LED Driver with I^{2}C Compatible and 3-wire Serial Interface for 8×16 LEDs in Dot Matrix

BU16501KS2

General Description

BU16501KS2 is "Matrix LED Driver" that is the most suitable for Home Appliance.

It can control 8x16 (128 dot) LED Matrix by internal 8-channel PMOS SWs and 16-channel LED drivers.

It can control the brightness in each dot by the setting of the internal register.

It supports SPI and I^{2}C interface.

Key Specifications

- Operating power supply voltage range: 2.7V to 5.5V
- Oscillator frequency: 1.2MHz (Typ.)
- Operating temperature range: -40℃ to +85℃

Package W(Typ) x D(Typ) x H(Max)

SQFP-T52M 12.00mm x 12.00mm x 1.60mm

Features

- LED Matrix driver (8x16)
    - It has 8-channel PMOS SWs and 16-channel current drivers with 1/8 TDM timing driven sequentially.
    - Put ON/OFF (for every dot)
    - The current drivers can drive from 0 to 20.00mA current with "16" steps(for every dot)
    - The current drivers can drive maximum 42.5mA/Line (ISET=47kΩ)
    - 64 steps of the luminance control by PWM (common setting for all dots)
- Interface
    - SPI and I^{2}C BUS FS mode (max 400 kHz) Compability.
   - For I^{2}C mode, I^{2}C Device address is selectable (74h or 75h).
- Thermal Shutdown

Applications

Mobile phone, portable device, home electrical appliance, and general consumer equipment.
Device provided with LED display application.
LED display.
Amusement, Traffic Signboards, hobby, etc.

Pin plan

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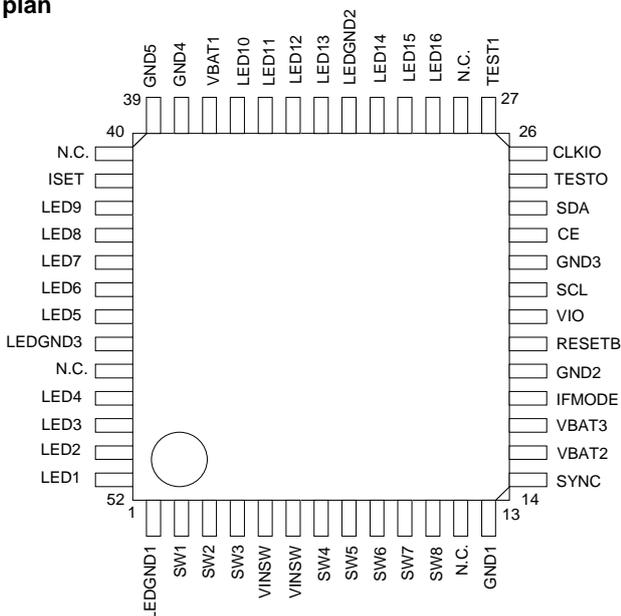
Typical Application Circuit

8×16
Dot Matrix Unit

Matrix Direction
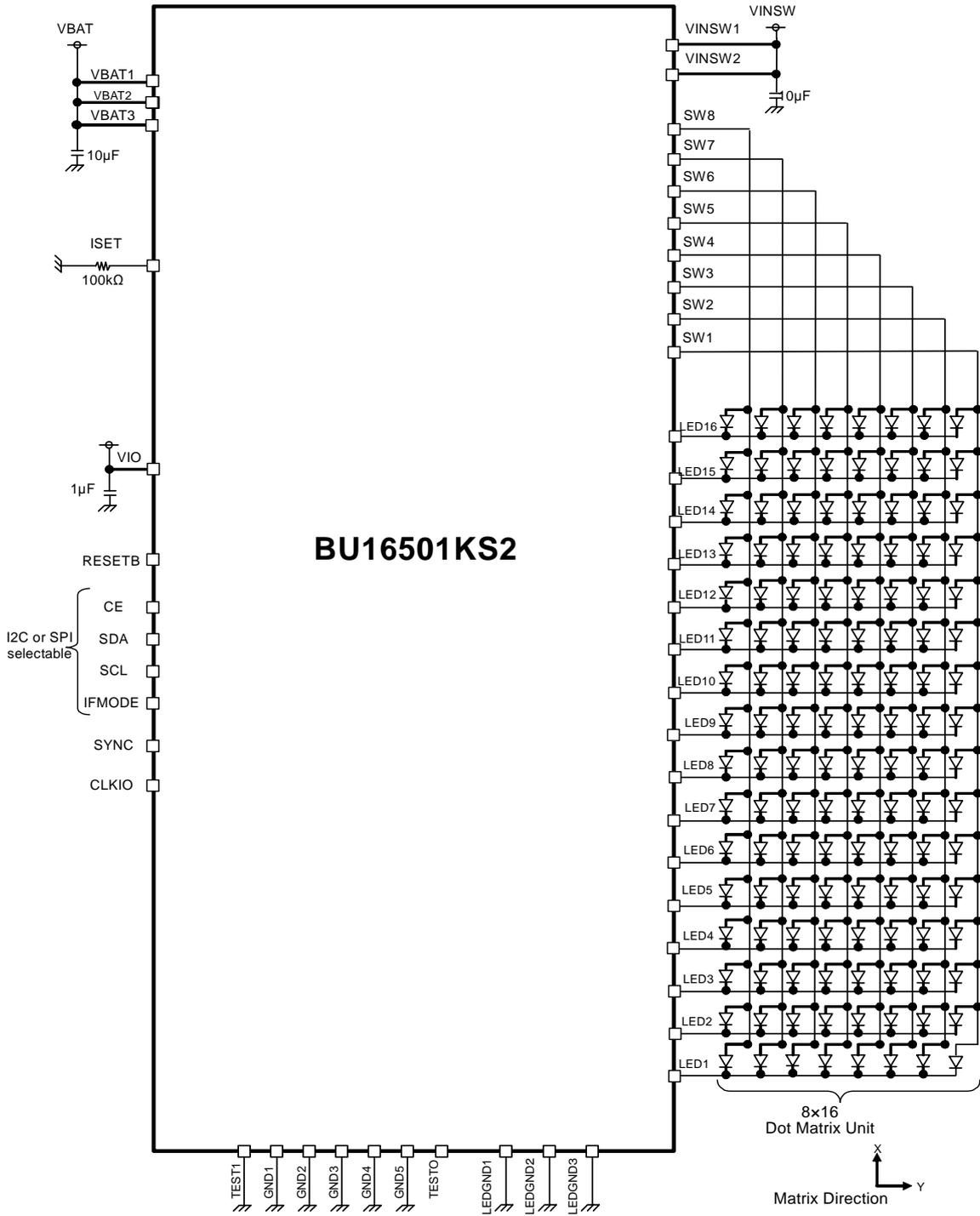
Pin Descriptions

No	Pin Name	I/O	Pull down	Unused processing setting	ESD Diode For Power	ESD Diode For Ground	Functions	Equivalent Circuit
1	LEDGND1	-	-	-	VBAT	-	Ground	B
2	SW1	O	-	VINSW	VINSW	GND	P-MOS SW1 output	C
3	SW2	O	-	VINSW	VINSW	GND	P-MOS SW2 output	C
4	SW3	O	-	VINSW	VINSW	GND	P-MOS SW3 output	C
5	VINSW1	-	-	-	-	GND	Power supply for SW1-8	A
6	VINSW2	-	-	-	-	GND	Power supply for SW1-8	A
7	SW4	O	-	VINSW	VINSW	GND	P-MOS SW4 output	C
8	SW5	O	-	VINSW	VINSW	GND	P-MOS SW5 output	C
9	SW6	O	-	VINSW	VINSW	GND	P-MOS SW6 output	C
10	SW7	O	-	VINSW	VINSW	GND	P-MOS SW7 output	C
11	SW8	O	-	VINSW	VINSW	GND	P-MOS SW8 output	C
12	NC	-	-	-	-	-	-	-
13	GND1	-	-	-	VBAT	-	Ground	B
14	SYNC	I	-	GND	VBAT	GND	External synchronous input pin	D
15	VBAT2	-	-	-	-	GND	Battery is connected	A
16	VBAT3	-	-	-	-	GND	Battery is connected	A
17	IFMODE	I	-	GND	VBAT	GND	I^2C/SPI select pin (L: I^2C, H: SPI)	D
18	GND2	-	-	-	VBAT	-	Ground	B
19	RESETB	I	-	GND	VBAT	GND	Reset input pin (L: reset, H: reset cancel)	D
20	VIO	-	-	-	VBAT	GND	I/O Power supply is connected	I
21	SCL	I	-	-	VBAT	GND	SPI, I^2C CLK input pin	D
22	GND3	-	-	-	VBAT	-	Ground	B
23	CE	I	-	GND	VBAT	GND	SPI enable pin(H;Enable), or I^2C slave address selection (L: 74h, H: 75h)	D
24	SDA	I/O	-	-	VBAT	GND	SPI DATA input / I^2C DATA input-output pin	F
25	TESTO	O	-	OPEN	VBAT	GND	Test output pin1	G
26	CLKIO	I/O	500Ω	OPEN	VBAT	GND	Reference CLK input / output pin	M
27	TEST1	I	94kΩ	GND	VBAT	GND	Test input pin 1	E
28	NC	-	-	-	-	-	-	-
29	LED16	O	-	GND	-	GND	LED16 driver output	K
30	LED15	O	-	GND	-	GND	LED15 driver output	K
31	LED14	O	-	GND	-	GND	LED14 driver output	K
32	LEDGND2	-	-	-	VBAT	-	Ground	B
33	LED13	O	-	GND	-	GND	LED13 driver output	K
34	LED12	O	-	GND	-	GND	LED12 driver output	K
35	LED11	O	-	GND	-	GND	LED11 driver output	K
36	LED10	O	-	GND	-	GND	LED10 driver output	K
37	VBAT1	-	-	-	-	GND	Battery is connected	A
38	GND4	-	-	-	VBAT	-	Ground	B
39	GND5	-	-	-	VBAT	-	Ground	B
40	NC	-	-	-	-	-	-	-
41	ISET	I	-	-	VBAT	GND	LED Constant Current Driver Current setting pin	J
42	LED9	O	-	GND	-	GND	LED9 driver output	K
43	LED8	O	-	GND	-	GND	LED8 driver output	K
44	LED7	O	-	GND	-	GND	LED7 driver output	K
45	LED6	O	-	GND	-	GND	LED6 driver output	K
46	LED5	O	-	GND	-	GND	LED5 driver output	K
47	LEDGND3	-	-	-	VBAT	-	Ground	B
48	NC	-	-	-	-	-	-	-
49	LED4	O	-	GND	-	GND	LED4 driver output	K
50	LED3	O	-	GND	-	GND	LED3 driver output	K
51	LED2	O	-	GND	-	GND	LED2 driver output	K
52	LED1	O	-	GND	-	GND	LED1 driver output	K

