



MLX90291

SMD Programmable Linear Hall Sensor IC Featuring PWM Output

Features and Benefits

- Programmable Hall effect sensor
 - 12-bit 125Hz PWM output signal proportional to the magnetic flux density
 - Switch function
- Measurement range from $\pm 15\text{mT}$ to $\pm 400\text{mT}$
- Low noise output signal (PWM jitter)
- Programmable through the connector (supply, ground & output)
- 16 bit customer ID number (48 bit MLX ID for traceability purposes)
- SOIC8 package RoHS compliant
- Lead free component, suitable for lead free soldering profile 260 °C

Application Examples

- Rotary position sensor
- Linear position sensor
- Contactless switch

Ordering Code

| Product Code | Temperature Code | Package Code | Option Code | Packing Form Code |
|--------------|------------------|--------------|-------------|-------------------|
| MLX90291 | K | DC | BCA-000 | TU |
| MLX90291 | K | DC | BCA-000 | RE |

Legend:

Temperature Code: K for Temperature Range -40 °C to 125 °C

Package Code: DC for SOIC8

Packing Form: TU for Tube, RE for Reel

Ordering Example: MLX90291-KDC-BCA-000-TU

1 Functional Diagram

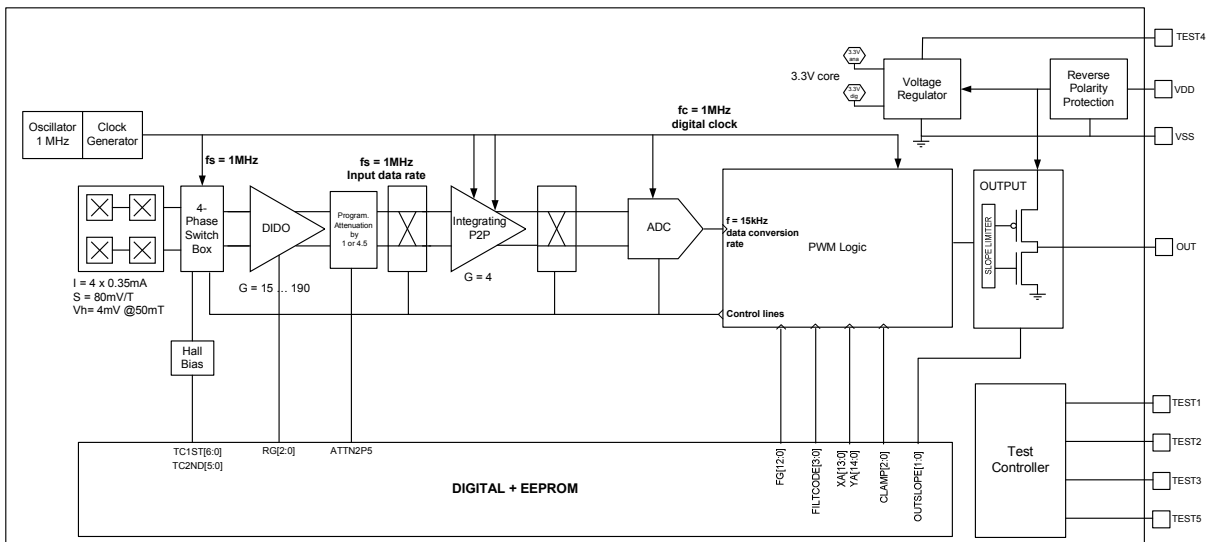


Figure 1: Block diagram

2 General Description

The MLX90291 is a monolithic programmable linear Hall sensor IC, which can provide a PWM output signal proportional to the externally applied magnetic flux density or act as a switch with a programmable threshold level. The transfer characteristic of the MLX90291 is fully programmable (offset, gain, clamping levels, ...).



