

S-25C010A/020A/040A H Series

105°C OPERATION SPI SERIAL E²PROM FOR AUTOMOTIVE

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Rev.2.0_00_c

The S-25C010A/020A/040A H series devices are high-temperature operation SPI serial E^2 PROMs for automotive components. The S-25C010A/020A/040A H series has the capacity of 1 K-bit, 2 K-bit, and 4 K-bit, and the organization is 128 words \times 8-bit, 256 words \times 8- bit, and 512 words \times 8-bit, respectively.

Page write and sequential read are available.

■ Features

Operating voltage range: Read: 2.5 V to 5.5 V

Write: 2.5 V to 5.5 V

• Operation frequency 6.5 MHz (4.5 V to 5.5 V)

• SPI mode (0, 0) and (1, 1)

Page Write: 16 bytes / page

Sequential read

 Monitors Write to the memory by a status register
 Write protect: Software, Hardware Protect area: 25%, 50%, 100%

Function to prevent malfunction by monitoring clock pulse

• Write protect function during the low power supply voltage

• CMOS schmitt input ($\overline{\text{CS}}$, SCK, SI, $\overline{\text{WP}}$, $\overline{\text{HOLD}}$)

• Endurance: 10⁶ cycles/word^{*1} (at +85°C)

 8×10^5 cycles/word^{*1} (at +105°C)

• Data retention: 100 years (at +25°C)

50 years (at +105°C)

Memory capacitance: S-25C010A 1 K-bit

S-25C020A 2 K-bit S-25C040A 4 K-bit

• Data before shipment: Memory array FFh, BP1 = 0, BP0 = 0

• Lead-free, Sn 100%, halogen-free*2

*1. For each address (Word: 8-bit)

*2. Refer to "■ Product Name Structure" for details.

■ Packages

- 8-Pin SOP (JEDEC)
- 8-Pin TSSOP

Caution Before using the product in medical equipment or automobile equipment including car audio, keyless entry and engine control unit, contact to SII is indispensable.

■ Pin Configurations

8-Pin SOP (JEDEC) Top view

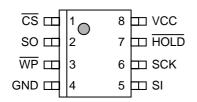


Figure 1

S-25C010A0H-J8T2UD S-25C020A0H-J8T2UD S-25C040A0H-J8T2UD

Table 1

Pin No.	Symbol	Description
1	CS*1	Chip select input
2	so	Serial data output
3	WP *1	Write protect input
4	GND	Ground
5	SI ^{*1}	Serial data input
6	SCK*1	Serial clock input
7	HOLD *1	Hold input
8	VCC	Power supply

^{*1.} Do not use it in high impedance.

8-Pin TSSOP Top view

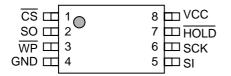


Figure 2

S-25C010A0H-T8T2UD S-25C020A0H-T8T2UD S-25C040A0H-T8T2UD

Table 2

Pin No.	Symbol	Description
1	CS*1	Chip select input
2	so	Serial data output
3	WP *1	Write protect input
4	GND	Ground
5	SI ^{*1}	Serial data input
6	SCK*1	Serial clock input
7	HOLD *1	Hold input
8	VCC	Power supply
	·	_

^{*1.} Do not use it in high impedance.

Remark 1. See Dimensions for details of the package drawings.

2. Please select products of environmental code = U for Sn 100%, halogen-free products.

■ Block Diagram

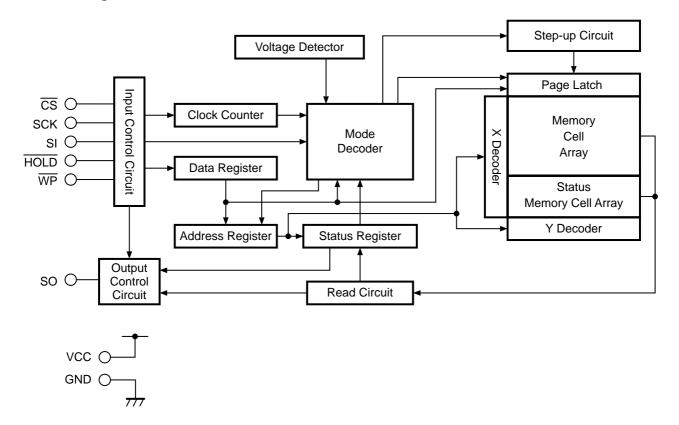


Figure 3

■ Absolute Maximum Ratings

Table 3

Item	Symbol	Absolute Maximum Rating	Unit
Power supply voltage	V _{CC}	−0.3 to +7.0	V
Input voltage	V _{IN}	−0.3 to +7.0	V
Output voltage	V _{OUT}	-0.3 to $V_{\text{CC}} + 0.3$	V
Operating ambient temperature	T _{opr}	−40 to +105	°C
Storage temperature	T _{stg}	−65 to +150	°C

Caution The absolute maximum ratings are rated values exceeding which the product could suffer physical damage. These values must therefore not be exceeded under any conditions.

■ Recommended Operating Conditions

Table 4

Item	Symbol	Condition	Min.	Max.	Unit
Dower gupply voltage	V _{CC}	Read operation	2.5	5.5	V
Power supply voltage	V CC	Write operation	2.5	5.5	V
High level input voltage	V _{IH}	V_{CC} = 2.5 V to 5.5 V	$0.7 \times V_{CC}$	V _{CC} + 1.0	V
Low level input voltage	V_{IL}	V _{CC} = 2.5 V to 5.5 V	-0.3	$0.3 \times V_{CC}$	V

■ Pin Capacitance

Table 5

 $(Ta = +25^{\circ}C, f = 1.0 MHz, V_{CC} = 5 V)$

		1			cc - c
Item	Symbol	Condition	Min.	Max.	Unit
Input capacitance	C _{IN}	$V_{IN} = 0 \text{ V } (\overline{CS}, SCK, SI, \overline{WP}, \overline{HOLD})$	_	8	pF
Output capacitance	C _{OUT}	V _{OUT} = 0 V (SO)	-	10	pF

■ Endurance

Table 6

Item	Symbol	Operating Ambient Temperature	Min.	Max.	Unit
Endurance	N	–40°C to +85°C	10 ⁶	_	cycles / word*1
Endurance	N _W	−40°C to +105°C	8×10^5	-	cycles / word*1

^{*1.} For each address (Word: 8 bits)

■ Data Retention

Table 7

Item	Symbol	Operation Ambient Temperature	Min.	Max.	Unit
Data retention		+25°C	100	_	year
Data retention	_	-40°C to +105°C	50	ı	year

■ DC Electrical Characteristics

Table 8

Item	Symbol	Condition		V to 3.0 V .5 MHz	$V_{CC} = 3.0$ $f_{SCK} = 5$		$V_{CC} = 4.5$ $f_{SCK} = 6$		Unit
			Min.	Max.	Min.	Max.	Min.	Max.	
Current consumption (READ)	I _{CC1}	No load at SO pin	_	1.5	_	2.0	_	2.5	mA

