



Adjustable Precision Shunt Regulator

■ Features

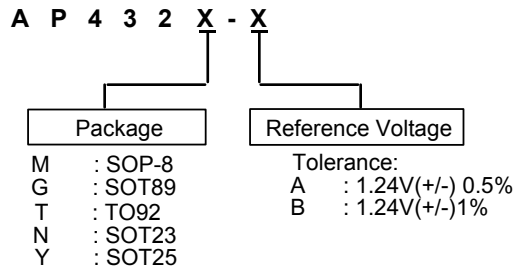
- Precision reference voltage
 - B : $1.24V \pm 1\%$
 - A : $1.24V \pm 0.5\%$
- Sink current capability: 200mA.
- Minimum cathode current for regulation: $150\mu A$
- Equivalent full-range temp coefficient: $30 \text{ ppm}/^\circ C$
- Fast turn-on Response.
- Low dynamic output impedance: 0.2Ω
- Programmable output voltage to 20v
- Low output noise
- Packages: SOT89, SOT23, SOT25, SOP8 and TO92
- RoHS Compliant & Halogen Free Product

■ General Description

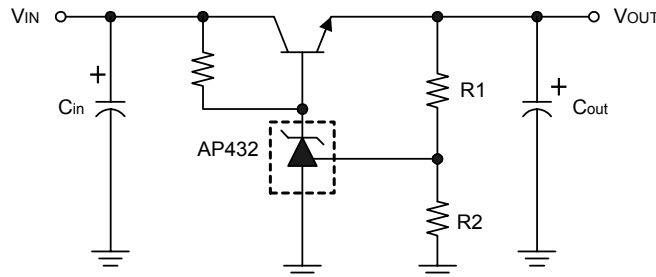
The AP432 are 3-terminal adjustable precision shunt regulators with guaranteed stable temperature over the applicable extended commercial temperature range. The output voltage may be set at any level greater than $1.24V (V_{REF})$ up to 20V merely by selecting two external resistors that act as a voltage divider network. These devices have a typical output impedance of 0.2Ω . Active output circuitry provides very sharp turn-on characteristics, making these devices excellent improved replacements for Zener diodes in many applications.

The precise $\pm 1\%$ reference voltage tolerance of the AP432 make it possible in many applications to avoid the use of a variable resistor, consequently saving cost and eliminating drift and reliability problems associated with it.

■ Ordering Information



■ Typical Application Circuit

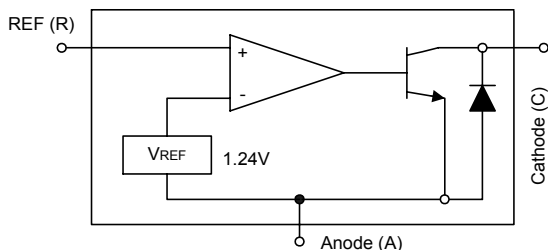


$$V_{OUT} = (1 + R1/R2)V_{REF}$$

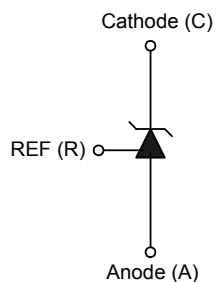
Precision Regulator



■ Block Diagram



■ Symbol



■ Pin Configuration

| Order Number | Pin Configuration (Top View) |
|--------------------|------------------------------|
| AP432G (SOT-89) | |
| AP432T (TO-92) | |
| AP432M (SOP-8) | |

| Order Number | Pin Configuration (Top View) |
|--------------------|------------------------------|
| AP432N (SOT-23) | |
| AP432Y (SOT-25) | |



