## AN-9737

# Design Guideline for Single-Stage Flyback AC-DC Converter Using FL6961 for LED Lighting 

## Summary

This application note presents single-stage Power Factor Correction (PFC) and focuses on how to select and design the flyback transformer for $16.8 \mathrm{~W}(24 \mathrm{~V} / 0.7 \mathrm{~A})$ solution for universal input for LED lighting applications using FL6961. The flyback converter using FL6961 operates in Critical Conduction Mode (CRM) and has functions such as CC/CV feedback circuit, soft-starting, and the cycle-by-cycle current limit for LED lighting applications.

## Introduction

These days, engineers use various types of LEDs for general lighting systems because of their long life, excellent efficacy, price, environmental benefits, and requirements from end users. At the same time, high power factor (PF), isolation for safety, and constant current control (CC) for constant LED color are becoming requirements.

Conventional regulation is the minimum power factor correction for input power base above 25 W , but many want to reduce power ratings and the new Energy-Star directive for solid-state lighting requires a power factor greater than 0.9 for commercial applications. Expect PF regulations to become more stringent.

## Basic Operation: High Power Factor Flyback Converter

The basic idea of achieving high power factor (PF) flyback converter is to use a Critical Conduction Mode (CRM) PFC controller. The conventional PFC IC, such as FL6961, has constant on-time and variable off-time control method, which means the input average current always follows the input voltage shape.

Figure 1 shows the typical application schematic of singlestage PFC topology. The main difference of normal CRM boost converter is that single-stage PFC doesn't use a large electrolytic capacitor after the full rectification diode. Normally, the single-stage PFC method uses a small capacitor ( C 1 in Figure 1) to act as a noise filter to attenuate high-frequency components and doesn't use the INV pin for output voltage regulation.


Figure 1. Simplified Schematic of High-Power Factor Flyback Converter with FLS6961

Figure 2 shows typical waveforms of the simplified circuit of a flyback converter with CRM. When the MOSFET (Q1) turns on, the primary current in primary side linearly increases and is clamped at a certain internal level because the FL6961 doesn't have cycle-by-cycle current limit like a conventional current mode control IC (such as FAN7527B). Its peak level is determined by the primary magnetizing inductance value and the fixed on-time. Instead of the cycle-by-cycle primary current limit, the FL6961 has an overcurrent protection (OCP) function. If the current sensing signal is larger than internal detection level, the FL6961 doesn't get output signal for operating the MOSFET (Q1).


Figure 2. Key Waveforms of Flyback Converter on CRM

The FL6961 has a constant on-time across the whole range. The input average current always follows the peak input current, as shown in the equation:

$$
\begin{equation*}
I_{A V G(M O S F E T)}=\frac{1}{2} I_{P K} t_{O N} \tag{1}
\end{equation*}
$$

This is also proportional to the instantaneous input voltage. This means the input current shape is always the same as the input voltage shape. The reverse diode voltage is linearly increased and is equal to:

$$
\begin{equation*}
V_{P K(\text { DIODE })}=V_{O}+V_{I N} \frac{N_{S}}{N_{P}} \tag{2}
\end{equation*}
$$

During the MOSFET off-time, which is also the diode ontime; the input current instantly drops to zero, the diode in the secondary side conducts, and the diode current linearly decreases. The peak current of the secondary side is the same as the multiplication of the primary peak current and turns ratio between the primary side $\left(\mathrm{N}_{\mathrm{P}}\right)$ and secondary side
$\left(\mathrm{N}_{\mathrm{S}}\right)$ and naturally decreases to zero. The average current of the secondary side is:

$$
\begin{equation*}
I_{A V G(D I O D E)}=\frac{1}{2} \frac{N_{P}}{N_{S}} I_{P K} t_{o f f} \tag{3}
\end{equation*}
$$

Since the diode forward-voltage drop decreases as current decreases, the output voltage reflects the primary winding and adds additional voltage due to overshoot made by resonance between the leakage inductance on primary-side winding and parasitic capacitance on the MOSFET (Q1). As a result, a superimposed voltage occurs on the MOSFET during off-time as:

$$
\begin{equation*}
V_{\operatorname{MOSFET}(o f f)}=V_{I N}+V_{R}+V_{O S} \tag{4}
\end{equation*}
$$

where $\mathrm{V}_{\mathrm{R}}$ is the reflected voltage and $\mathrm{V}_{\mathrm{OS}}$ is the voltage overshoot term.