Table 9

ltem	Symbol	Condition		V to 3.0 V 3.5 MHz	$V_{CC} = 3.0$ $f_{SCK} = 5$	V to 4.5 V 5.0 MHz	$V_{CC} = 4.5$ $f_{SCK} = 6$		Unit
			Min.	Max.	Min.	Max.	Min.	Max.	
Current consumption (WRITE)	I _{CC2}	No load at SO pin	_	2.0	_	2.5	1	3.0	mA

Table 10

		Table	; 10				
ltom	Cymbol	Condition	$V_{CC} = 2.5 \text{ V to}$			V to 5.5 V	Unit
Item	Symbol	Condition	Min.	Max.	Min.	Max.	Ullit
Standby current consumption	I _{SB}	CS = V _{CC} , SO = Open Other inputs are V _{CC} or GND	-	8.0	-	10.0	μА
Input leakage current	ILI	V_{IN} = GND to V_{CC}	ı	2.0	_	2.0	μΑ
Output leakage current	I_{LO}	V_{OUT} = GND to V_{CC}	ı	2.0	_	2.0	μΑ
Low level output voltage	V_{OL1}	I _{OL} = 2.0 mA	_	_	_	0.4	V
Low level output voltage	V_{OL2}	I _{OL} = 1.5 mA	ı	0.4	_	0.4	V
High lovel output voltage	V_{OH1}	$I_{OH} = -2.0 \text{ mA}$	_	_	$0.8 \times V_{CC}$	_	V
High level output voltage	V_{OH2}	$I_{OH} = -0.4 \text{ mA}$	$0.8 \times V_{CC}$	_	$0.8 \times V_{CC}$	_	V

■ AC Electrical Characteristics

Table 11 Measurement Conditions

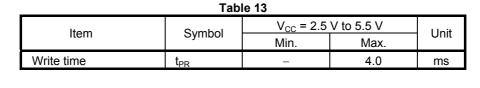
Input pulse voltage	$0.2 \times V_{CC}$ to $0.8 \times V_{CC}$
Output reference voltage	$0.5 \times V_{CC}$
Output load	100 pF

Table 12

Item	Item	Cumbal	V _{CC} = 2.5	V to 5.5 V	$V_{CC} = 3.0$	V to 5.5 V	V _{CC} = 4.5	V to 5.5 V	Unit
CS setup time during CS tcss ct. 90 - 90 - 65 - ns	item	Syllibol	Min.	Max.	Min.	Max.	Min.	Max.	Offic
Tailling	SCK clock frequency	f _{SCK}	_	3.5	ı	5.0	_	6.5	MHz
Tissing Loss CH 90 - 90 - 65 - 18	·	t _{CSS.CL}	90	-	90	_	65	-	ns
CS hold time during		t _{CSS.CH}	90	_	90	_	65	_	ns
CS hold time during CS rising t _{CSH,CH} 90 - 90 - 65 - ns	CS deselect time	t _{CDS}	160	-	140	_	110	_	ns
CS hold time during CS rising t _{CSH,CH} 90 - 90 - 65 - ns SCK clock time "H" "1 t _{HIGH} 125 - 95 - 65 - ns SCK clock time "L" "1 t _{LIGW} 125 - 95 - 65 - ns Rising time of SCK clock "2 t _{RSK} - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 μ _L SI data input bold time t _{DB} 20 - 20 - 20 - 20 - ns SCK "L" hold time t _{DH} 30 - 30 - 30 - ns SCK "L" hold time t _{SKH,HL} 40 - 40 - 40 - 45 - ns SCK "L" setup time t _{SKS,HL} 40 - 0 -	CS hold time during CS falling	t _{CSH.CL}	90	_	90	_	65	_	ns
SCK clock time "H" "1	CS hold time during CS rising		90	=	90	_	65	_	ns
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	SCK clock time "H" *1	1	125	-	95	_	65	_	ns
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		t _{LOW}	125	_	95	_	65	_	ns
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Rising time of SCK clock *2		-	1	_	1	_	1	μS
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Falling time of SCK clock *2	t _{FSK}	_	1	_	1	_	1	μS
SCK "L" hold time during HOLD rising tskh.hh 70 - 70 - 45 - ns SCK "L" hold time during HOLD falling tskh.hl 40 - 40 - 30 - ns SCK "L" setup time during HOLD falling tsks.hl 0 - 0 - 0 - ns SCK "L" setup time during HOLD rising tsks.hl 0 - 0 - 0 - ns Disable time of SO output *2 toz - 100 - 100 - 75 ns Delay time of SO output *2 toz - 120 - 90 - 60 ns Hold time of SO output *2 toz - 80 - 70 - 50 ns Falling time of SO output *2 toz - 80 - 70 - 50 ns Disable time of SO output *2 toz - 80 - 70 - 50 ns	SI data input setup time	1	20	1	20	_	20	_	ns
SCK "L" hold time during HOLD rising t_SKH.HH 70 - 70 - 45 - ns SCK "L" hold time during HOLD falling t_SKH.HL 40 - 40 - 30 - ns SCK "L" setup time during HOLD falling t_SKS.HL 0 - 0 - 0 - ns SCK "L" setup time during HOLD rising t_SKS.HH 0 - 0 - 0 - ns Disable time of SO output ** t_OZ - 100 - 100 - 75 ns Delay time of SO output ** t_OZ - 120 - 90 - 60 ns Hold time of SO output ** t_OZ - 120 - 90 - 60 ns Rising time of SO output ** t_OZ - 80 - 70 - 50 ns Falling time of SO output ** t_OZ - 80 - 70 - 50 ns	SI data input hold time	t _{DH}	30	1	30	_	30	_	ns
SCK *L" hold time t _{SKH.HL} 40 - 40 - 30 - ns			70	-	70	_	45	_	ns
		-OK1.1111					_		
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		torarru	40	_	40	_	30	_	ns
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	during HOLD falling	SKH.HL	10		10		- 00		110
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	·	t	0		0		0		ne
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	during HOLD falling	^L SKS.HL	U	_	U	_	U	_	115
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	SCK "L" setup time	4	_		0		0		20
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	during HOLD rising	^L SKS.HH	0	_	U	_	U	_	118
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Disable time of SO output *2	t _{OZ}	_	100	-	100	_	75	ns
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Delay time of SO output	t _{OD}	_	120	_	90	_	60	ns
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		t _{OH}	0	_	0	_	0	_	ns
Disable time of SO output during \overline{HOLD} falling $\overline{^{*2}}$ $t_{OZ.HL}$ $ 100$ $ 100$ $ 75$ ns Delay time of SO output during \overline{HOLD} rising $\overline{^{*2}}$ $t_{OD.HH}$ $ 80$ $ 80$ $ 60$ ns \overline{WP} setup time t_{WS1} 0 $ 0$ $ 0$ $ ns$ \overline{WP} hold time t_{WH1} 0 $ 0$		t _{RO}	-	80	_	70	-	50	ns
during $\overline{\text{HOLD}}$ falling *2 $t_{\text{OZ.HL}}$ - 100 - 100 - 75 ns Delay time of SO output during $\overline{\text{HOLD}}$ rising *2 $t_{\text{OD.HH}}$ - 80 - 80 - 60 ns $\overline{\text{WP}}$ setup time t_{WS1} 0 - 0 - 0 - ns $\overline{\text{WP}}$ hold time t_{WH1} 0 - 0 - 0 - ns $\overline{\text{WP}}$ release / setup time t_{WS2} 0 - 0 - ns	Falling time of SO output *2	t _{FO}	-	80	_	70	-	50	ns
	Disable time of SO output	_		100		400		75	
	during HOLD falling *2	LOZ.HL	_	100	_	100	_	75	TIS
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Delay time of SO output	1		00		00		00	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	during HOLD rising *2	t _{OD.HH}	-	80	_	80	_	60	ns
WP release / setup time t _{WS2} 0 - 0 - ns	WP setup time	t _{WS1}	0	_	0	_	0	-	ns
	WP hold time	t _{WH1}	0	_	0	_	0	_	ns
	WP release / setup time	t _{WS2}	0		0	_	0	_	ns
			150		150	_	100	_	ns