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4 Glossary of Terms

| | |
|-------|--|
| Tesla | Units for the magnetic flux density, 1 mT = 10 Gauss |
| TC | Temperature Coefficient in ppm/°C |
| NC | Not Connected |
| ADC | Analog-to-Digital Converter |
| PTC | Programming Through Connector |
| POR | Power on Reset |
| INL | Integral Non Linearity |
| DNL | Differential Non Linearity |
| PWM | Pulse Width Modulation |

5 Absolute Maximum Ratings

| Parameter | Symbol | Value | Units |
|--|------------------|--|-------|
| Positive Supply Voltage (over-voltage) | Vdd | +20 | V |
| Reverse Supply Voltage Protection | | -10 -14 (200s max, T _A = +25 °C) | V |
| Positive Output Voltage | | +10 +14 (200s max, T _A = +25 °C) | V |
| Output Current | I _{out} | 20 | mA |
| Reverse Output Voltage ⁽¹⁾ | | -5 | V |
| Reverse Output Current ⁽¹⁾ | | -50 | mA |
| Operating Ambient Temperature Range | T _A | -40 to +150 | °C |
| Storage Temperature Range | T _S | -55 to +150 | °C |
| Magnetic Flux Density | | ± 10 | T |

Table 1: Absolute maximum ratings

(1) Realized through an on-chip resistor along the output line

Exceeding the absolute maximum ratings may cause permanent damage. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

6 Pin Definitions and Descriptions

| Pin № | Name | Type | Function |
|-------|-------|---------|----------------------------------|
| 1 | VDD | Supply | Supply Voltage |
| 2 | VSS | Ground | Ground Voltage |
| 3 | TEST4 | N/A | MLX Test and factory calibration |
| 4 | OUT | Digital | Sensor output signal |
| 5 | TEST5 | N/A | MLX Test and factory calibration |
| 6 | TEST3 | N/A | MLX Test and factory calibration |
| 7 | TEST2 | N/A | MLX Test and factory calibration |
| 8 | TEST1 | N/A | MLX Test and factory calibration |

Table 2: Pin definition and description – S08 package

It is recommended to connect the MLX test pins to the Ground for optimal EMC results. See section 14 for a recommended application diagram

7 General Electrical Specifications

Operating Parameters $T_A = -40^{\circ}\text{C}$ to 125°C , $V_{DD} = 5.0\text{ V}$, using recommended application diagram, unless otherwise specified.

| Parameter | Symbol | Test Conditions | Min | Typ | Max | Units |
|---|-----------------|--|--------------------|-----|--------------------|---------------|
| Nominal Supply Voltage | V_{DD} | | 4.5 | 5 | 5.5 | V |
| Supply Current | I_{DD} | | | 8 | 10 | mA |
| Peak Supply Current | I_{DDpeak} | During power-up and PWM switching | | | 15 | mA |
| Reset Voltage (POR) | V_{POR} | | 2.2 | | 2.7 | V |
| POR Threshold Hysteresis | $V_{PORHYST}$ | | | 0.3 | | V |
| Operating Threshold (rising) | $V_{OPERATING}$ | | | 3.3 | 3.8 | V |
| Under-Voltage Threshold (falling) | V_{UNDER} | Immediate diagnostic low without reset in case of recovery | 2.7 | 3 | | V |
| Operating / Under-Voltage Threshold | V_{HYST} | | | 0.1 | | V |
| Programming Voltage | V_{PROG} | Not Locked Part Output = High Impedance | 6.7 | 7.4 | 7.7 ⁽¹⁾ | V |
| Overvoltage detection | V_{OVER} | Output = High Impedance | 7.5 ⁽¹⁾ | 8.5 | | V |
| Load resistance range (Pull-up/down) | R_L | Pull-up OUT to 5V | 2 | 4.7 | | k Ω |
| Load Capacitor range | C_L | Between OUT and GND | | 10 | | nF |
| Output Saturation Voltage Push Pull Mode | $V_{SATPPHI}$ | $I_{OUT} = +2\text{ mA}$ | $V_{DD} - 0.3$ | | | V |
| | $V_{SATPPLO}$ | $I_{OUT} = -2\text{ mA}$ | | | 0.3 | V |
| Output Saturation Voltage Open Drain Mode | V_{SATOD} | $I_{OUT} = -2\text{ mA}$ Output = Low (Driver ON) | | | 0.3 | V |
| Output Leakage Current Open Drain Mode | I_{LEAKOD} | $V_{OUT} = +5\text{ V}$ Output = High (Driver OFF) | | 2 | 10 | μA |
| Output Short Circuit Current | $I_{OUTSCGND}$ | Current limitation fully ON | + 15 | | + 28 | mA |
| | $I_{OUTSCVDD}$ | Current limitation fully ON | - 28 | | - 15 | mA |