Pin ESD Type

Figure 1. Pin ESD Type

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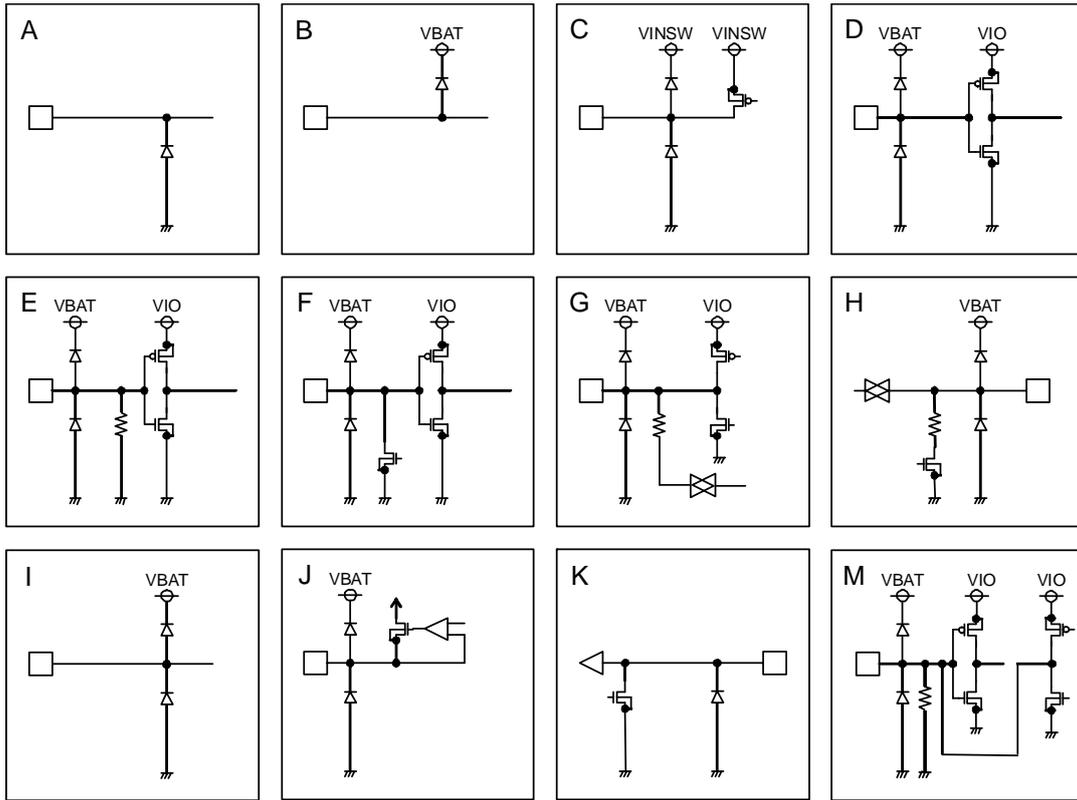
Absolute Maximum Ratings (Ta=25℃)

Parameter	Symbol	Limits	Unit
Terminal voltage	VMAX	-0.3 to +7	V
Power Dissipation [(note1)]	Pd	1.30	W
Operating Temperature Range	Topr	-40 to +85	℃
Storage Temperature Range	Tstg	-55 to +125	℃

(Note1)　Power dissipation deleting is 13mW/°C, when it's used in over 25°C
　　　　(ROHM's standard one layer board has been mounted.)
　　　　The power dissipation of the IC has to be less than the one of the package.

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Recommended Operating Ratings (Ta=-40 to 85℃)

Parameter	Symbol	Limits	Unit
VBAT input voltage	VBAT	2.7 to 5.5	V
VINSW input voltage	VINSW	2.7 to 5.5	V
VIO pin voltage	VIO	1.65 to 5.5	V

Electrical Characteristics
(Unless otherwise specified, Ta=25℃, VBAT=5.0V, VINSW=5.0V, VIO=5.0V)

Parameter	Symbol	Limit			Unit	Condition
		Min	Typ	Max		
[Circuit Current]						
VBAT Circuit current 1	IBAT1	-	0	3.0	µA	RESETB=0V, VIO=0V
VBAT Circuit current 2	IBAT2	-	0.7	5.0	µA	RESETB=0V, VIO=5.0V
VBAT Circuit current 3	IBAT3	-	2.1	3.5	mA	When LED1-16 are active with 10.67mA settings.
[UVLO]						
UVLO Threshold	VUVLO	-	2.1	2.5	V	VBAT falling
UVLO Hysteresis	VHYUVLO	50	-	-	mV	
[LED Driver] (LED1-16)						
Maximum output current	ILEDMax1	-	20.00	-	mA	LED1-16 ,ISET＝100kΩ
	ILEDMax2	-	42.50	-	mA	LED1-16 ,ISET＝47kΩ
Output current	ILED	-7.0	-	+7.0	%	I=10.67mA setting, VLED=1V ISET=100kΩ
LED current Matching	ILEDMT	-	-	5	%	ILEDMT= (ILEDMax-ILEDMin)/(ILEDMax+ILEDMin) I=10.67mA setting, VLED=1V, ISET=100kΩ
Driver pin voltage range	VLED1	0.2	-	VBAT - 1.4	V	LED1-16 ,ISET＝100kΩ
LED OFF Leak current	ILKLED	-	-	1.0	µA	
[PMOS switch]						
Leak current at OFF	ILEAKP	-	-	1.0	µA	
Resistor at ON	RonP	-	1.0	-	Ω	Isw=160mA, VINSW=5.0V
[OSC]						
OSC frequency	fosc	0.96	1.2	1.44	MHz	
[CE, SYNC, IFMODE]						
L level input voltage	VIL1	-0.3	-	0.25 x VIO	V	
H level input voltage	VIH1	0.75 x VIO	-	VIO +0.3	V	
input current	Iin1	-	0	1	µA	Input voltage = from (0.1 x VIO) to (0.9 x VIO)

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Electrical Characteristics - continued

Parameter	Symbol	Limit			Unit	Condition
		Min	Typ	Max		
[SDA, SCL]						
L level input voltage	VIL2	-0.3	-	0.25×VIO	V	
H level input voltage	VIH2	0.75×VIO	-	VIO+0.3	V	
Input hysteresis	Vhys	0.05×VIO	-	-	V	
L level output voltage (for SDA pin)	VOL2	-	-	0.3	V	IOL=3mA
Input current	Iin2	-3	-	3	µA	Input voltage = from (0.1 x VIO) to (0.9 x VIO)
[RESETB]						
L level input voltage	VIL3	-0.3	-	0.25×VIO	V	
H level input voltage	VIH3	0.75×VIO	-	VIO+0.3	V	
Input current	Iin3	-	0	1	µA	Input voltage = from (0.1 x VIO) to (0.9 x VIO)
【CLKIO(output)】						
L level output voltage	VOL1	-	-	0.4	V	IOL=2mA
H level output voltage	VOH1	VIO-0.4	-	-	V	IOH=-2mA
【CLKIO(input)】						
L level input voltage	VIL4	-0.3	-	0.25×VIO	V	
H level input voltage	VIH4	0.75×VIO	-	VIO+0.3	V	
Input current	Iin4	-	10	20	µA	Input voltage =5.0V

(Unless otherwise specified, Ta=25°C, VBAT=5.0V, VINSW=5.0V, VIO=5.0V)

| Parameter	Symbol	Limit			Unit	Condition
		Min	Typ	Max		
SCL cycle time	tscyc	76	-	-	ns	
H period of SCL cycle	Twhc	35	-	-	ns	
L period of SCL cycle	Twlc	35	-	-	ns	
SDA setup time	Tss	38	-	-	ns	
SDA hold time	Tsh	38	-	-	ns	
Write interval	Tcsw	38	-	-	ns	
Write interval (after RAM accsess)		2.1	-	-	µs	(Note 1)
		ECLK x 2	-	-	s	(Note 2)
CE setup time	Tcss	55	-	-	ns	
CE hold time	Tcgh	48	-	-	ns	

(Note 1) When it used internal clock.
(Note 2) When it used external clock. (ECLK means the cycle of external clock)

(Unless otherwise specified, Ta=25 °C, VBAT=5.0V, VINSW=5.0V, VIO=5.0V)

Parameter	Symbol	Standard-mode			Fast-mode			Unit
		Min	Typ	Max	Min	Typ	Max	
【I²C BUS format】								
SCL clock frequency	fSCL	0	-	100	0	-	400	kHz
LOW period of the SCL clock	tLOW	4.7	-	-	1.3	-	-	µs
HIGH period of the SCL clock	tHIGH	4.0	-	-	0.6	-	-	µs
Hold time (repeated) START condition After this period, the first clock is generated	tHD;STA	4.0	-	-	0.6	-	-	µs
Set-up time for a repeated START condition	tSU;STA	4.7	-	-	0.6	-	-	µs
Data hold time	tHD;DAT	0	-	3.45	0	-	0.9	µs
Data set-up time	tSU;DAT	250	-	-	100	-	-	ns
Set-up time for STOP condition	tSU;STO	4.0	-	-	0.6	-	-	µs
Bus free time between a STOP and START condition	tBUF	4.7	-	-	1.3	-	-	µs