^{*1.} The clock cycle of the SCK clock (frequency f_{SCK}) is $1/f_{SCK}$ μ s. This clock cycle is determined by a combination of several AC characteristics. Note that the clock cycle cannot be set as $(1/f_{SCK}) = t_{LOW}$ (Min.) + t_{HIGH} (Min.) by minimizing the SCK clock cycle time.

^{*2.} These are values of sample and not 100% tested.



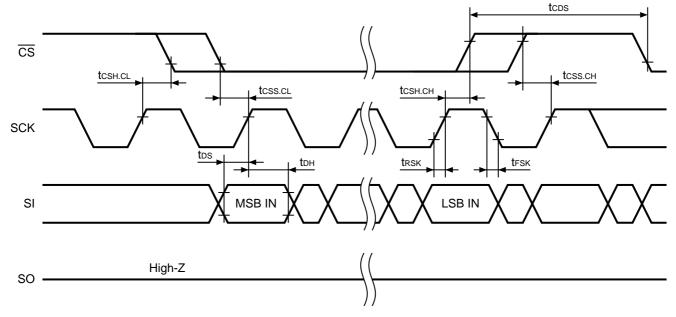


Figure 4 Serial Input Timing

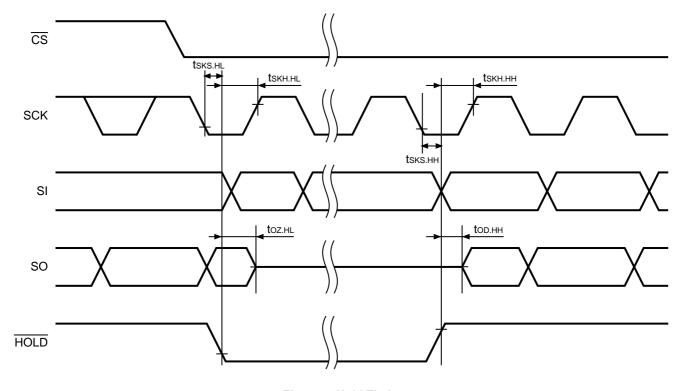


Figure 5 Hold Timing

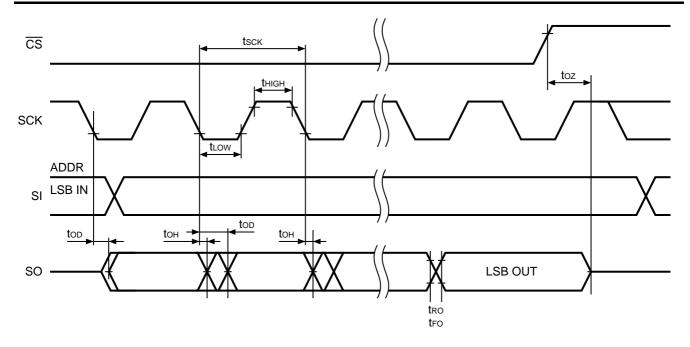


Figure 6 Serial Output Timing

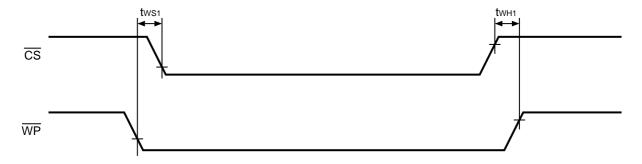


Figure 7 Valid Timing in Write Protect

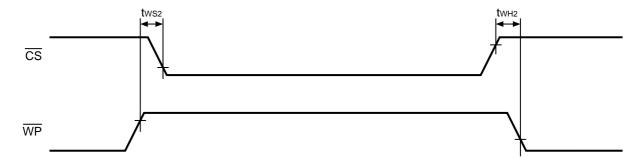


Figure 8 Invalid Timing in Write Protect

■ Pin Function

1. CS (Chip select input) pin

This is an input pin to set a chip in the select status. In the "H" input level, the device is in the non-select status and its output is high impedance. The device is in standby as long as it is not in Write inside. The device goes in active by setting the chip select to "L". Input any instruction code after power-on and a falling of chip select.

2. SI (Serial data input) pin

This pin is to input serial data. This pin receives an instruction code, an address and Write data. This pin latches data at rising edge of serial clock.

3. SO (Serial data output) pin

This pin is to output serial data. The data output changes at falling edge of serial clock.

4. SCK (Serial clock input) pin

This is a clock input pin to set the timing of serial data. An instruction code, an address and Write data are received at a rising edge of clock. Data is output at falling edge of clock.

5. WP (Write protect input) pin

This is an input pin to protect memory data when Write instruction (WRITE, WRSR) is being input. By setting this pin to "L", the WEL bit in the status register is set to "L". Therefore S-25C010A/020A/040A does not Write to the E^2 PROM, however, it accepts other instructions. Fix this pin "H" or "L" not to set it in the floating state.

Refer to "■ Protect Operation" for details.

6. HOLD (HOLD input) pin

This pin is used to pause serial communications without setting the device in the non-select status.

In the hold status, the serial output goes in high impedance, the serial input and the serial clock go in "Don't care".

During the hold operation, be sure to set the device in active by setting the chip select (CS pin) to "L".

Refer to "■ Hold Operation" for details.

■ Instruction Setting

Tables 14 and **15** are the lists of instructions for the S-25C010A/020A/040A. The instruction is able to be input by changing the $\overline{\text{CS}}$ pin "H" to "L". Input the instruction in the MSB first. Each instruction code is organized with 1-byte as shown below. If the S-25C010A/020A/040A receives any invalid instruction code, the device goes in the non-select status.