Table 3: General electrical parameters

(1) No overlap possible at the same temperature

8 Magnetic specification

Operating Parameters $T_A = -40^{\circ}\text{C}$ to 125°C , $V_{DD} = 5.0\text{ V}$, unless otherwise specified.

| Parameter | Symbol | Test Conditions | Min | Typ | Max | Units |
|-----------------------------|--------|-----------------|----------|----------|-----------|-------|
| Magnetic Flux Density range | B | | ± 15 | ± 40 | ± 400 | mT |

Table 4: Magnetic specification

9 Timing specification

Operating Parameters $T_A = -40^{\circ}\text{C}$ to 125°C , $V_{DD} = 5.0\text{ V}$, unless otherwise specified

| Parameter | Symbol | Test Conditions | Min | Typ | Max | Units |
|---|---------------|--|-----------------------|---|------|------------|
| Power Up Sequence | t_{ON1} | $0 < V_{DD} < V_{POR}$ | F(V _{DDSR}) | | | ms |
| | t_{ON2} | $V_{POR} < V_{DD} < V_{OPERATING}$ | F(V _{DDSR}) | | | ms |
| | t_{ON3} | $V_{DD} > V_{OPERATING}$ | | 1 | | Cycle |
| Power Supply Slew rate(external) | V_{DDSR} | | 0.0005 | | 5 | V/ μ s |
| EEPROM Check | t_{EEPROM} | EEPROM dump + CRC check | | 0.5 | 1 | ms |
| Main Oscillator Frequency | F_{OSC} | Tolerance $\pm 10\%$ | 921 | 1024 | 1127 | kHz |
| Tick Time | t_{TICK} | | | 0.98 | | μ s |
| PWM Cycle Duration | $Cycle_{PWM}$ | $2^{13} t_{TICK}$ | | 8 | | ms |
| PWM Output Frequency | F_{PWM} | $F_{OSC}/2^{13}$ | | 125 | | Hz |
| Sampling Frequency | F_{SAMPLE} | Analog sampling | | F_{OSC} | | |
| Conversion Rate @ $F_{OSC} = 1024\text{ kHz}$ | F_{CONV} | Measurement: 40 analog samples Conversion (ADC): 25 μ s | | 70 | | μ s |
| Low pass filtering (First order filter) @ $F_{OSC} = 1024\text{ kHz}$ @ -3 db | F_{FILTER} | FILTERCODE = 9 FILTERCODE = 8 FILTERCODE = 7 FILTERCODE = 6 FILTERCODE = 5 FILTERCODE = 4 FILTERCODE = 3 FILTERCODE = 2 | | 4 9 17 35 70 139 279 557 | | Hz |
| Output Slope current generator | I_{SLOPE} | OUTSLOPE = 0 OUTSLOPE = 1 OUTSLOPE = 2 OUTSLOPE = 3 | | 4 6 11 20 | | mA |

Table 5: Timing specification of the analog output

10 PWM output specification

Operating Parameters $T_A = -40^{\circ}\text{C}$ to 125°C , $V_{dd} = 5.0\text{ V}$, unless otherwise specified