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Block Diagram

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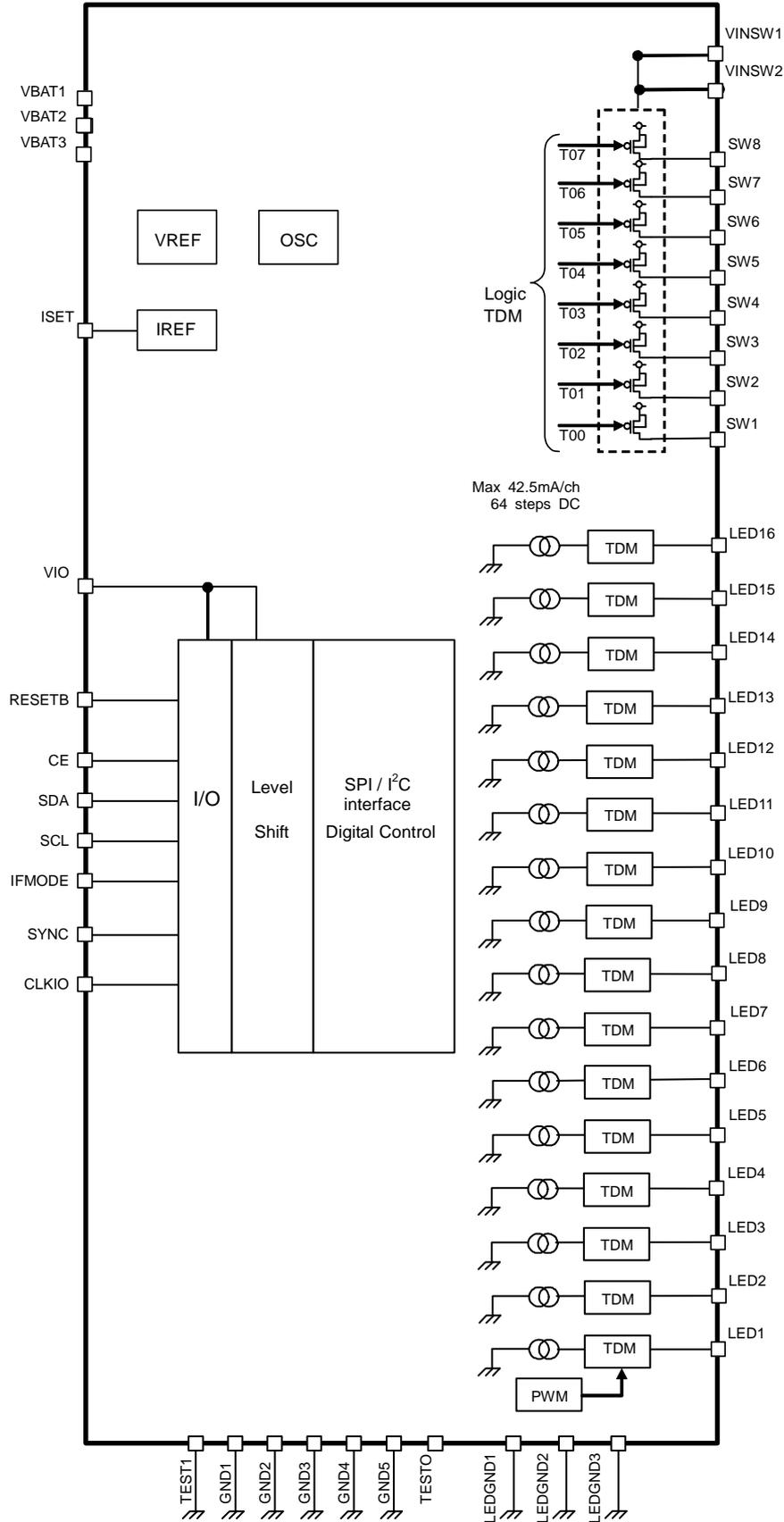
Serial Interface

1. SPI format

・When IFMODE is set to "H", it can interface with SPI format.

・The serial interface is four terminals (serial clock terminal (SCL), serial data input terminal (SDA), and chip selection input terminal (CE)).

（1）Write operation

・Data is taken into an internal shift register with rising edge of SCL. (Max of the frequency is 13MHz.)

・The receive data becomes enable in the "H" section of CE. (Active "H".)

・The transmit data is forwarded (with MSB-First) in the order of write command "0"(1bit), the control register address (7bit) and data (8bit).
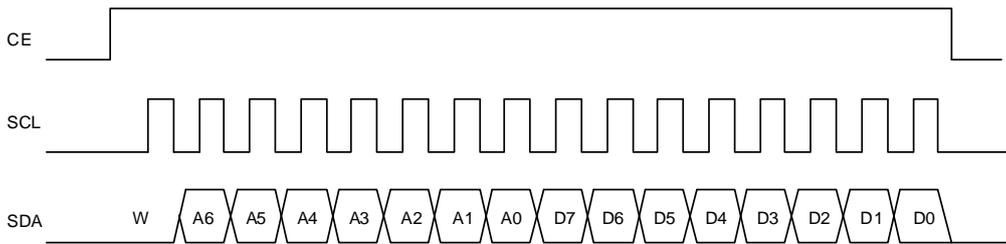
Figure 2.   Writing format

（2）Timing diagram
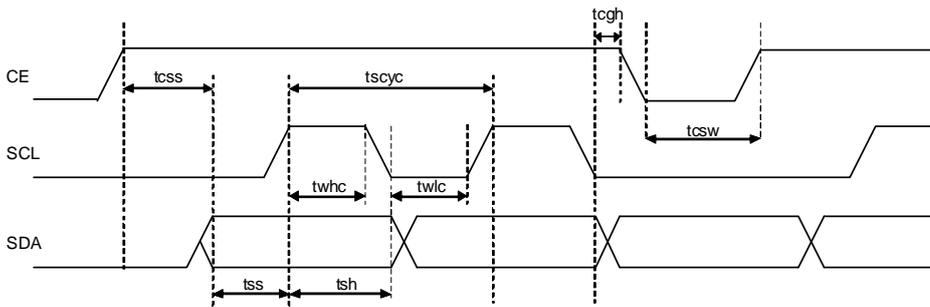
Figure 3.   Timing diagram (SPI format)

2. I^2C BUS format

When IFMODE is set to "L", it can interface with I^2C BUS format.

(1) Slave address

CE	A7	A6	A5	A4	A3	A2	A1	R/W
L	1	1	1	0	1	0	0	0
H	1	1	1	0	1	0	1	

(2) Bit Transfer

SCL transfers 1-bit data during H. During H of SCL, SDA cannot be changed at the time of bit transfer. If SDA changes while SCL is H, START conditions or STOP conditions will occur and it will be interpreted as a control signal.
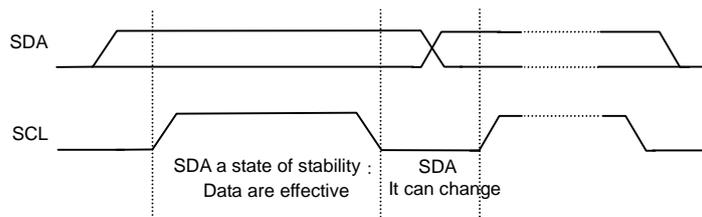

Figure 4.   Bit transfer (I^2C format)

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Serial Interface - continued

(3) START and STOP condition

When SDA and SCL are H, data is not transferred on the I^{2}C- bus. This condition indicates, if SDA changes from H to L while SCL has been H, it will become START (S) conditions, and an access start, if SDA changes from L to H while SCL has been H, it will become STOP (P) conditions and an access end.
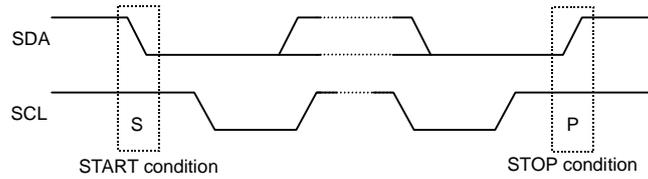

Figure 5. START/STOP condition (I^{2}C format)

(4) Acknowledge

It transfers data 8 bits each after the occurrence of START condition. A transmitter opens SDA after transfer 8bits data, and a receiver returns the acknowledge signal by setting SDA to L.
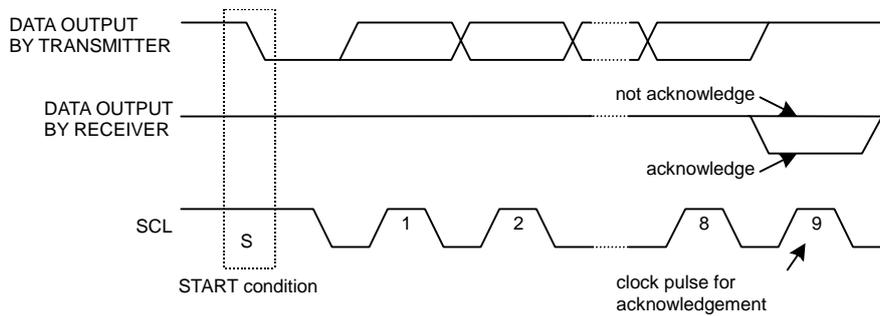

Figure 6. Acknowledge (I^{2}C format)

(5) Writing protocol

A register address is transferred by the next 1 byte that transferred the slave address and the write-in command. The 3rd byte writes data in the internal register written in by the 2nd byte, and after 4th byte or, the increment of register address is carried out automatically. However, when a register address turns into the last address (40h), it is set to 00h by the next transmission. After the transmission end, the increment of the address is carried out.


A=acknowledge(SDA LOW)
Ā=not acknowledge(SDA HIGH)
S=START condition
P=STOP condition
*1: Write Timing
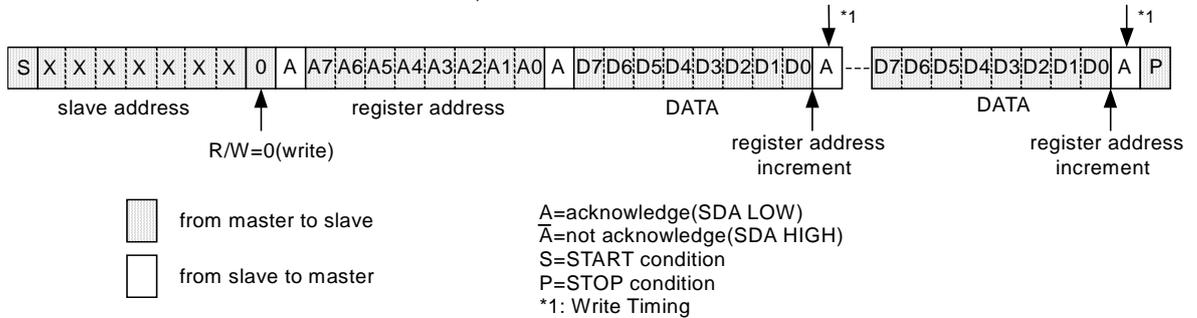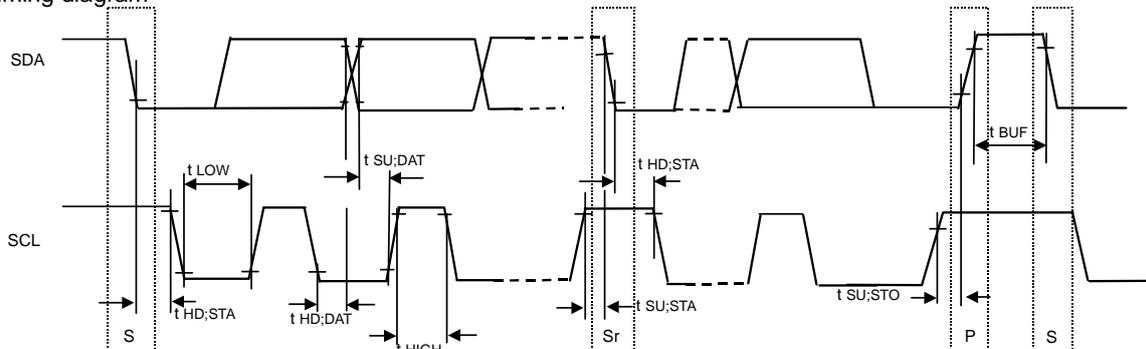
(6) Timing diagram

Figure 7. Timing diagram (I^{2}C C format)

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Register List

(Note) Please be sure to write "0" in the register which is not assigned.
It is prohibition to write data to the address which is not assigned.