1. S-25C010A/020A

Table 14 Instruction Set

		Instruction code	Address	Data
Instruction	Operation	SCK input clock	SCK input clock	SCK input clock
		1 to 8	9 to 16	17 to 24
WREN	Write enable	0000 X110	_	_
WRDI	Write disable	0000 X100	_	_
RDSR	Read the status register	0000 X101	b7 to b0 output*1	_
WRSR	Write in the status register	0000 X001	b7 to b0 input	_
READ	Read memory data	0000 X011	A7 ^{*2} to A0	D7 to D0 output*3
WRITE	Write memory data	0000 X010	A7 ^{*2} to A0	D7 to D0 input

^{*1.} Sequential data reading is possible.

Remark X = Don't care.

2. S-25C040A

Table 15 Instruction Set

		Instruction code	Address	Data
Instruction	Operation	SCK input clock	SCK input clock	SCK input clock
		1 to 8	9 to 16	17 to 24
WREN	Write enable	0000 X110	_	_
WRDI	Write disable	0000 X100	_	_
RDSR	Read the status register	0000 X101	b7 to b0 output*1	_
WRSR	Write in the status register	0000 X001	b7 to b0 input	_
READ	Read memory data	0000 [A8 ^{*2}]011	A7 to A0	D7 to D0 output*3
WRITE	Write memory data	0000 [A8 ^{*2}]010	A7 to A0	D7 to D0 input

^{*1.} Sequential data reading is possible.

^{*2.} In the S-25C010A, A7 = Don't care because the address range is A6 to A0.

^{*3.} After outputting data in the specified address, data in the following address is output.

^{*2.} In the S-25C040A, assign bit A8 in the address into the fifth bit in an instruction code.

^{*3.} After outputting data in the specified address, data in the following address is output.

Operation

1. Status register

The status register's organization is below. The status register can Write and Read by a specific instruction.

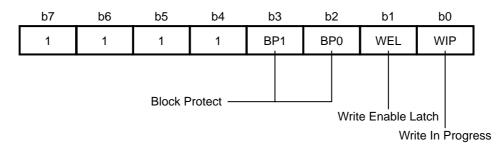


Figure 9 Organization of Status Register

The status/control bits of the status register are as follows.

1.1 BP1, BP0 (b3, b2) : Block protect

Bit BP1 and BP0 are composed of the nonvolatile bit. The area size of Software Protect with respect to WRITE instructions is defined by the BP1 and BP0 bits. Rewriting these bits is possible by the WRSR instruction. To protect the memory area against the WRITE instruction, set either or both of bit BP1 and BP0 to "1". Rewriting bit BP1 and BP0 is possible unless they are in Hardware Protect mode.

Refer to "■ Protect Operation" for details of "Block Protect".

1.2 WEL (b1): Write enable latch

Bit WEL shows the status of internal Write Enable Latch. Bit WEL is set by the WREN instruction only. If bit WEL is "1", this is the status that Write Enable Latch is set. If bit WEL is "0", Write Enable Latch is in reset, so that the S-25C010A/020A/040A does not receive the WRITE or WRSR instruction. Bit WEL is reset after these operations;

- The power supply voltage is dropping
- Power-on
- After performing WRDI
- After the Write operation by the WRSR instruction
- After the Write operation by the WRITE instruction
- After setting the WP pin to "L"

1.3 WIP (b0): Write in progress

Bit WIP is a Read Only bit. It indicates whether the internal memory is in the Write operation or not by the WRITE or WRSR instruction. Bit WIP is "1" during the Write operation but "0" during any other status. **Figure 10** shows the usage example.

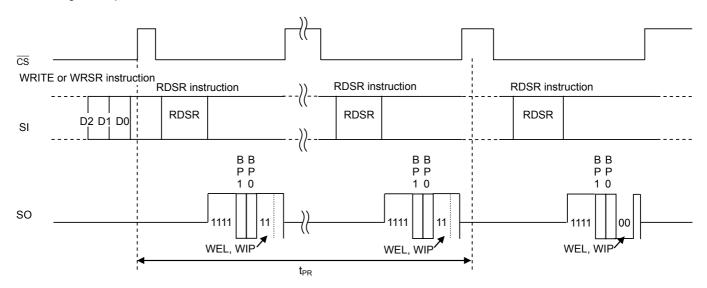


Figure 10 Usage Example of WEL, WIP Bits during Write

2. Write enable (WREN)

Before writing data (WRITE and WRSR), be sure to set bit Write Enable Latch (WEL). This instruction is to set bit WEL. Its operation is below.

After selecting the device by the chip select (\overline{CS}), input the instruction code from serial data input (SI). To set bit WEL, set the device in the non-select status by \overline{CS} at the 8th clock of the serial clock (SCK). To cancel the WREN instruction, input the clock different from a specified value (n = 8 clock) while \overline{CS} is in "L".

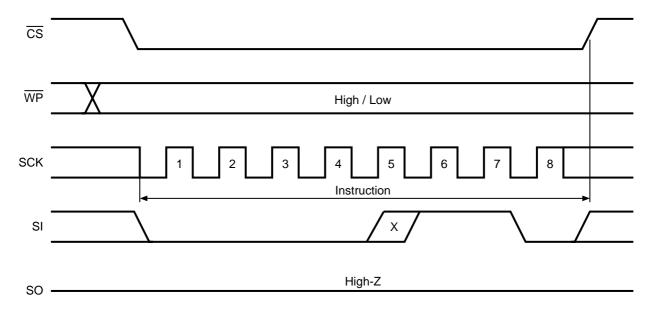


Figure 11 WREN Operation

3. Write disable (WRDI)

The WRDI instruction is one of ways to reset bit Write Enable Latch (WEL). After selecting the device by the chip select (\overline{CS}) , input the instruction code from serial data input (SI).

To reset bit WEL, set the device in the non-select status by \overline{CS} at the 8th clock of the serial clock. To cancel the WRDI instruction, input the clock different from a specified value (n = 8 clock) while \overline{CS} is in "L".

Bit WEL is reset after the operations shown below.

- The power supply voltage is dropping
- Power-on
- After performing WRDI
- After the completion of Write operation by the WRSR instruction
- · After the completion of Write operation by the WRITE instruction
- After setting the WP pin to "L"

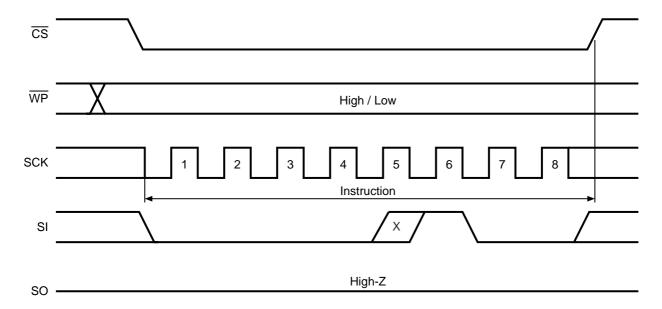


Figure 12 WRDI Operation

4. Read the status register (RDSR)

Reading data in the status register is possible by the RDSR instruction. During the Write operation, it is possible to confirm the progress by checking bit WIP.