| Parameter | Symbol | Test Conditions | Min | Typ | Max | Units |
|--|--|---|------|--------|------|--------------------|
| PWM Output Clamping | SCG _{PWM} | CLAMP = 0 | 1 | | 99 | %DC |
| | | CLAMP = 1 | 4 | | 96 | |
| | | CLAMP = 2 | 5 | | 95 | |
| | | CLAMP = 3 | 6 | | 94 | |
| | | CLAMP = 4 | 7 | | 93 | |
| | | CLAMP = 5 | 8 | | 92 | |
| | | CLAMP = 6 | 9 | | 91 | |
| PWM Output Offset | PWM _{OFF} | Programming Range | 0 | | 100 | %DC |
| PWM Output Offset Resolution | PWM _{OFFRES} | Programming Resolution | | 0.025 | | %DC |
| PWM Output Slope | S | 10%-90% Swing | 0.1 | 1 | 6.4 | %DC/mT |
| PWM Output Slope Resolution | S _{RES} | % of Slope target value (fine gain) | | 0.025 | | % |
| PWM Resolution | LSB _{PWM} | 12 bits | | 0.0125 | | %DC |
| SWITCH Low Level Threshold | SWITCH _{LO} | Switch mode Programming range | 0 | | 100 | % |
| SWITCH High Level Threshold | SWITCH _{HI} | Switch mode Programming range | 0 | | 100 | % |
| SWITCH Programming resolution | SWITCH _{RES} | Switch mode Resolution | | 0.025 | | % |
| PWM Linearity | DNL _{PWM} INL _{PWM} | 13 bits resolution | -1 | | 1 | LSB _{PWM} |
| | | 40 mT – 1%DC/mT | -2 | | 2 | |
| PWM Jitter | JIT _{PWM} | S = 1% DC/mT F _{PWM} = 125 Hz Filter setting: m=32 | -2 | | +2 | LSB _{PWM} |
| PWM Clamping Accuracy | Clamp _{ACC} | | -2 | | +2 | LSB _{PWM} |
| Intrinsic Offset Thermal Drift | $\Delta^{\text{T}}\text{Offset}$ | 25 °C to -40 °C 25 °C to 125 °C | -0.1 | | +0.1 | mT |
| Thermal Sensitivity Drift | $\Delta^{\text{T}}\text{S}$ | After calibration @ MLX full temperature range | -150 | 0 | +150 | ppm/°C |
| Sensitivity thermal coefficient resolution | RES | Incremental TC Adjust 5 bits over $\pm 800\text{ppm}/^{\circ}\text{C}$ | | 50 | | ppm/°C |

Table 6: PWM output specification

11 Fault modes

Operating Parameters $T_A = -40^{\circ}\text{C}$ to 125°C , $V_{dd} = 5.0\text{ V}$, unless otherwise specified

| Parameter | Symbol | Test Conditions | Min | Typ | Max | Units |
|------------------------------|----------------------|-----------------------------|-----|-----|-----|-------|
| Output signal in Fault state | Fault _{OUT} | EEPROM parity fail | 4 | | - | V |
| Parity Fail Criterion | n _{PARITY} | Successive CRC fails before | - | 2 | - | Count |
| Broken VSS | VBR _{VSS} | Pull-Up resistor = 5K | 4 | | | V |
| Broken VDD | VBR _{VDD} | Pull-Up resistor = 5K | 4 | | | V |

Table 7: Fault modes

12 Programmable Items

12.1 Parameter table

| Parameter | Bits | Comment |
|-----------|------|--|
| OUTMODE | 1 | Push pull or open drain output drive |
| ROUGHGAIN | 3 | Rough gain preamplifier |
| FINEGAIN | 13 | Digital fine gain adjustment from -3.999 to +3.999 |
| XA | 14 | Offset before gain |
| YA | 15 | Offset after gain, (Xa,Ya) defines the zero Gauss point |
| CLAMP | 3 | Clamp high and clamp low level |
| FILTCODE | 4 | Digital output filter |
| OUTSLOPE | 2 | Output Slope Control |
| DCDEF | 1 | PWM Duty Cycle Definition |
| TC1ST | 7 | Sensitivity temperature drift correction 1 st order |
| TC2ND | 6 | Sensitivity temperature drift correction 2 nd order |
| OFFDRIFT | 6 | Residual Offset Correction |
| SWITCH | 1 | PWM/Switch mode |
| PLATEPOL | 1 | Invert Sensitivity Sign |
| ATTN2P5 | 1 | Attenuator block switch |
| CSTID | 16 | Melexis ID |

Table 8: Customer programmable items

12.2 Output mode configuration (OUTMODE)

OUTMODE configures the output driver.

| OUTMODE | Output Driver |
|---------|----------------|
| 0 | PWM Open-drain |
| 1 | PWM Push-pull |

Table 9: Output configuration

12.3 Sensitivity programming (ROUGHGAIN, FINEGAIN)

ROUGHGAIN[2:0]

This 3-bit register controls the gain of the pre-amplifier.

