow of heat away from the IC and into the surrounding air.

Each material in the heat flow path between the IC and the outside environment will have a thermal resistance. Like series electrical resistances, these resistances are summed to determine the value of $R_{\rm PIA}$.

$$R_{\Theta IA} = R_{\Theta IC} + R_{\Theta CS} + R_{\Theta SA} \tag{3}$$

where:

 $R_{\Theta IC}$ = the junction-to-case thermal resistance,

R_{OCS} = the case-to-heatsink thermal resistance, and

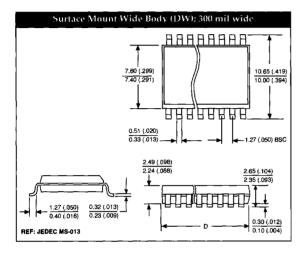
 $R_{\Theta SA}$ = the heatsink-to-ambient thermal resistance.

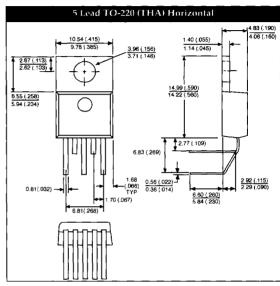
 $R_{\Theta JC}$ appears in the package section of the data sheet. Like $R_{\Theta JA}$ it is a function of package type. $R_{\Theta CS}$ and $R_{\Theta SA}$ are functions of the package type, heatsink and the interface between them. These values appear in heat sink data sheets of heat sink manufacturers.

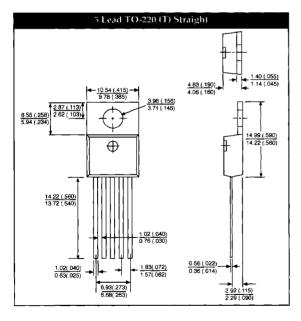
Package Specification

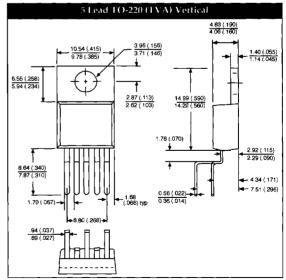
PACKAGE DIMENSIONS IN mm (INCHES)					
D					
Lead Count	Me	Metric		English	
	Max	Min	Max	Min	
16 Lead SO Wide	10.50	10.10	.413	.398	

Therm	al Data	5 Lead TO-220	7 Lead D²PAK	16 Lead SOIC Wide	
$R_{\Theta JC}$	typ	2.1	2.1	23	°C/V
Resa	typ	50	10-50*	105	°C/V

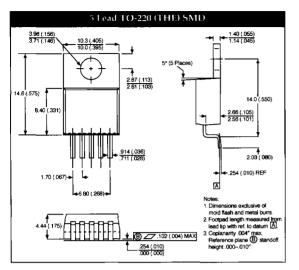


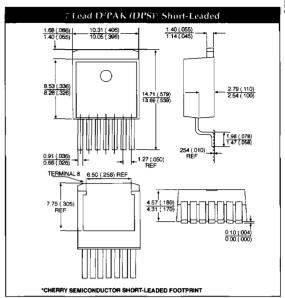






PACKAGE DIMENSIONS IN mm (INCHES)





Ordering Information			
Part Number	Description		
CS8126-1YT5	5 Lead TO-220 Straight		
CS8126-1YTVA5	5 Lead TO-220 Vertical		
CS8126-1YTHA5	5 Lead TO-220 Horizontal		
CS8126-2GT5	5 Lead TO-220 Straight		
CS8126-2GTVA5	5 Lead TO-220 Vertical		
CS8126-2GTHA5	5 Lead TO-220 Horizontal		
CS8126-1YTHE5	5 Lead TO-220 Surface Mount		
CS8126-1YTHER5	5 Lead TO-220 Surface Mount (tape & reel)		
CS8126YDPS7	7 Lead D ² PAK Short-Leaded		
CS8126YDPSR7	7 Lead D2PAK Short-Leaded (tape & reel)		
CS8126YDW16	16 Lead SOIC Wide		
CS8126YDWR16	16 Lead SOIC Wide (tape & reel)		

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