Set the chip select (\overline{CS}) "L" first. After that, input the instruction code from serial data input (SI). The status of bit in the status register is output from serial data output (SO). Sequential Read is available for the status register. To stop the Read cycle, set \overline{CS} to "H".

It is possible to read the status register always. The bits in it are valid and can be read by RDSR even in the Write cycle.

However, during the Write cycle in progress, nonvolatile bits BP1 and BP0 are fixed in a certain value. These updated values of bit can be obtained by inputting another new RDSR instruction after the Write cycle has completed. Contrarily, two of Read Only bits WEL and WIP are being updated while the Write cycle is in progress.

b7, b6, b5, and b4 are "1" when they are read by the RDSR instruction.

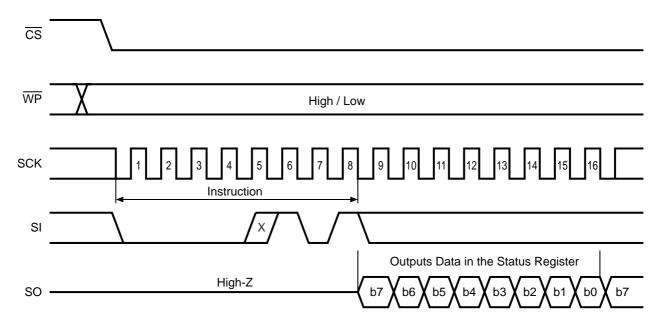


Figure 13 RDSR Operation

5. Write in the status register (WRSR)

The values of status register (BP1, BP0) can be rewritten by inputting the WRSR instruction. But b7, b6, b5, b4, b1, b0 of status register cannot be rewritten. b7 to b4 are always "1" when reading the status register.

Before inputting the WRSR instruction, set bit WEL by the WREN instruction. The operation of WRSR is shown below. Set the chip select (\overline{CS}) "L" first. After that, input the instruction code and data from serial data input (SI). To start WRSR Write (t_{PR}) , set the chip select (\overline{CS}) to "H" after inputting data or before inputting a rising of the next serial clock. It is possible to confirm the operation status by reading the value of bit WIP during WRSR Write. Bit WIP is "1" during Write, "0" during any other status. Bit WEL is reset when Write is completed.

With the WRSR instruction, the values of BP1 and BP0; which determine the area size the users can handle as the Read Only memory; can be changed. When signal $\overline{\text{WP}}$ is "L", however, the WRSR instruction is not be performed (Refer to "**Protect Operation**").

Bits BP1 and BP0 keep the value which is the one prior to the WRSR instruction during the WRSR instruction. The newly updated value is changed when the WRSR instruction has completed.

To cancel the WRSR instruction, input the clock different from a specified value (n = 16 clock) while \overline{CS} is in "L".

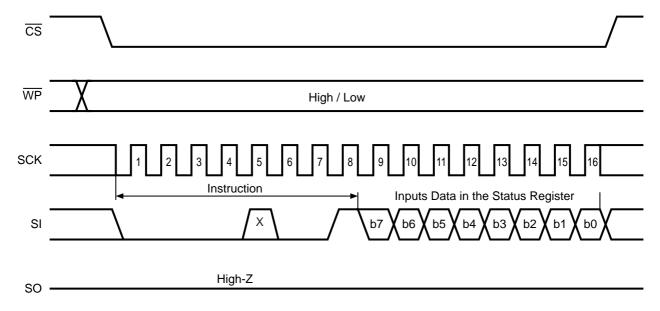


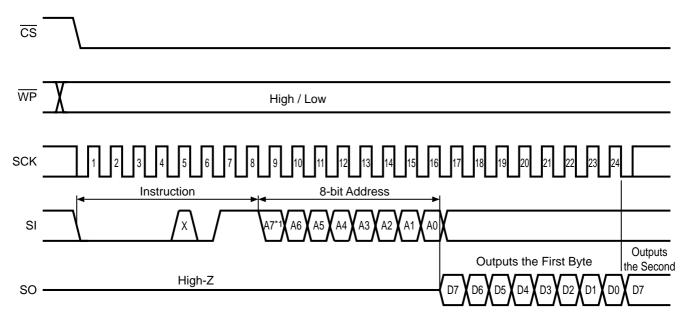
Figure 14 WRSR Operation

6. Read memory data (READ)

The READ operation is shown below. Input the instruction code and the address from serial data input (SI) after inputting "L" to the chip select (\overline{CS}). The input address is loaded to the internal address counter, and data in the address is output from the serial data output (SO).

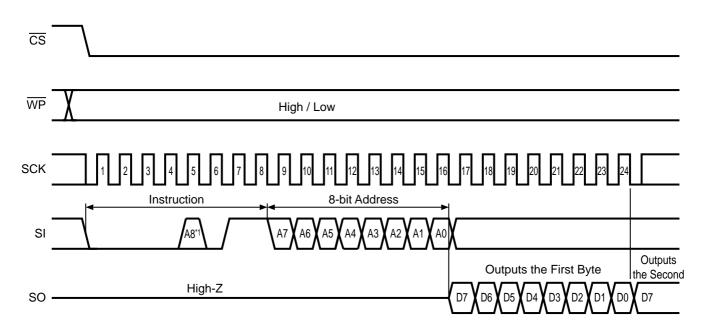
Next, by inputting the serial clock (SCK) keeping the chip select (\overline{CS}) in "L", the address is automatically incremented so that data in the following address is sequentially output. The address counter rolls over to the first address by increment in the last address.

To finish the Read cycle, set \overline{CS} to "H". It is possible to raise the chip select always during the cycle. During Write, the READ instruction code is not be accepted or operated.



^{*1} In the S-25C010A, A7 = Don't care because the address range is A6 to A0.

Figure 15 READ Operation (S-25C010A/020A)



^{*1} In the S-25C040A, assign bit A8 in the address into the fifth bit in an instruction code.

Figure 16 READ Operation (S-25C040A)

7. Write memory data (WRITE)

Figures 17 and **18** show the timing charts when inputting 1-byte data. Input the instruction code, the address and data from serial data input (SI) after inputting "L" to the chip select (\overline{CS}). To start WRITE (t_{PR}), set the chip select (\overline{CS}) to "H" after inputting data or before inputting a rising of the next serial clock. Bit WIP and WEL are reset to "0" when Write has completed.