Control register

Address	default	D7	D6	D5	D4	D3	D2	D1	D0	Block	Remark
00h	00h	-	-	-	-	-	-	-	SFTRST	RESET	Software Reset
01h	00h	-	-	-	-	OSCEN	-	-	-	OSC	OSC ON/OFF control
11h	00h	LED8ON	LED7ON	LED6ON	LED5ON	LED4ON	LED3ON	LED2ON	LED1ON	LED driver	LED1-8 Enable
12h	00h	LED16ON	LED15ON	LED14ON	LED13ON	LED12ON	LED11ON	LED10ON	LED9ON		LED9-16 Enable
20h	00h	-	-	PWMSET[5:0]						PWM	LED1-16 PWM setting
21h	00h	CLKSEL[1:0]		-	-	SYNCACT	SYNCON	CLKOUT	CLKIN	CLK	CLK selection, SYNC operation control
2Dh	00h	-	-	-	-	-	PWMEN	-	-	MATRIX	PWM ON/OFF setting
30h	00h	-	-	-	-	-	-	-	START		LED matrix control
31h	00h	-	-	-	-	-	-	-	CLRA		Matrix data clear
7Fh	00h	-	-	-	-	-	-	-	RMCG	RMAP	Resistor map change

Pattern register

Address	default	D7	D6	D5	D4	D3	D2	D1	D0	Block	R/W	Remark
01h	00h	ILED01SET[3:0]				ILED00SET[3:0]				MATRIX DATA	W	Data for Matrix 01/00
02h	00h	ILED03SET[3:0]				ILED02SET[3:0]					W	Data for Matrix 03/02
03h	00h	ILED05SET[3:0]				ILED04SET[3:0]					W	Data for Matrix 05/04
04h	00h	ILED07SET[3:0]				ILED06SET[3:0]					W	Data for Matrix 07/06
05h	00h	ILED11SET[3:0]				ILED10SET[3:0]					W	Data for Matrix 11/10
06h	00h	ILED13SET[3:0]				ILED12SET[3:0]					W	Data for Matrix 13/12
07h	00h	ILED15SET[3:0]				ILED14SET[3:0]					W	Data for Matrix 15/14
08h	00h	ILED17SET[3:0]				ILED16SET[3:0]					W	Data for Matrix 17/16
09h	00h	ILED21SET[3:0]				ILED20SET[3:0]					W	Data for Matrix 21/20
0Ah	00h	ILED23SET[3:0]				ILED22SET[3:0]					W	Data for Matrix 23/22
0Bh	00h	ILED25SET[3:0]				ILED24SET[3:0]					W	Data for Matrix 25/24
0Ch	00h	ILED27SET[3:0]				ILED26SET[3:0]					W	Data for Matrix 27/26
0Dh	00h	ILED31SET[3:0]				ILED30SET[3:0]					W	Data for Matrix 31/30
0Eh	00h	ILED33SET[3:0]				ILED32SET[3:0]					W	Data for Matrix 33/32
0Fh	00h	ILED35SET[3:0]				ILED34SET[3:0]					W	Data for Matrix 35/34
10h	00h	ILED37SET[3:0]				ILED36SET[3:0]					W	Data for Matrix 37/36
11h	00h	ILED41SET[3:0]				ILED40SET[3:0]					W	Data for Matrix 41/40
12h	00h	ILED43SET[3:0]				ILED42SET[3:0]					W	Data for Matrix 43/42
13h	00h	ILED45SET[3:0]				ILED44SET[3:0]					W	Data for Matrix 45/44
14h	00h	ILED47SET[3:0]				ILED46SET[3:0]					W	Data for Matrix 47/46
15h	00h	ILED51SET[3:0]				ILED50SET[3:0]					W	Data for Matrix 51/50
16h	00h	ILED53SET[3:0]				ILED52SET[3:0]					W	Data for Matrix 53/52
17h	00h	ILED55SET[3:0]				ILED54SET[3:0]					W	Data for Matrix 55/54
18h	00h	ILED57SET[3:0]				ILED56SET[3:0]					W	Data for Matrix 57/56
19h	00h	ILED61SET[3:0]				ILED60SET[3:0]					W	Data for Matrix 61/60
1Ah	00h	ILED63SET[3:0]				ILED62SET[3:0]					W	Data for Matrix 63/62
1Bh	00h	ILED65SET[3:0]				ILED64SET[3:0]					W	Data for Matrix 65/64
1Ch	00h	ILED67SET[3:0]				ILED66SET[3:0]					W	Data for Matrix 67/66
1Dh	00h	ILED71SET[3:0]				ILED70SET[3:0]					W	Data for Matrix 71/70
1Eh	00h	ILED73SET[3:0]				ILED72SET[3:0]					W	Data for Matrix 73/72
1Fh	00h	ILED75SET[3:0]				ILED74SET[3:0]					W	Data for Matrix 75/74
20h	00h	ILED77SET[3:0]				ILED76SET[3:0]					W	Data for Matrix 77/76
21h	00h	ILED81SET[3:0]				ILED80SET[3:0]					W	Data for Matrix 81/80
22h	00h	ILED83SET[3:0]				ILED82SET[3:0]					W	Data for Matrix 83/82
23h	00h	ILED85SET[3:0]				ILED84SET[3:0]					W	Data for Matrix 85/84
24h	00h	ILED87SET[3:0]				ILED86SET[3:0]					W	Data for Matrix 87/86
25h	00h	ILED91SET[3:0]				ILED90SET[3:0]					W	Data for Matrix 91/90
26h	00h	ILED93SET[3:0]				ILED92SET[3:0]					W	Data for Matrix 93/92
27h	00h	ILED95SET[3:0]				ILED94SET[3:0]					W	Data for Matrix 95/94
28h	00h	ILED97SET[3:0]				ILED96SET[3:0]					W	Data for Matrix 97/96
29h	00h	ILEDA1SET[3:0]				ILEDA0SET[3:0]					W	Data for Matrix A1/A0
2Ah	00h	ILEDA3SET[3:0]				ILEDA2SET[3:0]					W	Data for Matrix A3/A2
2Bh	00h	ILEDA5SET[3:0]				ILEDA4SET[3:0]					W	Data for Matrix A5/A4
2Ch	00h	ILEDA7SET[3:0]				ILEDA6SET[3:0]					W	Data for Matrix A7/A6
2Dh	00h	ILEDB1SET[3:0]				ILEDB0SET[3:0]					W	Data for Matrix B1/B0
2Eh	00h	ILEDB3SET[3:0]				ILEDB2SET[3:0]					W	Data for Matrix B3/B2
2Fh	00h	ILEDB5SET[3:0]				ILEDB4SET[3:0]					W	Data for Matrix B5/B4

Pattern register - continued

Address	default	D7	D6	D5	D4	D3	D2	D1	D0	Block	R/W	Remark
30h	00h	ILEDB7SET[3:0]				ILEDB6SET[3:0]				MATRIX DATA	W	Data for Matrix B7/B6
31h	00h	ILEDC1SET[3:0]				ILEDC0SET[3:0]					W	Data for Matrix C1/C0
32h	00h	ILEDC3SET[3:0]				ILEDC2SET[3:0]					W	Data for Matrix C3/C2
33h	00h	ILEDC5SET[3:0]				ILEDC4SET[3:0]					W	Data for Matrix C5/C4
34h	00h	ILEDC7SET[3:0]				ILEDC6SET[3:0]					W	Data for Matrix C7/C6
35h	00h	ILEDD1SET[3:0]				ILEDD0SET[3:0]					W	Data for Matrix D1/D0
36h	00h	ILEDD3SET[3:0]				ILEDD2SET[3:0]					W	Data for Matrix D3/D2
37h	00h	ILEDD5SET[3:0]				ILEDD4SET[3:0]					W	Data for Matrix D5/D4
38h	00h	ILEDD7SET[3:0]				ILEDD6SET[3:0]					W	Data for Matrix D7/D6
39h	00h	ILEDE1SET[3:0]				ILEDE0SET[3:0]					W	Data for Matrix E1/E0
3Ah	00h	ILEDE3SET[3:0]				ILEDE2SET[3:0]					W	Data for Matrix E3/E2
3Bh	00h	ILEDE5SET[3:0]				ILEDE4SET[3:0]					W	Data for Matrix E5/E4
3Ch	00h	ILEDE7SET[3:0]				ILEDE6SET[3:0]					W	Data for Matrix E7/E6
3Dh	00h	ILEDF1SET[3:0]				ILEDF0SET[3:0]					W	Data for Matrix F1/F0
3Eh	00h	ILEDF3SET[3:0]				ILEDF2SET[3:0]					W	Data for Matrix F3/F2
3Fh	00h	ILEDF5SET[3:0]				ILEDF4SET[3:0]					W	Data for Matrix F5/F4
40h	00h	ILEDF7SET[3:0]				ILEDF6SET[3:0]					W	Data for Matrix F7/F6

Register Map

Address 00h   < Software Reset >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
00h	W	-	-	-	-	-	-	-	SFTRST
Initial value	00h	-	-	-	-	-	-	-	0

Bit 0：SFTRST   Software Reset
　　　　"0"：　　　Reset cancel
　　　　"1"：　　　Reset（All register initializing）
SFTRST register return to 0 automatically.

Address 01h   <OSC control >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
01h	W	-	-	-	-	OSCEN	-	-	-
Initial value	00h	-	-	-	-	0	-	-	-

Bit 3：OSCEN   OSC block ON/OFF control
　　　　"0"：OFF（Initial）
　　　　"1"：ON

This register should not change into "1 "→" 0" at the time of START (30h, D0) register ="1" setup (under lighting operation).
This register must be set to "0" after LED putting out lights ("START register = 0"), and please surely stop an internal oscillation circuit.