The reflected voltage, $V_{R}$, is affected by the turns ratio between the primary and secondary side of the transformer and the output voltage, calculated as:

$$
\begin{equation*}
V_{R}=\frac{N_{P}}{N_{S}} V_{O} \tag{5}
\end{equation*}
$$

Figure 3 shows the ideal waveforms of the primary-side current at MOSFET (Q1) and the secondary-side current at the diode. The input peak and average current on the primary side follows input voltage instantaneously. Normally, secondary-side current on the diode is larger than the primary side because of the turns ratio.


Figure 3. Ideal Waveforms

As a result, designers should consider two conditions before component selection: voltage and current capacity on primary-side MOSFET(Q1) and secondary-side diode (D3) to make a stable system with margin.

Figure 4 shows a guide to deciding two components on the boundary condition of flyback converter topology.


Figure 4. Boundary Conditions of Flyback Converter Topology (Refer to AN-8025)

$$
P=I_{o}\left(V_{o}+V_{d}\right)=0.7(24+1)=17.5[\mathrm{~W}]
$$

Step 4. Calculate the maximum input current, $\mathrm{I}_{\max }$ :

$$
I_{i n(\max )}=\frac{P_{o}}{V_{\min } \eta}=\frac{17.5}{(\sqrt{2} \times 90)(0.82)}=0.168[\mathrm{~A}]
$$

Step 5. Calculate the MOSFET voltage drop, $\mathrm{V}_{\mathrm{vd}}$ :

$$
V_{v d}=I_{i n(\max )} R_{M O S}=0.168[\mathrm{~V}]
$$

Step 6. Calculate the primary voltage on transformer, $\mathrm{V}_{\mathrm{p}}$ :
$V_{P}=V_{\text {min }}-V_{v d}=127-0.168 \approx 127[\mathrm{~V}]$
$\mathrm{V}_{\mathrm{p}}=126.83$ use 127
Step 7. Calculate the primary peak current, $\mathrm{I}_{\mathrm{ppk}}$ :

$$
I_{p p k}=\frac{2 T P}{\eta V_{p} t_{o n(\max )}}=\frac{2\left(20 \times 10^{-6}\right)(17.5)}{0.82(127)\left(7 \times 10^{-6}\right)}=0.96[\mathrm{~A}]
$$

Step 8. Calculate the primary rms current, $\mathrm{I}_{\text {prms }}$ :

$$
I_{p r m s}=I_{p p k} \sqrt{\frac{t_{o n}}{3 T}}=0.96 \sqrt{\frac{\left(7 \times 10^{-6}\right)}{3\left(20 \times 10^{-6}\right)}}=0.32 \text { [A] }
$$

Step 9. Calculate the required minimum inductance, L:
$L=\frac{V_{p} t_{o n(\max )}}{I_{p p k}}=\frac{127\left(7 \times 10^{-6}\right)}{0.96}=0.926[\mathrm{mH}]$
$\mathrm{L}=0.926[\mathrm{mH}]$ use $1[\mathrm{mH}]$
Step 10. Calculate the energy-handing capability in wattseconds, w-s:

$$
E N G=\frac{L I_{p p k}^{2}}{2}=\frac{\left(1 \times 10^{-3}\right)\left(0.96^{2}\right)}{2}=0.0004608[\mathrm{w}-\mathrm{s}]
$$

Step11. Calculate the electrical conditions, $\mathrm{K}_{\mathrm{e}}$ :
$K_{e}=0.145 P B_{m}^{2} \times 10^{-4}=0.145(17.5)\left(0.35^{2}\right) \times 10^{-4}=0.00003108$
Step 12. Calculate the core geometry, $\mathrm{K}_{\mathrm{g}}$ :

Step 3. Calculate the output power:
$K_{g}=\frac{(E N G)^{2}}{K_{e} \alpha}=\frac{(0.0004608)^{2}}{0.00003108(0.5)}=0.0136\left[\mathrm{~cm}^{5}\right]$
Step 13. See Table 2 for core size.
To prevent core saturation, select a little big core after comparing two $\mathrm{K}_{\mathrm{g}}$ values: calculate value at Step 12 vs. the existing value in Table 2.