■ **Absolute Maximum Ratings**

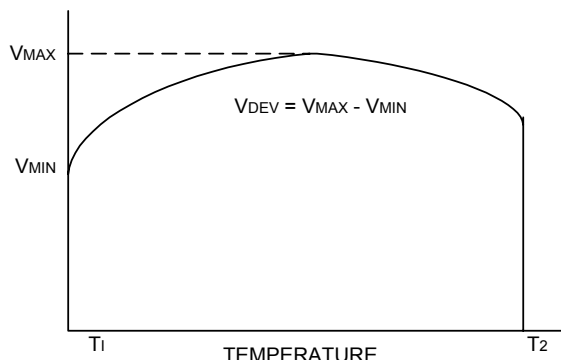
| | |
|-------------------------------------|---------------|
| Cathode Voltage..... | 20V |
| Continuous cathode current | -10mA ~ 250mA |
| Reference input current range | 10mA |
| Operating temperature range | -40 °C ~ 85°C |
| Lead Temperature..... | 260°C |
| Storage Temperature | -65°C ~ 150°C |
| Power Dissipation (Notes 1, 2) | |
| SOT-89 | 0.80W |
| TO-92..... | 0.78W |
| SOT-23 | 0.25W |
| SOT-25..... | 0.25W |
| SOP-8..... | 0.6W |

Note 1: $T_J, \max = 150^\circ\text{C}$.

Note 2: Ratings apply to ambient temperature at 25°C .

■ **Electrical Characteristics** ($T_a=25^\circ\text{C}$, unless otherwise specified.)

| Parameter | Test conditions | Symbol | Min. | Typ. | Max. | Unit |
|---|---|--|-------|------|-------|---------------|
| Reference Voltage | $V_{KA} = V_{ref}, I_{KA} = 10\text{mA}$ (Fig.1) | -B | 1.227 | 1.24 | 1.252 | V |
| | | -A | 1.233 | | 1.246 | |
| Deviation of Reference Input Voltage over Temperature (Note 3) | $V_{KA} = V_{REF}, I_{KA} = 10\text{mA}, T_a = \text{full range}$ (Fig.1) | V_{REF} | | 3.0 | 20 | mV |
| Ratio of the Change in Reference Voltage to the Change in Cathode Voltage | $I_{KA} = 10\text{mA}$ (Fig.2) $V_{KA} = 20 \sim V_{REF}$ | $\frac{\Delta V_{REF}}{\Delta V_{KA}}$ | | -1.4 | -2.0 | mV/V |
| Reference Input Current | $R1 = 10\text{K}\Omega, R2 = \infty$ $I_{KA} = 10\text{mA}$ (Fig.2) | I_{REF} | | 1.4 | 3.5 | μA |
| Deviation of Reference Input Current over Temperature | $R1 = 10\text{K}\Omega, R2 = \infty$ $I_{KA} = 10\text{mA}$ $T_a = \text{Full range}$ (Fig.2) | αI_{REF} | | 0.4 | 1.2 | μA |
| Minimum Cathode Current for Regulation | $V_{KA} = V_{REF}$ (Fig.1) | $I_{KA(\min)}$ | | 0.15 | 0.3 | mA |
| Off-state Current | $V_{KA} = 20\text{V}, V_{REF} = 0\text{V}$ (Fig.3) | $I_{KA(\text{off})}$ | | 0.1 | 1.0 | μA |
| Dynamic Output Impedance (Note 4) | $V_{KA} = V_{REF}$ Frequency $\leq 1\text{KHz}$ (Fig.1) | $ Z_{KA} $ | | 0.2 | 0.5 | Ω |



Note 3. Deviation of reference input voltage, V_{DEV}, is defined as the maximum variation of the reference over the full temperature range.

The average temperature coefficient of the reference input voltage α V_{REF} is defined as:

$$|\alpha V_{REF}| = \frac{\left(\frac{V_{DEV}}{V_{REF(25^\circ C)}}\right) \times 10^6}{T_2 - T_1} \dots\dots\dots (\text{ppm}/^\circ\text{C})$$

Where:

T₂ - T₁ = full temperature change.

α V_{REF} can be positive or negative depending on whether the slope is positive or negative.