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Register Map - continued

Address 11h   < LED1-8 Enable >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
11h	W	LED8ON	LED7ON	LED6ON	LED5ON	LED4ON	LED3ON	LED2ON	LED1ON
Initial value	00h	0	0	0	0	0	0	0	0

Bit 0 : LED1ON   LED1 ON/OFF setting
      "0" : LED1   OFF（initial）
      "1" : LED1   ON

Bit 1 : LED2ON   LED2 ON/OFF setting
      "0" : LED2   OFF（initial）
      "1" : LED2   ON

Bit 2 : LED3ON   LED3 ON/OFF setting
      "0" : LED3   OFF（initial）
      "1" : LED3   ON

Bit 3 : LED4ON   LED4 ON/OFF setting
      "0" : LED4   OFF（initial）
      "1" : LED4   ON

Bit 4 : LED5ON   LED5 ON/OFF setting
      "0" : LED5   OFF（initial）
      "1" : LED5   ON

Bit 5 : LED6ON   LED6 ON/OFF setting
      "0" : LED6   OFF（initial）
      "1" : LED6   ON

Bit 6 : LED7ON   LED7 ON/OFF setting
      "0" : LED7   OFF（initial）
      "1" : LED7   ON

Bit 7 : LED8ON   LED8 ON/OFF setting
      "0" : LED8   OFF（initial）
      "1" : LED8   ON

(Note) Current setting follows ILEDXXSET[3:0] register.

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Register Map - continued

Address 12h < LED9-16 Enable >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
12h	W	LED16 ON	LED15 ON	LED14 ON	LED13 ON	LED12 ON	LED11 ON	LED10 ON	LED9 ON
Initial value	00h	0	0	0	0	0	0	0	0

Bit 0 : LED9ON   LED9 ON/OFF setting
"0" : LED9   OFF（initial）
"1" : LED9   ON

Bit 1 : LED10ON   LED10 ON/OFF setting
"0" : LED10   OFF（initial）
"1" : LED10   ON

Bit 2 : LED11ON   LED11 ON/OFF setting
"0" : LED11   OFF（initial）
"1" : LED11   ON

Bit 3 : LED12ON   LED12 ON/OFF setting
"0" : LED12   OFF（initial）
"1" : LED12   ON

Bit 4 : LED13ON   LED13 ON/OFF setting
"0" : LED13   OFF（initial）
"1" : LED13   ON

Bit 5 : LED14ON   LED14 ON/OFF setting
"0" : LED14   OFF（initial）
"1" : LED14   ON

Bit 6 : LED15ON   LED15 ON/OFF setting
"0" : LED15   OFF（initial）
"1" : LED15   ON

Bit 7 : LED16ON   LED16 ON/OFF setting
"0" : LED16   OFF（initial）
"1" : LED16   ON

(Note) Current setting follows ILEDXXSET[3:0] register.

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Register Map - continued

Address 20h < LED1-16 PWM setting >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
20h	W	-	-	PWMSET [5:0]					
Initial value	00h	-	-	0	0	0	0	0	0

Bit 5-0 : PWMSET[5:0]   LED1-16 PWM DUTY setting
"000000" : 0/63＝0%(initial)
"000001" : 1/63＝1.59%
：
：
"100000" : 32/63＝50.8%
：
：
"111110" : 62/63＝98.4%
"111111" : 63/63＝100%

(Note)Please refer to Description of operation, chapter 2

Address 21h <Clock control / SYNC operation control>

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
21h	W	CLKSEL[1:0]		-	-	SYNCACT	SYNCON	CLKOUT	CLKIN
Initial value	00h	0	0	-	-	0	0	0	0

Bit 0 : CLKIN   Selection CLK for PWM control
"0" : Internal OSC (initial)
"1" : External CLK input (to CLKIO pin)

Bit 1 : CLKOUT   Output CLK enable
"0" : CLK is not output (initial)
"1" : Output selected CLK from CLKIO pin

As for CLKIN & CLKOUT, setting change is forbidden under OSCEN (01h, D3) register ="1" and
also under clock input to CLKIO terminal.

Bit 2 : SYNCON   SYNC operation enable
"0" : Disable SYNC operation (initial)
"1" : SYNC pin control LED driver ON/OFF

Bit 3 : SYNCACT   SYNC operation setting
"0" : When SYNC pin is "L", LED drivers are ON (initial)
"1" : When SYNC pin is "H", LED drivers are ON

Bit 7-6 : CLKSEL[1:0] Select Clock Frequency
"00" : 1.2MHz (initial)
"01" : 300kHz
"10" : 150kHz
"11" : 37.5kHz

Register Map - continued

Address 2Dh < PWM ON/OFF setting >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
2Dh	W	-	-	-	-	-	PWMEN	-	-
Initial value	00h	-	-	-	-	-	0	-	-

Bit 2：PWMEN　PWM control at LED1-16 ON/OFF setting
　　　"0"：PWM operation is invalid（initial value）
　　　"1"：PWM operation is valid

　　　(Note)Please refer to Description of operation, chapter 2

Address 30h < LED Matrix control >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
30h	W	-	-	-	-	-	-	-	START
Initial value	00h	-	-	-	-	-	-	-	0

Bit 0：START　Lighting/turning off bit of MATRIX LED(LED1-16)
　　　"0"：MATRIX LED（LED1-16）　　Lights out (initial)
　　　"1"：MATRIX LED（LED1-16）　　Lighting start

Address 31h 　< Matrix data clear >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
31h	W	-	-	-	-	-	-	-	CLRA
Initial value	00h	-	-	-	-	-	-	-	0

Bit 0：CLRA　　Reset Pattern register
　　　"0"：Pattern register is not reset and writable（initial value）
　　　"1"：Pattern register is reset

(Note)CLRA register return to 0 automatically.

Address 7Fh 　< Register map change >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
7Fh	W	-	-	-	-	-	-	-	RMCG
Initial value	00h	-	-	-	-	-	-	-	0

Bit 0：RMCG　　Change register map
　　　"0"：Control register is selected（initial value）
　　　"1"：Pattern register is selected

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Register Map - continued

Address 01h-40h   < Pattern register data >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
01-40h	W	ILEDXXSET [3:0]				ILEDXXSET [3:0]			
Initial value	00h	0	0	0	0	0	0	0	0

Bit7-4/Bit 3-0：ILEDXXSET[3:0]   LED output current setting for Pattern matrix data

ILEDxxSET[3:0]				電流値
0	0	0	0	0 [mA]
0	0	0	1	1/15 x ILEDmax [mA]
0	0	1	0	2/15 x ILEDmax [mA]
·	·	·	·	1/15 x ILEDmax [mA] Step
·	·	·	·	
·	·	·	·	
·	·	·	·	
1	1	0	1	13/15 x ILEDmax [mA]
1	1	1	0	14/15 x ILEDmax [mA]
1	1	1	1	15/15 x ILEDmax [mA]

example：ILEDmax=20mA (ISET=100 kΩ) , LED current setting as below.

"0000"： 0.00mA
"0001"： 1.33mA
"0010"： 2.67mA
"0011"： 4.00mA
"0100"： 5.33mA
"0101"： 6.67mA
"0110"： 8.00mA
"0111"： 9.33mA
"1000"： 10.67mA（initial value）
"1001"： 12.00mA
"1010"： 13.33mA
"1011"： 14.67mA
"1100"： 16.00mA
"1101"： 17.33mA
"1110"： 18.67mA
"1111"： 20.00mA

(Note) In a SPI interface, the interval to the following access has regulation after this address access.
   For details, please refer to the clause of the chapter of serial interface, and the electrical property of a SPI format.
(Note) The change of this register needs OSC frequency or CLKIO external input frequency.
   Please set "Address 01H" or "Address 21H" before the change of this register.

Description of operation
  1. LED Matrix
  1-1. Lighting method of dot Matrix
      It can control 8 x 16 Matrix.
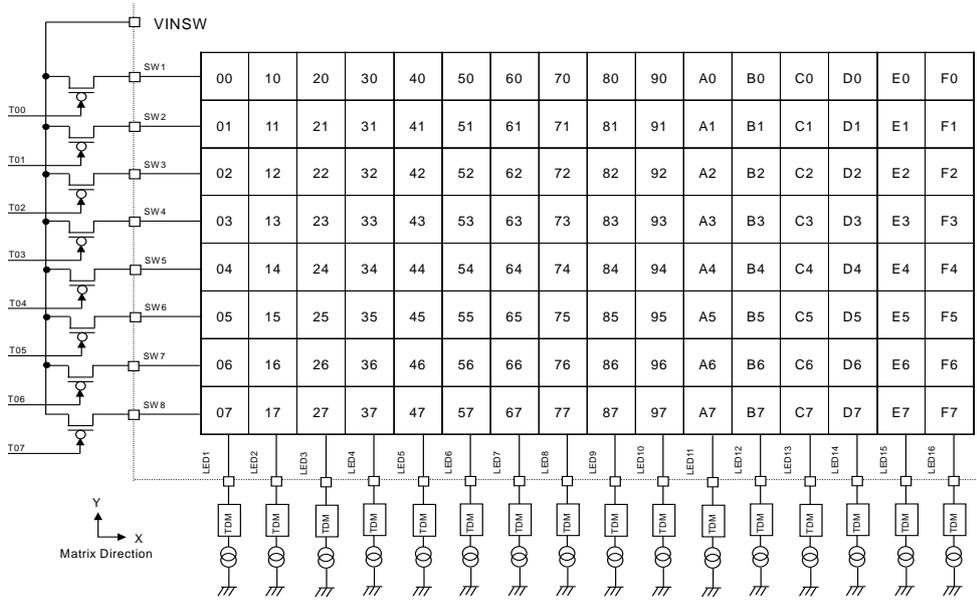
Figure 8.   8 x 16 LED Matrix coordinate

The SW1 – SW8 is turned on by serial. LED is driven one by one within the ON period.

PWM period＝524clk（＠1.2MHz、436.7us)
1/8TDMA period＝559clk（＠1.2MHz、465.8us)
TDMA period＝4472clk（＠1.2MHz、3.73ms)
Duty is variable 0/63 and between 1/63 and 63/63 of PWM period.