The PQ-42016 has a little bit big $\mathrm{K}_{\mathrm{g}}$ value ( 0.01327 ) in Table 2 with 2500 permeability ( $\mu \mathrm{i}$ ).

Step 14. Calculate the current density, J.:
$J=\frac{2(E N G) \times 10^{4}}{B_{m} A_{P} K_{u}}=\frac{2(0.0004608) \times 10^{4}}{0.35(0.2484)(0.4)}=265\left[\mathrm{~A} / \mathrm{cm}^{2}\right]$
Step 15. Calculate the required wire area. $\mathrm{A}_{\mathrm{W}(\mathrm{B})}$ :
$A_{W(B)}=\frac{I_{r m s}}{J}=\frac{0.32}{265}=0.001207 \quad\left[\mathrm{~cm}^{2}\right]$
Step 16. Calculate the number of turns, N :
$N=\frac{W_{a} K_{u}}{A_{w(B)}}=\frac{0.4283 \times 0.4}{0.001207}=141.93[\mathrm{~T}]$
$\mathrm{N}=141.93$; use 142 turns.
Step 17. Calculate the required gap, $\mathrm{l}_{\mathrm{g}}$ :
$l_{g}=\frac{0.4 \pi(N)(\Delta I) \times 10^{-4}}{\Delta B_{m}}=\frac{0.4 \pi(142)(0.96) \times 10^{-4}}{0.35}=0.0489[\mathrm{~cm}]$
Step 18. Calculate the new turns using a gap from Step 15.
$N=\sqrt{\frac{L\left(l_{g}+\frac{M P L}{\mu_{i}}\right)}{0.4 \pi\left(A_{c}\right)}}=\sqrt{\frac{1 \times 10^{-3}\left(0.0489+\frac{3.74}{2500}\right)\left(10^{8}\right)}{0.4 \pi(0.58)}}=83.153$
$\mathrm{N}=83.153$; use $83[\mathrm{~T}]$.
where $\mu_{i}$ is permeability of selected core material and MPL is Magnetic Path Length of selected core.

Step 19. Calculate the fringing flux, F:
$F=\left(1+\frac{l_{g}}{\sqrt{A_{c}}} \ln \frac{2 G}{l_{g}}\right)=\left(1+\frac{0.0489}{\sqrt{0.58}} \ln \frac{2(1.001)}{0.0489}\right)=1.238$
where G is window height of selected core.
Step 20. Calculate the new turns, $\mathrm{N}_{\text {new }}$ :
$N=\sqrt{\frac{l_{g} L}{(0.4 \pi)\left(A_{c}\right) F\left(10^{-8}\right)}}=\sqrt{\frac{0.0489 \times 1 \times 10^{5}}{(0.4 \pi)(0.58)(1.238)}}=73.6^{[\mathrm{T}]}$
$\mathrm{N}_{\text {new }}=73.6$; use 74 .
Step 21. Calculate the AC flux density in Tesla, $\mathrm{B}_{\mathrm{AC}}$ :
$B_{a c}=\frac{(0.4 \pi) N\left(\frac{I_{P K}}{2}\right) F\left(10^{-4}\right)}{l_{g}}=\frac{(0.4 \pi)(74)\left(\frac{0.96}{2}\right)(1.238)\left(10^{-4}\right)}{0.0489}=0.113[$
Step 22. Calculate the new wire size, $\mathrm{A}_{\mathrm{W}(\mathrm{B})}$ :
$A_{W(B)}=\frac{W_{a} K_{u}}{N_{\text {new }}}=\frac{0.4283 \times 0.4}{74}=0.002315\left[\mathrm{~A} / \mathrm{cm}^{2}\right]$
Step 23. Calculate the skin depth at expected operating frequency at low input voltage. The skin depth is the radius of the wire.
$\gamma=\frac{6.62}{\sqrt{f}}=\frac{6.62}{\sqrt{50 \times 10^{3}}}=0.02960[\mathrm{~cm}]$
Step 24.Calculate the required wire area under considering skin depth :
Wire $_{A}=\pi\left(r^{2}\right)=0.0027535\left[\mathrm{~cm}^{2}\right]$
Step 25. Select a wire size with the required area from Table 4. If the area is not within $10 \%$ of the required area, then go to the next smallest size.
AWG=\#23
$\mathrm{A}_{\mathrm{W}(\mathrm{B})}=0.00259\left[\mathrm{~cm}^{2}\right]$
$\mu \Omega / \mathrm{cm}=666$
Step 26. Calculate the required number of primary strands, $\mathrm{S}_{\mathrm{np}}$ :