Note 4. The dynamic output impedance, R_Z, is defined as:

$$|Z_{KA}| = \frac{\Delta V_{KA}}{\Delta I_{KA}}$$

When the device is programmed with two external resistors R1 and R2 (see Figure 2.), the dynamic output impedance of the overall circuit, is defined as:

$$|Z_{KA}'| = \frac{\Delta V}{\Delta I} \approx |Z_{KA}| \left(1 + \frac{R1}{R2}\right)$$

■ Test Circuits

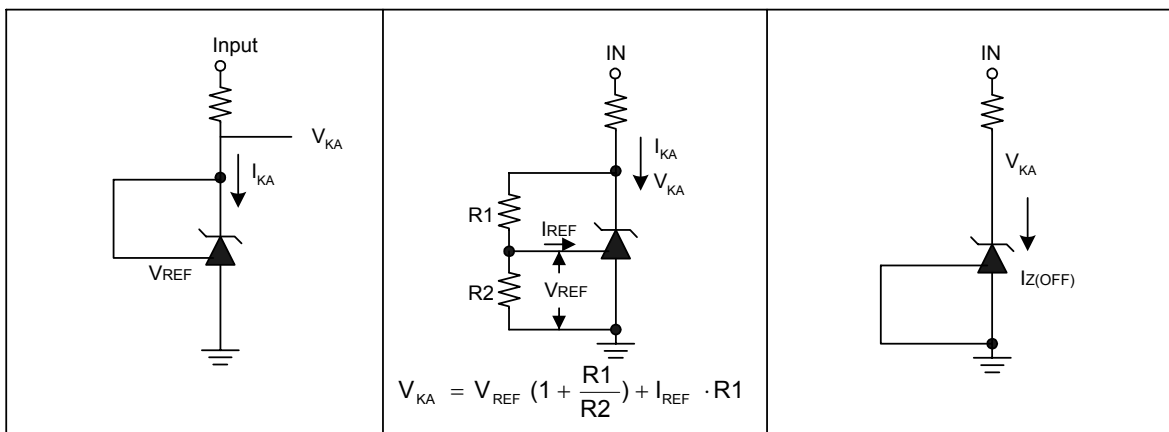


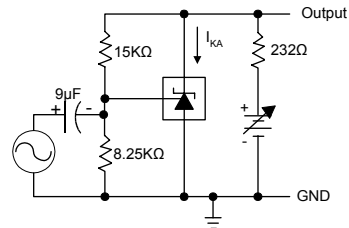
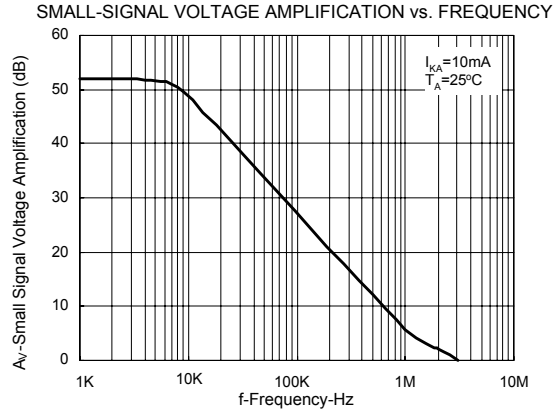
Fig1. Test Circuit for V_{KA} = V_{REF}

Fig2. Test circuit for V_{KA} > V_{REF}

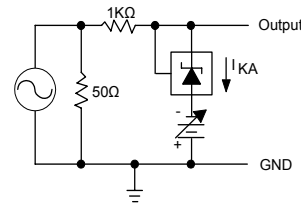
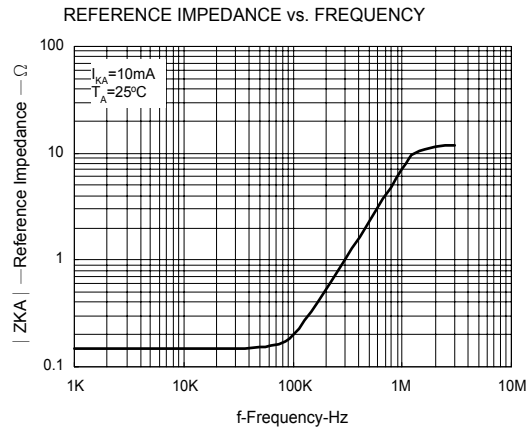
Fig3. Test Circuit for off-state Current