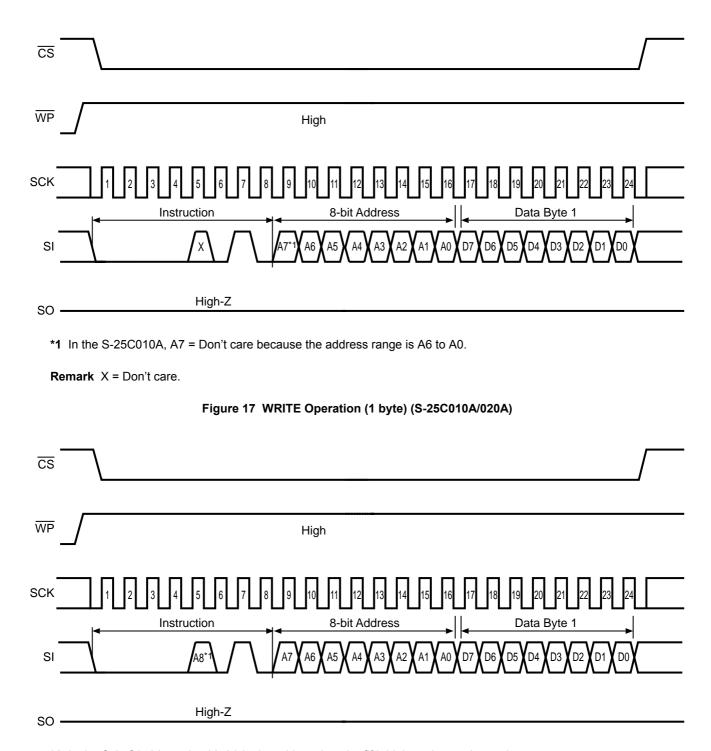
The S-25C010A/020A/040A can Page Write of 16 bytes. Its function to transmit data is as same as Byte Write basically, but it operates Page Write by receiving sequential 8-bit Write data as much data as page size has. Input the instruction code, the address and data from serial data input (SI) after inputting "L" in \overline{CS} , as the WRITE operation (page) shown in **Figures 19** and **20**. Input the next data while keeping \overline{CS} in "L". After that, repeat inputting data of 8-bit sequentially. At the end, by setting \overline{CS} to "H", the WRITE operation starts (t_{PR}).

4 of the lower bits in the address are automatically incremented every time when receiving Write data of 8-bit. Thus, even if Write data exceeds 16 bytes, the higher bits in the address do not change. And lower 4 bits in the address roll over so that Write data which is previously input is overwritten.

These are cases when the WRITE instruction is not accepted or operated.

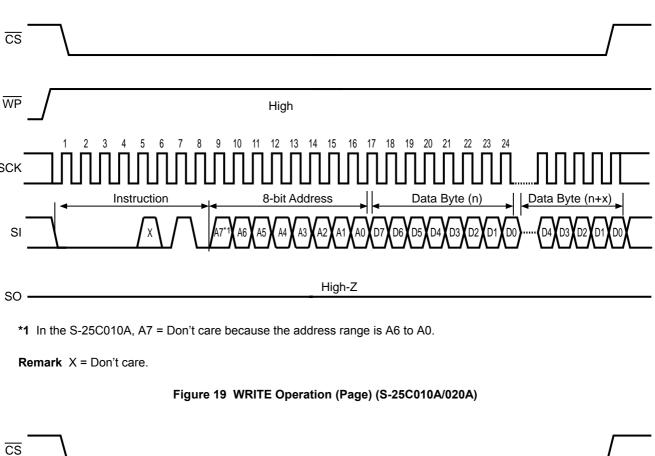
- Bit WEL is not set to "1" (not set to "1" beforehand immediately before the WRITE instruction)
- · During Write
- The address to be written is in the protect area by BP1 and BP0.
- The WP signal is in "L".

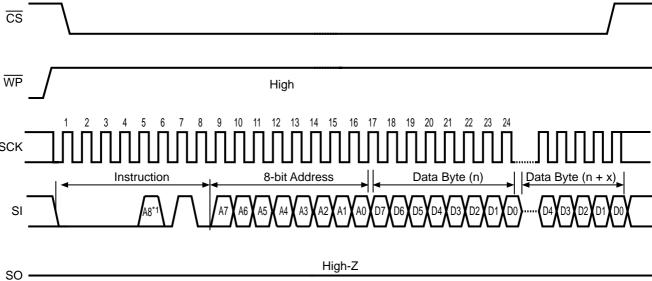
To cancel the WRITE instruction, input the clock different from a specified value (n = 16 + m \times 8 clocks) while $\overline{\text{CS}}$ is in "L".



^{*1} In the S-25C040A, assign bit A8 in the address into the fifth bit in an instruction code.

Figure 18 WRITE Operation (1 byte) (S-25C040A)





^{*1} In the S-25C040A, assign bit A8 in the address into the fifth bit in an instruction code.

Figure 20 WRITE Operation (Page) (S-25C040A)

■ Protect Operation

Table 16 shows the block settings of Write protect. Setting value in Protect Bits (BP1, BP0) in the status register protect data in the area of all/50%/25% of the memory address.

Setting signal WP to "L" provides the following settings.

- Write protect for the WRITE, WRSR instructions
- Reset bit WEL

Figures 7 and 8 show the Valid timing in Write protect and Invalid timing in Write protect.

Table 16 Block Settings of Write Protect

The state of the s					
Status Register		Area of Write Protect	Address of Write protect block		
BP1	BP0	Area or write Protect	S-25C040A	S-25C020A	S-25C010A
0	0	0%	None	None	None
0	1	25%	180h to 1FFh	C0h to FFh	60h to 7Fh
1	0	50%	100h to 1FFh	80h to FFh	40h to 7Fh
1	1	100%	000h to 1FFh	00h to FFh	00h to 7Fh

■ Hold Operation

The hold operation is used to pause serial communications without setting the device in the non-select status. In the hold status, the serial data output goes in high impedance, and both of the serial data input and the serial clock go in "Don't care". Be sure to set the chip select ($\overline{\text{CS}}$) to "L" to set the device in the select status during the hold status.

Generally, during the hold status, the device holds the select status. But if setting the device in the non-select status, the users can finish the operation even in progress.

Figure 21 shows the hold operation. Set Hold (\overline{HOLD}) to "L" when the serial clock (SCK) is in "L", Hold (\overline{HOLD}) is switched at the same time the hold status starts. If setting Hold (\overline{HOLD}) to "H", Hold (\overline{HOLD}) is switched at the same time the hold status ends.

Set Hold (HOLD) to "L" when the serial clock (SCK) is in "H"; the hold status starts when the serial clock goes in "L" after Hold ($\overline{\text{HOLD}}$) is switched. If setting Hold ($\overline{\text{HOLD}}$) to "H", the hold status ends when the serial clock goes in "L" after Hold ($\overline{\text{HOLD}}$) is switched.

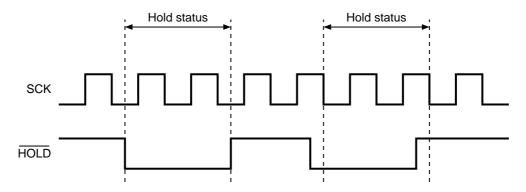


Figure 21 Hold Operation

■ Write Protect Function during the Low Power Supply Voltage

The S-25C010A/020A/040A has a built-in detection circuit which operates with the low power supply voltage. The S-25C010A/020A/040A cancels the Write operation (WRITE, WRSR) when the power supply voltage drops and power-on, at the same time, goes in the Write protect status (WRDI) automatically to reset bit WEL. The detection voltage is 1.20 V typ., the release voltage is 1.35 V typ., and its hysteresis is approx. 0.15 V (Refer to **Figure 22**).