$$
S_{n p}=\frac{A_{w(B)}}{\text { Wire }_{A}}=\frac{0.002315}{0.00259}=0.8938
$$

This means that the selected wire from the Step 25, AWG23, is enough or has enough margins for supplying the primaryside current on the flyback converter.

Step 27. Calculate the secondary and auxiliary turns, $\mathrm{N}_{\mathrm{s}}$ $\mathrm{N}_{\mathrm{aux}}$ :
$N_{s}=\frac{N_{p}\left(V_{o}+V_{d}\right)\left(1-D_{\max }\right)}{\left(V_{p} D_{\max }\right)}=\frac{74(24+1)(1-0.35)}{(\sqrt{2} \times 90)(0.35)}=27.05$
$\mathrm{N}_{\mathrm{s}}=27.05$; use 27.
$N_{\text {aux }}=\frac{N_{p}\left(V_{o}+V_{d}\right)\left(1-D_{\max }\right)}{\left(V_{p} D_{\max }\right)}=\frac{74(15+1)(1-0.35)}{(\sqrt{2} \times 90)(0.35)}=17.31$
$\mathrm{N}_{\mathrm{aux}}=17.31$; use 17 .
Step 28. Calculate the secondary peak current, $\mathrm{I}_{\mathrm{spk}}$ :
$I_{s p k}=\frac{2 I_{o}}{\left(1-D_{\max }\right)}=\frac{2(0.7)}{1-0.35}=2.153[\mathbf{A}]$
Step 29. Calculate the secondary rms current, $\mathrm{I}_{\mathrm{srms}}$ :
$I_{s r m s}=I_{s p k} \sqrt{\frac{\left(1-D_{\max }\right)}{3}}=2.153 \sqrt{\frac{(1-0.35)}{3}}=1.0021[\mathrm{~A}]$
Step 30. Calculate the secondary wire area, $\mathrm{A}_{\mathrm{sw}(\mathrm{B})}$ :

$$
A_{S W(B)}=\frac{I_{r m s}}{J}=\frac{1.0021}{265}=0.003781\left[\mathrm{~cm}^{2}\right]
$$

Step 31. Select a wire size with the required area from Table 4. If the area is not within $10 \%$ of the required area, go to the next smallest size.

AWG=\#22
$\mathrm{A}_{\mathrm{W}(\mathrm{B})}=0.003243[\mathrm{~cm} 2]$
$\mu \Omega / \mathrm{cm}=531.4$
Step 32. Calculate the required number of primary strands, $\mathrm{S}_{\mathrm{np}}$ :
$S_{n p}=\frac{A_{s w(B)}}{\text { Wire }_{A}}=\frac{0.003243}{0.00259}=1.2521$
This requires the AWG21 wire with two strands for secondary-side winding on the flyback converter.

| Adapted Core Size |  | PQ-42614 | AWG |
| :---: | :---: | :---: | :---: |
| Turns | Primary | 74 | 23 |
|  | Secondary | 27 | 22/2 Strands |
|  | Auxiliary | 17 |  |
| Estimated gap[mm] |  | 0.489 |  |