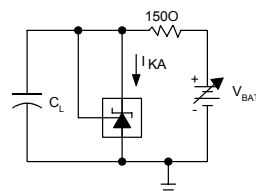
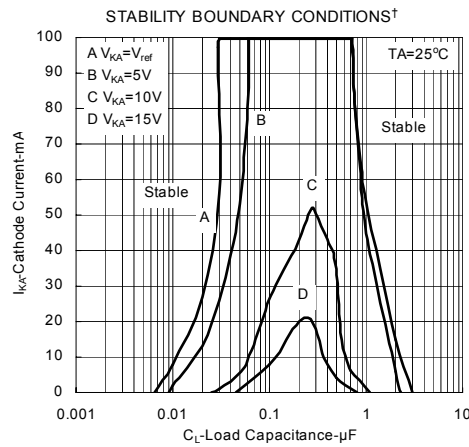
Typical Performance Characteristics



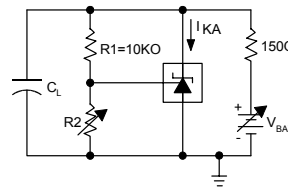
TEST CIRCUIT FOR VOLTAGE AMPLIFICATION



TEST CIRCUIT FOR REFERENCE IMPEDANCE



TEST CIRCUIT FOR CURVE A

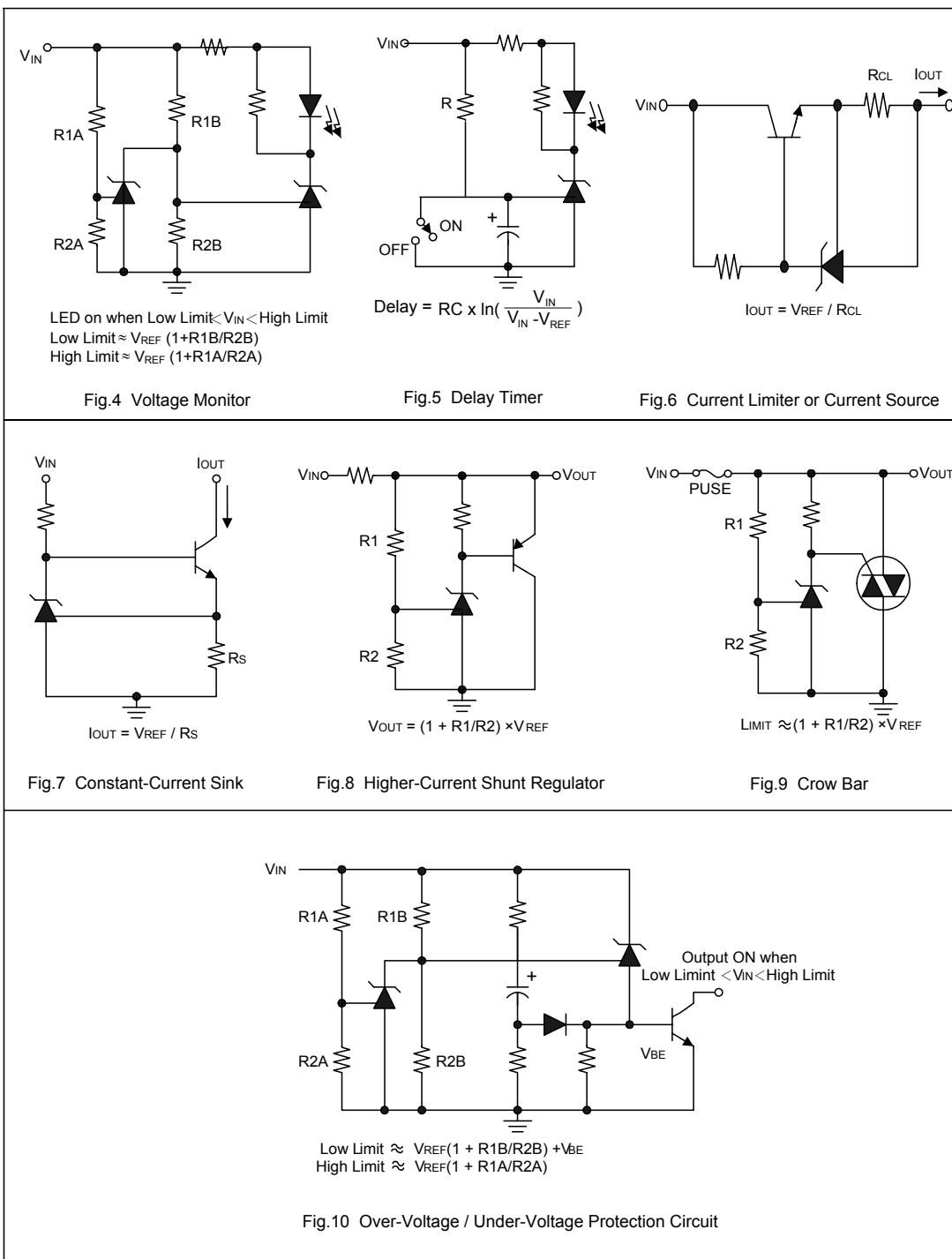


TEST CIRCUIT FOR CURVE B, C, AND D

†The areas under the curves represent conditions that may cause the device to oscillate. For curves B, C, and D, R2 and V+ were adjusted to establish the initial V_{KA} and I_{KA} conditions with $C_L = 0.0V_{BATT}$ and C_L were then adjusted to determine the ranges of stability.



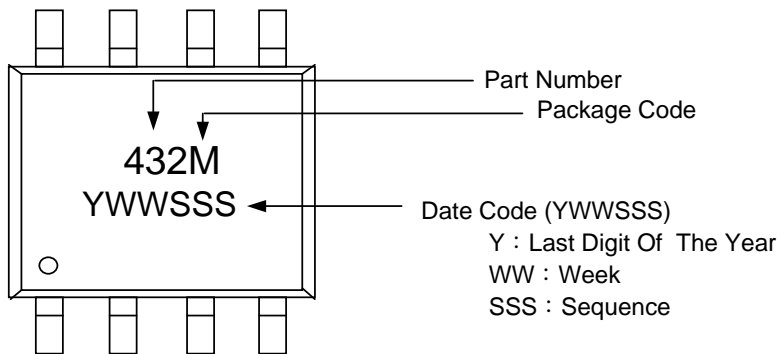
Application Examples



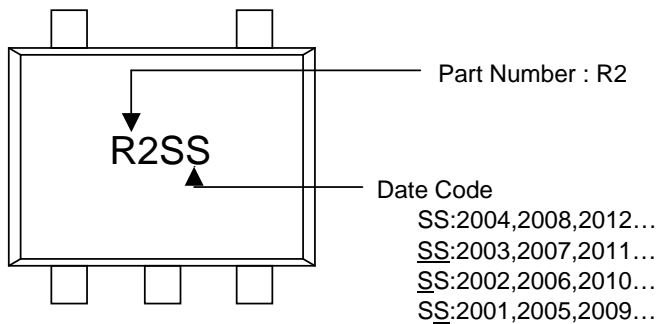


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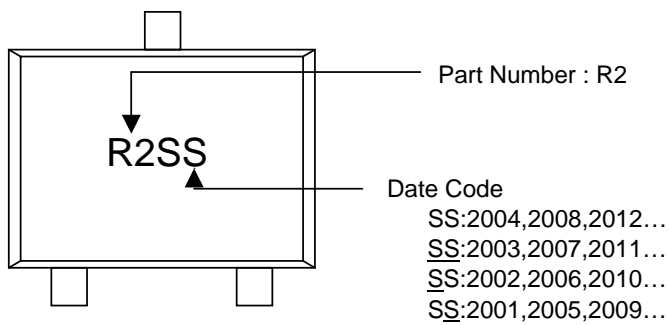
SO-8



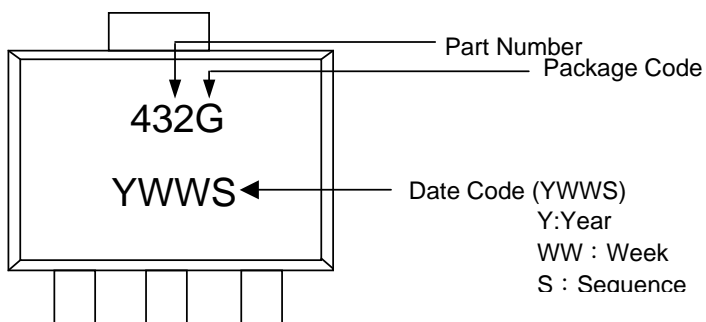
SOT-23-5L



SOT-23



SOT-89





MARKING INFORMATION

TO-92