To operate Write, after the power supply voltage dropped once but rose to the voltage level which allows Write again, be sure to set the Write Enable Latch bit (WEL) before operating Write (WRITE, WRSR).

In the Write operation, data in the address written during the low power supply voltage is not assured.

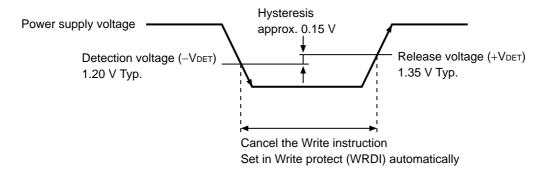


Figure 22 Operation during Low Power Supply Voltage

■ I/O Pin

1. Connection of input pin

All input pins in S-25C010A/020A/040A have the CMOS structure. Do not set these pins in high impedance during operation when you design. Especially, set the \overline{CS} input in the non-select status "H" during power-on/off and standby. The error Write does not occur as long as the \overline{CS} pin is in the non-select status "H". Set the \overline{CS} pin to V_{CC} via a resistor (the pull-up resistor of 10 k Ω to 100 k Ω). To prevent the error for sure, it is recommended to set other input pins than the \overline{CS} pin via a pull-up resistor.

2. Equivalent circuit of input and output pin

Figures 23 and **24** show the equivalent circuits of input pins in S-25C010A/020A/040A. A pull-up and pull-down elements are not included in each input pin, pay attention not to set it in the floating state when you design.

Figure 25 shows the equivalent circuit of the output pin. This pin has the tri-state output of "H" level/"L" level/high impedance.

2. 1 Input pin

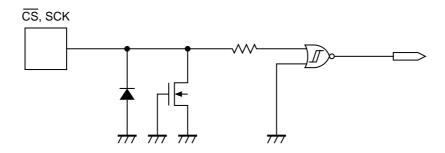


Figure 23 CS, SCK Pins

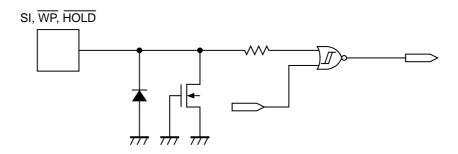


Figure 24 SI, WP, HOLD Pins

2. 2 Output pin

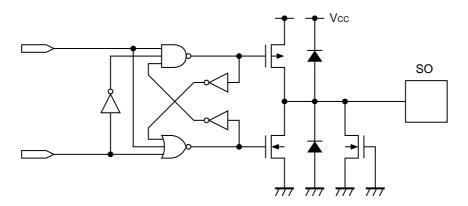


Figure 25 SO Pin

3. Precaution for use

- Absolute maximum ratings: Do not operate these ICs in excess of the absolute maximum ratings (as listed on the data sheet). Exceeding the supply voltage rating can cause latch-up.
- Operations with moisture on the S-25C010A/020A/040A pins may occur malfunction by short-circuit between pins.
 Especially, in occasions like picking the S-25C010A/020A/040A up from low temperature tank during the evaluation. Be sure that not remain frost on the S-25C010A/020A/040A's pins to prevent malfunction by short-circuit.

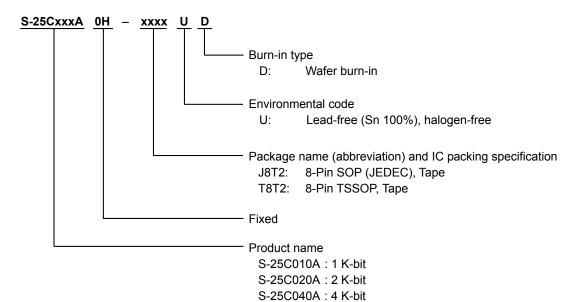
Also attention should be paid in using on environment, which is easy to dew for the same reason.

■ Precaution

- Do not apply an electrostatic discharge to this IC that exceeds the performance ratings of the built-in electrostatic protection circuit.
- SII claims no responsibility for any and all disputes arising out of or in connection with any infringement of the products including this IC upon patents owned by a third party.

■ Product Name Structure

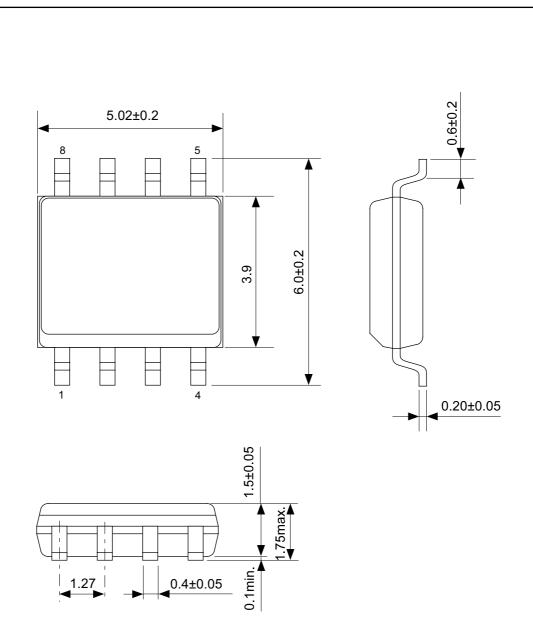
1. Product name



Remark Please contact our sales office for products with product name structure other than those specified above.

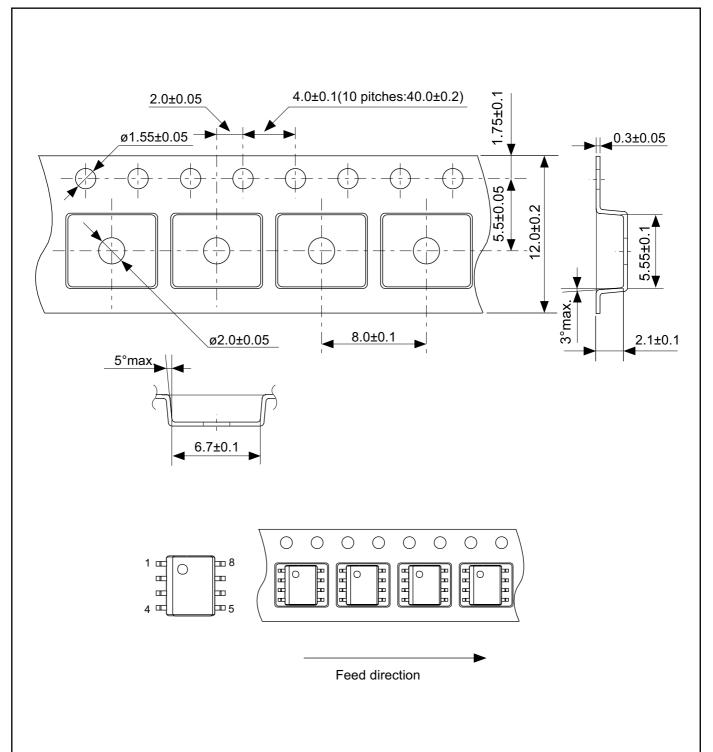
2. Package

Daakaga nama		Drawing code	
Package name	Package	Tape	Reel
8-Pin SOP (JEDEC)	FJ008-A-P-SD	FJ008-D-C-SD	FJ008-D-R-S1
8-Pin TSSOP	FT008-A-P-SD	FT008-E-C-SD	FT008-E-R-S1