Figure 9.   SW timing

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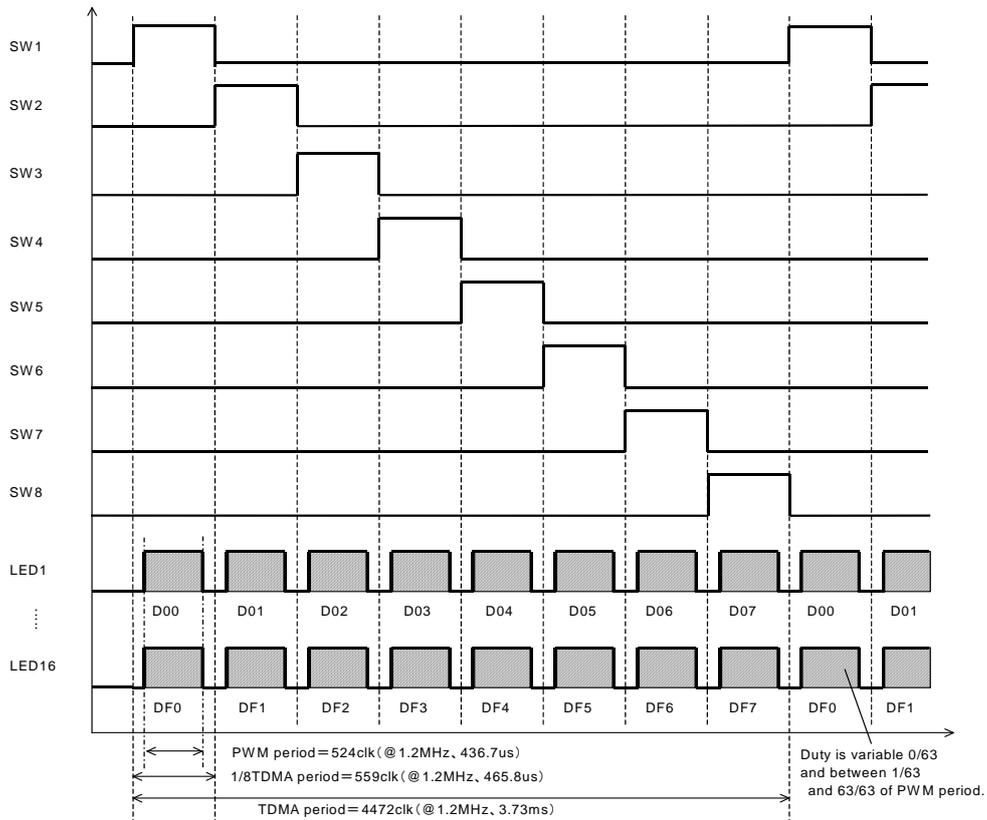
Description of operation - continued

1-2. LED lighting example

The following command set is the example of LED matrix lighting.

1) 7Fh	00000000	Select control register
2) 21h	00000000	Select internal OSC for CLK
3) 01h	00001000	Start OSC
4) 11h	11111111	Set LED1-8 enable
5) 12h	11111111	Set LED9-16 enable
6) 20h	00111111	Set Max Duty at Slop Set Max Duty
7) 7Fh	00000001	Select Pattern register to write matrix data
8) 01-40h	xxxxxxxx	Write pattern data
9) 7Fh	00000000	Select control register, Pattern register to output for matrix
10) 30h	00000001	Start lighting
11) 30h	00000000	Light off

2. LED Driver Current Control

It can be controlled PWM Duty and DC current for LED driver current.

	Item	Control object	Control detail	Setting Registers	
				Name (Note1)	Bits
(A)(Note2)	PWM Duty	Whole matrix	0/63 to 63/63 (64 step)	PWMSET	6
(B)(Note3)	DC current	Each matrix dot	0 to 20.00mA (16 step)	ILEDXXSET	4

(Note1) The "XX" shows the matrix number from "00" to "F7". Please refer 8x16 LED Matrix coordinate.
(Note2) For setting(A), please refer to P14 :register map of   address 20H.
(Note3) For setting(B), please refer to P16 :register map of   address 01H-40H.
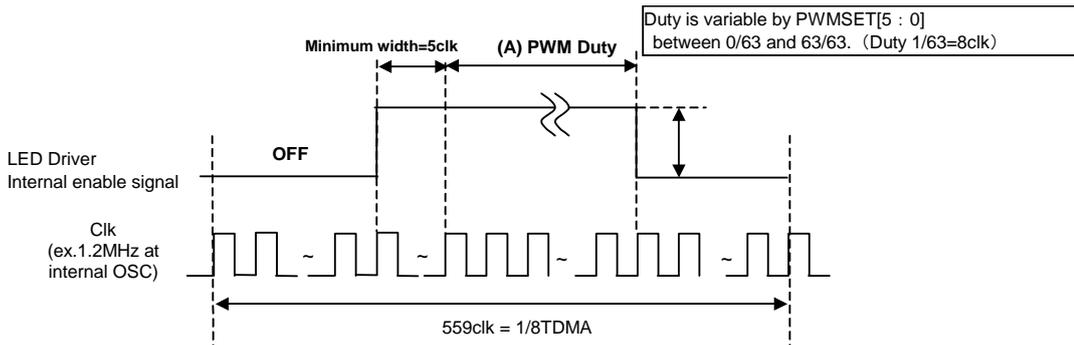
Figure 10.   LED output current timing and PWM cycle

524clk of PWM period is set in the 1/8 TDM period (559clk).
PWM is operated 63 steps of 8clk. TDM period is 3.73ms (@1.2MHz).
Moreover, it has the starting waiting time of a constant current driver by 20clk.
PWM"H" time turns into ON time after waiting 20clk.
(However, LED driver is set "OFF" compulsorily at PWM=0% setting.)
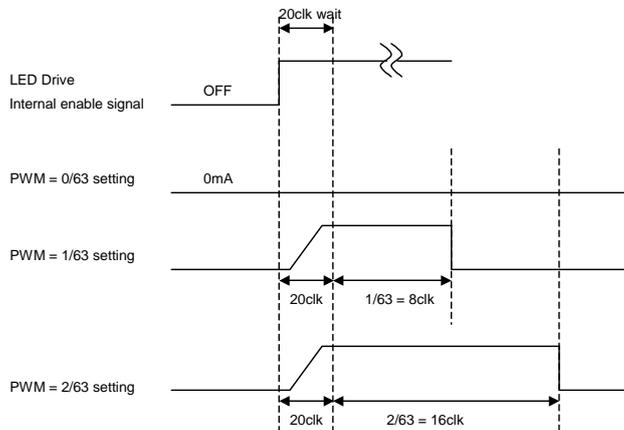
Figure 11. LED output current timing and a PWM cycle

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Description of operation - continued

3. About LEDMax current setting

LED Current is variable by RISET resister connecting ISET terminal. Maximum LED current can be leads by next formula.

$$ILEDmax [A] = 2.0 / RISET [k\Omega] \quad (Typ)$$

Caution that Maximum LED current value is up to 42.5mA.

<ISET terminal resister value vs LED Current (calculation)>
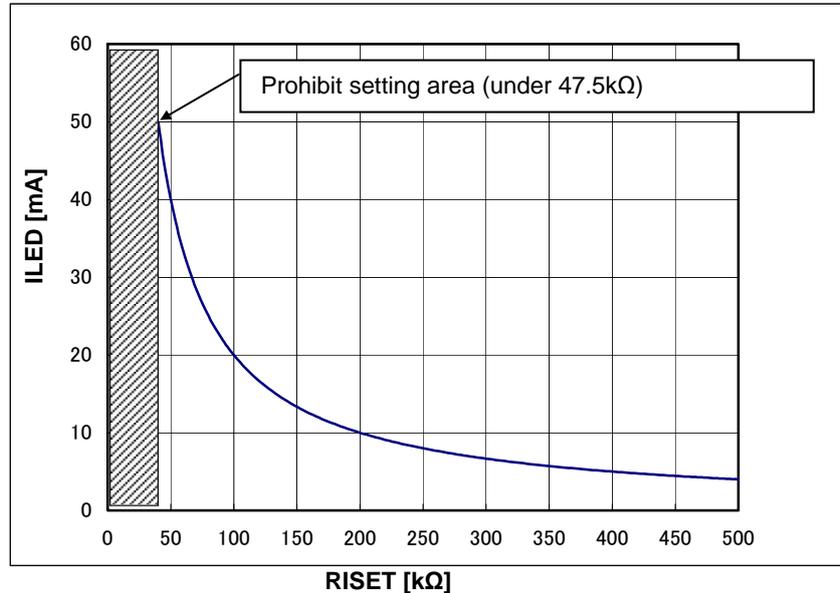
Figure 12.   ILED vs RISET

In case of RISET = 100[kΩ], Maximum LED current is 20.0mA.
There are Maximum LED current and Delta LED current value in next table. If you change the RISET value, you can calculate LED current on each step by next table.

Recommended RISET value is 100[kΩ].
In case of RISET under 47.5 [kΩ], ISET short function may be effective.

An example for setting DC current=16mA , PWMDuty=50.8%
1. ILEDMax current setting (set by external resistor):
   RISET=100kΩ -> ILEDmax[A]= 2.0 / RISET [kΩ]=20mA.

2. DC current setting (set by register/Each matrix dot can be set):
   ILEDxxSET[3:0]="1100" -> ILEDxx[A]=12/15 * ILEDmax=16mA.
   Please refer to P16 to set register of address01H-40H.

3. PWM duty setting (set by register /whole matrix):
   PWMSET[5:0]="100000" (50.8%) -> ILEDxx[A]=16mA * 50.8%=8.128mA.
   Please refer to P14 to set register of address20H.

4. 1/8TDM active -> ILEDxx[A]=8.128mA * 1/8=1.016mA.

   For this case, average 1.016mA LED current is loaded to one LED.

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Description of operation - continued

4.   Power up sequence
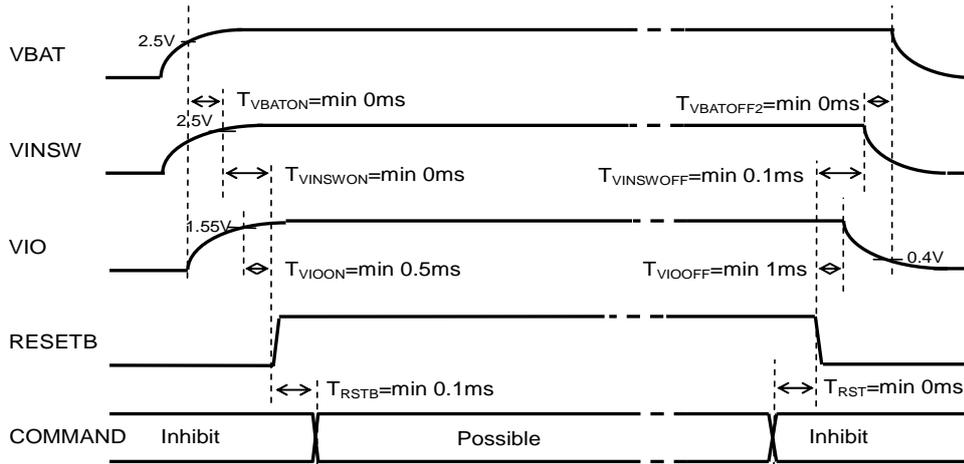
Figure 13.   Power up sequence

Please take sufficient wait time for each Power/Control signal.
However, if VBAT<2.1V(Typ) or Ta >T_{TSD}(Typ:175℃), the command input is not effective because of the protection operation

5.   Reset

There are two kinds of reset, software reset and hardware reset

(1)   Software reset
・All the registers are initialized by SFTRST="1".
・SFTRST is an automatically returned to "0". (Auto Return 0).