## B. MOSFET and Diode Selection

Step 33. Calculate the maximum voltage of MOSFET drain voltage at primary side:

$$
V_{\text {MOSEET(off) }}=V_{I N}+V_{R}+V_{O S}=V_{I N}+\frac{N_{P}}{N_{S}} V_{O}+V_{O S}=490.54[\mathrm{~V}]
$$

where $\mathrm{V}_{\text {Os }}$ is assumed $\sim 50 \mathrm{~V}$ and its peak can degrade external snubber circuit performance. This means a 600 V MOSFET can be used with some margin. Minimum requirements of the MOSFET are summarized below.

| Current Rating [A] |  | Voltage Rating [V] |  |
| :---: | :---: | :---: | :---: |
| Calculation | $+20 \%$ Margin | Calculation | $+20 \%$ Margin |
| 0.96 | 1.152 | 490.54 | 588.65 |

Step 34. Calculate the maximum voltage of diode at secondary side:

$$
V_{P K(\text { DIODE })}=V_{O}+V_{I N} \frac{N_{S}}{N_{P}}=24+265 \sqrt{2} \frac{27}{74}=160.74[\mathrm{~V}]
$$

This means a 200 V diode can be used with some margin. The minimum requirement of the secondary diode as summarized below.

| Current rating [A] |  | Voltage rating [V] |  |
| :---: | :---: | :---: | :---: |
| Calculation | $+20 \%$ Margin | Calculation | $+20 \%$ Margin |
| 2.153 | 2.584 | 160.74 | 192.88 |

## C. Sensing Resistor

The CS pin of FL6961 has over-current protection (OCP) over the whole operating period and its internal clamping level, $\mathrm{V}_{\text {LIMIT, }}$ is 0.8 V .


Figure 5. Switching Current Limit
Normally, it is reasonable to set the OCP level to 1.5 times higher than the peak current at primary side.

$$
I_{\text {LIMIT }}=1.5 I_{P P K}=\frac{3 T P}{\eta V_{p} t_{o n(\max )}}=1.44
$$

Calculate the sensing resistor as:

$$
R_{\text {sensing } g} \leq \frac{0.8}{I_{\text {LIMIT }}}=0.55[\Omega]
$$

## D. Voltage and Current Feedback for CC/CV Function

The constant voltage and current output is adapted by measuring the actual output voltage and current with external passive components and an op amp in the evaluation board. Because the output loads, the High Bright LED (HB LED) and passive components are effected by ambient temperature. Use the feedback path for stable operation.


Figure 6. Feedback Circuit for CC/CV Operation

Normally, the CC block is dominate over the CV block in steady state and the CV block acts as the Over-Voltage Protection (OVP) at transient or abnormal mode, such as noload condition.

The output signal of CC block is determined as:

$$
V_{O_{-} c c}=R_{4}\left(\frac{V_{s e n \sin g_{-} C C}}{R_{2}}-\frac{V_{r e f}}{R_{3}}\right)+\frac{1}{C_{1}} \int\left(\frac{V_{\operatorname{sen} \sin g_{-} C C}}{R_{2}}-\frac{V_{r e f}}{R_{3}}\right) d t
$$

where the $\mathrm{V}_{\text {sensing_CC }}$ means the sensing voltage from the sensing resistor (R1) and its values is as:
$V_{s e n \sin g_{-} C C}=I_{o} \times R_{1}$
The output signal of CV block is determined as:

$$
\begin{aligned}
& V_{O_{-} C V}=\left(\frac{R_{6}}{R_{5}+R_{6}}\right) V_{\text {sensing_CV }}+\frac{R_{8}}{R_{7}}\left[\left(\frac{R_{6}}{R_{5}+R_{6}}\right)\right. \\
& \left.V_{\text {sensing_CV }}-V_{\text {ref }}\right]+\frac{1}{C_{2}} \frac{1}{R_{7}} \int\left(\frac{R_{6}}{R_{5}+R_{6}} V_{\text {sensing_CV }}-V_{\text {ref }}\right) d t
\end{aligned}
$$