- The MSB controls the enable of the PREAMP function with a gain of 4.3 (~2mA extra I_{DD})
- The 2 LSB control the gain of the MAINAMP



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| Value | Typical Gain |
|-------|--------------|
| 0 | 15.0 |
| 1 | 21.6 |
| 2 | 31.1 |
| 3 | 44.8 |
| 4 | 64.5 |
| 5 | 92.9 |
| 6 | 133.7 |
| 7 | 192.6 |

Table 10: ROUGHGAIN versus amplifier gain

FINEGAIN[12:0]

Value defines the digital gain adjustment

- The code 1024 corresponds to a gain of 1
- The MSB is the sign bit which acts as a polarity bit
- FINEGAIN gain range is from -3.9999 to +3.9999

12.4 Offset / output quiescent voltage programming (XA, YA)

XA[13:0]

PWM mode: Offset trimming before FINEGAIN block

Switch mode: Threshold for the output to switch

YA[14:0]

PWM mode: Offset trimming after FINEGAIN block

Switch mode: Hysteresis for the output to switch

Both parameters together define the zero Gauss point in PWM mode

In switch mode, XA is used to set the threshold and YA to set the hysteresis

| Case YA > 0 | Case YA < 0 | Output State |
|--------------------|--------------------|--------------|
| ADC < 4.XA - 16.YA | ADC < 4.XA | Set to Zero |
| ADC > 4.XA | ADC > 4.XA - 16.YA | Set to One |
| Otherwise | Otherwise | Unchanged |

Table 11: Output state as function of XA and YA in switch mode

12.5 Clamping level programming (CLAMP)

CLAMP[2:0] defines the clamping level of the PWM output

| CLAMP | Minimal output [%DC] | Maximal output [%DC] |
|-------|----------------------|----------------------|
| 0 | 1 | 99 |
| 1 | 4 | 96 |
| 2 | 5 | 95 |
| 3 | 6 | 94 |
| 4 | 7 | 93 |
| 5 | 8 | 92 |
| 6 | 9 | 91 |
| 7 | 10 | 90 |

Table 12: CLAMP parameter versus output.

12.6 Bandwidth and filter programming (FILTCODE)

FILTCODE[3:0] allows adjusting the internal bandwidth of the sensor in order to optimize for speed or resolution.

| FILTCODE | Cut off frequency [Hz] | Attenuation [dB] | Tau [ms] |
|----------|------------------------|------------------|----------|
| 2 | 557 | -8.0 | 0.29 |
| 3 | 279 | -11.2 | 0.57 |
| 4 | 139 | -14.4 | 1.14 |
| 5 | 70 | -18.1 | 2.29 |
| 6 | 35 | -22.4 | 4.57 |
| 7 | 17 | -27.1 | 9.14 |
| 8 | 9 | -32.3 | 18.29 |
| 9 | 4 | -38.1 | 36.57 |

Table 13: FILTCODE settings PWM mode

12.7 Current limitation (OUTSLOPE)

2 Bit register to set the current limitation for slew rate control

| OUTSLOPE | Current limitation [mA] |
|----------|-------------------------|
| 0 | 4 |
| 1 | 6 |
| 2 | 11 |
| 3 | 20 |

Table 14: Current limitation

12.8 PWM Mode duty cycle definition (DCDEF)

The PWM duty cycle definition is as follows.

| DCDEF | PWM duty cycle definition |
|-------|--|
| 0 | $t_{\text{Low}} / (t_{\text{Low}} + t_{\text{High}})$ |
| 1 | $t_{\text{High}} / (t_{\text{Low}} + t_{\text{High}})$ |