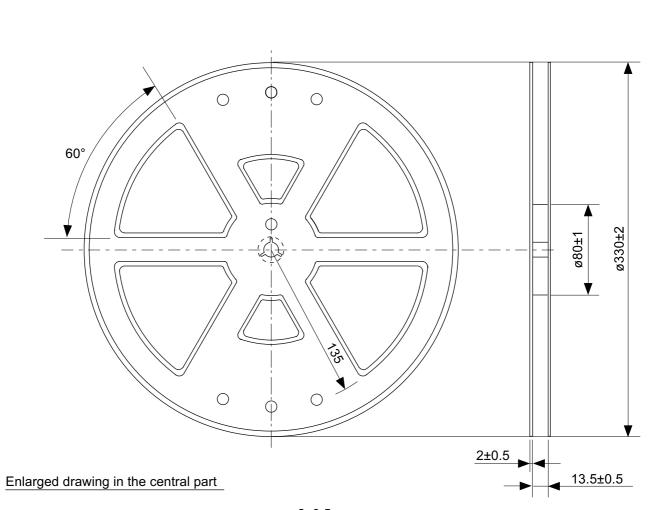
No. FJ008-A-P-SD-2.1

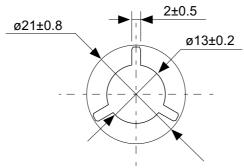
TITLE	SOP8J-D-PKG Dimensions		
No.	FJ008-A-P-SD-2.1		
SCALE			
UNIT	mm		
Seiko Instruments Inc.			



No. FJ008-D-C-SD-1.1

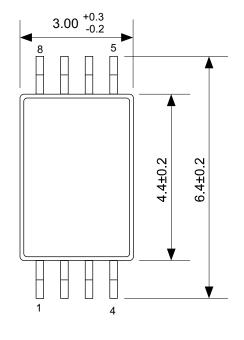
TITLE	SOP8J-D-Carrier Tape		
No.	FJ008-D-C-SD-1.1		
SCALE			
UNIT	mm		
Seiko Instruments Inc.			

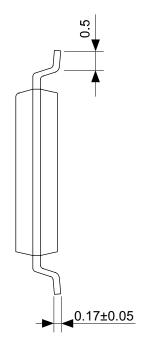


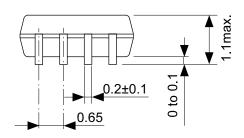


No. FJ008-D-R-S1-1.0

TITLE	SOP8J-D-Reel			
No.	FJ008-D-R-S1-1.0			
SCALE		QTY.	4,000	
UNIT	mm			
Seiko Instruments Inc.				

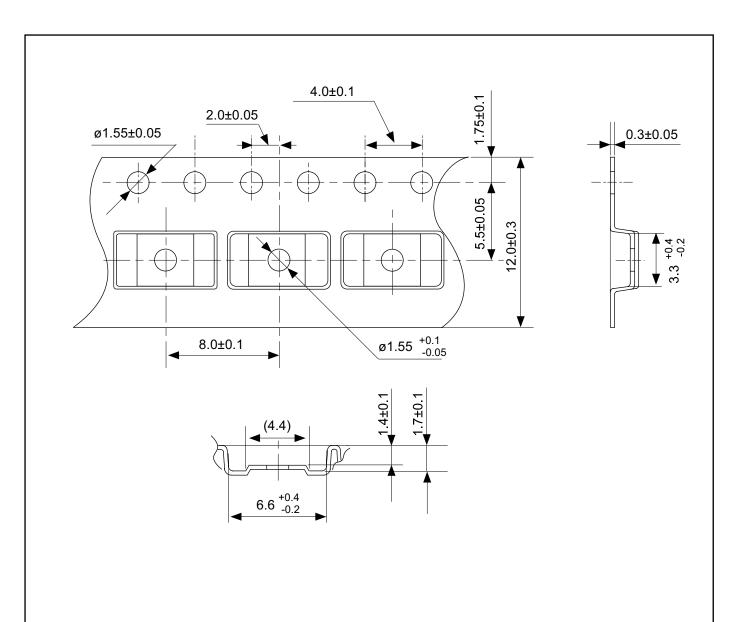


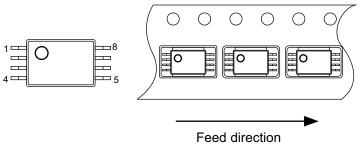




No. FT008-A-P-SD-1.1

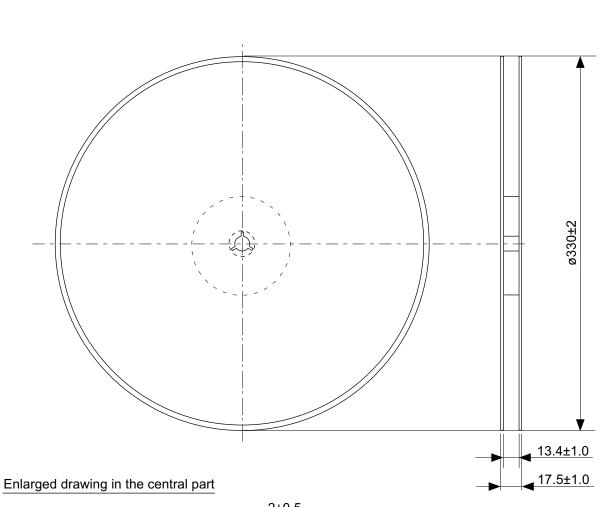
TITLE	TSSOP8-E-PKG Dimensions		
No.	FT008-A-P-SD-1.1		
SCALE			
UNIT	mm		
0-:1 1			
Seiko Instruments Inc.			

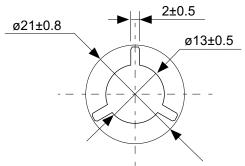




No. FT008-E-C-SD-1.0

TITLE	TSSOP8-E-Carrier Tape		
No.	FT008-E-C-SD-1.0		
SCALE			
UNIT	mm		
Seiko Instruments Inc.			





No. FT008-E-R-S1-1.0

TITLE	TSSOP8-E-Reel		
No.	FT008-E-R-S1-1.0		
SCALE	QTY. 4,000		
UNIT	mm		
Seiko Instruments Inc.			

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