(2)   Hardware reset
・It shifts to hardware reset by changing RESETB pin "H" → "L".
・The condition of all the registers under hardware reset pin is returned to the Initial Value,
  and it stops accepting all address.
  All LED driver turn off.
・It's possible to release from a state of hardware reset by changing RESETB pin "L" → "H".
  RESETB pin has delay circuit. It doesn't recognize as hardware reset in "L" period under 5μs.

6.   Thermal shutdown
A thermal shutdown function is effective at all blocks of those other than VREF.
Return to the state before detection automatically at the time of release.

7.   UVLO Function (VBAT Voltage Low-Voltage Detection)
UVLO function is effective at all blocks of those other than VREF, and when detected, those blocks function is stopped.
Return to the state before detection automatically at the time of release.

Description of operation - continued

8. I/O

When the RESETB pin is Low, the input buffers (SDA and SCL) are disabling for the Low consumption power.
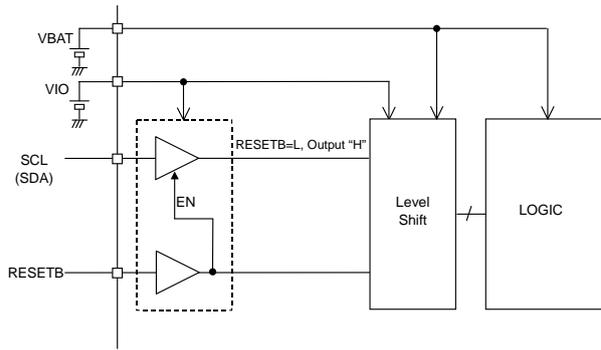
Figure 14.   Input disabling by RESETB

9. Standard Clock Input and Output

It is possible to carry out synchronous operation of two or more ICs using the input-and-output function of a standard clock.
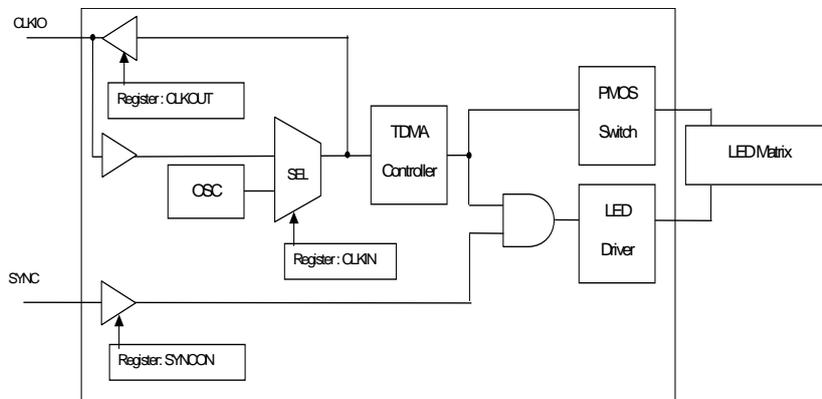
Figure 15.   I/O part equivalent circuit diagram

・When a clock is supplied from the exterior

Inputting an external standard clock from CLKIN and setting register CLKIN=1, IC operates with the clock inputted from CLKIN as a standard clock.

・When the built-in oscillation circuit of one IC is used

When a clock cannot be supplied from the exterior, it is possible to synchronize between ICs by the connection as the following figure.
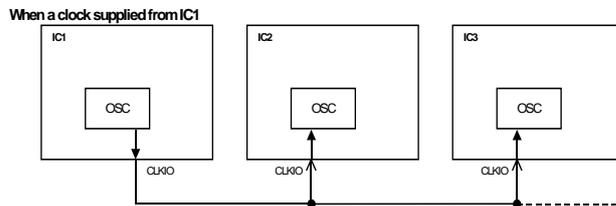
Figure 16.   It is an example of application for the usage of two or more.

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Description of operation - continued

10. External ON/OFF Synchronization (SYNC Terminal)

Lighting of LED that synchronized with the external signal is possible.

By setting H/L of SYNC terminal, LED drivers output is set ON/OFF.

It's asynchronous operation with the internal TDMA control.
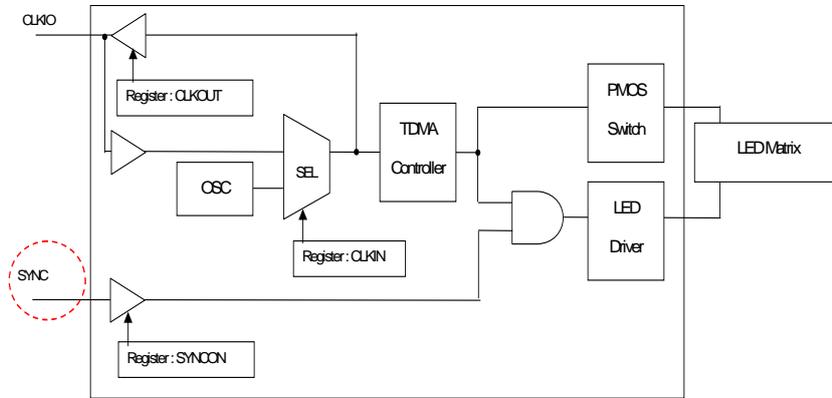
Figure 17. I/O part equivalent circuit diagram

11. About terminal processing of the function which is not used

Please set up a test terminal and the unused terminal as the following table.

Especially, if an input terminal is not fixed, it may occur the unstable state of a device and the unexpected internal current.

Terminal name	Processing	Reason
SYNC	GND Short	In order to avoid an unfixed state.
CLKIO	Open	Pin is fixed to L because pin is connected with a Pull down register of 500Kohm
TEST1	GND Short	The input terminal for a test (94k Ω Pull down)
TESTO	Open	The output terminal for a test
LED Terminal	GND Short	In order to avoid an unfixed state. (Register setup in connection with LED terminal that is not used is forbidden.)
SW Terminal	VINSW Short	In order to avoid an unfixed state. (Register setup in connection with SW terminal that is not used is forbidden.)

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Description of operation - continued

12. Setting about VINSW

VINSW is Power Supply about LED Current. It needs proper Voltage range of LED terminal to get proper LED Current (refer to Page5). If it needs the voltage range, it needs to set up proper Voltage range of VINSW which is Power Supply about LED.
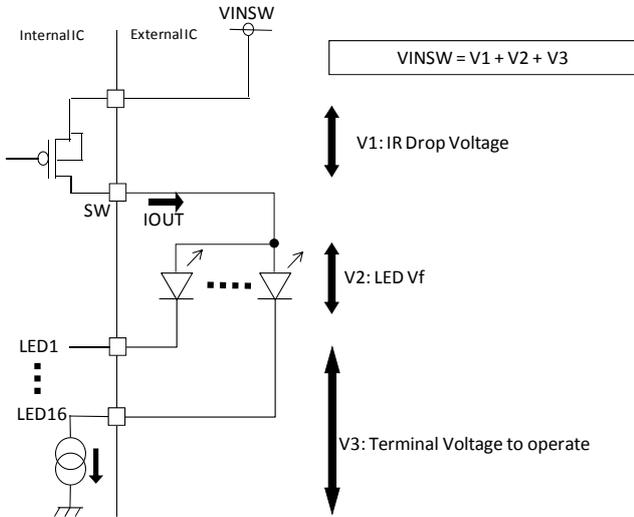
Figure 18. Set up VINSW
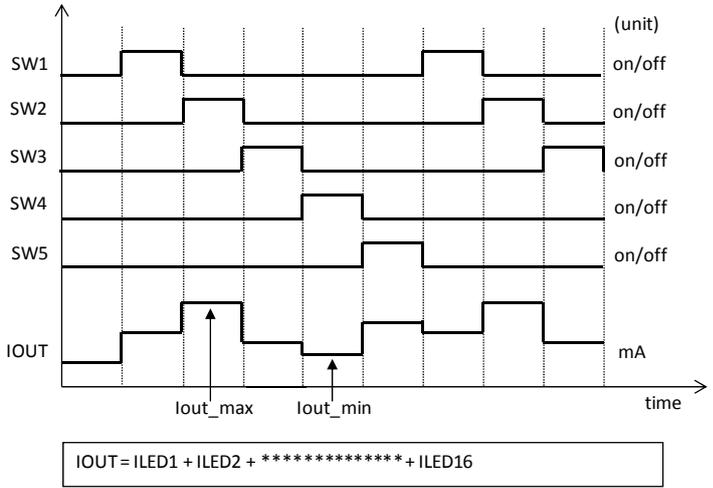
Figure 19. SW timing and IOUT

VINSW's Voltage range is made by V1, V2, V3. (refer to Figure 18)

$VINSW\_max = V1\_min + V2\_min + V3\_max$

$VINSW\_min = V1\_max + V2\_max + V3\_min$

V1:IR Drop Voltage

V1 is IR Voltage drop by SW's Resistor at ON and IOUT which is the sum of every LED Current. It is V1's maximum and minimum that it multiplies by SW's Resistor at ON and IOUT maximum and minimum in each SW timing. Please estimate IOUT by setting application. (refer to figure 19). Please refer to page 5 about SW's Resistor at ON. (And it needs to estimate parasitic resistor on PCB's current route).

$V1\_max = Ron * Iout\_max$

$V1\_min = Ron * Iout\_min$

V2: LED Vf

V2 is the Voltage drop by LED's Vf. Please confirm about all LED's Vf.

$V2\_max = Vf\_max$

$V2\_min = Vf\_min$

V3: Terminal Voltage to operate

V3 is the terminal Voltage to operate LED Current. (refer to page 5). The minimum is made by IC's ability. The maximum is made by VBAT's minimum in Voltage range.