Table 15: PWM duty cycle definition

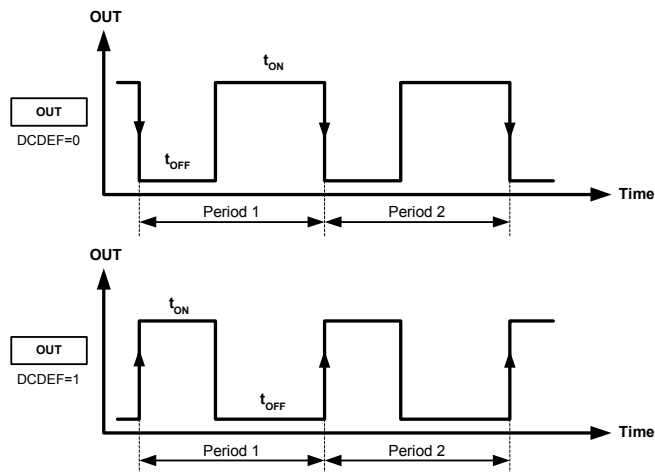


Figure 2: Two different PWM modes

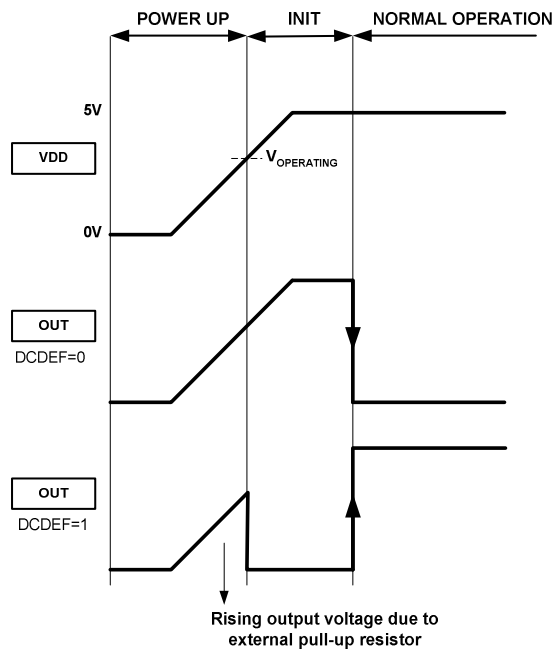


Figure 3: Power-on behaviour of the two different modes

12.9 Sensitivity and temperature drift programming (TC1ST, TC2ND)

TC1ST[6:0]

Programming first order sensitivity temperature drift

| Value | Typical 1 st order TC |
|----------|----------------------------------|
| 0 | +2740ppm/°C |
| 63 or 64 | 0ppm/°C |
| 127 | -2950ppm/°C |

Table 16: TC1ST parameter

TC2ND[5:0]

Programming second order sensitivity temperature drift

| Value | Typical 2 nd order TC |
|---------|----------------------------------|
| 0 or 32 | 0 ppm/°C ² |
| 31 | +6.8 ppm/°C ² |
| 63 | -6.1 ppm/°C ² |

Table 17: TC2ND parameter

12.10 Offset temperature drift programming (OFFDRIFT)

OFFDRIFT[5:0] parameter defines the offset behaviour over temperature (1st order)

| Value | Offset drift correction |
|---------|-------------------------|
| 0 or 32 | 0 mV/°C |
| 31 | +0.9 mV/°C |
| 63 | -0.9 mV/°C |

Table 18: OFFDRIFT parameter versus correction

12.11 Functional mode (SWITCH)

| Value | Offset drift correction |
|-------|-------------------------|
| 0 | PWM output mode |
| 1 | Switch output mode |

Table 19: SWITCH parameter

12.12 Polarity (PLATEPOL)

PLATEPOL parameter changes the sign of the measured sensitivity
Default value = 0



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12.13 Attenuator (ATTN2P5)

Switch to control the attenuation block in the signal path

| Value | ATTN2P5 |
|-------|--------------------------|
| 0 | Attenuation factor = 1 |
| 1 | Attenuation factor = 4.5 |

Table 20: Attenuation settings

12.14 Customer ID (CSTID)

16-bit customer programmable ID

13 Recommended Application Diagrams

13.1 Resistor and Capacitor Values

| Part | Description | Value | Unit |
|------|-------------------------------|-------|------------|
| C1 | Decoupling, EMI, ESD | 10 | nF |
| C2 | Supply capacitor, EMI, ESD | 100 | nF |
| R1 | Pull up or pull down resistor | 4.7 | k Ω |

Table 21: Resistive and capacitive values for the recommended application diagrams