where the $\mathrm{V}_{\text {sensing_Cv }}$ means the output voltage on this circuit and this voltage is divided by two resistors, R5 and R6, and connected to non-inverted pin at the op amp.
Normally, set this divided voltage, $\left(\frac{R_{6}}{R_{5}+R_{6}}\right) V_{\text {sensing_CV }}$, to $V_{r e f}$ or a little bit smaller value in steady state condition because the main role of this block is over-voltage protection. There are more high-voltage transfers to the output stage at transient or an abnormal case such as overvoltage output condition than in the steady state.

## E. Soft-Start / Overshoot Prevention Function

Normally, the High Bright (HB) LED has a forward-current limitation to prevent the LED burn-out due to over-power dissipation. Thererfore, the output overshoot function is needed through the whole operating period. Though there are CC/CV blocks for output regulation, those blocks do not operate in transient modes, because they block have a long response time and cannot act instantly. Figure 7 shows the output voltage overshoot compression method using diode and resistor. The current flows through resistor, R9, and diode, D204, at startup, which is the period before activating the CC/CV block, and then decrease at steady state. The quantity of by-passing current goes into the feedback block on the control IC, FL6961, and controls the output power gradually.


Figure 7. Soft-Start / Overshoot Prevention Method

Table 2. Various Core Types and Size

| Part \# | $\mathbf{M L T}$ <br> $[\mathbf{c m}]$ | $\mathbf{M P L}$ <br> $[\mathbf{c m}]$ | $\mathbf{G}[\mathbf{c m}]$ | $\mathbf{A}_{\mathbf{c}}[\mathbf{c m}]$ | $\mathbf{W}_{\mathbf{a}}$ <br> $\left[\mathbf{c m}^{2}\right]$ | $\mathbf{A}_{\mathbf{p}_{\mathbf{4}}}$ <br> $\left[\mathbf{c m}^{\mathbf{]}}\right.$ | $\mathbf{K}_{\mathbf{g}_{\mathbf{5}}}$ <br> $\left[\mathbf{c m}^{5}\right]$ | $\mathbf{P e r m}$ | $\mathbf{A L}$ | Manufacturer |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RM-42316 | 4.17 | 3.80 | 1.074 | 0.640 | 0.454 | 0.2900 | 0.017820 | 2500 | 2200 | Magnetics |
| PQ-42610 | 5.54 | 2.94 | 0.239 | 1.05 | 0.1177 | 0.1235 | 0.00937 | 2500 | 6310 | Magnetics |
| PQ-42614 | 5.54 | 3.33 | 0.671 | 0.709 | 0.3304 | 0.2343 | 0.01200 | 2500 | 4585 | Magnetics |
| PQ-42016 | 4.34 | 3.74 | 1.001 | 0.580 | 0.4283 | 0.2484 | 0.01327 | 2500 | 2930 | Magnetics |
| EPC-25 | 4.930 | 5.92 | 1.800 | 0.4640 | 0.8235 | 0.3810 | 0.01438 | 2300 | 1560 | Magnetics |
| El-44008 | 7.77 | 5.19 | 0.356 | 0.9950 | 0.3613 | 0.3595 | 0.018416 | 2500 | 4103 | Magnetics |
| EFD-25 | 4.78 | 5.69 | 1.86 | 0.5810 | 0.6789 | 0.3944 | 0.01917 | 1800 | 1800 | Philips |