$V3\_max = VBAT\_min – 1.4V$

$V3\_min = 0.2V$

--Example of Setting VINSW—

Condition: VBAT=3.2 – 4.0 V, Iout_max = 100mA, Iout_min = 20mA, Vf_max = 3.0V, Vf_min = 2.5V

$V1\_max = 1\ ohm * 100mA = 0.1V$ $V1\_min = 1\ ohm * 20mA = 0.02V$

$V2\_max = 3.0V$ $V2\_min = 2.5V$

$V3\_max = 3.2V – 1.4V = 1.8V$ $V3\_min = 0.2V$

$VINSW\_max = 0.02V + 2.5V + 1.8V = 4.32V$

$VINSW\_min = 0.1V + 3.0V + 0.2V = 3.3V$

This is proper Voltage range about VINSW.

Power dissipation (On the ROHM's standard one layer board)
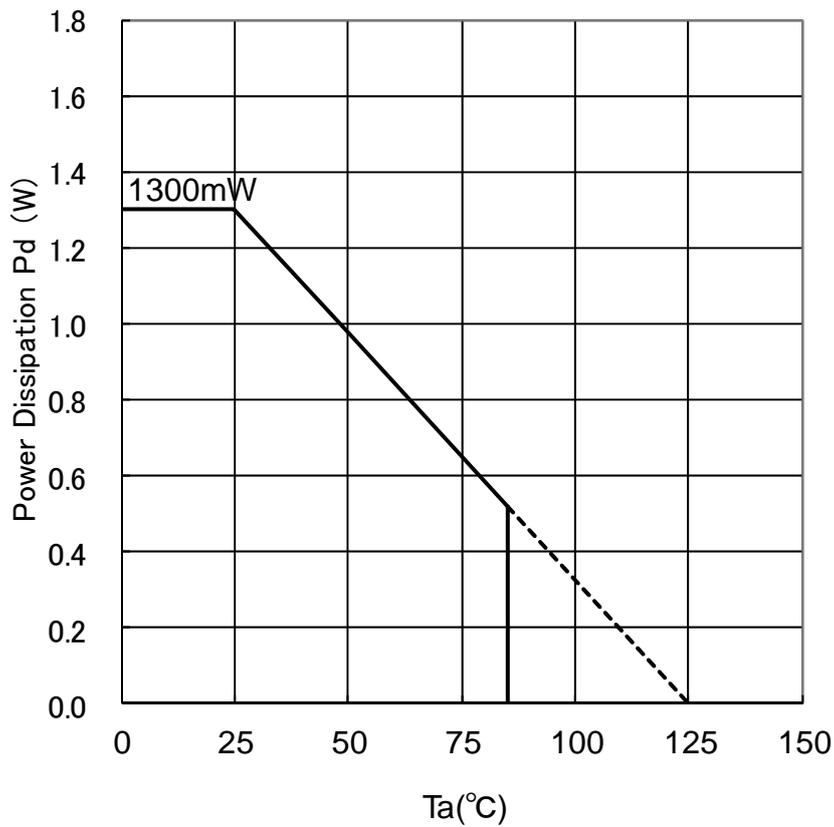
<Calculator>
P_d=(VINSW-V_f) x I_{LED} x N(Channel)
ex)
VINSW=5V, Vf=3.2V, I_{LED} =20mA,N=16channel, P_d =(5-3.2) x 20 x 16=576mW

Please adjust VINSW and I_{LED} in order to prevent P_d from exceeding 1300mV of power dissipation.

*VINSW: VINSW input voltage
*V_f: Diode V_f
*I_{LED}: LED Current
*N(Channel): LED Channel

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Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. The absolute maximum rating of the Pd stated in this specification is when the IC is mounted on a 70mm x 70mm x 1.6mm glass epoxy board. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

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Operational Notes – continued

11.   Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

12.   Regarding the Input Pin of the IC

In the construction of this IC, P-N junctions are inevitably formed creating parasitic diodes or transistors. The operation of these parasitic elements can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions which cause these parasitic elements to operate, such as applying a voltage to an input pin lower than the ground voltage should be avoided. Furthermore, do not apply a voltage to the input pins when no power supply voltage is applied to the IC. Even if the power supply voltage is applied, make sure that the input pins have voltages within the values specified in the electrical characteristics of this IC.

13.   Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

14. Thermal Shutdown Circuit(TSD)

This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's power dissipation rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF all output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

Ordering Information

B	U	1	6	5	0	1	K	S	2	-	E 2

Part Number

Package
KS2: SQFP-T52M

Packaging and forming
specification
E2: Embossed tape and reel

Marking Diagram

SQFP-T52M (TOP VIEW)

BU16501KS2

Part Number Marking

LOT Number

1PIN MARK
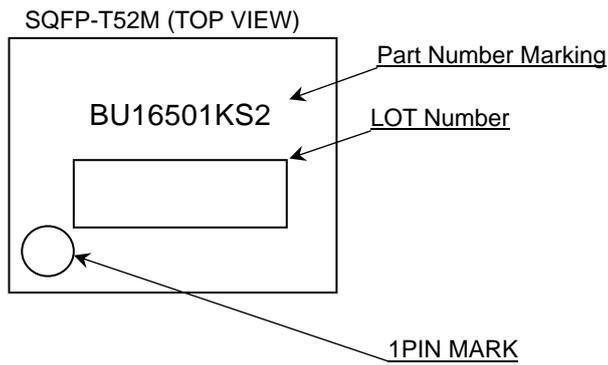
Physical Dimensions Tape and Reel Information
SQFP-T52M
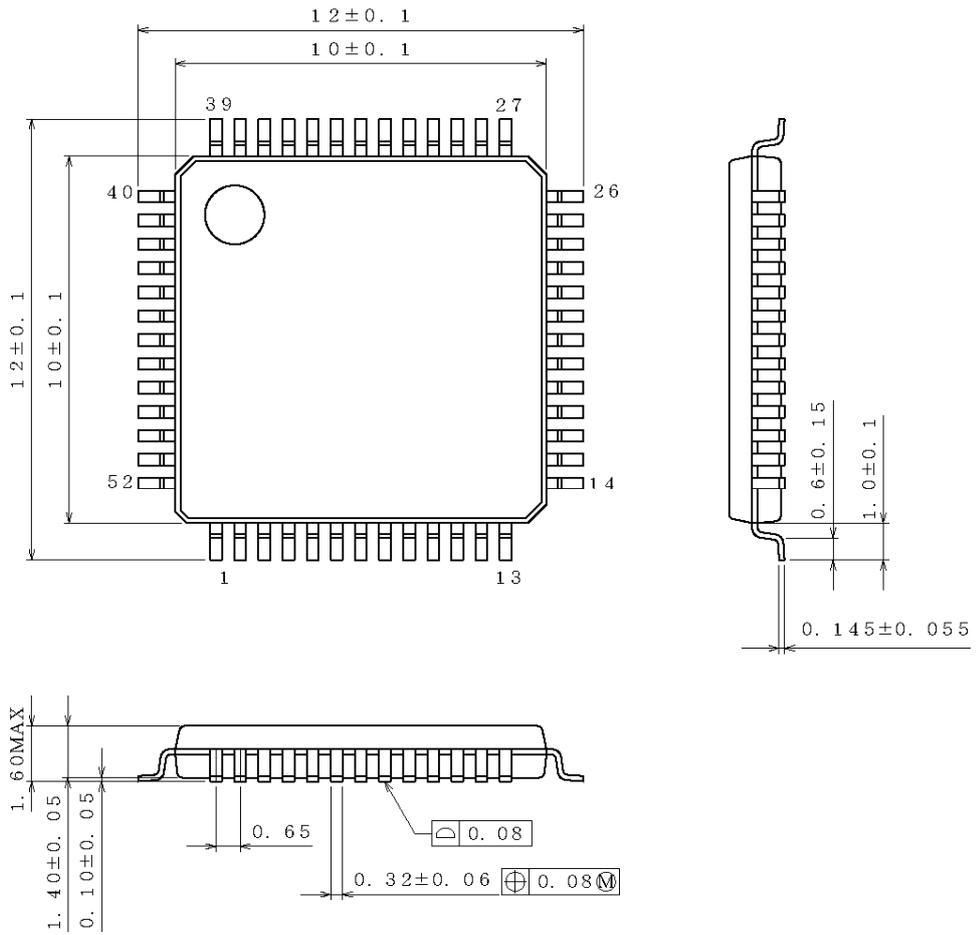
(UNIT : mm)

<Tape and Reel information>	
Tape	Embossed carrier tape
Quantity	1000pcs
Direction of feed	E2 (The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand)

*Order quantity needs to be multiple of the minimum quantity.

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Revision History

Date	Revision	Changes
01.Oct.2013	001	New Release

TSZ02201-0G3G0CZ00250-1-2
01.Oct.2013 Rev.001

Notice

Precaution on using ROHM Products

1. Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment [(Note 1)], transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.

(Note1) Medical Equipment Classification of the Specific Applications

JAPAN	USA	EU	CHINA
CLASSⅢ	CLASSⅢ	CLASSⅡb	CLASSⅢ
CLASSⅣ		CLASSⅢ	

2. ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
   [a] Installation of protection circuits or other protective devices to improve system safety
   [b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure

3. Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
   [a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
   [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
   [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl_2, H_2S, NH_3, SO_2, and NO_2
   [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
   [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
   [f] Sealing or coating our Products with resin or other coating materials
   [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
   [h] Use of the Products in places subject to dew condensation

4. The Products are not subject to radiation-proof design.

5. Please verify and confirm characteristics of the final or mounted products in using the Products.

6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.

7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.

8. Confirm that operation temperature is within the specified range described in the product specification.

9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

Precaution for Mounting / Circuit board design

1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.

2. In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

Precautions Regarding Application Examples and External Circuits

1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.

2. You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

Precaution for Electrostatic

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of Ionizer, friction prevention and temperature / humidity control).

Precaution for Storage / Transportation

1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
    [a] the Products are exposed to sea winds or corrosive gases, including Cl2, H2S, NH3, SO2, and NO2
    [b] the temperature or humidity exceeds those recommended by ROHM
    [c] the Products are exposed to direct sunshine or condensation
    [d] the Products are exposed to high Electrostatic

2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.

3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.

4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

Precaution for Product Label

QR code printed on ROHM Products label is for ROHM's internal use only.

Precaution for Disposition

When disposing Products please dispose them properly using an authorized industry waste company.

Precaution for Foreign Exchange and Foreign Trade act

Since our Products might fall under controlled goods prescribed by the applicable foreign exchange and foreign trade act, please consult with ROHM representative in case of export.

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