13.2 Pull down resistor for diagnostic low

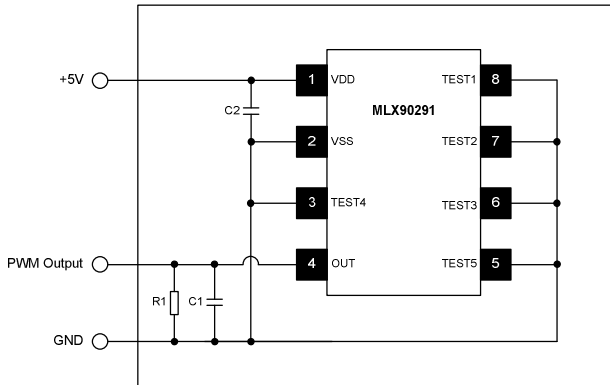


Figure 4: Diagnostic low

13.3 Pull up resistor for diagnostic high

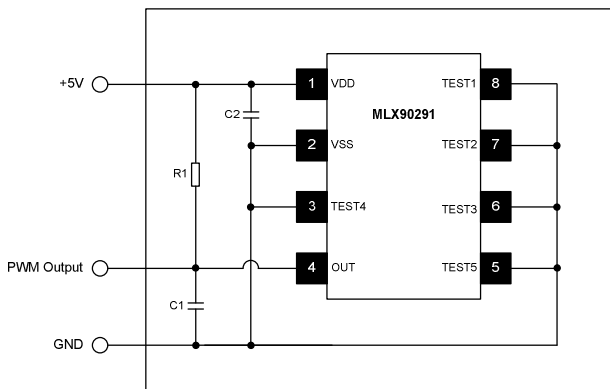


Figure 5: Diagnostic high

14 Standard information regarding manufacturability of Melexis products with different soldering processes

Our products are classified and qualified regarding soldering technology, solderability and moisture sensitivity level according to following test methods:

Reflow Soldering SMD's (Surface Mount Devices)

- IPC/JEDEC J-STD-020
Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices (classification reflow profiles according to table 5-2)
- EIA/JEDEC JESD22-A113
Preconditioning of Nonhermetic Surface Mount Devices Prior to Reliability Testing (reflow profiles according to table 2)

Wave Soldering SMD's (Surface Mount Devices) and THD's (Through Hole Devices)

- EN60749-20
Resistance of plastic- encapsulated SMD's to combined effect of moisture and soldering heat
- EIA/JEDEC JESD22-B106 and EN60749-15
Resistance to soldering temperature for through-hole mounted devices

Iron Soldering THD's (Through Hole Devices)

- EN60749-15
Resistance to soldering temperature for through-hole mounted devices

Solderability SMD's (Surface Mount Devices) and THD's (Through Hole Devices)

- EIA/JEDEC JESD22-B102 and EN60749-21
Solderability

For all soldering technologies deviating from above mentioned standard conditions (regarding peak temperature, temperature gradient, temperature profile etc) additional classification and qualification tests have to be agreed upon with Melexis.

The application of Wave Soldering for SMD's is allowed only after consulting Melexis regarding assurance of adhesive strength between device and board.

Melexis recommends reviewing on our web site the General Guidelines [soldering recommendation](http://www.melexis.com/Quality_soldering.aspx) (http://www.melexis.com/Quality_soldering.aspx) as well as [trim&form recommendations](http://www.melexis.com/Assets/Trim-and-form-recommendations-5565.aspx) (<http://www.melexis.com/Assets/Trim-and-form-recommendations-5565.aspx>).

Melexis is contributing to global environmental conservation by promoting **lead free** solutions. For more information on qualifications of **RoHS** compliant products (RoHS = European directive on the Restriction Of the use of certain Hazardous Substances) please visit the quality page on our website: <http://www.melexis.com/quality.aspx>

15 ESD Precautions

Electronic semiconductor products are sensitive to Electro Static Discharge (ESD). Always observe Electro Static Discharge control procedures whenever handling semiconductor products.