Table 3. PQ-42016 Core Dimensions
(Magnetics: http://www.mag-inc.com/home/Advanced-Search-Results?pn=42016


| $(\mathrm{mm})$ | Nominal: | Tol. min.: | Tol. max.: |
| :---: | :---: | :---: | :---: |
| A | 21.3 | -0.4 | +0.4 |
| B | 8.1 | -0.1 | +0.1 |
| 2B | 16.2 | -0.2 | +0.2 |
| C | 14.0 | -0.4 | +0.4 |
| D | 5.15 | -0.16 | +0.15 |
| 2D | 10.3 | -0.3 | +0.3 |
| E | 18.0 | -0.4 | +0.4 |
| F | 8.8 | -0.2 | +0.2 |
| G | 12.0 Min. |  |  |
| H | 4.0 Min. |  |  |
| J | 8.13 |  |  |
| Eff. Parameters |  |  |  |
| Ae mm ${ }^{2}$ | Amin mm ${ }^{2}$ | le mm | Ve mm ${ }^{3}$ |
| 61.9 | 59.1 | 37.6 | 2330 |

Table 4. Wire Table

| AWG | Bare Wire Area |  | $\mu \Omega / \mathrm{cm}$ | Heavy Insulation |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Cm2 | CIR-MIL |  | Cm2 | Turns/cm | Turns/cm2 |
| 20 | 0.005188 | 1024.0 | 332.3 | 0.006065 | 11.37 | 98.93 |
| 21 | 0.004116 | 812.30 | 418.9 | 0.004837 | 12.75 | 124.0 |
| 22 | 0.003243 | 640.10 | 531.4 | 0.003857 | 14.25 | 155.5 |
| 23 | 0.002588 | 510.80 | 666.0 | 0.003135 | 15.82 | 191.3 |
| 24 | 0.002047 | 404.0 | 842.1 | 0.002514 | 17.63 | 238.6 |
| 25 | 0.001623 | 320.40 | 1062.0 | 0.002002 | 19.8 | 299.7 |
| 26 | 0.001280 | 252.80 | 1345.0 | 0.001603 | 22.12 | 374.2 |
| 27 | 0.001021 | 201.60 | 1687.6 | 0.001313 | 24.44 | 456.9 |
| 28 | 0.008048 | 158.80 | 2142.7 | 0.0010515 | 27.32 | 570.6 |
| 29 | 0.0006470 | 127.70 | 2664.3 | 0.0008548 | 30.27 | 701.9 |

## Schematic



Figure 8. Schematic

## Bill Of Materials

| Item Number | Part Reference | Value | Quantity | Description (Manufacturer) |
| :---: | :---: | :---: | :---: | :---: |
| 1 | U101 | FL6961 | 1 | CRM PFC Controller (Fairchild Semiconductor) |
| 2 | U102 | FOD817 | 1 | Opto-Coupler (Fairchild Semiconductor) |
| 3 | U201 | KA431 | 1 | Shunt Regulator (Fairchild Semiconductor) |
| 4 | U202 | KA358A(LM2904) | 1 | Dual Op Amp (Fairchild Semiconductor) |
| 5 | Q101 | FQPF3N80C | 1 | 800V/3A MOSFET (Fairchild Semiconductor) |
| 6 | D101 | DF04 | 1 | 1.5A SMD Bridge-Diode (Fairchild Semiconductor) |
| 7 | D102 | RS1M | 1 | 1000V/1A Ultra-Fast Recovery Diode (Fairchild Semiconductor) |
| 8 | D103 | RS1G | 1 | 400V/1A Fast Recovery Diode (Fairchild Semiconductor) |
| 9 | D201,D204 | EGP30D | 2 | 200V/3A Ultra-Fast Recovery Diode (Fairchild Semiconductor) |
| 10 | $\begin{aligned} & \text { D202,D203, } \\ & \text { D205,D206 } \end{aligned}$ | LL4148 | 3 | General-Purpose Diode (Fairchild Semiconductor) |
| 11 | $\begin{gathered} \text { R101,R102, } \\ \text { R103 } \end{gathered}$ | 82K $\Omega$ | 3 | SMD Resistor1206 |
| 12 | R104 | $120 \mathrm{k} \Omega$ | 1 | SMD Resistor1206 |
| 13 | R105 | $10 \mathrm{~K} \Omega$ | 1 | SMD Resistor1206 |
| 14 | R106 | $20 \mathrm{~K} \Omega$ | 1 | SMD Resistor1206 |
| 15 | R107 | $9.1 \mathrm{k} \Omega$ | 1 | SMD Resistor1206 |
| 16 | R108 | $47 \Omega$ | 1 | SMD Resistor 1206 |
| 17 | R109 | $10 \Omega$ | 1 | SMD Resistor 1206 |
| 18 | R110 | $220 \mathrm{~K} \Omega$ | 1 | 2W |
| 19 | R111 | $30 \mathrm{~K} \Omega$ | 1 | SMD Resistor 1206 |
| 20 | R112,R113 | $1 \Omega$ | 2 | SMD Resistor 1206 |
| 21 | $\begin{gathered} \text { R201,R202, } \\ \text { R203 } \end{gathered}$ | $1 \Omega$ | 3 | SMD Resistor 1206 |
| 22 | R204 | $2.2 \Omega$ | 1 | SMD Resistor 0806 |
| 23 | R205 | $4.3 \mathrm{~K} \Omega$ | 1 | SMD Resistor 0806 |
| 24 | R206 | $1.5 \mathrm{~K} \Omega$ | 1 | SMD Resistor 0806 |
| 25 | R207 | $30 \mathrm{~K} \Omega$ | 1 | SMD Resistor 0806 |
| 26 | R208 | $51 \mathrm{~K} \Omega$ | 1 | SMD Resistor 0806 |
| 27 | R209 | $33 \mathrm{~K} \Omega$ | 1 | SMD Resistor 0806 |
| 28 | R210 | $3.9 \mathrm{~K} \Omega$ | 1 | SMD Resistor 0806 |
| 29 | R211 | $120 \mathrm{~K} \Omega$ | 1 | SMD Resistor 0806 |
| 30 | R212 | $47 \mathrm{~K} \Omega$ | 1 | SMD Resistor 0806 |
| 31 | R213 | $4.7 \mathrm{~K} \Omega$ | 1 | SMD Resistor 0806 |
| 32 | R214 | 47K $\Omega$ | 1 | SMD Resistor 0806 |