16 Package Information

16.1 SOIC8 Package Dimensions

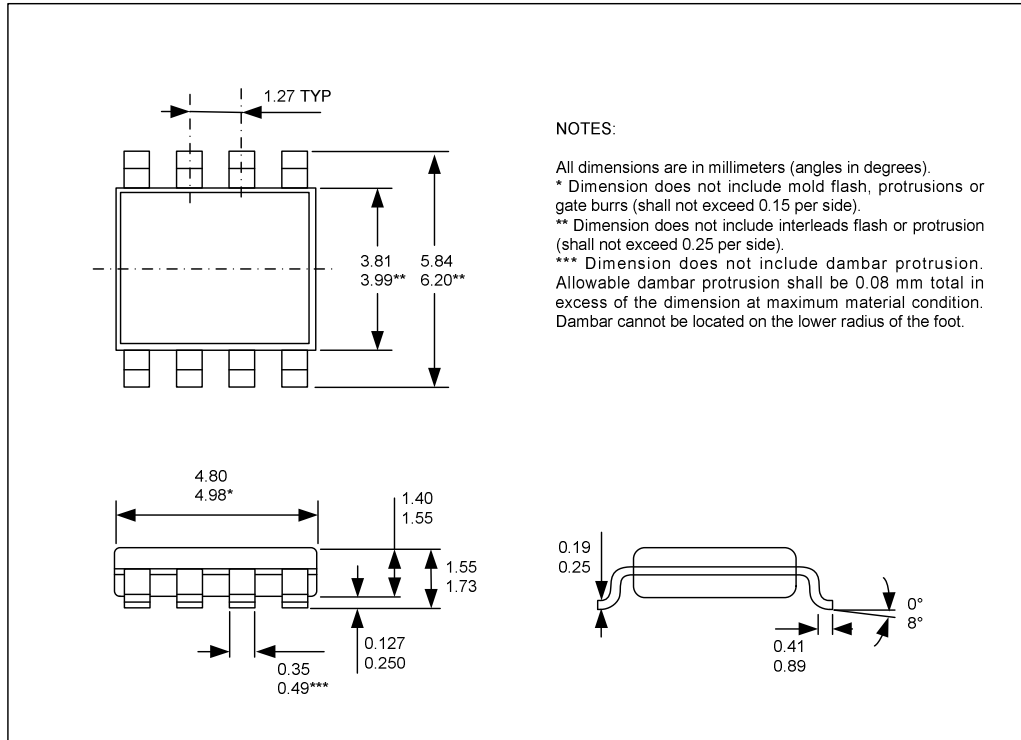


Figure 6: Package dimensions

16.2 SOIC8 Pin Out and Marking

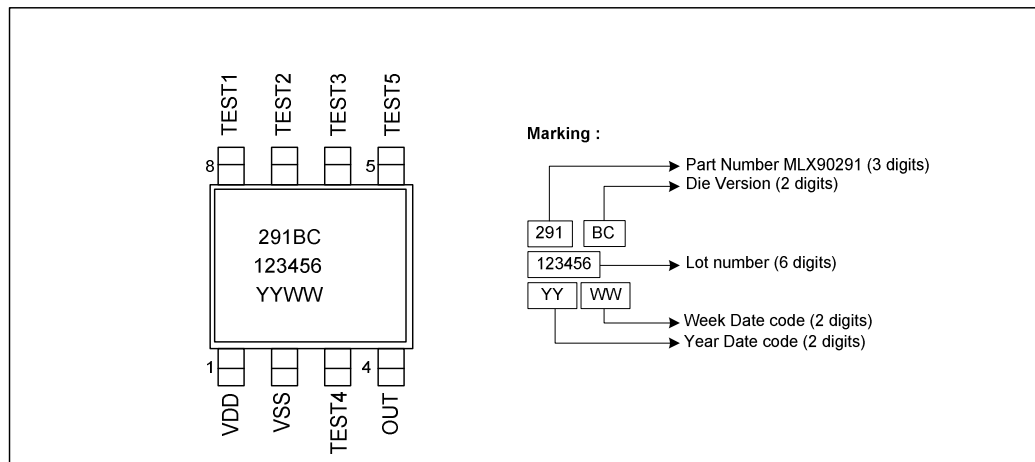


Figure 7: Pin out and marking

16.3 SOIC8 Hall plate positioning

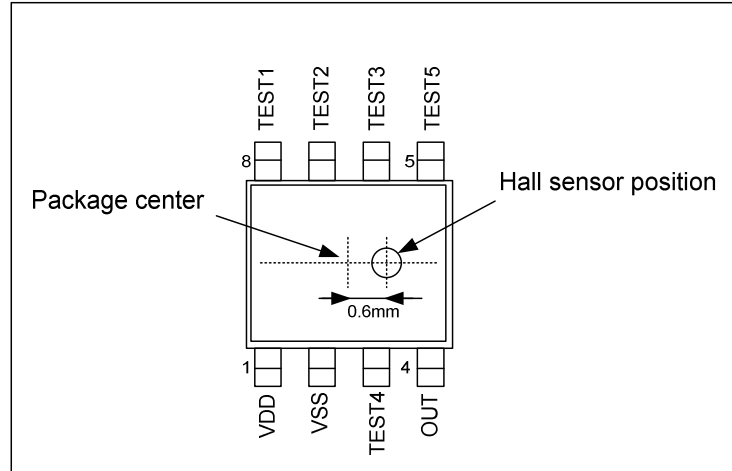


Figure 8: Hall Plate positioning



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