## Bill Of Materials (Continued)

| Item Number | Part Reference | Value | Quantity | Description (Manufacturer) |
| :---: | :---: | :---: | :---: | :---: |
| 33 | C101 | 100nF/250V | 1 | X - Capacitor |
| 34 | C102 | 47nF/250V | 1 | X - Capacitor |
| 35 | C103 | 100nF/630V | 1 | Film Capacitor |
| 36 | C104 | $33 \mu \mathrm{~F} / 35 \mathrm{~V}$ | 1 | Electrolytic Capacitor |
| 37 | C105 | $2.2 \mathrm{nF} / 1 \mathrm{kV}$ | 1 | Y-Capacitor |
| 38 | C106 | $2.2 \mu \mathrm{~F}$ | 1 | SMD Capacitor 0805 |
| 39 | C107 | 30 pF | 1 | SMD Capacitor 0805 |
| 40 | C108 | 100nF | 1 | SMD Capacitor 0805 |
| 41 | C201,C202 | 470رF/35V | 2 | Electrolytic capacitor |
| 42 | C203 | $1 \mu \mathrm{~F}$ | 1 | SMD Capacitor 0805 |
| 43 | C204 | 470nF | 1 | SMD Capacitor 0805 |
| 44 | C205 | 10رF/35V | 1 | Electrolytic Capacitor |
| 45 | LF101,LF102 | 80 mH | 2 | Line Filter |
| 46 | L101 | $27 \mu \mathrm{H}$ | 1 | Line Filter |
| 47 | L102 | $6.8 \mu \mathrm{H}$ | 1 | Line Filter |
| 48 | L201 | $5 \mu \mathrm{H}$ | 1 | Output Inductor |
| 49 | F101 | 1A/250V | 1 | Fuse |
| 50 | T1 | PQ-42016 | 1 | 1 mH |

## Related Datasheets

FL6961 - Single-Stage Flyback and Boundary Mode PFC Controller for Lighting
AN-8025 - Design Guideline of Single-Stage Flyback AC-DC Converter Using FAN7530 for LED Lighting

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